More Random Sampling Methods

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1.1 Specific Distributions

Requires random real numbers. This section shows algorithms to sample several popular non-uniform distributions. The algorithms are exact unless otherwise noted, and applications should choose algorithms with either no error (including rounding error) or a user-settable error bound. See the **appendix** for more information.

1.1.1 Normal (Gaussian) Distribution

The <u>normal distribution</u> (also called the Gaussian distribution) takes the following two parameters:

- mu (μ) is the mean (average), or where the peak of the distribution's "bell curve" is.
- sigma (σ), the standard deviation, affects how wide the "bell curve" appears. The probability that a normally-distributed random number will be within one standard deviation from the mean is about 68.3%; within two standard deviations (2 times sigma), about 95.4%; and within three standard deviations, about 99.7%. (Some publications give σ^2 , or variance, rather than standard deviation, as the second parameter. In this case, the standard deviation is the variance's square root.)

There are a number of methods for sampling the normal distribution. An application can combine some or all of these.

- $1. \ \, \text{The ratio-of-uniforms method (given as Normal Ratio Of Uniforms below)}.$
- 2. In the Box-Müller transformation, mu + radius * cos(angle) and mu + radius *

- sin(angle), where angle = RNDRANGEMaxExc(0, 2 * pi) and radius = sqrt(Expo(0.5)) * sigma, are two independent normally-distributed random numbers. The polar method (given as NormalPolar below) likewise produces two independent normal random numbers at a time.
- 3. Karney's algorithm to sample from the normal distribution, in a manner that minimizes approximation error and without using floating-point numbers (Karney 2014)(1).
- 4. The following are approximations to the normal distribution:
 - The sum of twelve RNDRANGEMaxExc(0, sigma) numbers (see Note 13), subtracted by 6 * sigma. See NormalCLT below, which also includes an optional step to "warp" the random number for better accuracy (Kabal 2000/2019)⁽²⁾ See also "Irwin-Hall distribution" on Wikipedia. D. Thomas (2014)⁽³⁾, describes a more general approximation called CLT_k, which combines k uniform random numbers as follows: RNDU01() RNDU01() + RNDU01()
 - Inversions of the normal distribution's cumulative distribution function (CDF), including those by Wichura, by Acklam, and by Luu (Luu 2016)⁽⁴⁾. See also "A literate program to compute the inverse of the normal CDF". Notice that the normal distribution's inverse CDF has no closed form.

For surveys of Gaussian samplers, see (Thomas et al. $2007)^{(5)}$, and (Malik and Hemani $2016)^{(6)}$.

```
METHOD NormalRatioOfUniforms(mu, sigma)
    while true
        a=RNDU01ZeroExc()
        b=RNDRANGE(0,sqrt(2.0/exp(1.0)))
        if b*b <= -a * a * 4 * ln(a)
          return (RNDINT(1) * 2 - 1) *
            (b * sigma / a) + mu
        end
    end
END METHOD
METHOD NormalPolar(mu, sigma)
 while true
    a = RNDU01ZeroExc()
    b = RNDU01ZeroExc()
    if RNDINT(1) == 0: a = 0 - a
    if RNDINT(1) == 0: b = 0 - b
    c = a * a + b * b
    if c != 0 and c <= 1
       c = sqrt(-ln(c) * 2 / c)
       return [a * sigma * c + mu, b * sigma * c + mu]
    end
  end
END METHOD
METHOD NormalCLT(mu, sigma)
  sum = 0
  for i in 0...12: sum=sum+RNDRANGEMaxExc(0, sigma)
  sum = sum - 6*sigma
  // Optional: "Warp" the sum for better accuracy
  ssq = sum * sum
  sum = ((((0.0000001141*ssg - 0.0000005102) *
            ssq + 0.00007474) *
            ssq + 0.0039439) *
            ssq + 0.98746) * sum
  return sum + mu
```

Notes:

- 1. The standard normal distribution is implemented as Normal (0, 1).
- Methods implementing a variant of the normal distribution, the discrete Gaussian distribution, generate integers that closely follow the normal distribution. Examples include the one in (Karney 2014)⁽¹⁾, an improved version in (Du et al. 2020)⁽⁷⁾, as well as so-called "constant-time" methods such as (Micciancio and Walter 2017)⁽⁸⁾ that are used above all in lattice-based cryptography.

