

We have implemented a basic form of block-based hybrid video coder using a fixed block size of 8X8.

- I. Successfully implemented the intra-frame prediction using modes 0, 1, and 2.
- II. EBMA module was developed based on intensity values with a range of  $\pm 8$ .
- III. Best prediction block was chosen for the method which has the least variance for the error block.
- IV. DCT was done using cv2.dct, and then quantisation was performed between values of 0-16 with 3 different step sizes of 1, 2, and 4.
- V. The number of non-zero coefficients for  $q=1$ , 2, and 4 were 465544, 462573, and 451678 respectively
- VI. The final reconstruction gave us following results.
  - A. For  $q=1$



B. For  $q = 2$



C. For  $q = 4$

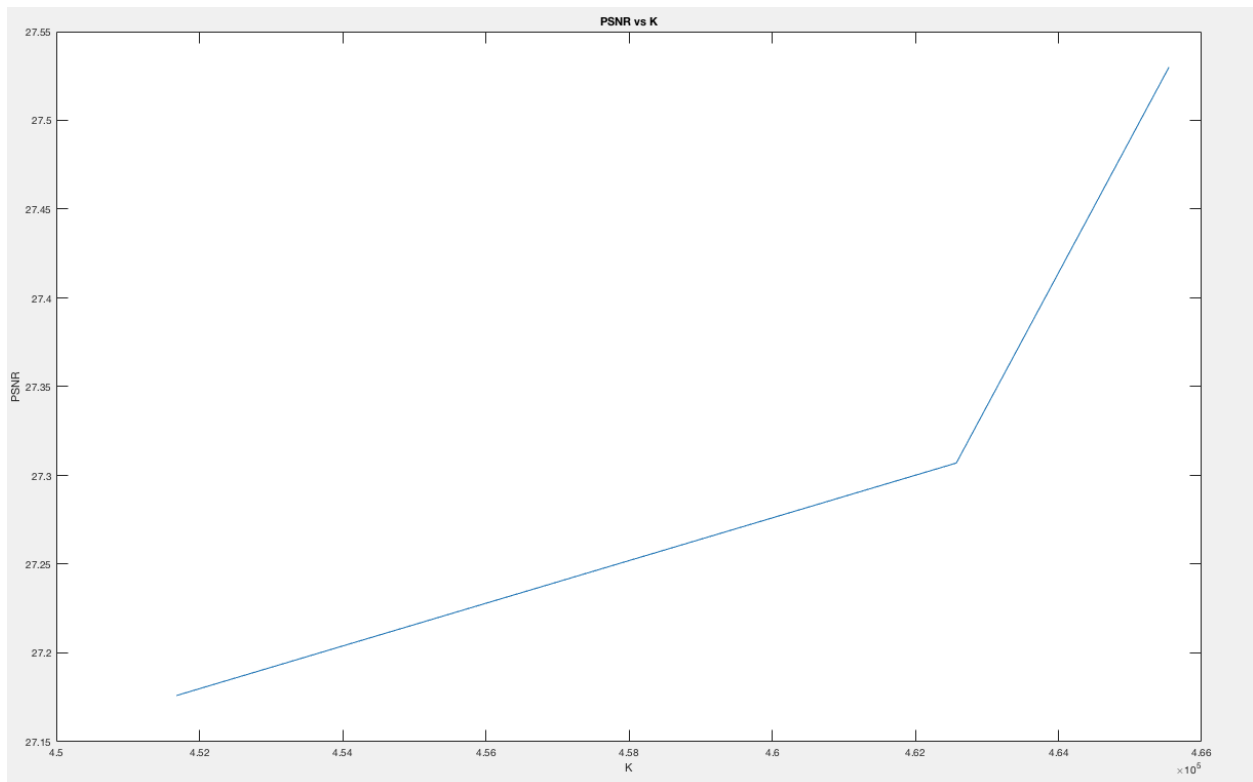


Thus we see some kind of loss since the frames were too far away. If we see the 2 frames



we can see that since the frames are very far away, the section where most of the motion takes place get distorted the most.

The PSNR vs K plot is



Thus we see that as K increases, the PSNR also increases which should be the case in quantisation. K here represents the number of non-zero elements in the quantised DCT of the error blocks.