**Autonomous Development Task**

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# Task 1

Launch: **$ roslaunch loco loco\_key.launch**

ROS Development Studio Project: <http://www.rosject.io/l/15addacb/>

GitHub Link for “loco.py”: <https://github.com/adhammo/Autonomous-Dev>

# Task 2

perspective.py GitHub Link: <https://github.com/adhammo/Autonomous-Dev>

