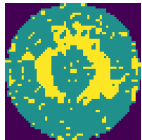


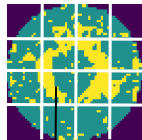
Sample



CNN



*predicted
defect*



Sample



Measurement
system



GRU

h_t



Confidence
estimator



*trust /
do not trust*

p_t

*predicted
defect*

action a_t :
next patch

RL agent
(controller)

state s_t
reward r_t