YOLOv3 Documentation

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ONE

YOLOV3 TRAIN

src.train2.main(inputs)

Main driver script for training the YOLOv3 network.

Inputs:

inputs: an input file formatted according to the InputFile class

Outputs:

inputs.outdir/results.txt: output metrics for each training epoch
inputs.loaddir/latest.pt: checkpoint file for latest network configuration
inputs.loaddir/best.pt: checkpoint file for best current network configuration
inputs.loaddir/backup.pt: checkpoint file for backup purposes

TWO

YOLOV3 DETECT

class src.detect.ConvNetb(num_classes=60)

forward(x)

Defines the computation performed at every call.

Should be overridden by all subclasses.

Note: Although the recipe for forward pass needs to be defined within this function, one should call the Module instance afterwards instead of this since the former takes care of running the registered hooks while the latter silently ignores them.

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YOLOV3 INPUTFILE

FOUR

YOLOV3 MODELS

class src.models.Darknet (config_path, img_size=416)

YOLOv3 object detection model

forward (*x*, targets=None, requestPrecision=False, weight=None, epoch=None)

Defines the computation performed at every call.

Should be overridden by all subclasses.

Note: Although the recipe for forward pass needs to be defined within this function, one should call the Module instance afterwards instead of this since the former takes care of running the registered hooks while the latter silently ignores them.

class src.models.EmptyLayer

Placeholder for 'route' and 'shortcut' layers

class src.models.YOLOLayer(anchors, nC, img_dim, anchor_idxs)

forward (p, targets=None, requestPrecision=False, weight=None, epoch=None)

Defines the computation performed at every call.

Should be overridden by all subclasses.

Note: Although the recipe for forward pass needs to be defined within this function, one should call the Module instance afterwards instead of this since the former takes care of running the registered hooks while the latter silently ignores them.

src.models.create_modules (module_defs)

Constructs module list of layer blocks from module configuration in module_defs

Creates a yolo-v3 layer configuration file from desired options

src.models.parse_model_config(path)

Parses the yolo-v3 layer configuration file and returns module definitions

CHAPTER	
FIVE	

YOLOV3 NETWORKTRAINER

YOLOV3 TARGET

```
class src.targets.Target.Target(inputs)
  Class for handling target pre-processing tasks.

apply_mask_to_filtered_data()
    Method to apply mask to filtered data variables.

compute_bounding_box_clusters_using_kmeans(n_clusters)

Method to compute bounding box clusters using kmeans.
```

Inputs:

n_clusters: number of desired kmeans clusters

compute_cropped_data()

Method to crop image data based on the width and height. Filtered variables are then computed based on the updated image coordinates.

compute_filtered_data_mask()

Method to compute filtered data by applying several filtering operations.

compute_filtered_variables_from_filtered_coords()

Method to compute filtered variables from filtered coordinates.

${\tt compute_filtered_variables_from_filtered_xy} \ (\,)$

Method to compute filtered variables from filtered xy.

${\tt compute_image_weights_with_filtered_data}\ ()$

Method to compute image weights from filtered data. Weight is simply inverse of class frequency.

edge_requirements (w_lim, h_lim, x2_lim, y2_lim)

Method to compute filtering based on edge specifications.

Inputs:

w_lim: limit for image widthh_lim: limit for image heightx2_lim: limit for image x2y2_lim: limit for image y2

Outputs:

indices where filtered variables satisfy the dimension requirements.

load_target_file()

Method to load a targetfile of type specified in the input file. Supported types: .json.

manual_dimension_requirements(area_lim, w_lim, h_lim, AR_lim)

Method to compute filtering based on specified dimension requirements.

Inputs:

area_lim: limit for image areaw_lim: limit for image widthh_lim: limit for image heightAR_lim: limit for image aspect ratio

Outputs:

indices where filtered variables satisfy the dimension requirements.

process_target_data()

Method to perform all target processing.

set_image_w_and_h()

Method to set width and height of images associated with targets.

sigma_rejection_indices (filtered_data)

Method to compute a mask based on a sigma rejection criterion.

Inputs:

filtered_data: data to which sigma rejection is applied and from which mask is computed

Outputs:

mask_reject: binary mask computed from sigma rejection

strip_image_number_from_chips_and_files()

Method to strip numbers from image filenames from both chips and files.

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YOLOV3 FCN_SIGMA_REJECTION

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YOLOV3 FCN_SIGMA_REJECTION

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NINE	

YOLOV3 DATASETPROCESSING

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YOLOV3 DATASETS

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YOLOV3 UTILS

```
utils.utils.bbox_iou (box1, box2, x1y1x2y2=True)
Returns the IoU of two bounding boxes

utils.utils.build_targets (pred_boxes, pred_conf, pred_cls, target, anchor_wh, nA, nC, nG, requestPrecision)
returns nGT, nCorrect, tx, ty, tw, th, tconf, tcls

utils.utils.compute_ap (recall, precision)
Compute the average precision, given the recall and precision curves. Code originally from https://github.com/rbgirshick/py-faster-rcnn. # Arguments
recall: The recall curve (list). precision: The precision curve (list).

# Returns The average precision as computed in py-faster-rcnn.
```

Returns The average precision as compared in py-18

utils.utils.load_classes (path)

Loads class labels at 'path'

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