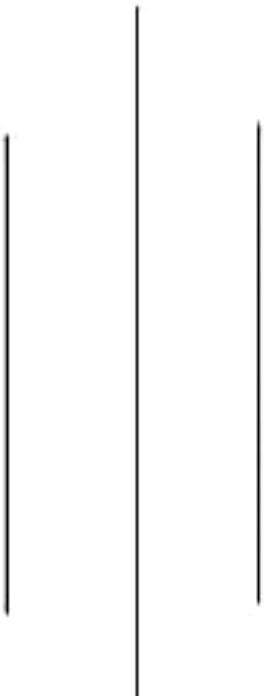


NEPAL COLLEGE OF INFORMATION TECHNOLOGY

Balkumari, Lalitpur

Affiliated to Pokhara University



ASSIGNMENT FOR COMPUTER GRAPHICS



ASSIGNMENT 3

Submitted by:

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computer graphics

Assignment 3

- 1) A point $P(20, 20)$ in a circular window with its center at $(100, 100)$ and a radius of 90 pixels is required to be mapped to a point in circular viewport having its at $(50, 50)$ and radius of 40 pixels. Where will the point P be placed after the transformation?

Soln

$$\text{Radius}_{\text{in window}} (w_r) = 90 \quad (x_{wc}, y_{wc}) = (100, 100)$$

$$\text{Radius}_{\text{in viewport}} (v_r) = 40 \quad (x_{vc}, y_{vc}) = (50, 50)$$

$$S_x, S_y = \frac{v_r}{w_r} = \frac{40}{90} = 0.44 \quad : S_y = \frac{v_r}{w_r} = 0.44$$

$$\text{Composite Matrix } (C_m) = T(x_{vc}, y_{vc}) \cdot S_{vw} \cdot T(-x_{wc}, -y_{wc})$$

$$= \begin{bmatrix} 1 & 0 & 50 \\ 0 & 1 & 50 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0.44 & 0 & 0 \\ 0 & 0.44 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -100 \\ 0 & 1 & -100 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.44 & 0 & 6 \\ 0 & 0.44 & 6 \\ 0 & 0 & 1 \end{bmatrix}$$

$$S_0, P' = C_m \cdot P$$

$$= \begin{bmatrix} 0.44 & 0 & 6 \\ 0 & 0.44 & 6 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 20 \\ 20 \\ 1 \end{bmatrix} = \begin{bmatrix} 14.8 \\ 14.8 \\ 1 \end{bmatrix}$$

Hence, the point $P(20, 20)$ after being mapped to viewport will be $P'(14.8, 14.8) \approx P'(15, 15)$ Ans

- (Q2) A triangle with vertices $A(5, 2)$, $B(4, 1)$, $C(6, 4)$ is required to be rotated in a clockwise direction by 45° degrees about any arbitrary point $(4, 4)$. Find out the final coordinate positions of the triangle after performing the desired transformation.

SOP

$$\text{Here, } \Theta = -45^\circ \text{ (cw)}$$

NOW,

$$\text{composite matrix (cm)} = T_{(4, 4)} \cdot R_{\Theta=45^\circ}^{(cw)} \cdot T_{(-4, -4)}$$

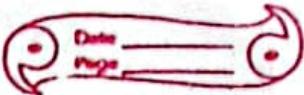
$$= \begin{bmatrix} 1 & 0 & 4 \\ 0 & 1 & 4 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos(-45) & -\sin(-45) & 0 \\ \sin(-45) & \cos(-45) & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -4 \\ 0 & 1 & -4 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 4 \\ 0 & 1 & 4 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos 45 & \sin 45 & 0 \\ -\sin 45 & \cos 45 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -4 \\ 0 & 1 & -4 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.707 & 0.707 & -1.66 \\ -0.707 & 0.707 & 4 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{Hence, } P' = cm \cdot P$$

$$= \begin{bmatrix} 0.707 & 0.707 & -1.66 \\ -0.707 & 0.707 & 4 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 & 4 & 6 \\ 2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$



$$= \begin{bmatrix} 3.29 & 1.87 & 3.29 \\ 1.87 & 1.87 & 0.46 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\approx \begin{bmatrix} 3 & 2 & 3 \\ 2 & 2 & 0 \\ 1 & 1 & 1 \end{bmatrix}$$

Hence, the vertices of triangle after transformation are
 $A'(3, 2), B'(2, 2), C'(3, 0)$.

- (Q3) Reflect a triangle $A(1, 0), B(3, 1), C(1, 2)$ about line $y = -2x + 5$
 then scale it about a fixed point $P(10, 10)$.

Sol:

$$\text{Here, } y = -2x + 5$$

$$\text{So, } m = -2$$

$$\text{or, } \theta = \tan^{-1}(-2)$$

$$\therefore \theta = -63.43^\circ$$

lets assume scaling factor as '2' in both directions.

