
CoRTOS:

A minimal OS for Ajit

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Overview

Objective

Design a functionally complete programming environment for application design and its runtime on the Ajit processor.

Major Features

- Supports Multi-Core Ajit Processor
- Supports synchronization and message passing queues between software threads.
- Programmable trap/interrupt handling.

Current Status

Provides a functionally complete set of features.

Dependency

A complete Ajit development environment setup

Programing with CoRTOS

Create a project with a config.yaml

A project in CoRTOS is a folder with all the C/C++/Assembly files and a `config.yaml` file that describes the project.

Use the API

CoRTOS, along with Ajit's Access Routines provides many convenient APIs to help with application development.

Refer the CoRTOS examples

Simple programs that demonstrate most CoRTOS features.

Creating a Project

A Project and its config.yaml

Project Directory Layout

A user project directory in CoRTOS is a folder with all the C/C++/Assembly files and a `config.yaml` file that describes the project.

config.yaml

This file describes the specification of the target hardware and the software configuration of the project.

***Refer to examples in CoRTOS.**

config.yaml - using yaml syntax ([short yaml tutorial](#))

Describes Hardware

- Processor description, #cores, #threads, and 32/64 bit ISA.
- Memory description, memory mapped IO region and other regions.
- Devices supported and their specifications.

Describes Software

- Build/Execute parameters
- User function to hardware thread mapping.
- Specify dynamic memory pool
- Program traps/interrupts.

config.yaml - describes project

It only has two components.

Hardware:

. . .

Software:

. . .

config.yaml - Hardware

Describes the Ajit specific hardware configuration to CoRTOS.

Hardware:

Processor: ...

Memory: ...

Devices: ...

config.yaml - Hardware.Processor

Processor:

Cores: 1 # 1 to 8 only

ThreadsPerCore: 2 # 1 or 2 only

ISA: 32 # 32/64 bit (Default: 32)

config.yaml - Hardware.Memory

Describes various hardware memory regions. E.g. Flash Memory, RAM, NC RAM, Memory Mapped IO

NC RAM is a special non-cacheable ram region in the hardware memory system. It is for the devices to directly write to memory without caring about the processor cache.

```
Memory:
  MaxPhysicalAddrBitWidth: 36    # hw bus addr bit width
  Flash:
    StartAddr: 0x0               # physical address
    SizeInMegaBytes: 16
    Permissions: RXC             # (Read,Write,eXecute,Cacheable)
  RAM:
    StartAddr: 0x40000000         # physical address
    SizeInMegaBytes: 128
    Permissions: RWXC
  NCRAM:
    StartAddr: 0x80000000         # physical address
    SizeInMegaBytes: 16
    Permissions: RW
  MMIO: # Memory Mapped IO
    StartAddr: 0xFFFF0000        # physical address
    EndAddr: 0xFFFFFFFF
    Permissions: RW
```

config.yaml - Hardware.Devices

./AjitPublicResources/tools/ajit_access_routines_mt/include/device_addresses.h

All devices
communicate with the
processor using
memory mapped IO.

```
Devices:
- Name: Timer
  MemoryRegion:
    StartAddr: 0xFFFF3100 # physical addr (in MMIO)
    SizeInBytes: 256 # 16x16
    Permissions: RW
  NamedRegisters:
    Control: 0xFFFF3100
- Name: InterruptController
  ...
- Name: Serial
  MemoryRegion:
    ...
- Name: ScratchArea
  MemoryRegion:
    StartAddr: 0xFFFF2C00
    SizeInBytes: 1024
    Permissions: RW
```

config.yaml - Software

Software:

StartupFuncName: ...

BuildAndExecute: ...

ProgramThreads: ...

DynamicMemroy: ...

Interrupts: ...

Traps: ...

config.yaml - Software.StartupFuncName

A startup function with “void (void)” signature.

StartupFuncName: user_func

user_func() is invoked
on thread (0,0) after
system initialization by
CoRTOS is complete.
All other user functions
on all threads start
after this function
completes.

config.yaml - Software.BuildAndExecute

Specifies the build and runtime parameters (for Ajit's C Reference Model) of the project.

The **BuildArgs** parameter is passed to the ``ajit_C_reference_model``. Refer the program to see all its options.

Note: Source sub-folders in the project can be specified in BuildArgs using ``-C`` and ``-S`` options.

