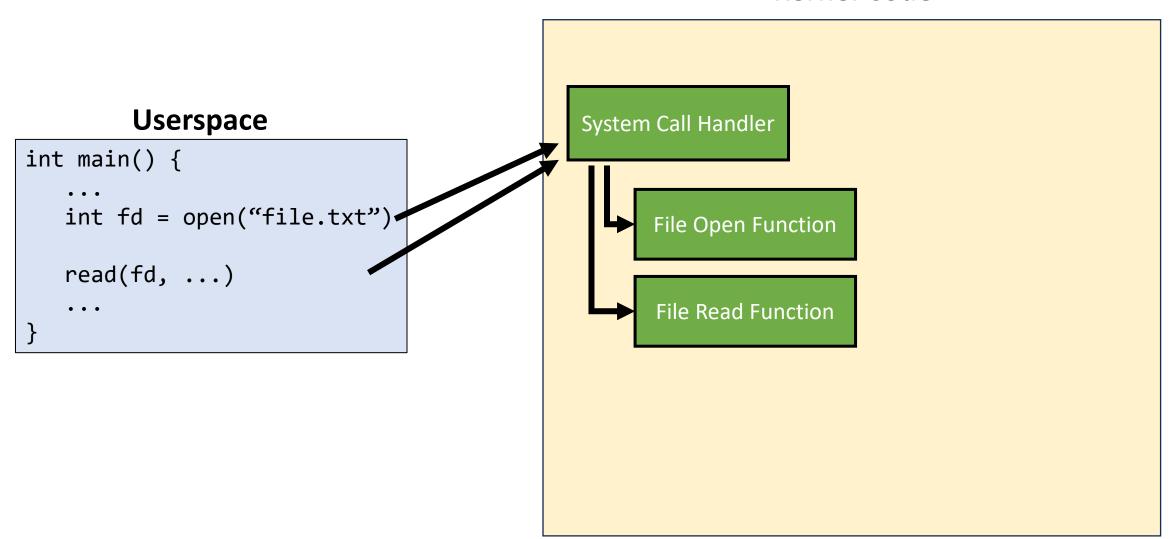
# Devices BYU Electrical & Computer Engineering IRA A. FULTON COLLEGE OF ENGINEERING

#### **Linux System Calls**



At the end of last class we looked at the list of syscalls:

https://chromium.googlesource.com/chromiumos/docs/+/HEAD/constants/syscalls.md

Where are the system calls to talk to hardware devices?

- UART
- Disk
- Video card
- Physical memory
- USB devices

#### Calling Function in Drivers

#### **Userspace**

```
int main() {
    ...
    uart_get_input() ???
    ...
}
```

Don't our device drivers provide functions that we can call to access the devices?

- Look like ordinary files in the filesystem, but are special files
- They are interfaces to the driver that controls the device
- By using system calls that operate on files, our code can interface with the driver.

They are not real files...

Have you used a device file before?

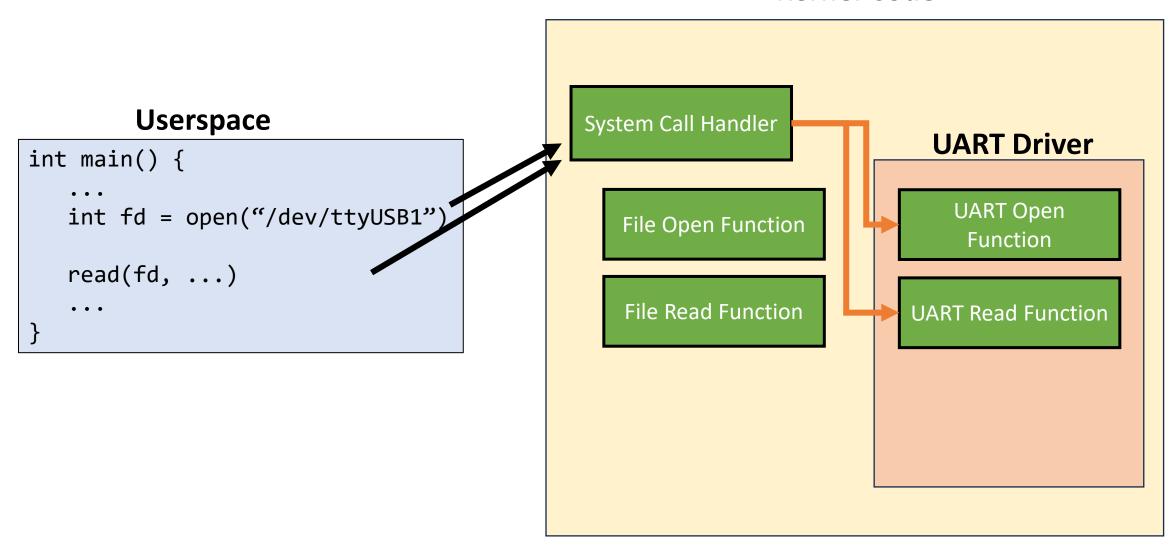
#### Pseudo-devices [edit]

Device nodes on Unix-like systems do not necessarily have to correspond to physical devices. Nodes that lack this correspondence form the group of pseudo-devices. They provide various functions handled by the operating system. Some of the most commonly used (character-based) pseudo-devices include:

- /dev/null accepts and discards all input written to it; provides an end-of-file indication when read from.
- /dev/zero accepts and discards all input written to it; produces a continuous stream of null characters (zero-value bytes) as output when read
  from.
- /dev/full produces a continuous stream of null characters (zero-value bytes) as output when read from, and generates an ENOSPC ("disk full") error when attempting to write to it.
- /dev/random produces bytes generated by the kernel's cryptographically secure pseudorandom number generator. Its exact behavior varies by implementation, and sometimes variants such as /dev/urandom or /dev/arandom are also provided.
- /dev/stdin, /dev/stdout, /dev/stderr access the process's standard streams.
- /dev/fd/n accesses the process's file descriptor n.