$$C_m = \underbrace{S_{m=-2, y=2}}_{C_m} T_{(0, 5)} \cdot R_{O_{CW}}^{-63.43^\circ} R_{f_n} \cdot R_{O_{CW}}^{63.43^\circ} T_{(0, -5)}$$

$$= \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos 63.43^\circ & \sin 63.43^\circ & 0 \\ -\sin 63.43^\circ & \cos 63.43^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos 63.43^\circ & -\sin 63.43^\circ & 0 \\ \sin 63.43^\circ & \cos 63.43^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -5 \\ 0 & 0 & 1 \end{pmatrix}$$



$$\begin{aligned}
 &= \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 5 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -0.599 & -0.80 & 4 \\ -0.80 & 0.599 & -2.99 \\ 0 & 0 & 1 \end{pmatrix} \\
 &= \begin{pmatrix} -1.19 & -1.60 & 8.00 \\ -1.60 & 1.19 & 4.00 \\ 0 & 0 & 1 \end{pmatrix}
 \end{aligned}$$

$$S_0, P^1 = C_m \cdot P$$

$$\begin{pmatrix} -1.19 & -1.60 & 8 \\ -1.60 & 1.19 & 4 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 3 & 1 \\ 0 & 1 & 2 \\ 1 & 1 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 6.81 & 2.83 & 3.61 \\ 2.4 & 0.39 & 4.78 \\ 1 & 1 & 1 \end{pmatrix}$$

Hence, Final coordinates are
 $(7,2), (13,0), (14,5)$

- Q4) A triangle with vertices $A(5,2), B(4,1), C(6,1)$ is required to be reflected about an arbitrary line $y = 2x + 1$. Find out the final coordinate positions of the triangle after performing the desired transformation.

Sol?

Given line, $y = 2x + 1$

$$S_0, m = 2$$

$$\text{or, } \theta = \tan^{-1}(2)$$

$$\therefore \theta = 63.43^\circ$$

$$\text{Composite Matrix (C}_m\text{)} = R_{\theta \text{ ccw}}^{63.43} R_{f_n} \cdot R_{\theta \text{ cw}}^{-63.43}$$

$$= \begin{bmatrix} \cos 63.43^\circ & -\sin 63.43^\circ & 0 \\ \sin 63.43^\circ & \cos 63.43^\circ & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



$$= \begin{bmatrix} -0.59 & 0.81 & 0 \\ 0.81 & 0.59 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{Now, } P' = C_m \times P$$

$$= \begin{bmatrix} -0.59 & 0.81 & 0 \\ 0.81 & 0.59 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 & 4 & 6 \\ 2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} -1.33 & -1.55 & -2.73 \\ 5.23 & 3.83 & 5.45 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\approx \begin{bmatrix} -1 & -2 & -3 \\ 5 & 4 & 5 \\ 1 & 1 & 1 \end{bmatrix}$$

Hence, vertices after transformation are A'(-1, 5), B'(-2, 4), C'(-3, 5).

- (Q5) A triangle with vertices A(5, 2), B(4, 1), C(6, 1) is required to be rotated by 45 degrees in CCW direction about
 i) origin and
 ii) line y = 5.

Soln

i) origin

Step 1: Rotate the object by 45° in CCW.

$$R_{O, \text{CCW}}^{45^\circ} = \begin{bmatrix} \cos 45^\circ & -\sin 45^\circ & 0 \\ \sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

The required component matrix is as,



$$= \begin{bmatrix} 0.7071 & -0.7071 & 0 \\ 0.7071 & 0.7071 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

NOW,

$$\begin{bmatrix} 0.7071 & -0.7071 & 0 \\ 0.7071 & 0.7071 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 & 4 & 6 \\ 2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 2.1213 & 2.1213 & 3.5355 \\ 4.9497 & 3.5355 & 4.9497 \\ 1 & 1 & 1 \end{bmatrix}$$

(iii) $y = 5$ line :

Step 1 : Translate the line $y = 5$ to x -axis.

Step 2 : Rotate the object by 45° in ccw.

Step 3 : Translate back the line along with rotated object to original position

The composite matrix is as,

$$C_m = T(0, 5) \cdot R_{ccw}^{45^\circ} \cdot T(0, -5)$$

$$C_m = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 5 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos 45^\circ & -\sin 45^\circ & 0 \\ \sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -5 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.7071 & -0.7071 & 0 \\ 0.7071 & 0.7071 & 5 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -5 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.7071 & -0.7071 & 3.53 \\ 0.7071 & 0.7071 & 1.46 \\ 0 & 0 & 1 \end{bmatrix}$$

QUESTION

Now, the matrix coordinates after rotation is,

$$\begin{aligned}
 P' &= \begin{bmatrix} 0.7071 & -0.7071 & 3.53 \\ 0.7071 & 0.7071 & 1.46 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 & 4 & 6 \\ 2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \\
 &= \begin{bmatrix} 5.6513 & 5.6513 & 7.0685 \\ 6.4093 & 4.9955 & 6.4097 \\ 1 & 1 & 1 \end{bmatrix}
 \end{aligned}$$

Hence, the points are A'(6, 6), B'(6, 5), C'(7, 6).

- Q6) clip a line with end point coordinates A(-1, 6), B(5, -8) against a clip window with its lower left corner at (-2, -5) and upper right corner at (4, 8) using cohen-sutherland algorithm.

SOL

Step 1: Establish region codes for line end points

A(-1, 6)

L: -1 < -2 F '0'

R: -1 > 4 F '0'

B: 6 < -5 F '0'

T: 6 > 8 F '0'

B(5, -8)

L: 5 < -2 F 0

R: 5 > 4 T 1

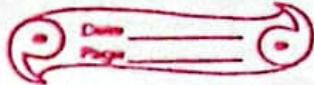
B: -8 < -5 T 1

T: -8 > 8 F 0

So, Bits = 0000

Bits for B = 0110

So, this is not the case of full visibility.



step 2: Perform AND operation of region codes.

$$\begin{array}{r} 0000 \\ 0110 \\ \hline 0000 \end{array}$$

so, this is the case of partial visibility.

