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Quiz2

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https://github.com/adhvik24/EE3900/blob/main/quiz2/main.tex

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https://github.com/adhvik24/EE3900/blob/main/quiz2/code.py

PROBLEM 3.7 (A)

3.7 (a) The input to a casual linear time-invariant system is

$$x[n] = u[-n-1] + \left(\frac{1}{2}\right)^n u[n] \tag{0.0.1}$$

The z-transform of the output of this system is

$$Y(z) = \frac{-\frac{1}{2}z^{-1}}{\left(1 - \frac{1}{2}z^{-1}\right)\left(1 + z^{-1}\right)}$$
(0.0.2)

- (a) Determine H(z), the z-transform of the system impulse response. Be sure to specify the region of convergence.
- (b) What is the region of convergence for Y(z).
- (c) Determine y[n].

Solution 3.7(a)

Definition 1. We say that a system is **Causal** if the output of a system at a given time instance is independent of the future input values, i.e the output at a particular instance only depends on the present and past input values.

Lemma 0.1. A system is causal if and only if the transfer function h[n] satisfies h[n] = 0, n < 0

Proof. Let the input signal be given by x[n] and the output signal be given by y[n], then, we know in an LTI system:

$$y[n] = h[n] * x[n] = \sum_{k=-\infty}^{\infty} h[k]x[n-k]$$
 (0.0.3)

Since, y[n] is causal, it should be independent of future values of n.

If k < 0, then n - k > n, which is undesirable, and thus, to keep y[n] independent of future values, h[k] = 0, k < 0

Lemma 0.2. A system is said to be causal if and only if the ROC of the impulse function lies outside the outermost pole.

Lemma 0.3. *If* $x[n] = a^n u[n]$, *where*

$$u[n] = \begin{cases} 1 & n \ge 0 \\ 0 & otherwise \end{cases}$$
 (0.0.4)

then $x[n] \stackrel{\mathcal{Z}}{\rightleftharpoons} X[z] = \frac{1}{1 - az^{-1}}$ with ROC = |z| > a

Proof. Using the formula for the sum of an infinite GP, we get:

$$x[n] = \begin{cases} a^n & n \ge 0\\ 0 & otherwise \end{cases}$$
 (0.0.5)

$$Z{x[n]} = X[z] = \sum_{n=-\infty}^{\infty} x[n]z^{-n}$$
 (0.0.6)

$$= \sum_{n=-\infty}^{0} 0 \times z^{-n} + \sum_{n=0}^{\infty} (az^{-1})^{n}$$
 (0.0.7)

$$= \frac{1}{1 - az^{-1}}, ROC = |az^{-1}| < 1 \tag{0.0.8}$$

$$= \frac{1}{1 - az^{-1}}, ROC = |z| > a \tag{0.0.9}$$

Lemma 0.4. If $x[n] = -a^n u[-n-1]$, then $x[n] \stackrel{Z}{\rightleftharpoons} X[z] = \frac{1}{1-az^{-1}}$ with ROC = |z| < a

Proof. Using the formula for the sum of an infinite GP, we get:

$$x[n] = \begin{cases} -a^n & n \le -1\\ 0 & otherwise \end{cases}$$
 (0.0.10)

$$Z\{x[n]\} = X[z] = \sum_{n=-\infty}^{\infty} x[n]z^{-n}$$

$$= \sum_{n=-\infty}^{\infty} \{-a^n u[-n-1]\} z^{-n}$$

$$= \sum_{n=-\infty}^{-1} -a^n z^{-n} + \sum_{n=-1}^{\infty} 0 \times z^{-1}$$

$$= -\sum_{n=1}^{\infty} (a^{-1}z)^n = 1 - \sum_{n=0}^{\infty} (a^{-1}z)^n$$

$$= 1 - \frac{1}{1 - a^{-1}z}, ROC = |a^{-1}z| < 1$$

$$X[z] = \frac{1}{1 - az^{-1}}, ROC = |z| < a \qquad (0.0.11)$$

We are given x[n] as,

$$x[n] = u[-n-1] + \left(\frac{1}{2}\right)^n u[n]$$
 (0.0.12)

Then the z-transform of x[n] using (0.3) and (0.4)is,

$$X(z) = \frac{-1}{1 - z^{-1}} + \frac{1}{1 - \frac{1}{2}z^{-1}}, \frac{1}{2} < |z| < 1$$
 (0.0.13)
$$H(z) = \frac{(1 - z^{-1})}{(1 + z^{-1})} \text{ and the ROC is } |z| > 1$$

We know that H(z) is,

$$H(z) = \frac{Y(z)}{X(z)}$$
 (0.0.14)

Using Y(z) and (0.0.13) in (0.0.14), will result in H(z) as,

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\frac{-\frac{1}{2}z^{-1}}{(1-\frac{1}{2}z^{-1})(1+z^{-1})}}{\frac{-1}{1-z^{-1}} + \frac{1}{1-\frac{1}{2}z^{-1}}}$$

$$= \frac{-\frac{1}{2}z^{-1}}{(1-\frac{1}{2}z^{-1})(1+z^{-1})} \cdot \frac{(1-\frac{1}{2}z^{-1})(1-z^{-1})}{-\frac{1}{2}z^{-1}}$$

$$H(z) = \frac{(1-z^{-1})}{(1+z^{-1})}$$

$$H(z) = \frac{2}{(1+z^{-1})} - 1 \qquad (0.0.16)$$

From the above decomposition, we find that the poles of H(z) are z = -1, and the zeroes are z = 1, as shown in the plot-zero diagram given below. Thus, we can also say the outermost pole is z = -1, and thus, from (0.2), As given the system is casual, that implies **ROC** is |z| > 1.

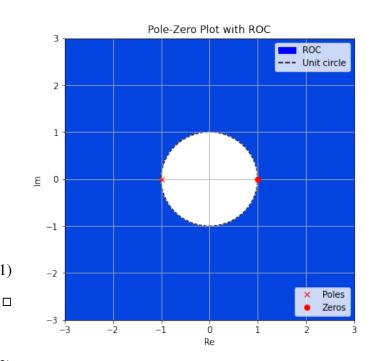


Fig. 1: Pole-Zero plot for H(z)

.. Z transform of the system impulse response is