#### 1

# EE3025 ASSIGNMENT- 1

## PEDAVEGI ADITYA - EE18BTECH11034

Download all python codes from

https://github.com/adi2000pedavegi/ee3025-idp/ tree/master/Assignment-1/codes

and latex-tikz codes from

https://github.com/adi2000pedavegi/ee3025-idp/ tree/master/Assignment-1

#### 1 Problem

The command

in Problem 2.3 is executed through following difference equation

$$\sum_{m=0}^{M} a(m) y(n-m) = \sum_{k=0}^{N} b(k) x(n-k)$$
 (1.0.1)

where input signal is x(n) and output signal is y(n) with intial values all 0. Replace **signal.filtfilt** with your own routine and verify

## 2 Solution

Using the properties of z-transform

$$Z\{x(n-k)\} = z^{-k}X(z)$$
 (2.0.1)

$$Z{y(n-m)} = z^{-m}Y(z)$$
 (2.0.2)

where X(z) and Y(z) are the respective z-transforms of x(n) and y(n) respectively.

Converting the difference equation into its z-transform equation

$$Y(z)\sum_{m=0}^{M} a(m)z^{-m} = X(z)\sum_{k=0}^{N} b(k)z^{-k}$$
 (2.0.3)

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k=0}^{N} b(k) z^{-k}}{\sum_{k=0}^{M} a(m) z^{-m}}$$
(2.0.4)

From the coefficients b,a and from (2.0.4) evaluating H(f)

Using built in fft command evaluating X(f) from x(n)

From

$$Y(f) = H(f)X(f)$$
 (2.0.5)

Using built in ifft command evaluating y(n) from Y(f)

Below is the following python code for the above question

codes/ee18btech11034.py

Below is the soundfile constructed from output signal y using own routine filter

codes/7.1\_Sound\_With\_ReducedNoise.wav

### 3 Verification

Plotting the time domain output signal evaluated from both own routine filter and signal.filtfilt command

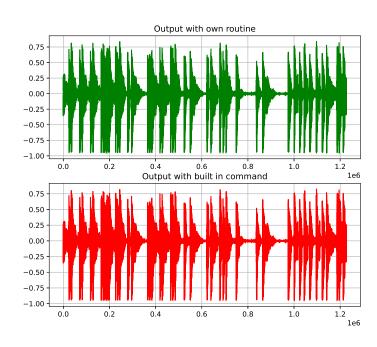


Fig. 0: Time domain response