Expt/Pr.,

$$\text{Here, slope}(m) = \frac{y_2 - y_1}{x_2 - x_1} = \frac{-8 - 6}{5 - (-1)} = \frac{-14}{6}$$

Step 3: Determine intersection points of line with window boundaries.

For B(5, -8),

For bit 2,

$$y = 8 \quad n = n_{\text{window}} = 8$$

and, ~~x~~

$$\text{and, } y = y_1 + m(n - n_1) \\ = -8 + \frac{-14}{6}(8 - 4)$$

$$\therefore y = \frac{-31}{3} = -10.33 \approx -10 \therefore y = \frac{-17}{3}$$

$$(n', y') = (4, \cancel{-10.33}) \quad (n', y') = (4, -\frac{17}{3})$$

For bit 3, $y = y_{\text{min}} = -5$

and,

$$n = n_1 + \frac{1}{m}(y - y_1) \\ = 4 + \frac{6}{-14}(-5 - \cancel{\frac{-31}{3}})$$



$$B_r n = 1 \cancel{= 3} 3.71$$

$$\therefore n \approx 4$$

$$\text{Hence, } B \text{ is } (n', y') = (4, -5)$$

The coordinates of the end points of visible line segment after clipping are $A'(-1, 6)$ and $B'(2, -5)$. Ans

(Q7) Derive the composite transformation matrix that reflects an object about line 'L' with necessary figures.

Sol:

Let the line 'L' be considered as $y = mx + c$.

Step 1: The line is translated through factor $(a; -c)$ along with the object to be reflected, such that the line passes through origin.

Step 2: Now, the line along with the object is rotated until it aligns with one of the major coordinate axes (consider X-axis) by angle θ .

where, $\theta = \tan^{-1}(m)$ $\xrightarrow{\text{value}}$ Derived from eq?

Step 3: The reflection of the object is taken along n -axis.

Step 4: After reflection, the line along with the object is rotated back to the same slope with angle ' θ ' but in opposite direction.

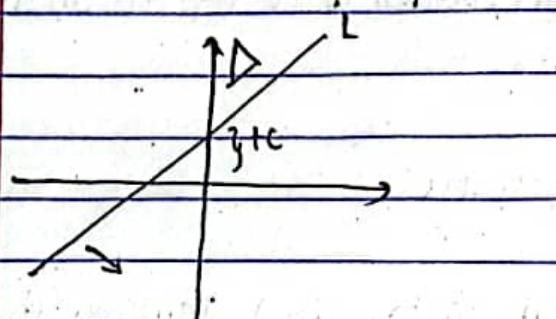
Step 5: Now, we perform inverse translation to bring the line back to its initial location along with the reflected object.



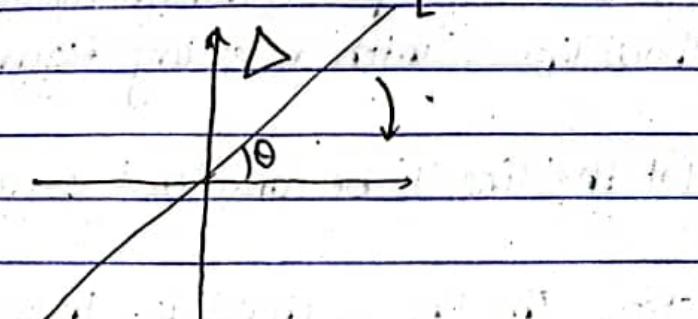
The composite matrix is,

$$C_m = T_{(0, +c)} \cdot R_{\text{cw}} R_{fx} R_{\text{cw}} T_{(0, -c)}$$

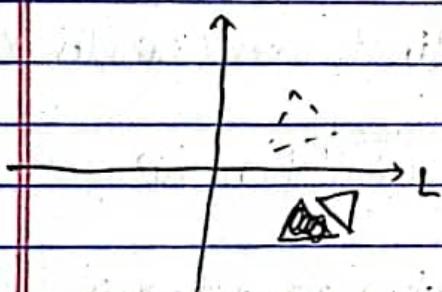
$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix} \begin{pmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos\theta & \sin\theta & 0 \\ -\sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -c \\ 0 & 0 & 1 \end{pmatrix}$$



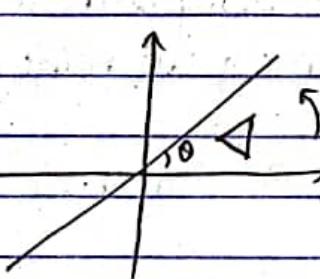
Step 1 : Translation



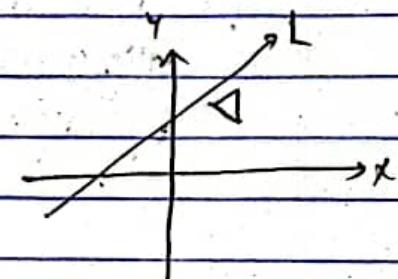
Step 2 : Rotation



Step 3 : Reflection



Step 4 : Inverse
Rotation



Step 5 :
Inverse translation

- (Q8) Find scaling transformation matrix to scale s_x, s_y units with respect to fixed point $P(x_1, y_1)$.

Y'all

Step 1 : The fixed point $P(x,y)$ along with the object to be rotated about it, is translated to origin.