Additionally, BSD-specific pseudo-devices with an ioctl interface may also include:

- /dev/pf allows userland processes to control PF through an ioctl interface.
- /dev/bio provides ioctl access to devices otherwise not found as /dev nodes, used by bioctl to implement RAID management in OpenBSD and NetBSD.
- /dev/sysmon used by NetBSD's envsys framework for hardware monitoring, accessed in the userland through proplib(3) by the envstat utility.<sup>[8]</sup>



#### **ECEN427 PYNQ Hardware System**

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https://byu-cpe.github.io/ecen427/documentation/hardware/

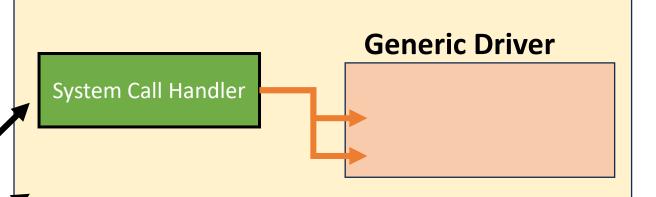
#### Linux System Calls

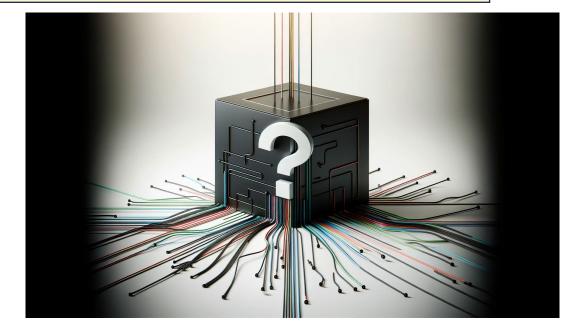
Do we really need a separate driver for every hardware device?

Can we make a generic driver?

#### Userspace

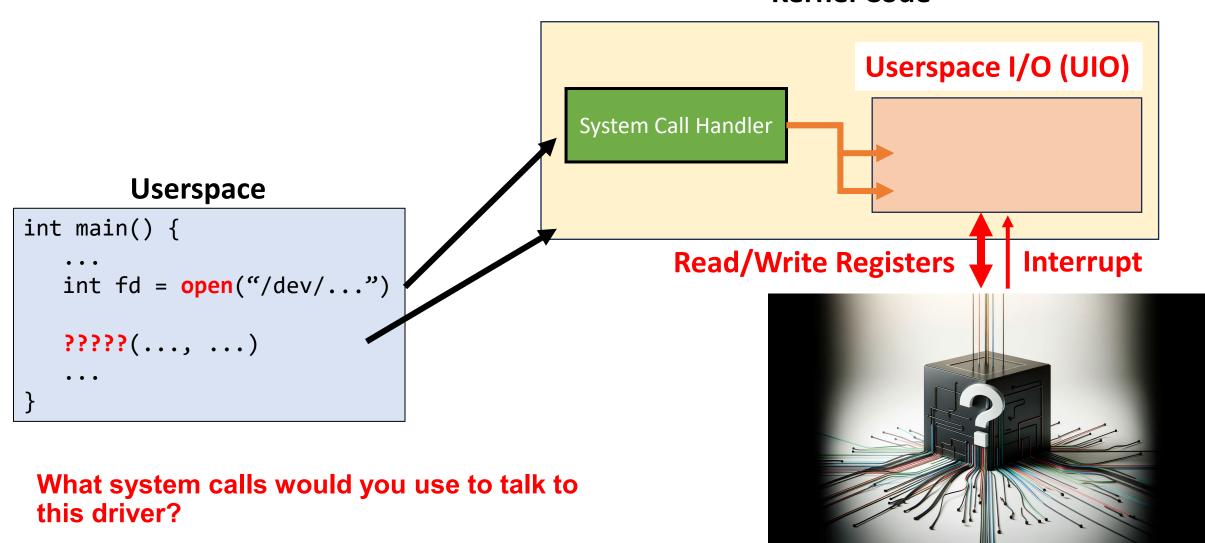
```
int main() {
    ...
    int fp = open("/dev/...")
    ?????(..., ...)
    ...
}
```





# What kinds of things do you need to do with a hardware device you know nothing about?

#### **Linux System Calls**



## Before learning more, let's pause and cover a few more operating system concepts...

mmap()

Map files (or devices) into memory

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#### **Userspace I/O**

- Read/Write addresses (registers):
  - mmap()
  - Access registers via pointer returned from mmap
- Enable interrupts:
  - write() a 1
  - You must write 4 bytes
- Wait for interrupt:
  - read()
  - You must read 4 bytes

#### **ECEN427 PYNQ Software System**

https://byu-cpe.github.io/ecen427/documentation/software-stack/

- The UIO linux driver is not meant to actually serve as the device driver
- It provides an interface that allows you to write drivers in userspace.
- In lab 2, you will create userspace drivers for the buttons, switches and interrupt controller
  - These will interface with the UIO kernel driver to access the devices
- Example <a href="https://github.com/byu-cpe/ecen427">https://github.com/byu-cpe/ecen427</a> student/blob/main/userspace/drivers/uio example/generic u io example.c