1.1.2 Gamma Distribution

The following method generates a random number that follows a *gamma distribution* and is based on Marsaglia and Tsang's method from $2000^{(9)}$ (which is an approximate but simple algorithm) and (Liu et al. 2015)⁽¹⁰⁾. Usually, the number expresses either—

- the lifetime (in days, hours, or other fixed units) of a random component with an average lifetime of meanLifetime, or
- a random amount of time (in days, hours, or other fixed units) that passes until as many events as meanLifetime happen.

Here, meanLifetime must be an integer or noninteger greater than 0, and scale is a scaling parameter that is greater than 0, but usually 1 (the random gamma number is multiplied by scale).

```
METHOD GammaDist(meanLifetime, scale)
    // Needs to be greater than 0
    if meanLifetime <= 0 or scale <= 0: return error
    // Exponential distribution special case if
    // `meanLifetime` is 1 (see also (Devroye 1986), p. 405)
    if meanLifetime == 1: return Expo(1.0 / scale)
    if meanLifetime < 0.3 // Liu, Martin, Syring 2015
      lamda = (1.0/meanLifetime) - 1
      w = meanLifetime / (1-meanLifetime) * exp(1)
       r = 1.0/(1+w)
      while true
            z = 0
            x = RNDU01()
            if x \le r: z = -\ln(x/r)
            else: z = -Expo(lamda)
            ret = exp(-z/meanLifetime)
            eta = 0
            if z \ge 0: eta=exp(-z)
            else: eta=w*lamda*exp(lamda*z)
            if RNDRANGE(0, eta) < exp(-ret-z): return ret * scale
      end
    end
    d = meanLifetime
    if meanLifetime < 1: d = d + 1
    d = d - (1.0 / 3) // NOTE: 1.0 / 3 must be a fractional number
    c = 1.0 / sqrt(9 * d)
    while true
        x = 0
        while true
           x = Normal(0, 1)
```

```
v = c * x + 1;
v = v * v * v
if v > 0: break
end
u = RNDU01ZeroExc()
x2 = x * x
if u < 1 - (0.0331 * x2 * x2): break
if ln(u) < (0.5 * x2) + (d * (1 - v + ln(v))): break
end
ret = d * v
if meanLifetime < 1
ret = ret * pow(RNDU01(), 1.0 / meanLifetime)
end
return ret * scale
END METHOD
```

Note: The following is a useful identity for the gamma distribution: GammaDist(a) = BetaDist(a, b - a) * GammaDist(b) (Stuart 1962)(11).

1.1.3 Beta Distribution

The beta distribution is a bounded-domain probability distribution; its two parameters, a and b, are both greater than 0 and describe the distribution's shape. Depending on a and b, the shape can be a smooth peak or a smooth valley.

The following method generates a random number that follows a *beta distribution*, in the interval [0, 1).

```
METHOD BetaDist(a, b)
  if b==1 and a==1: return RNDU01()
  // Min-of-uniform
  if a==1: return 1.0-pow(RNDU01(),1.0/b)
  // Max-of-uniform. Use only if a is small to
  // avoid accuracy problems, as pointed out
  // by Devroye 1986, p. 675.
  if b==1 and a < 10: return pow(RNDU01(),1.0/a)
  x=GammaDist(a,1)
  return x/(x+GammaDist(b,1))
END METHOD</pre>
```

I give an <u>error-bounded sampler</u> for the beta distribution (when a and b are both 1 or greater) in a separate page.

1.1.4 von Mises Distribution

The von Mises distribution describes a distribution of circular angles and uses two parameters: mean is the mean angle and kappa is a shape parameter. The distribution is uniform at kappa = 0 and approaches a normal distribution with increasing kappa.

