



DEPARTMENT OF COMPUTER SCIENCE & ENGINEERING

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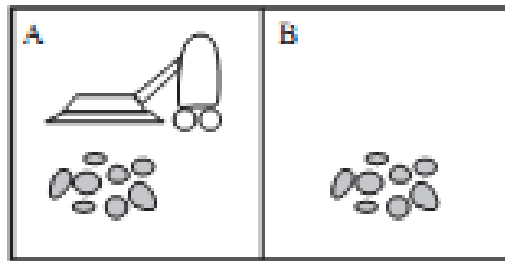
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CSL5402 *Artificial Intelligence Lab*

Lab 4 Assignment

List of Experiments:

1. (a) WAP to implement a performance-measuring environment simulator for the following vacuum-cleaner world diagram. Your implementation should be modular so that the sensors, actuators, and environment characteristics (size, shape, dirt placement etc.) can be changed easily.



- (b) In the addition of the above program (i.e., in 1(a)), WAP to implement a simple reflex agent for the vacuum environment. Run the environment with this agent for all possible initial dirt configurations and agent locations.
2. WAP to implement a model-based reflex agent for the automatic taxi driver environment. Run the environment with this agent for all possible assumptions made by you which makes it model-based.
3. WAP to implement a goal-based reflex agent for the automatic taxi driver in a road map environment. Run the environment with this agent for all possible assumptions made by you which makes it goal-based agent.