

CS618 Project
Porting Constraint Generation to GCC 5.2.0

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GCC Resource Center

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Contents

1	Introduction	2
2	Approach Followed	2
3	List of Constraints Generated by the Plugin	2
3.1	Basic Pointer Constraints	2
3.1.1	Single Pointer to Integer	2
4	Change Patterns	5
5	Future Work	5

1 Introduction

This report documents the work done to port the constraint generation plugin from GCC 4.7.2 to GCC 5.2.0. The constraint generation plugin extracts the pointer based constraints from the GIMPLE IR during LTO (Link Time Optimization) phase and dumps them in an output file. These constraints are then used for many other pointer analysis based optimizations developed in-house.

The rest of the report documents the general approach followed to port the plugin; then the list of constraints detected by the plugin are listed with test cases; then the pattern of changes observed from GCC 4.7.2 to GCC 5.2.0 are listed (although not exhaustive); and at last the future work discusses the work remaining.

2 Approach Followed

This section summarises the approach followed to port the plugin. We believe this might help us to port other (if any) plugins in the future. Some of the methods are specific for this plugin. We tried understanding the code before making changes, but the direct source level changes eventually gave much quicker results. The basic approaches are enumerated below:

1. Compilation was the first problem. So we adopted the incremental approach where we added source code in logical units, files, functions etc. This helped us tackle small number of issues at a time. The functions were added by following the call hierarchy from the top. This helped us include only those functions that were reachable/used. This helped reduce the size of the code drastically.
2. How to adapt the source code was another problem. Here we compared the tree-ssa-structalias.c in GCC 4.7.2 and GCC 5.2.0, and most of the differences were straight forward to understand. This worked because, the plugin was an adaptation of tree-ssa-structalias.c in GCC 4.7.2.

3 List of Constraints Generated by the Plugin

This section tries to enumerate all possible constraints. Each test-case and its constraints are listed below.

The programs have been created with some naming conventions of variables to make it easy to understand the type of constraints when reading. Table 1 outlines the names and their associated meaning.

3.1 Basic Pointer Constraints

Constraints related to pointer(s) to basic datatypes.

3.1.1 Single Pointer to Integer

Here the pointer is pointing to an integer. It could point to any other basic datatype, generating similar constraints.

Name	Meaning
i	Read 'i' as 'integer'.
pi	Read 'pi' as 'pointer-to integer'.
ppi	Read 'ppi' as 'pointer-to pointer-to integer'. Therefore, *ppi would be a pointer-to integer.
piA, piB	Read 'piA' as 'pointer-to integer A'. Capital letter suffixes like A, B, ... are used only to make the names distinct.
f	Read 'f' as 'function'.
fA, fB	Functions with different names. Capital letter suffixes like A, B, ... are used to make the names distinct. Read 'fA' as 'function A'.
fp	Read 'fp' as 'function parameter'. Note that here 'p' is used after 'f' and hence is no more read as 'points-to'.

Table 1: Testcase variables naming conventions

```

1 // This program enumerates the semantically meaningful
2 // statements possible using a single pointer
3 // variable (pointer to int).
4 int* f (int *piFormal);
5 int main() {
6     int i = 17;
7     int *pi;
8
9     pi = &i;
10    i = *pi;
11    *pi = 19;
12    pi = pi + 1;
13    pi = pi - 1;
14    pi++;
15    pi--;
16    pi = 0;
17    pi = 17;
18    f (pi);
19
20    return 0;
21 }
22
23 int* f (int *pifp) {
24     return pifp;
25 }