The algorithm below generates a random number from the von Mises distribution, and is based on the Best-Fisher algorithm from 1979 (as described in (Devroye 1986)⁽¹²⁾ with errata incorporated).

```
METHOD VonMises(mean, kappa)
  if kappa < 0: return error
  if kappa == 0
     return RNDRANGEMinMaxExc(mean-pi, mean+pi)
  end
  r = 1.0 + sqrt(4 * kappa * kappa + 1)</pre>
```

```
rho = (r - sqrt(2 * r)) / (kappa * 2)
    s = (1 + rho * rho) / (2 * rho)
    while true
        u = RNDRANGEMaxExc(-pi, pi)
        v = RNDU01Zero0neExc()
        z = cos(u)
        W = (1 + s*z) / (s + z)
        y = kappa * (s - w)
        if y*(2 - y) - v >= 0 or ln(y / v) + 1 - y >= 0
           if angle<-1: angle=-1
           if angle>1: angle=1
           // NOTE: Inverse cosine replaced here
           // with `atan2` equivalent
           angle = atan2(sqrt(1-w*w),w)
           if u < 0: angle = -angle
           return mean + angle
        end
    end
END METHOD
```

1.1.5 Stable Distribution

As more and more independent random numbers, generated the same way, are added together, their distribution tends to a <u>stable distribution</u>, which resembles a curve with a single peak, but with generally "fatter" tails than the normal distribution. (Here, the stable distribution means the "alpha-stable distribution".) The pseudocode below uses the Chambers-Mallows-Stuck algorithm. The Stable method, implemented below, takes two parameters:

- alpha is a stability index in the interval (0, 2].
- beta is an asymmetry parameter in the interval [-1, 1]; if beta is 0, the curve is symmetric.

```
METHOD Stable(alpha, beta)
    if alpha <=0 or alpha > 2: return error
    if beta < -1 or beta > 1: return error
    halfpi = pi * 0.5
    unif=RNDRANGEMinMaxExc(-halfpi, halfpi)
    c=cos(unif)
    if alpha == 1
       s=sin(unif)
       if beta == 0: return s/c
       expo=Expo(1)
       return 2.0*((unif*beta+halfpi)*s/c -
         beta * ln(halfpi*expo*c/(unif*beta+halfpi)))/pi
    else
       z=-tan(alpha*halfpi)*beta
       ug=unif+atan2(-z, 1)/alpha
       cpow=pow(c, -1.0 / alpha)
       return pow(1.0+z*z, 1.0 / (2*alpha))*
          (sin(alpha*ug)*cpow)*
          pow(cos(unif-alpha*ug)/expo, (1.0 - alpha) / alpha)
    end
END METHOD
```

Methods implementing the strictly geometric stable and general geometric stable distributions are shown below (Kozubowski 2000)⁽¹³⁾. Here, alpha is in (0, 2], lamda is greater than 0, and tau's absolute value is min(1, 2/alpha - 1). The result of Geometric Stable

is a symmetric Linnik distribution if tau = 0, or a Mittag-Leffler distribution if tau = 1 and alpha < 1.

```
METHOD GeometricStable(alpha, lamda, tau)
   rho = alpha*(1-tau)/2
   sign = -1
   if RNDINT(1)==0 or RNDU01() < tau
       rho = alpha*(1+tau)/2
       sign = 1
   end
  w = 1
   if rho != 1
      rho = rho * pi
     cotparam = RNDRANGE(0, rho)
     w = sin(rho)*cos(cotparam)/sin(cotparam)-cos(rho)
   return Expo(1) * sign * pow(lamda*w, 1.0/alpha)
END METHOD
METHOD GeneralGeoStable(alpha, beta, mu, sigma)
   z = Expo(1)
   if alpha == 1: return mu*z+Stable(alpha, beta)*sigma*z+
          sigma*z*beta*2*pi*ln(sigma*z)
   else: return mu*z+
          Stable(alpha, beta)*sigma*pow(z, 1.0/alpha)
END METHOD
```

1.1.6 Multivariate Normal (Multinormal) Distribution

The following pseudocode calculates a random vector (list of numbers) that follows a *multivariate normal (multinormal) distribution*. The method MultivariateNormal takes the following parameters:

