

Adham Elshabrawy

437-998-2322 | adhamtarek.el@gmail.com | www.linkedin.com/in/adham-elshabrawy | www.github.com/adham-elshabrawy

EDUCATION

Queen's University

Mechatronics & Robotics Automation Engineering

IBM Certificate

Machine Learning with Python

Kingston, ON

Sep. 2023 – May 2027

Apr. 2024 – June 2024

PROFESSIONAL EXPERIENCE

Mechatronics Design Intern

May 2025 – Aug. 2025

FYELABS

Hamilton, ON

- Led a team of 5 to automate a food dispenser, defining client requirements and aligning with firmware, PCB, and mechanical teams.
- Designed and implemented embedded control logic in C/C++ for a system integrating 8+ motors, and 10+ sensors, reducing operation time by 60%
- Spearheaded the automation of a contact lens manufacturing process for an innovative glaucoma treatment, designing the full control sequence and achieving 97% dispensing accuracy.

Mechatronics Design Intern

May 2024 – Aug. 2024

FYELABS

Hamilton, ON

- Integrated GPS modules, accelerometers, and gyroscopes with Raspberry Pi platforms, writing optimized drivers using UART/I2C to enable real-time speed and position tracking with 95% accuracy.
- Designed an airtight battery enclosure in SolidWorks, ensuring zero air ingress/egress and protecting next-generation battery materials from environmental exposure.
- Assisted in the circuit design of an industrial automated machine for synthesizing a new plastic material, and validated the PCB using an oscilloscope and a logic analyzer to ensure precise and reliable operation.

EXTRACURRICULAR EXPERIENCE

Director of Autonomy

June 2025 – Present

Queen's Autodrive Team

Kingston, ON

- Leading 25+ students across 4 subteams within the Autonomy division to advance a Level-4 autonomous vehicle, managing development cycles using Jira and Git.
- Architected CI/CD pipelines to automate unit testing and integration checks for C++ and Python nodes, reducing deployment errors
- Implemented machine learning algorithms in C++ and Python including D* Lite, Kalman/Particle filters, and Model Predictive Controller (MPC) improving system accuracy and performance.

PROJECTS

Autonomous Delivery Robot | Python, C++, ROS2, Linux

May 2025 – Present

- Engineered an autonomous hospital delivery robot on Raspberry Pi 4, utilizing sensor fusion for localization and obstacle detection in a live pharmacy.
- Achieved 93% path accuracy by developing a custom SLAM node and D* Lite algorithm to efficiently transport medication.

ShopVision | Python, PyTorch, CLIP, ChromaDB, OpenAI API

December 2025 – Present

- Built multimodal e-commerce search using CLIP embeddings and ChromaDB, enabling text-to-image and image-to-image product retrieval
- Integrated OpenAI (ChatGPT) API for AI-generated product descriptions and visual Q&A, with retrieval evaluation (Recall@K, MRR)

S&P 500 Stock Predictor | Python, Git

July 2024 – Aug. 2024

- Achieved 60% accuracy in predicting S&P 500 stock movements by engineering a machine learning classification model with scikit-learn, NumPy, and pandas on historical data.

TECHNICAL SKILLS

Languages: Python, C/C++, SQL, Bash, HTML/CSS, MATLAB, VHDL, Verilog, Assembly (NIOS II, ARM64).

Software Tools: Docker, CI/CD, Gazebo, SolidWorks, Altium Designer, Fusion 360, LTSpice, SimuLink.

Libraries: pandas, NumPy, Matplotlib, OpenCV, scikit-learn, PyTorch, TensorFlow.

Productivity Tools: Word, Excel, PowerPoint, Jira, Git.