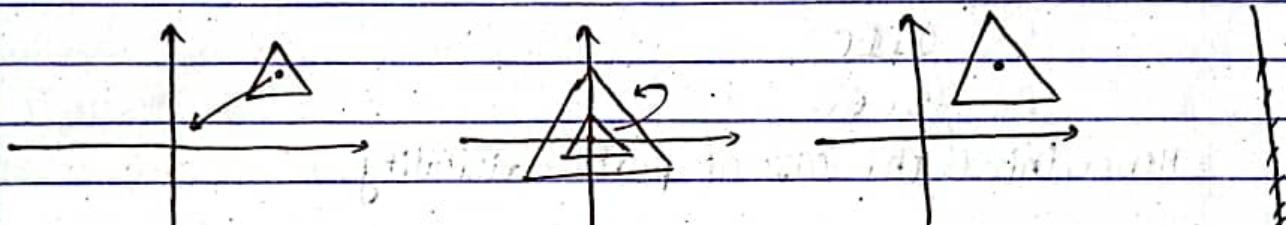
Step 2 : Now scale the object about origin by the desired scaling factor.

Step 3 : Translate back the fixed point which is at the coordinate origin along with the scaled object to its original location.

The composite matrix for these transformations is as follows:

$$C_m = T(-x, -y) \cdot S_{sx, sy} \cdot T(x, y)$$

$$= \begin{pmatrix} 1 & 0 & x \\ 0 & 1 & y \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & -x \\ 0 & 1 & -y \\ 0 & 0 & 1 \end{pmatrix}$$



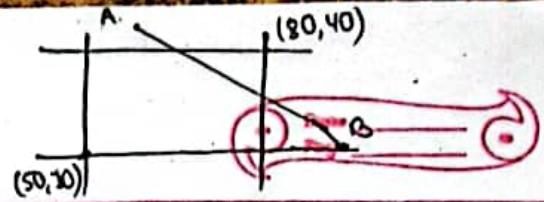
Step 1: Translation

Step 2: Scaling

Step 3: Reverse Translation

- (Q9) Use Cohen Sutherland's algorithm to clip line $(60, 50)-(100, 10)$ against window $(50, 10)-(80, 40)$.

Soln



Given points, A(60, 50) B(100, 10)

$$(x_{wmin}, y_{wmin}) = (50, 10)$$

$$(x_{wmax}, y_{wmax}) = (80, 40)$$

Step 1 : Establish region codes for line end points.

A(60, 50) :

$$L : 60 < 50 \quad F \quad 0$$

$$R : 60 > 80 \quad F \quad 0$$

$$B : 50 < 10 \quad F \quad 0$$

$$T : 50 > 40 \quad T \quad 1$$

$$\text{Region code} \Rightarrow \cancel{000}1000$$

B(100, 10) :

$$L : 100 < 50 \quad F \quad 0$$

$$R : 100 > 80 \quad T \quad 1$$

$$B : 10 < 10 \quad F \quad 0$$

$$T : 10 > 40 \quad F \quad 0$$

$$\text{Region code} \Rightarrow \cancel{100}0010$$

Hence, this isn't case of full visibility.

Step 2 : Perform logical AND operation of region codes.

0001

0100

0000

Hence, this is the case of partial visibility.

Step 3 : Determine intersection point of line with window boundaries.

$$\text{For } A, (x_1, y_1) = (60, 50)$$

$$y = y_{wmax} = 40$$

$$n = \frac{1}{m} (y - y_1) + n_1$$

$$= \frac{1}{-1} (40 - 50) + 60$$

$$\therefore n = 70$$

$$m = \frac{y_2 - y_1}{x_2 - x_1}$$

$$= \frac{10 - 50}{100 - 60}$$

$$= \frac{-40}{40} = -1$$

For B, $(x_1, y_1) = (100, 10)$

$$n = n_{\text{wman}} = 80$$

$$\begin{aligned} y &= m(n - n_1) + y_1 \\ &= -1(80 - 100) + 10 \\ \therefore y &= 30 \end{aligned}$$

Hence, the coordinates of the end points of visible line segment after clipping are ~~A(100, 40)~~, A'(70, 40) and B'(80, 30). Aw

- Q10) show that 2D reflection through n -axis followed by 2D reflection through line $y = -n$ is equivalent to a pure rotation (90 degrees) about origin.

soln

To prove, let's deduce the composite matrix C_{m1} and C_{m2} for two cases.

For first case,

$$C_{m1} =$$

R_{fx} Given line, $y = -n + 0$

$$\text{so, } m = -1$$

$$\therefore \theta = -45^\circ$$

composite matrix for line reflection = $R_{0_{cw}}^{-45^\circ} \cdot R_{fn} \cdot R_{0_{ccw}}^{45^\circ}$

Then, Final C_m with reflection through n -axis is,

$$C_{m1} = R_{0_{cw}}^{-45^\circ} \cdot R_{fn} \cdot R_{0_{ccw}}^{45^\circ} \cdot R_{fx}$$

$$= \begin{pmatrix} \cos 45^\circ & \sin 45^\circ & 0 \\ -\sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos 45^\circ & -\sin 45^\circ & 0 \\ \sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$



$$\text{So, } C_{M_1} = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Now, For the second case,

$$C_{M_2} = R \theta_{\text{cw}}^{-90^\circ}$$

$$= \begin{pmatrix} \cos 90^\circ & \sin 90^\circ & 0 \\ -\sin 90^\circ & \cos 90^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

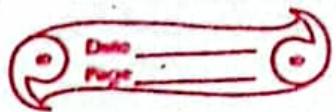
$$= \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Hence, we can observe $C_{M_1} = C_{M_2}$

So, 2D reflection through n -axis followed by 2D reflection through line $y=-n$ is equivalent to a pure rotation (90°) about origin.