- A list, mu (μ), which indicates the means to add to the random vector's components. mu can be nothing, in which case each component will have a mean of zero.
- A list of lists cov, that specifies a covariance matrix (Σ, a symmetric positive definite N×N matrix, where N is the number of components of the random vector).

```
METHOD Decompose(matrix)
  numrows = size(matrix)
  if size(matrix[0])!=numrows: return error
  // Does a Cholesky decomposition of a matrix
  // assuming it's positive definite and invertible
  ret=NewList()
  for i in 0...numrows
    submat = NewList()
    for j in 0...numrows: AddItem(submat, 0)
   AddItem(ret, submat)
  s1 = sqrt(matrix[0][0])
  if s1==0: return ret // For robustness
  for i in 0...numrows
    ret[0][i]=matrix[0][i]*1.0/s1
  end
  for i in 0...numrows
    msum=0.0
    for j in 0...i: msum = msum + ret[j][i]*ret[j][i]
    sq=matrix[i][i]-msum
    if sq<0: sq=0 // For robustness
```

```
ret[i][i]=math.sqrt(sq)
  end
  for i in 0...numrows
    for i in (j + 1) \dots numrows
      // For robustness
      if ret[j][j]==0: ret[j][i]=0
      if ret[j][j]!=0
        for k in 0...j: msum = msum + ret[k][i]*ret[k][j]
        ret[j][i]=(matrix[j][i]-msum)*1.0/ret[j][j]
      end
    end
  end
  return ret
END METHOD
METHOD MultivariateNormal(mu, cov)
  mulen=size(cov)
  if mu != nothing
    mulen = size(mu)
    if mulen!=size(cov): return error
    if mulen!=size(cov[0]): return error
  // NOTE: If multiple random points will
  // be generated using the same covariance
  // matrix, an implementation can consider
  // precalculating the decomposed matrix
  // in advance rather than calculating it here.
  cho=Decompose(cov)
  i = 0
  ret=NewList()
  vars=NewList()
  for j in 0...mulen: AddItem(vars, Normal(0, 1))
  while i<mulen
    nv=Normal(0,1)
    msum = 0
    if mu == nothing: msum=mu[i]
    for j in 0...mulen: msum=msum+vars[j]*cho[j][i]
    AddItem(ret, msum)
    i=i+1
  end
  return ret
end
```

Note: The **Python sample code** contains a variant of this method for generating multiple random vectors in one call.

Examples:

- 1. A **binormal distribution** (two-variable multinormal distribution) can be sampled using the following idiom: MultivariateNormal([mu1, mu2], [[s1*s1, s1*s2*rho], [rho*s1*s2, s2*s2]]), where mu1 and mu2 are the means of the two normal random numbers, s1 and s2 are their standard deviations, and rho is a *correlation coefficient* greater than -1 and less than 1 (0 means no correlation).
- 2. **Log-multinormal distribution**: Generate a multinormal random vector, then apply exp(n) to each component n.
- 3. A **Beckmann distribution**: Generate a random binormal vector vec, then apply Norm(vec) to that vector.
- 4. A Rice (Rician) distribution is a Beckmann distribution in which the

- binormal random pair is generated with m1 = m2 = a / sqrt(2), rho = 0, and s1 = s2 = b, where a and b are the parameters to the Rice distribution.
- 5. **Rice-Norton distribution**: Generate vec = MultivariateNormal([v,v,v], [[w,0,0],[0,w,0],[0,0,w]]) (where v = a/sqrt(m*2), w = b*b/m, and a, b, and m are the parameters to the Rice-Norton distribution), then apply Norm(vec) to that vector.
- 6. A **standard complex normal distribution** is a binormal distribution in which the binormal random pair is generated with s1 = s2 = sqrt(0.5) and mu1 = mu2 = 0 and treated as the real and imaginary parts of a complex number.
- 7. **Multivariate Linnik distribution**: Generate a multinormal random vector, then multiply each component by GeometricStable(alpha/2.0, 1, 1), where alpha is a parameter in (0, 2] (Kozubowski 2000)⁽¹³⁾.

1.1.7 Gaussian and Other Copulas

A copula is a way to describe the dependence between random numbers.

