

Autonomous Development Task

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Task 1

Launch: `$ roslaunch loco loco_key.launch`

ROS Development Studio Project: <http://www.rosetect.io/1/15addacb/>

GitHub Link for “loco.py”: <https://github.com/adhammo/Autonomous-Dev>

Task 2

perspective.py GitHub Link: <https://github.com/adhammo/Autonomous-Dev>