BuildAndExecute:

```
# Optional: Specify the log level. Default is NONE.  
# ALL<TRACE<DEBUG<INFO<ERROR<CRITICAL<NONE  
LogLevel: DEBUG  
OptimizationLevel: 2 # i.e. 02 (0, 1 or 2)  
Debug: No # Yes/No (Default: No)  
FirstDebugPort: 8888  
BuildArgs: "-D CORTOS_ENV"
```

Or for debug build use: **cortos build -g**

config.yaml - Software.ProgramThreads

Maps user functions to hardware threads.

func01 and func02 are
execute one after the other
on thread (0,0) and func10 is
executed on the next
available hardware thread.

```
ProgramThreads:
  - CortosInitCalls:
    - func01      # no naming restrictions
    - func02
  StackSize:
    SizeInKiloBytes: 16
  - CortosInitCalls:
    - func10      # no naming restrictions
  StackSize:
    SizeInBytes: 2048
```

config.yaml - Software.DynamicMemory

Size of dynamic memory pool can be specified.

```
DynamicMemory: # Dynamic Memory Configuration.  
  SizeInKiloBytes: 1000    # default is 4KB
```

When DynamicMemory is not specified, the system assumes a default size of 4KB.

config.yaml - Software.Interrupts

User can handle some hardware interrupts.

```
#####  
# Hardware interrupts.  
# Specify a list of hardware interrupt handlers  
# Index: An index from 1 to 15.  
# Function: <func_name> (of type void (*func_name)())  
  
#####  
Interrupts: # hardware interrupts  
- Index: 12 # serial interrupt index  
  Function: my_serial_interrupt_handler  
- Index: 15  
  Function: int_15_handler
```

config.yaml - Software.Traps

User can handle software traps. (Note the function signature type below)

```
#####  
# Software traps  
# Specify a list of hardware interrupt handlers  
# Index: An index from 1 to 15.  
# Function: <func_name>  
#           void (*func_name)(uint32_t,uint32_t,uint32_t)  
#####  
Traps: # software traps  
- Index: 12 # trap index  
  Function: trap_12_handler # no naming restrictions  
- Index: 15  
  Function: trap_15_handler
```

CoRTOS API

CoRTOS API (cortos.h)

This presentation may get out-dated when APIs are updated. The true source of APIs are the header files provided by CoRTOS. The APIs are well documented there.

CoRTOS environment:

#define **CORTOS_ENV**

is available to all projects

Locks and Synchronization (cortos_locks.h)

Get a pointer to a lock and then use it.

Queue and Message Passing (cortos_queues.h)

Dynamically/Staticly allocate a queue and start using it.

Dynamic Memory (cortos_bget.h)

Dynamically allocate memory at runtime.

Utilities: Printing Output etc. (cortos_utils.h)

cortos_printf(), cortos_exit() etc.

Logging: Printing log messages. (cortos_logging.h)

CORTOS_DEBUG(), CORTOS_INFO(), ...

***Examples in CoRTOS are a good demonstration of these APIs.**

API - using Locks (cortos_locks.h)

CoRTOS provides a pool of 256 cacheable and 256 non-cacheable (NC) locks.

```
uint8_t* lockPtr = cortos_reserveLock(1 /*i.e. NC lock*/);  
  
cortos_lock_acquire_buzy(lockPtr);  
  
// critical section code  
  
cortos_lock_release(lockPtr);  
  
//free the lock variable  
cortos_freeLock(lockPtr);  
// after free, the value in lockPtr should not be used.
```

See [example_100](#)

API - using Queues (cortos_queues.h)

User can dynamically/statically allocate queues. Here we show dynamic allocation.

writeCount and
readCount hold the actual
number of messages
written to or read from the
queue.

See [example_150](#)

```
struct CortosQueueHeader * volatile hdr = 0;
uint32_t msgs_a[4], msgs_b[4];

hdr = cortos_reserveQueue(
    sizeof(uint32_t) /*single msg size in bytes*/,
    2 /*length i.e. max messages in the queue*/,
    1 /*1 means non-cacheable*/);

writeCount = cortos_writeMessages(
    hdr, /* pointer to the queue */
    (uint8_t*)(msgs_a), /* message source */
    4 /*max number of messages to be written*/);

readCount = cortos_readMessages(
    hdr,
    (uint8_t*)(msgs_b), /* message destination */
    4 /*max number of messages to be read*/);
```

API - dynamic memory (cortos_bget.h)

Dynamically allocate and deallocate memory at runtime.

`_ncram` is for
non-cacheable RAM area
where the memory is
allocated.