One example is a *Gaussian copula*; this copula is sampled by sampling from a **multinormal distribution**, then converting the resulting numbers to *dependent* uniform random numbers. In the following pseudocode, which implements a Gaussian copula:

- The parameter covar is the covariance matrix for the multinormal distribution.
- erf(v) is the **error function** of the number v (see the appendix).

```
METHOD GaussianCopula(covar)
   mvn=MultivariateNormal(nothing, covar)
   for i in 0...size(covar)
     // Apply the normal distribution's CDF
     // to get uniform random numbers
     mvn[i] = (erf(mvn[i]/(sqrt(2)*sqrt(covar[i][i])))+1)*0.5
   end
   return mvn
END METHOD
```

Each of the resulting uniform random numbers will be in the interval [0, 1], and each one can be further transformed to any other probability distribution (which is called a *marginal distribution* here) by taking the quantile of that uniform number for that distribution (see "Inverse Transform Sampling", and see also (Cario and Nelson 1997) (14)

Examples:

- 1. To generate two correlated uniform random numbers with a Gaussian copula, generate GaussianCopula([[1, rho], [rho, 1]]), where rho is the Pearson correlation coefficient, in the interval [-1, 1]. (Other correlation coefficients besides rho exist. For example, for a two-variable Gaussian copula, the Spearman correlation coefficient srho can be converted to rho by rho = sin(srho * pi / 6) * 2. Other correlation coefficients, and other measures of dependence between random numbers, are not further discussed in this document.)
- 2. The following example generates two random numbers that follow a Gaussian copula with exponential marginals (rho is the Pearson correlation coefficient, and rate1 and rate2 are the rates of the two exponential

```
marginals).

METHOD CorrelatedExpo(rho, rate1, rate2)
  copula = GaussianCopula([[1, rho], [rho, 1]])
  // Transform to exponentials using that
  // distribution's quantile function
  return [-log1p(-copula[0]) / rate1,
        -log1p(-copula[1]) / rate2]

END METHOD
```

Note: The Gaussian copula is also known as the *normal-to-anything* method.

Other kinds of copulas describe different kinds of dependence between random numbers. Examples of other copulas are—

- the **Fréchet-Hoeffding upper bound copula** [x, x, ..., x] (e.g., [x, x]), where x = RNDU01(),
- the **Fréchet-Hoeffding lower bound copula** [x, 1.0 x] where x = RNDU01(),
- the **product copula**, where each number is a separately generated RNDU01() (indicating no dependence between the numbers), and
- the **Archimedean copulas**, described by M. Hofert and M. Mächler (2011)⁽¹⁵⁾.

1.1.8 Exponential Distribution: Another Error-Bounded Algorithm

The following method samples from an exponential distribution with a λ parameter greater than 0, expressed as lnum/lden (where the sampling occurs within an error tolerance of 2-precision). For more information, see "Partially-Sampled Random Numbers".

```
METHOD ZeroOrOneExpMinus(x, v)
  // Generates 1 with probability exp(-x/y) (Canonne et al. 2020)
  if y <= 0 or x<0: return error
  if x==0: return 1 // exp(0) = 1
  if x > y
   xf = floor(x/y)
    x = mod(x, y)
    if x>0 and ZeroOrOneExpMinus(x, y) == 0: return 0
    for i in 0...xf
     if ZeroOrOneExpMinus(1,1) == 0: return 0
    end
    return 1
  end
  r = 1
 oy = y
  while true
    if Zero0r0ne(x, y) == 0: return r
    r=1-r
    y = y + oy
  end
END METHOD
METHOD LogisticExp(lnum, lden, prec)
    // Generates 1 with probability 1/(exp(2^-prec)+1).
    // References: Alg. 6 of Morina et al. 2019; Carinne et al. 2020.
    denom=pow(2,prec)*lden
    while true
       if RNDINT(1)==0: return 0
       if ZeroOrOneExpMinus(lnum, denom) == 1: return 1
    end
END METHOD
```

```
METHOD ExpoExact(lnum, lden, precision)
  ret=0
  for i in 1..precision
    if LogisticExp(lnum, lden, i)==1: ret=ret+pow(2,-i)
  end
  while ZeroOrOneExpMinus(lnum,lden)==1: ret=ret+1
  return ret
END METHOD
```

Note: After ExpoExact is used to generate a random number, an application can append additional binary digits (such as RNDINT(1)) to the end of that number while remaining accurate to the given precision (Karney 2014)⁽¹⁾.