Q11) Prove that scaling followed by rotation is equivalent to shearing.

Soln



(Q12) Triangle with vertices $A(1,1), B(7,1), C(4,3)$ is required to be rotated about any arbitrary fixed point $(4,2)$ in a counter clockwise direction by 90 degrees. What will be the final coordinates of the triangle?

Soln

$$\text{Composite Matrix } (C_m) = T_{(4,2)} R_0^{90^\circ} \text{ccw } T_{(-4,-2)}$$

$$= \begin{pmatrix} 1 & 0 & 4 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos 90^\circ & -\sin 90^\circ & 0 \\ \sin 90^\circ & \cos 90^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & -4 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & -1 & 6 \\ 1 & 0 & -2 \\ 0 & 0 & 1 \end{pmatrix}$$

So, Final coordinates, $P' = C_m \cdot P$

$$= \begin{pmatrix} 0 & -1 & 6 \\ 1 & 0 & -2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 7 & 4 \\ 1 & 1 & 3 \\ 1 & 1 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 5 & 5 & 3 \\ -1 & 5 & 2 \\ 1 & 1 & 1 \end{pmatrix}$$

Hence, final coordinates triangle after rotation are

$$A(5, -1), B(5, 5), C(3, 2).$$

(Q13) A point $P(20,20)$ in a window with its lower most left corner at $(10,10)$ and uppermost right corner at $(100,100)$ is required to be mapped to a point in viewport having its lower most left corner at $(30,30)$ and uppermost right corner at $(90,80)$. Where will



the point, P be placed after the transformation?

sol:

Given, P(20, 20)

$$(x_{w\min}, y_{w\min}) = (10, 10)$$

$$(x_{w\max}, y_{w\max}) = (100, 100)$$

$$(x_{v\min}, y_{v\min}) = (30, 30)$$

$$(x_{v\max}, y_{v\max}) = (90, 80)$$

For this,

$$\text{Composite matrix} = T_{(x_{v\min}, y_{v\min})} \cdot S_{sx, sy} \cdot T_{(x_{w\min}, y_{w\min})} \quad \dots \text{--- } ①$$

$$\text{Here, } S_x = \frac{x_{v\max} - x_{v\min}}{x_{w\max} - x_{w\min}} \\ = \frac{90 - 30}{100 - 10} = \frac{60}{90} = 0.67$$

$$S_y = \frac{y_{v\max} - y_{v\min}}{y_{w\max} - y_{w\min}} \\ = \frac{80 - 30}{100 - 10} = \frac{50}{90} = 0.56$$

$$S_0, C_m = \begin{pmatrix} 1 & 0 & 30 \\ 0 & 1 & 30 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0.67 & 0 & 6 \\ 0 & 0.56 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & -10 \\ 0 & 1 & -10 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 0.67 & 0 & 23.3 \\ 0 & 0.56 & 24.4 \\ 0 & 0 & 1 \end{pmatrix}$$

$$S_0, P' = C_m \cdot P$$

$$= \begin{pmatrix} 0.67 & 0 & 23.3 \\ 0 & 0.56 & 24.4 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 20 \\ 20 \\ 1 \end{pmatrix} = \begin{pmatrix} 36.7 \\ 35.6 \\ 1 \end{pmatrix} \approx \begin{pmatrix} 37 \\ 36 \\ 1 \end{pmatrix}$$

Hence, the point P will be placed at (37, 36) Ans

Q14) Derive a composite transformation matrix for mapping a point P_{wc} in a circular window with a radius of 50 pixels and having its center at (50,50) to a circular view port with a radius of 20 pixels and having its center at (10,10).

soln

$$\text{Here, } (x_{wc}, y_{wc}) = (50, 50)$$

$$(x_{vc}, y_{vc}) = (10, 10)$$

$$\text{Then, } w_r = 50 \text{ pixels} \quad v_r = 20 \text{ pixels}$$

$$s_x, s_y = \frac{v_r}{w_r} = \frac{20}{50} = 0.4$$

$$C_m = T(x_{vc}, y_{vc}) \cdot S_{s_x, s_y} \cdot T(-x_{wc}, -y_{wc})$$

$$= \begin{pmatrix} 1 & 0 & 10 \\ 0 & 1 & 10 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0.4 & 0 & 0 \\ 0 & 0.4 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & -50 \\ 0 & 1 & -50 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 0.4 & 0 & -10 \\ 0 & 0.4 & -10 \\ 0 & 0 & 1 \end{pmatrix}$$

Q15) A window has its lower most left corner at (-5, 10) and its upper most right corner at (35, 40). Clip a line segment that has two end points (-20, 5) and (60, 20). If a viewport is defined by (6, 17) and (90, 80). Find the view port coordinates for the intersection points.

soln

$$(x_{wmin}, y_{wmin}) = (-5, 10)$$

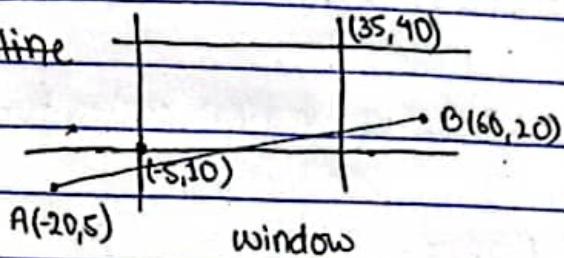
$$(x_{wmax}, y_{wmax}) = (35, 40)$$

$$(x_{wmin}, y_{wmin}) = (6, 17)$$

$$(x_{wmax}, y_{wmax}) = (90, 80)$$

End points of line : A(-20, 5) and B(60, 20)