See

- [example_200](#)
- [example_210](#)

```
uint32_t * volatile arr = 0;  
arr = (uint32_t*)cortos_bget(sizeof(uint32_t)*20);  
  
// use the memory
```

```
cortos_brel(arr); // free memory
```

```
uint32_t * volatile arr = 0;  
arr =  
(uint32_t*)cortos_bget_ncram(sizeof(uint32_t)*20);  
  
// use the memory  
  
cortos_brel_ncram(arr); // free memory
```

API - utilities (cortos_utils.h)

Some utilities provided by cortos.

These can be seen in
almost all the examples.

```
cortos_printf("hello %d", value); // thread safe
```

```
cortos_exit(exit_integer_code);
```

Ajit's access routines provide many more APIs.

API - logging (cortos_logging.h)

Thread safe logging support by CoRTOS. Use these instead of `cortos_printf``.

These can be seen in almost all the examples.

```
CORTOS_DEBUG("hello %d", value);
```

```
CORTOS_INFO("hello %d", value);
```

Along with the user message, this prints the thread id, source line number, and the number of elapsed ticks of the processor.

Logging Levels: ALL < TRACE < DEBUG < INFO < ERROR < CRITICAL < NONE

Example, if logging level is set to INFO, then TRACE and DEBUG messages disappear.

config.yaml: **Software.BuildAndExecute.LogLevel**: INFO

API - interrupts/traps (cortos_traps.h)

User can program 15 hardware interrupts and 15 software interrupts.

Invoke a software trap from C code:

```
__AJIT_SW_TRAP(5); // ta 5
```

Please see the following examples:

- **example_310 (interrupts)**
- **example_320 (traps)**

Declare volatiles carefully!

Global variables used across threads may need to be declared volatile by the programmer.

Please note the difference below:

```
volatile int * ptr; // a volatile int value
```

```
int * volatile ptr; // a volatile pointer
```

```
// a volatile pointer to a volatile int value  
volatile int * volatile ptr;
```

CoRTOS Examples Directory

CoRTOS Examples Directory

It contains various `example_XXX` directories. Go into any of these directories to build and run them

```
cd example_150
```

Remember to set paths
of the AJIT's setup.

```
./build.sh # builds the example
```

```
./run.sh # run using C Model
```

Example have `config.yaml` files which are meant to be used as reference for user projects.

LOCATION: In the ajit-toolchain repository: `cd os/rtos/cortos2/examples;`

Thank You

TODOs

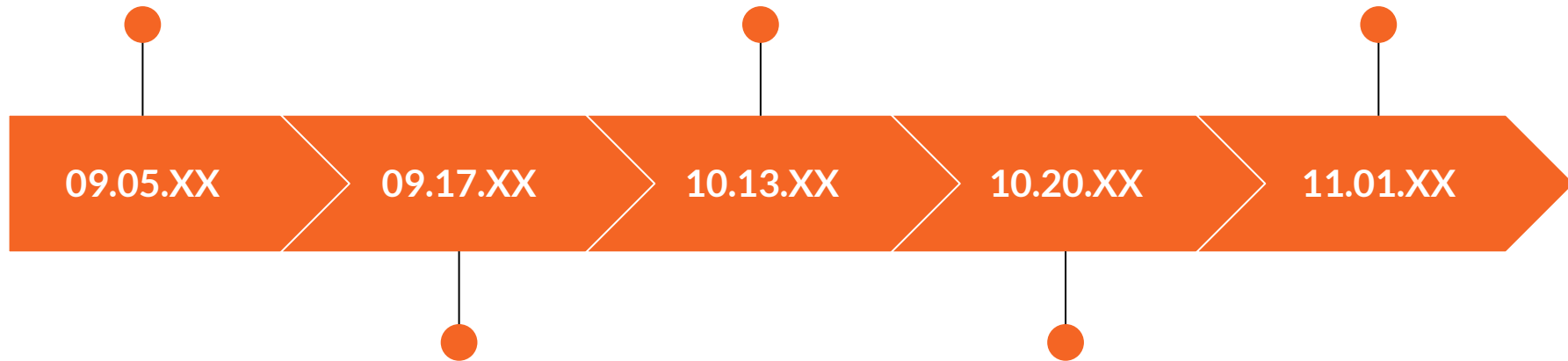
1. Standardise the API (done).
2. Improve system feedback (improved).
3. Add more tests (added three tests).

Questions/Suggestions?

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