2 Notes

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3 Appendix

3.1 Implementation of erf

The pseudocode below shows an approximate implementation of the <u>error function</u> erf, in case the programming language used doesn't include a built-in version of erf (such as JavaScript at the time of this writing). In the pseudocode, EPSILON is a very small number to end the iterative calculation.

```
METHOD erf(v)
   if v==0: return 0
   if v<0: return -erf(-v)
   if v==infinity: return 1
   // NOTE: For Java `double`, the following
   // line can be added:
   // if v>=6: return 1
   i=1
   ret=0
   zp=-(v*v)
   zval=1.0
```

```
den=1.0
while i < 100
    r=v*zval/den
    den=den+2
    ret=ret+r
    // NOTE: EPSILON can be pow(10,14),
    // for example.
    if abs(r)<EPSILON: break
    if i==1: zval=zp
    else: zval = zval*zp/i
    i = i + 1
end
    return ret*2/sqrt(pi)</pre>
END METHOD
```

3.2 A Note on Integer Generation Algorithms

There are many algorithms for the RNDINT(maxInclusive) method, which generates uniform random integers in [0, maxInclusive]. This section deals with "optimal" RNDINT algorithms in terms of the number of random bits they use on average (assuming we have a source of "truly" random bits).

Knuth and Yao (1976)⁽¹⁶⁾ showed that any algorithm that uses only random bits to generate random integers with separate probabilities can be described as a *binary tree* (also known as a *DDG tree* or *discrete distribution generating tree*). Random bits trace a path in this tree, and each leaf (terminal node) in the tree represents an outcome. They also gave lower bounds on the number of random bits an algorithm needs on average for this purpose. In the case of RNDINT, there are $n = \max_{n \in \mathbb{N}} \ln(\log_2(n))$ and at most $\log_2(n) + 2$ bits on average (where $\log_2(x) = \ln(x)/\ln(2)$). (17)

As also shown by Knuth and Yao, however, any integer generating algorithm that is both optimal and unbiased (exact) will also run forever in the worst case, even if it uses few random bits on average. This is because in most cases, n will not be a power of 2, so that n will have an infinite binary expansion, so that the resulting DDG tree will have to either be infinitely deep, or include "rejection leaves" at the end of the tree. (If n is a power of 2, the binary expansion will be finite, so that the DDG tree will have a finite depth and no rejection leaves.)

Because of this, there is no general way to "fix" the worst case of running forever, while still having an unbiased (exact) algorithm. For instance, modulo reductions can be represented by a DDG tree in which rejection leaves are replaced with labeled outcomes, but the bias occurs because only some outcomes can replace rejection leaves this way. Even with rejection sampling, stopping the rejection after a fixed number of iterations will likewise lead to bias, for the same reasons. However, which outcomes are biased this way depends on the algorithm.

The following are some ways to implement RNDINT. (The column "Unbiased?" means whether the algorithm generates random integers without bias, even if n is not a power of 2.)

Algorithm

$\begin{array}{c} \textbf{Time} \\ \textbf{Optimal? Unbiased? } \\ \textbf{Complexity} \end{array}$

Rejection sampling: Sample in a bigger range until a sampled number fits the smaller range.

Not always Yes Runs forever in worst case

Multiply-and-shift reduction: Generate bignumber, a k-bit random integer with many more bits than n has, then find (bignumber * n) >> k (see (Lemire 2016) ⁽¹⁸⁾ , (Lemire 2018) ⁽¹⁹⁾ , and the "Integer Multiplication" algorithm surveyed by M. O'Neill).	No	No	Constant
Modulo reduction: Generate bignumber as above, then find rem(bignumber, n)	No	No	Constant
Fast Dice Roller (Lumbroso 2013) ⁽²⁰⁾	Yes	Yes	Runs forever in worst case
Math Forum (2004) ⁽²¹⁾ or (Mennucci 2018) ⁽²²⁾ (batching/recycling random bits)	Yes	Yes	Runs forever in worst case
"FP Multiply" surveyed by M. O'Neill	No	No	Constant
Algorithm in "Conclusion" section by O'Neill	No	Yes	Runs forever in worst case
"Debiased" and "Bitmask with Rejection" surveyed by M. O'Neill $$	No	Yes	Runs forever in worst case

There are various techniques that can reduce the number of bits "wasted" by an integergenerating algorithm, and bring that algorithm closer to the theoretical lower bound of Knuth and Yao, even if the algorithm isn't "optimal". These techniques, which include batching, bit recycling, and randomness extraction, are discussed, for example, in the Math Forum page and the Lumbroso and Mennucci papers referenced above, and in (Devroye and Gravel 2015)⁽²³⁾.