Step 1 : Establish region codes for line



First, let's translate transform points to viewport.

$$\begin{aligned} C_{vr} &\approx S_x, S_y = \frac{y_{wmax} - y_{wmin}}{y_{wmax} - y_{wmin}} \\ &= \frac{90 - 6}{35 - (-5)} \\ &= 2.1 \end{aligned}$$

$$\begin{aligned} S_y &= \frac{y_{wmax} - y_{wmin}}{y_{wmax} - y_{wmin}} \\ &= \frac{80 - 17}{40 - 10} \\ &= 2.1 \end{aligned}$$

$$C_m = T(x_{wmin}, y_{wmin}) \cdot S_{x,y} \cdot T(-x_{wmin}, -y_{wmin})$$

$$= \begin{pmatrix} 1 & 0 & 6 \\ 0 & 1 & 17 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2.1 & 0 & 0 \\ 0 & 2.1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 5 \\ 0 & 1 & -10 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 2.1 & 0 & 16.5 \\ 0 & 2.1 & -4 \\ 0 & 0 & 1 \end{pmatrix}$$

The points mapped to viewport will be A' and B'.

$$P' = C_m \cdot P$$

$$= \begin{pmatrix} 2.1 & 0 & 16.5 \\ 0 & 2.1 & -4 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -20 & 60 \\ 5 & 20 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} -25.5 & 142.5 \\ 6.5 & 38 \\ 1 & 1 \end{pmatrix}$$



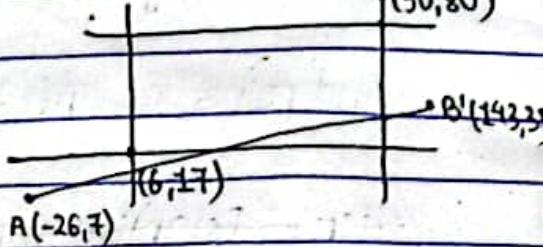
so, $A'(-26, 7)$ and $B'(143, 38)$

$\approx A'(-26, 7)$ and $B'(143, 38)$

(90, 28)

$B'(143, 38)$

Now, Let's find intersection points.



Step 1: Develop region codes for line end points

$A'(-26, 7)$

$B'(143, 38)$

L : $-26 < 6$ T 1

L : $143 < 6$ F 0

R : $-26 > 90$ F 0

R : $143 > 90$ T 1

B : $7 < 17$ T 1

B : $38 < 17$ F 0

T : $7 > 80$ F 0

T : $38 > 80$ F 0

Regi (0101)
~~(1110)~~

(0010)
~~(1110)~~

So, this is not the case of full visibility.

Step 2: Perform AND operation of region code of end points.

1010

0100

0000

So, this is the case of partial visibility.

Step 3: Find intersection points for end points.

$$\text{For } B' \text{ (1st slope (m))} = \frac{y_2 - y_1}{x_2 - x_1} = \frac{38 - 7}{143 + 26} = \frac{31}{169}$$

For $B'(143, 38)$,

$$x = x_{\max} = 90$$

$$y = m(x - x_1) + y_1 \\ = \frac{31}{169}(90 - 143) + 38$$

$$\therefore y = 28.27 \approx 28 \quad (90, 28)$$

For A'(-26, 7),

For bit 1,

$$n = n_{\min} = 6$$

$$\begin{aligned} y &= m(n - n_1) + y_1 \\ &= \frac{31}{169} (6 + 26) + 7 \end{aligned}$$

$$\therefore y = 12.86$$

$$\text{So, } (n', y') = (6, 12.86)$$

For bit 3,

$$y = y_{\min} = 17 \quad y = y_{\max} = 17$$

$$n = \frac{1}{m} (y - y_1) + n_1$$

$$= \frac{169}{31} (17 - 12.86) + 6$$

$$\therefore n = 28.57 \approx 29$$

$$\text{So, } (29, 17)$$

Hence, final coordinates of visible line end points are

A(90, 17), A(29, 17) and B(90, 28) AM

- Q16) Reduce a triangle with coordinates A(0,0), B(0,4), C(8,4), D(8,0) to twice its original about a fixed point P(4,2) also derive a transformation matrix to convert this rectangle into a square.

SOLN

$$C_m = T(4, 2) \cdot S_{S_x=\frac{1}{2}, S_y=\frac{1}{2}} \cdot T(-4, -2)$$

$$= \begin{pmatrix} 1 & 0 & 4 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & -4 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\therefore C_m = \begin{pmatrix} 0.5 & 0 & -4 \\ 0 & 0.5 & -4 \\ 0 & 0 & 1 \end{pmatrix}$$

$$P' = C_m \cdot P$$

$$= \begin{pmatrix} 0.5 & 0 & -4 \\ 0 & 0.5 & -4 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 8 & 8 \\ 0 & 4 & 4 & 0 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} -4 & 4 & 12 & 12 \\ -2 & 6 & 6 & -2 \\ 1 & 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 2 & 6 & 6 \\ 1 & 3 & 3 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

So, So, rectangle coordinates after reduction are

$(2,1), (2,3), (6,3), (6,1)$ Ans

To convert rectangle to square, Lets calculate 'l' & 'b' for rectangle,

$$l = B-A = 8$$

$$b = B-A = 4$$

So, Lets shorten the length from 8 to 4 in x-axis to be square.

$$\text{So, } S_x = \frac{4}{8} = 0.5$$

$$S_y = 1$$

So, using fined point, we first translate the fined point to center (0,0), scale by $S_x = 0.5, S_y = 1$ and translate back.

