The kernel first mounts the rootfs located in ram (ramfs) and runs the init process for this root. The rootramfs contains only the minimum necessary binaries such as mount and chroot that are required to run its init process along with minimum utilities such as ls and cat,etc.. The init process runs a bash script and requires input from the user:

- 1- if the user enters 1 it mounts the rootfs on partition 2 mmcblk0p2, changes its root to it and then runs the init process for that rootfs (Busy box init process)
- 2-if the ser enters 2 it mounts the rootfs on partition3 instead
- 3-if the user enters 3 it just opens a shell for the user and remains on the ramfs

The binaries for the rootramfs were statically compiled while the binaries for the rootfs on the block devices 2 and 3 where dynamically linked.

## 1- compiling the kernel:

## Building binaries using busy box

```
adhamwalaa@adhamwalaa-G3-3500:-/embedded_linux_kitch... × adhamwalaa@adhamwalaa-G3-3500:-/embedded_linux_kitche... × adhamwalaa@adhamwalaa-G3-3500:-/embedded_linux_kitche... × adhamwalaa@adhamwalaa-G3-3500:-/embedded_linux_kitche... × adhamwalaa@adhamwalaa-G3-3500:-/embedded_linux_kitche... × adhamwalaa@adhamwalaa-G3-3500:-/embedded_linux_kitchen/busybox$ make menuconfig

*** End of configuration.

*** Execute 'make' to build the project or try 'make help'.

*** Execute 'make' to build the project or try 'make help'.

*** Each of configuration.

*** Execute 'make' to build the project or try 'make help'.

*** Adhamwalaa@adhamwalaa-G3-3500:-/embedded_linux_kitchen/busybox$ export ARCH=arm

*** Each of configuration.

*** Execute 'make' to build the project or try 'make help'.

*** Each of configuration.

*** Execute 'make' to build the project or try 'make help'.

*** Each of configuration.

*** Execute 'make' to build the project or try 'make help'.

*** Each of configuration.

*** Execute 'make' to build the project or try 'make help'.

*** Each of configuration.

*** Execute 'make' to build the project or try 'make help'.

*** End of configuration.

*** Execute 'make' to build the project or try 'make help'.

*** End of configuration.

*** Execute 'make' to build the project or try 'make help'.

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*** Execute 'make' to build the project or try 'make help'.

*** End of configuration.

*** Execute 'make' to build the project or try 'make help'.

*** End of configuration.

*** End of configuration.

*** End of configuration.

*** End of configuration.

***
```

## Compressing the ramfs for u-boot:

```
ין דין אוין אוין ערן .
 ./bin/resume
./bin/reformime
 ./bin/sync
4104 blocks
 adhamwalaa@adhamwalaa-G3-3500:~/embedded_linux_kitchen/rootramfs$ cd ...
 adhamwalaa@adhamwalaa-G3-3500:~/embedded_linux_kitchen$ ls
busybox crosstool-ng initramfs.cpio linux qemu rootramfs rpi u-boot
Ladhamwalaa@adhamwalaa-G3-3500:~/embedded_linux_kitchen$ gzip initramfs.cpio
adhamwalaa@adhamwalaa-G3-3500:~/embedded linux kitchen$ mkimage -A arm -O linux,
 -T ramdisk -d initramfs.cpio.gz uRamdisk
 Image Name:
Created:
                Mon Feb 10 00:19:58 2025
Image Type:
                ARM Linux RAMDisk Image (gzip compressed)
 Data Size:
                1121862 Bytes = 1095.57 KiB = 1.07 MiB
Load Address: 00000000
 Entry Point: 00000000
 adhamwalaa@adhamwalaa-G3-3500:~/embedded_linux_kitchen$ ls
                                                          uRamdisk
adhamwalaa@adhamwalaa-G3-3500:~/embedded_linux_kitchen$ sudo cp uRamdisk /media/
 adhamwalaa/boot/
 adhamwalaa@adhamwalaa-G3-3500:~/embedded linux kitchen$
```

Kernel panic after user switches to mmcblk0p2 since the new root doesn't have an init process yet:

```
initramfs> 1

Mounting new root from /dev/mmcblk0p2...

EXT4-fs (mmcblk0p2): mounted filesystem 52344936-6f28-403c-b78c-3adc8c019d7e r/w with ordered data mode. Quota mode: disabled.

Root filesystem mounted successfully!

Switching to new root...

switch_root: '/init' is not a regular file

Kernel panic - not syncing: Attempted to kill init! exitcode=0x00000100

CPU: 0 PID: 1 Comm: switch_root Not tainted 6.6.74+ #1

Hardware name: ARM-Versatile Express

unwind_backtrace from show_stack+0x10/0x14

show_stack from dump_stack_lv1+0x50/0x68

dump_stack_lv1 from panic-0x108/0x31c

panic from make_task_dead+0x0/0x16c

---[ end Kernel panic - not syncing: Attempted to kill init! exitcode=0x00000100 ]---
```