Note: A similar question is how to generate a random integer given rolls of a fair die; more specifically, how to roll a k-sided die given a p-sided die. This can't be done without "wasting" randomness, unless "every prime number dividing k also divides p" (see "Simulating a dice with a dice" by B. Kloeckner, 2008). However, since randomness extraction can turn die rolls into unbiased bits, so that the discussion above applies, this question is interesting only when someone wants to build instructions to choose a number at random by rolling real dice or flipping real coins.

3.3 A Note on Weighted Choice Algorithms

Just like integer generation algorithms (see the previous section), weighted choice algorithms (implementations of WeightedChoice that sample with replacement) involve generating random integers with separate probabilities. And all of them can be described as a binary DDG tree just like integer generating algorithms.

In this case, though, the number of random bits an algorithm uses on average is bounded from below by the sum of binary entropies of all the probabilities involved. For example, say we give the four integers 1, 2, 3, 4 the following weights: 3, 15, 1, 2. The binary entropies of these weights are 0.4010... + 0.3467... + 0.2091... + 0.3230... = 1.2800... (because the sum of the weights is 21 and the binary entropy of 3/21 is (3/21) * log2(21/3) = 0.4010..., and so on for the other weights), so an optimal algorithm will use anywhere from 1.2800... to 3.2800... bits on average to generate a random number with these weights. (17) Another difference from integer generation algorithms is that usually a special data structure has to be built for the sampling to work, and often there is a need

to make updates to the structure as items are sampled.

The following are some ways to implement WeightedChoice. The algorithms are generally not optimal in terms of the number of bits used, unless noted. For these samplers to be error-bounded:

- Weights passed to these algorithms should first be converted to integers (see IntegerWeightsListFP or NormalizeRatios in "Sampling for Discrete Distributions" for conversion methods), or rational numbers when indicated.
- Floating-point arithmetic and floating-point random number generation (such as RNDRANGE()) should be avoided.

Notes

Fast

Loaded

Dice Roller Uses integer weights only, and samples using random bits ("fair coins"). (Saad et al., This sampler comes within 6 bits, on average, of the optimal number of bits. 2020)(24)

Samplers

described al., 2020) (25)

Rejection

sampling

Uses integer weights only, and samples using random bits. The samplers are in (Saad et optimal in the sense given here as long as the sum of the weights is of the form 2^k or $2^k - 2^m$.

> Given a list (weights) of n weights: (1) find the highest weight and call it max; (2) set i to RNDINT(n - 1); (3) With probability weights[i]/max (e.g., if ZeroOrOne(weights[i], max)==1 for integer weights), return i, and go to step 2 otherwise. (See, e.g., sec. 4 of the Fast Loaded Dice Roller paper, or the Tang or Klundert papers.) If the weights are instead "coins", each with a separate but unknown bias, the algorithm is also called Bernoulli race (Dughmi et al. 2017)(26); see also (Morina et al., 2019)(27): (1) set i to RNDINT(n - 1); (2) flip coin i (the first coin is 0, the second is 1, etc.), then return *i* if it returns 1 or heads, or go to step 1 otherwise.

(Bringmann

and

Shows a sampler designed to work on a sorted list of weights. Panagiotou

2012)⁽²⁸⁾.

Alias method (Walker

Michael Vose's version of the alias method (Vose 1991)⁽³⁰⁾ is described in "Darts, Dice, and Coins: Sampling from a Discrete Distribution".

Weights should be rational numbers. 1977)⁽²⁹⁾

(Klundert 2019)⁽²⁹⁾

Various data structures, with emphasis on how they can support changes in weights.

The

Bringmann-Larsen succinct data

Uses rejection sampling if the sum of weights is large, and a compressed structure otherwise.

structure (Bringmann and Larsen 2013)⁽³¹⁾

(Hübschle-Schneider

and Parallel weighted random samplers. Sanders 2019)⁽³²⁾.

Two- and multi-level search; flat method (Tang 2019)⁽³³⁾.