The transformation matrix will be,

$$C_m = T(x_f, y_f) \cdot S_{S_x=0.5, S_y=1} \cdot T(-x_f, -y_f)$$

$$\begin{aligned}
 &= \begin{pmatrix} 1 & 0 & 4 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0.5 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & -4 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix} \\
 &= \begin{pmatrix} 0.5 & 0 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \underline{\underline{A^{-1}}}
 \end{aligned}$$

(Q17) A triangle with vertices A(0,1,0), B(10,0), C(-10,0) is required to be shifted down by 5 units, then rotate in anticlockwise direction by 30° and scale by twice its original size. What will be the final location?

soM

Step 1: Shift down by 5 units i.e. $T_{(-s, -5)}$

Step 2: Rotate ccw by 30° i.e. $R_{\theta}^{30^\circ}$

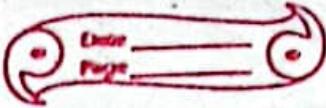
Step 3: Scale by $S_x = 2, S_y = 2$.

$$SO_1, C_m = S_{S_x=2, S_y=2} \cdot R_{\theta}^{30^\circ} \cdot T_{(-s, -5)}$$

$$\begin{aligned}
 &= \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos 30^\circ & -\sin 30^\circ & 0 \\ \sin 30^\circ & \cos 30^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & -5 \\ 0 & 1 & -5 \\ 0 & 0 & 1 \end{pmatrix} \\
 &= \begin{pmatrix} 1.73 & -1 & -3.66 \\ 1 & 1.73 & -13.66 \\ 0 & 0 & 1 \end{pmatrix}
 \end{aligned}$$

$$SO_1, P' = C_m P$$

$$\begin{aligned}
 &= \begin{pmatrix} 1.73 & -1 & -3.66 \\ 1 & 1.73 & -13.66 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 10 & -10 \\ 10 & 0 & 0 \\ 1 & 1 & 1 \end{pmatrix}
 \end{aligned}$$



$$= \begin{pmatrix} -13.66 & 13.66 & -20.98 \\ 3.66 & -3.66 & -23.66 \\ 1 & 1 & 1 \end{pmatrix}$$

$$\approx \begin{pmatrix} 14 & 14 & -21 \\ 4 & -4 & -24 \\ 1 & 1 & 1 \end{pmatrix}$$

Hence, final location will be A(14, 4), B(14, -4), C(-21, -24). Aw

- (Q18) Rotate triangle A(0,0), B(1,1), C(5,2) about origin and about point P(-1,-1) by 45° in a cc direction.

Soln

$$\text{Composite matrix } (C_m) = T_{(-1,-1)} \cdot R_O^{45^\circ} \text{ ccw} \cdot T_{(1,1)} \cdot R_O^{45^\circ} \text{ ccw}$$

$$= \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos 45^\circ & -\sin 45^\circ & 0 \\ \sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos 45^\circ & -\sin 45^\circ & 0 \\ \sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & -1 & -1 \\ 1 & 0 & 0.414 \\ 0 & 0 & 1 \end{pmatrix}$$

$$P' = C_m \cdot P$$

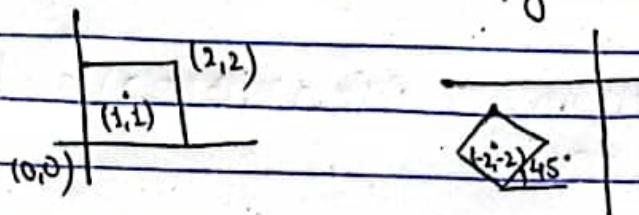
$$= \begin{pmatrix} 0 & -1 & -1 \\ 1 & 0 & 0.414 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 5 \\ 0 & 1 & 2 \\ 1 & 1 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} -1 & -2 & -3 \\ 0.414 & 1.414 & 5.414 \\ 1 & 1 & 1 \end{pmatrix}$$

Final points : A'(-1,0), B'(-2,1), C'(-3,5) Awz



(Q19) Write the series of transformation in matrix that are needed to place the square shown in the figure A reduced to one third of its original size, into the position shown in fig. B where the center of square is at (-2,-2).



Ans

$$C_m = T_{(-2,-2)} \cdot R_{0}^{45^\circ} \cdot S_{\frac{1}{3}, \frac{1}{3}} \cdot T_{(-1,-1)}$$

$$\begin{aligned} &= \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos 45^\circ & -\sin 45^\circ & 0 \\ \sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{3} & 0 & 0 \\ 0 & \frac{1}{3} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix} \\ &= \begin{pmatrix} 0.236 & -0.236 & -2 \\ 0.236 & 0.236 & -2.47 \\ 0 & 0 & 1 \end{pmatrix} \end{aligned}$$

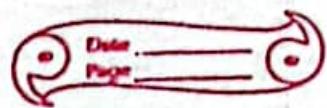
$$\text{To prove, } P' = C_m \cdot P$$

$$\begin{aligned} &= \begin{pmatrix} 0.236 & -0.236 & -2 \\ 0.236 & 0.236 & -2.47 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \\ &= \begin{pmatrix} -2 \\ -2 \\ 1 \end{pmatrix} \end{aligned}$$

Hence, series is as:

Step 1: Translation by factor (-1, -1) to bring object to origin.
(fixed point)

Step 2: scaling by factor $\frac{1}{3}$ in both axis.