```

Figure 1: test-01.c

Table 2: test-01 constraints

Tag	Content
Source	pi = &i
GIMPLE	pi_1 = &i
Constraint	LHS: var id 8, ptr_arith=0, offset 0(), type 0, name pi RHS: var id 9, ptr_arith=0, offset 0(), type 2, name i
Source	i = *pi
GIMPLE	i.0_2 = *pi_1
Constraint	Var id 8, name pi, offset 0
Source	pi = pi + 1
GIMPLE	pi_3 = pi_1 + 4
Constraint	LHS: variable id 8, ptr_arith=0, offset 0(), type 0, name pi, RHS: variable id 8, ptr_arith=1, offset 32(), type 0, name pi
Source	pi = pi - 1
GIMPLE	pi_4 = pi_3 + -4
Constraint	LHS: variable id 8, ptr_arith=0, offset 0(), type 0, name pi, RHS: variable id 8, ptr_arith=1, offset 18446744073709551584(), type 0, name pi
Source	pi++
GIMPLE	pi_5 = pi_4 + 4
Constraint	LHS: variable id 8, ptr_arith=0, offset 0(), type 0, name pi, RHS: variable id 8, ptr_arith=1, offset 32(), type 0, name pi
Source	pi--
GIMPLE	pi_6 = pi_5 + -4
Constraint	LHS: variable id 8, ptr_arith=0, offset 0(), type 0, name pi, RHS: variable id 8, ptr_arith=1, offset 18446744073709551584(), type 0, name pi
Source	pi = 0
GIMPLE	pi_7 = 0B
Constraint	LHS: variable id 8, ptr_arith=0, offset 0(), type 0, name pi, RHS: variable id 2, ptr_arith=0, offset 0(), type 2, name null
Source	pi = 17
GIMPLE	pi_8 = 17B
Constraint	No constraint generated
Source	f (pi)
GIMPLE	f (pi_8)
Constraint	LHS: variable id 7, ptr_arith=0, offset 0(), type 0, name pifp, RHS: variable id 8, ptr_arith=0, offset 0(), type 0, name pi
Source	...
GIMPLE	D.2363_2 = pifp_1(D)
Constraint	LHS: variable id 10, ptr_arith=0, offset 0(), type 0, name D.2363, RHS: variable id 7, ptr_arith=0, offset 0(), type 0, name piFormal
Source	return pifa

GIMPLE	return D.2363.2
Constraint	Var id 10, name D.2363, offset 0

4 Change Patterns

5 Future Work

1. The plugin source has to be logically understood.
2. A C constraint has to added. The C constraint, where a pointer is assigned an arbitrary integer (other than NULL) is not currently detected by the plugin.
3. C++ constraints have to be included.

Sr.No	Description	
1	Mapping old macros to new macros	<pre> #define VEC(A,B) vec<A> #define DEF_VEC_O(A) #define DEF_VEC_ALLOC_O(A,B) #define DEF_VEC_P(A) #define DEF_VEC_ALLOC_P(A,B) #define FOR_EACH_VEC_ELT1(A,B,C,D) FOR_EACH_VEC_ELT(*B,C,D) #define FOR_EACH_LOOP1(li,loop,C) FOR_EACH_LOOP(loop,C) #define VEC_length(A,B) (*(B)).length() #define VEC_free(A,B,C) (*C).release() #define VEC_pop(A,B) (*B).pop() #define VEC_index(A,B,C) ((*B)[C]) #define VEC_empty(A,B) ((*(B)).length() == 0) #define VEC_qsort(A,B,C) ((*(B)).qsort(C)) #define VEC_iterate(A,B,C,D) (*B).iterate(C, &(D)) #define VEC_safe_push(A,B,C,D) (*C).safe_push(D) #define VEC_last(A,B) &((*B)[(*B).length()-1]) #define VEC_alloc(A,B,C) new vec<A>() #define VEC_replace(T, V, I, V) (*V).[(I)] = (V) </pre>
2	Change in vector allocation	<pre> VEC(constructor_elt,gc) *v = VEC_alloc (constructor_elt, gc, 100); </pre>
		<pre> vec<constructor_elt>*v; vec_alloc (v, 100); </pre>
3	Change vector length api	<pre> VEC(tree, gc) *params; VEC_length (tree, params); </pre>
		<pre> vec<tree,va_gc >*params; params->length (); </pre>

4	Iterating through each basic block of each defined function.	<pre> 4.7 struct cgraph_node * cnode = NULL; for (cnode = cgraph_nodes; cnode; cnode = cnode->next) { // skip nodes without a body, and clone nodes, if (!gimple_has_body_p (cnode->decl) —— cnode->clone_of) continue; push_cfun(DECL_STRUCT_FUNCTION (cnode->decl)); basic_block current_block; FOR_EACH_BB (current_block) print_parsed_data (current_block); } </pre>
		<pre> 5.2 struct cgraph_node * cnode = NULL; FOR_EACH_DEFINED_FUNCTION (cnode) { struct function *func; if(!gimple_has_body_p (cnode->decl) —— cnode->clone_of) continue; func=DECL_STRUCT_FUNCTION (cnode->decl); push_cfun(func); basic_block current_block; FOR_EACH_BB_FN (current_block,func) print_parsed_data (current_block); } </pre>
5	Change in safe_push api	<pre> 4.7 vec<tree,va_gc>*vec; VEC_safe_push (tree_gc_vec, gc, tree_vector_cache, vec); </pre>
		<pre> 5.2 vec_safe_push (tree_vector_cache, vec); </pre>
6	Change in getName api	<pre> 4.7 struct cgraph_node *new_node; cgraph_node_name (new_node) </pre>
		<pre> 5.2 struct cgraph_node *new_node; new_node->name (); </pre>