Control Systems

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Abstract—This manual is an introduction to control systems based on GATE problems.Links to sample Python codes are available in the text.

Download python codes using

svn co https://github.com/gadepall/school/trunk/ control/codes

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6 Nyouist Plot

6.1. The number of directions and encirclements around the point -1+j0 in the complex plane by the Nyquist plot of

$$G(s) = \frac{1-s}{4+2s}$$

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Solution: First, we need to draw the polar plot

of given G(S). In the polar plot, substitute $s = i\omega$

$$G(j\omega) = \frac{1 - j\omega}{4 + 2j\omega} \tag{6.1.1}$$

$$\lim_{\omega \to \infty} G(j\omega) = \frac{1 - j\omega}{4 + 2j\omega}$$
 (6.1.2)

$$\lim_{\omega \to \infty} G(j\omega) = \frac{j\omega(\frac{1}{j\omega} - 1)}{j\omega(\frac{4}{j\omega} + 2)}$$
(6.1.3)

$$\lim_{\omega \to \infty} G(j\omega) = \frac{-1}{2} \angle 0 \tag{6.1.4}$$

which is equal to $\frac{1}{2}\angle -180$

As the Magnitude is taken positive in Nyquist Plot. Now substitute $\omega = 0$

$$\lim_{\omega \to 0} G(j\omega) = \frac{1 - j\omega}{4 + 2j\omega} = \frac{1}{4} \angle 0$$
 (6.1.5)

$$\angle(G(j\omega)) = \tan^{-1}(\frac{-\omega}{1}) - \tan^{-1}(\frac{\omega}{2}) \quad (6.1.6)$$

so from this at $\omega = 0$ $\angle G(j\omega) = 0$ and at $\omega = \infty$ $\angle G(j\omega) = -180$

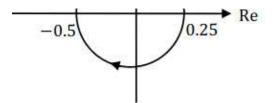
$$|(G(j\omega))| = \frac{\sqrt{1+\omega^2}}{\sqrt{16+4\omega^2}}$$
 (6.1.7)

when $\omega = 0 \mid (G(j\omega)) \mid = \frac{1}{4}$ and at when $\omega = \infty \mid (G(j\omega)) \mid = \frac{1}{2}$

Hence,magnitude should be every time positive.

So,we have to plot first 0.25 then we have to turn -180 degrees to that point i.e 180 degrees clockwise(in this case).

Now Plot the Polar Plot 1 from $\omega = 0$ to ∞



7 Compensators

7.1 Phase Lead

7.2 Example

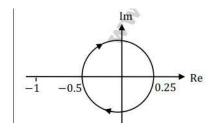
8 Gain Margin

8.1 Introduction

8.2 Example

Draw the Mirror image of the Polar Plot 1.

9 Phase Margin10 Oscillator



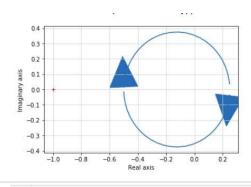
$$Put \ s = Re^{j\theta}$$

$$\lim_{R \to \infty} G(Re^{j\theta}) = \frac{1 - Re^{j\theta}}{4 + 2Re^{j\theta}} = \frac{-1}{2}$$

As there are no $e^{j\theta}$ terms,

There there will be no enclosed Nyquist path here.

So, for this Transfer function G(s), the Nyquist plot is same as the Polar plot.



As from the observed plot the co-ordinate -1 + j0 is outside the contour.

Hence, the number of encirclements around the the given co-ordinate is zero.