

AYETI CIBOLAHAN S.

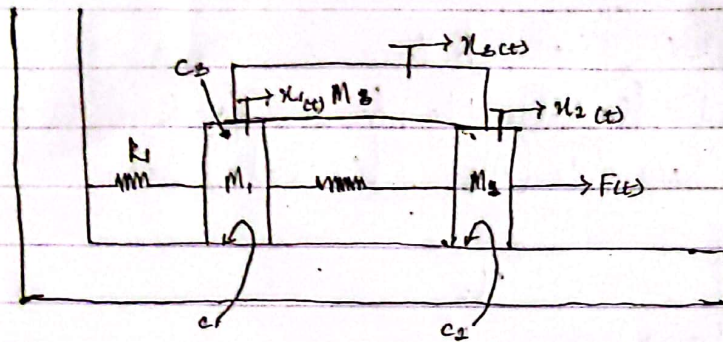
Mechanical engineering.

EES/18/19/0175

MEC 403 (ASSIGNMENT)

40014

- 2] Give a mechanical system, resolve the form of the block diagram & calculate the transfer function.



Write the equation of motion that relates them together.

→ Mass  $M_1$

$$\left[ \begin{array}{l} \text{Sum of Impedances} \\ \text{Connected to motion} \\ \text{of } M_1 \end{array} \right] X_1(s) - \left[ \begin{array}{l} \text{Sum of Impedances} \\ \text{between } M_1 \text{ and } M_2 \end{array} \right] X_2(s) =$$

$$\left[ \begin{array}{l} \text{Sum of Impedances} \\ \text{between } M_1 \text{ and } M_3 \end{array} \right] X_3(s) = \left[ \begin{array}{l} \text{Sum of applied} \\ \text{Force at } M_1 \end{array} \right]$$

$$[M_1 s^2 + (c_1 + c_3)s + (K_1 + K_2)]X_1(s) - K_2 X_2(s) - C_3 X_3(s) = 0 \dots \dots (1)$$

→ Mass  $M_2$

$$\left[ \begin{array}{l} \text{Sum of Impedances} \\ \text{Connected to the} \\ \text{motion } M_2 \end{array} \right] X_2(s) - \left[ \begin{array}{l} \text{Sum of Impedances} \\ \text{between } M_1 \text{ and} \\ M_2 \end{array} \right] X_1(s) - \left[ \begin{array}{l} \text{Sum of Impedances} \\ \text{between } M_2 \text{ and } M_3 \end{array} \right] X_3(s) =$$

$$= \left[ \begin{array}{l} \text{Sum of applied} \\ \text{Force at } M_2 \end{array} \right]$$

$$[M_2 s^2 + (c_2 + c_4)s + K_2]X_2(s) - K_2 X_1(s) - C_4 X_3(s) = F_2(s) \dots \dots (2)$$



→ Mass  $M_3$

$$\left[ \begin{array}{c} \text{Sum of Impedances} \\ \text{Connected to the} \\ \text{Motion of } M_3 \end{array} \right] X_{3cs} - \left[ \begin{array}{c} \text{Sum of Impedances} \\ \text{between } m_1 \text{ \& } \\ m_2 \end{array} \right] X_{1cs} - \left[ \begin{array}{c} \text{Sum of Impedances} \\ \text{between } m_2 \text{ \& } m_3 \end{array} \right] X_{2cs} \\ = \left[ \begin{array}{c} \text{Sum of applied forces} \\ \text{at } M_3 \end{array} \right]$$

$$[M_3 s^2 + (C_3 + C_4)s] X_{3cs} - C_{3s} X_{1cs} - C_{4s} X_{2cs} = 0 \dots (3)$$

Resolving The EOM

$$\begin{aligned} [M_1 s^2 + (C_3 + C_4)s + (k_1 + k_2)] X_{1cs} - k_2 X_{2cs} - C_{3s} X_{3cs} &= 0 \\ -k_2 X_{1cs} + [M_2 s^2 + (C_2 + C_4)s + k_2] X_{2cs} - C_{4s} X_{3cs} &= F_{cs} \\ -C_{3s} X_{1cs} - C_{4s} X_{2cs} + [M_3 s^2 + (C_3 + C_4)s] X_{3cs} &= 0 \end{aligned}$$

$$\left| \begin{array}{ccc} X_1 & X_2 & X_3 \\ M_1 s^2 + (C_3 + C_4)s + (k_1 + k_2) & -k_2 & -C_{3s} \\ -k_2 & M_2 s^2 + (C_2 + C_4)s + k_2 & -C_{4s} \\ -C_{3s} & -C_{4s} & M_3 s^2 + (C_3 + C_4)s \end{array} \right|$$

Using Crammer's rule to solve for  $X_{1cs}$

$$X_{1cs} = \frac{\begin{vmatrix} 0 & -k_2 & -C_{3s} \\ F_{cs} & M_2 s^2 + (C_2 + C_4)s + k_2 & -C_{4s} \\ 0 & -C_{4s} & M_3 s^2 + (C_3 + C_4)s \end{vmatrix}}{\Delta}$$

$$\Delta = \begin{vmatrix} M_1 s^2 + (C_3 + C_4)s + k_2 & -k_2 \\ -k_2 & M_2 s^2 + (C_2 + C_4)s + k_2 \\ -C_{3s} & -C_{4s} & M_3 s^2 + (C_3 + C_4)s \end{vmatrix}$$

$$\begin{aligned} & -[-k_2] \begin{vmatrix} F_{cs} & -C_{4s} \\ 0 & M_3 s^2 + (C_3 + C_4)s \end{vmatrix} \\ & + [-C_{3s}] \begin{vmatrix} F_{cs} & M_2 s^2 + (C_2 + C_4)s + k_2 \\ 0 & -C_{4cs} \end{vmatrix} \end{aligned}$$

$$\begin{aligned} &= 0 + k_2 [F_{cs} \cdot [M_3 s^2 + (C_3 + C_4)s] + C_{3s} (F_{cs} \cdot C_{4cs})] \\ &= F_{cs} [k_2 (M_3 s^2 + (C_3 + C_4)s) + [C_{3s} \cdot C_{4s}]] \end{aligned}$$



$$X_{ics} = F_{cs} \frac{[k_2 (M_3 S^a + [C_3 + C_4]_s) + [C_{3s} \cdot C_{4s}]]}{\Delta}$$

$$\frac{X_{ics}}{F_{cs}} = \frac{k_2 [M_3 S^a + [C_3 + C_4]_s] + [C_{3s} \cdot C_{4s}]}{\Delta}$$