Step 3: Rotation by 45° in counter clockwise direction.

Step 4: Translate to by factor $(-2, -2)$ to move fined point to reqd point as in fig.

- Q20) Reflect a point triangle with vertices A(4, 1), B(5, 2) and C(4, 3) about line $3x - 4y + 8 = 0$

Soln

$$\text{Given line, } -4y = -3x - 8$$

$$\text{or, } y = \frac{3}{4}x + 2$$

$$\text{Here, } m = \frac{3}{4}; c = 2$$

$$\text{so, } \theta = \tan^{-1}\left(\frac{3}{4}\right) = 36.87^\circ$$

For reflection,

$$C_m = T_{(0, 2)} \cdot R_{cw}^{36.87^\circ} \cdot R_{fx} \cdot R_{cw}^{-36.87^\circ} \cdot T_{(0, -2)}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos 36.87 & -\sin 36.87 & 0 \\ \sin 36.87 & \cos 36.87 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos 36.87 & \sin 36.87 & 0 \\ -\sin 36.87 & \cos 36.87 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0.279 & 0.960 & -1.92 \\ 0.960 & -0.279 & 0.559 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 0.279 & 0.960 & -1.92 \\ 0.960 & -0.279 & 2.559 \\ 0 & 0 & 1 \end{pmatrix}$$

$$S_0, P' = C_m \cdot P$$

$$= \begin{pmatrix} 0.279 & 0.960 & -1.92 \\ 0.960 & -0.279 & 2.559 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 4 & 5 & 4 \\ 1 & 2 & 3 \\ 1 & 1 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 0.159 & 1.39 & 2.079 \\ 6.12 & 6.80 & 5.560 \\ 1 & 1 & 1 \end{pmatrix}$$

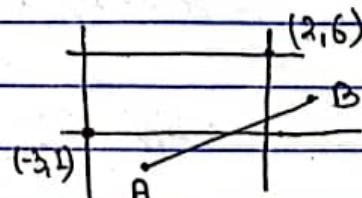
Hence, Final triangle vertices are approximately,

$$A(0, 6), B(1, 7), C(2, 6)$$

- Q21) Clip a line with end points A(1, -2) and B(3, 3) against a clip window with its lower left corner at (-3, 1) and upper right corner at (2, 6).

Soln

Line end points : A(1, -2) , B(3, 3)



Step 1: Develop region codes for line end points.

A(1, -2) :

L : $1 < -3$ F 0

R : $1 > 2$ F 0

B : $-2 < 1$ T 1

T : $-2 > 6$ F 0

Code : (0100)

B(3, 3) :

L : $3 < -3$ F 0

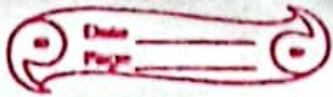
R : $3 > 2$ T 1

B : $3 < 1$ F 0

T : $3 > 6$ F 0

Code : (0010)

So, this is not the case of full visibility.



Step 2: Perform AND operation of region codes of end points.

0100

0010

0000

So, this is the case of partial visibility.

Step 3: Find intersection points with clip window.

For A, (1, -2)

$$m = \frac{y_2 - y_1}{x_2 - x_1} = \frac{3 - (-2)}{3 - 1} = \frac{5}{2}$$

$$y = y_{\text{window}} = 1$$

$$n = \frac{1}{m}(y - y_1) + n_1$$

$$= \frac{2}{5}(1 + 2) + 1$$

$$= 2.2 \quad (2.2, 1) \approx (2, 1)$$

For B, (3, 3)

$$n = n_{\text{window}} = 2$$

$$y = m(n - n_1) + y_1$$

$$= \frac{5}{2}(2 - 3) + 3$$

$$= 0.5$$

$$\approx (2, 0.5) \approx (2, 1)$$

Hence, the visible end points of line are A(2, 1) and B(2, 1)

i.e. line passes through intersection point of clip window.



(Q2) Prove that reflection about line $y = -x$ is equivalent to reflection about y -axis followed by a counter clockwise rotation by 90° .

82"

case I : Reflection about line $y = -x$,

Here, $m = -1$

$$m \cdot \theta = -\tan^{-1}(-1)$$

$$\therefore \theta = -45^\circ$$

$$C_m = R_{\text{cw}}^{-45^\circ} \cdot R_{fx} \cdot R_{\text{ccw}}^{+45^\circ}$$

$$= \begin{pmatrix} \cos 45^\circ & \sin 45^\circ & 0 \\ -\sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos 45^\circ & -\sin 45^\circ & 0 \\ \sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

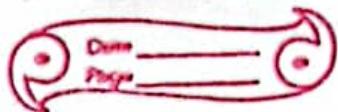
$$\therefore C_{m_1} = \begin{pmatrix} 0 & -1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

case II : counter clockwise rotation by 90° after R_{fy} .

$$C_m = R_{\text{ccw}}^{90^\circ} \cdot R_{fy}.$$

$$= \begin{pmatrix} \cos 90^\circ & -\sin 90^\circ & 0 \\ \sin 90^\circ & \cos 90^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\therefore C_{m_2} = \begin{pmatrix} 0 & -1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$



As the composite matrix obtained in both cases are same,
reflection about $y = -x$ is equivalent to reflection about
 y -axis followed by a counter clockwise rotation by 90 degrees.