"Loaded Die from numbers: (1) Set cumu to 1 and i to 0; (2) with probability probs[i]/cumu, return i; (3) subtract probs[i] from cumu, then add 1 to i, then go to step 2. For a correctness proof, see "Darts, Dice, and Coins".

Generates a DDG tree from the binary expansions of the probabilities. Is optimal, or at least nearly so. This is suggested in exercise 3.4.2 of chapter that and Yao (1976) (1

discretegen method, and also described in (Roy et al. 2013)⁽³⁴⁾. discretegen can work with probabilities that are irrational numbers (which have infinite binary expansions) as long as there is a way to calculate the binary expansion "on the fly".

(Han and Uses cumulative probabilities as input. An error-bounded version is described in (Devroye and Gravel 2015)⁽²³⁾ and comes within 3 bits, on average, of the optimal number of bits.

Note: If the source of randomness is a "biased coin" which returns heads with *unknown* probability of heads and false otherwise, it can be turned into a "fair" coin (and so output unbiased bits) via *randomness extraction* (see my **Note on Randomness Extraction**), so that the algorithms above can be used.

3.4 Exact, Error-Bounded, and Approximate Algorithms

There are three kinds of randomization algorithms:

- 1. An *exact algorithm* is an algorithm that samples from the exact distribution requested, assuming that computers
 - o can store and operate on real numbers of any precision, and
 - can generate independent uniform random real numbers of any precision

(Devroye 1986, p. 1-2)⁽¹²⁾. However, an exact algorithm implemented on real-life computers can incur rounding and other errors, especially errors involving floating-point arithmetic or irrational numbers. An exact algorithm can achieve a guaranteed bound on accuracy (and thus be an *error-bounded algorithm*) using either arbitrary-precision or interval arithmetic (see also Devroye 1986, p. 2)⁽¹²⁾. All methods given on this page are exact unless otherwise noted. Note that RNDU01 or RNDRANGE are exact in theory, but have no required implementation.

- 2. An *error-bounded algorithm* is an exact algorithm with further requirements described below:
 - If the ideal distribution is discrete (takes on a countable number of values), the

- algorithm samples exactly from that distribution.
- If the ideal distribution is continuous, the algorithm samples from a distribution
 that is close to the ideal within a user-specified error tolerance (see below for
 details). The algorithm can instead sample a random number only partially, as
 long as the fully sampled number can be made close to the ideal within any
 error tolerance desired.
- The algorithm incurs no approximation error not already present in the inputs (except errors needed to round the final result to the user-specified error tolerance).

Many error-bounded algorithms use random bits as their only source of random numbers. An application should use error-bounded algorithms whenever possible.

3. An *inexact*, *approximate*, or *biased algorithm* is neither exact nor error-bounded; it uses "a mathematical approximation of sorts" to generate a random number that is close to the desired distribution (Devroye 1986, p. 2)⁽¹²⁾. An application should use this kind of algorithm only if it's willing to trade accuracy for speed.

Most algorithms on this page, though, are not *error-bounded*, but even so, they may still be useful to an application willing to trade accuracy for speed.

There are many ways to describe closeness between two distributions. As one suggestion found in (Devroye and Gravel 2015)⁽²³⁾, an algorithm has accuracy ϵ (the user-specified error tolerance) if it samples random numbers whose distribution is close to the ideal distribution by a Wasserstein L_{∞} distance ("earth-mover distance") of not more than ϵ .

Examples:

- 1. Generating an exponential random number via -ln(RNDU01()) is an *exact* algorithm (in theory), but not an *error-bounded* one for common floating-point number formats. The same is true of the Box-Müller transformation.
- 2. Generating an exponential random number in the manner described in another section of this page is an error-bounded algorithm. Karney's algorithm for the normal distribution (Karney 2014)⁽¹⁾ is also error-bounded because it returns a result that can be made to come close to the normal distribution within any error tolerance desired simply by appending more random digits to the end (an example when the return value has 53 bits after the point is as follows: for i in 54..100: ret = ret + RNDINT(1) * pow(2,-i)). See also (Oberhoff 2018)⁽³⁶⁾.
- 3. Examples of *approximate algorithms* include generating a Gaussian random number via a sum of RNDU01(), or most cases of generating a random integer via modulo reduction (see "A Note on Integer Generation Algorithms").

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