Zero Shot Task Oriented Dialog

Anonymous ACL submission

Abstract

This document is a supplement to the general instructions for *ACL authors. It contains instructions for using the LaTeX style file for ACL 2023. The document itself conforms to its own specifications, and is, therefore, an example of what your manuscript should look like. These instructions should be used both for papers submitted for review and for final versions of accepted papers.

1 Introduction

2 Methodology

012

017

019

034

Steps: Pretraining(CE Loss), Training (loss on target only)

Context: Dialog History like SimpleTOD DST instead of dialog history

Additional info Schema List of system actions User actions Service Results

Contrastive Loss User action, System action System Action, NLG

3 Experimental Setup

3.1 Datasets

We use the SGD (Rastogi et al., 2020) and SGD-X (Lee et al., 2022) datasets to conduct experiments. Seen domains are obtained from the train schema file and unseen domains from the eval and test schema files. The models are trained on seen domains and inference is performed on all, seen and unseen domains.

To evaluate the performance of the models, we use metrics from SGD, MultiWoz 2.0 benchmark (Ramadan et al., 2018) and introduce 2 novel metrics: Average Action Accuracy, Joint Action Accuracy. These new metrics are similar to the goal metrics in SGD, but are performed on the actions. For response generation, we report the ROUGE-2 (Lin and Och, 2004) score and GLEU (Wu et al., 2016) instead of BLEU as it performs better on

individual sentence pairs. The combined score is calculated as suggested in (Mehri et al., 2019) with (Inform + Success) \times 0.5 + GLEU.

039

042

043

044

047

054

060

061

062

063

064

065

066

067

068

069

070

071

073

074

4 Related Works

4.1 Supervised End to End Models

Pretrained language models like BERT (Devlin et al., 2019), GPT-2 (Radford et al., 2019) and T5 (Raffel et al., 2019) have been used extensively in the literature for End to End models for TOD systems (Hosseini-Asl et al., 2020), (Peng et al., 2021), (Lee et al., 2020), (Yang et al., 2020), (Jeon and Lee, 2021), (Sun et al., 2022), (Yang et al., 2022), (Noroozi et al., 2020). In these models, the context consists of user and system utterance, whereas in our model we use the last user utterance and the previous state DST as context. Moreover, most of these models have the best performance in supervised settings and do not have the primary focus on zero-shot generalization.

4.2 Zero Shot End to End Models

Zero Shot DST models (Feng et al., 2020), (Zhao et al., 2022) incorporate schema as part of the context and generalize well for DST, however these models do not focus on system actions and response generation.

References

Jacob Devlin, Ming-Wei Chang, Kenton Lee, and Kristina Toutanova. 2019. Bert: Pre-training of deep bidirectional transformers for language understanding. ArXiv, abs/1810.04805.

Yue Feng, Yang Wang, and Hang Li. 2020. A sequenceto-sequence approach to dialogue state tracking. In Annual Meeting of the Association for Computational Linguistics.

Ehsan Hosseini-Asl, Bryan McCann, Chien-Sheng Wu, Semih Yavuz, and Richard Socher. 2020. A simple language model for task-oriented dialogue. *ArXiv*, abs/2005.00796.

076	Hyunmin Jeon and Gary Geunbae Lee. 2021. Dora:	Yonghui Wu, Mike Schuster, Zhifeng Chen, Quoc V.
077	Toward policy optimization for task-oriented dia-	Le, Mohammad Norouzi, Wolfgang Macherey,
078	logue system with efficient context. Comput. Speech	Maxim Krikun, Yuan Cao, Qin Gao, Klaus
079	Lang., 72:101310.	Macherey, Jeff Klingner, Apurva Shah, Melvin Johnson, Xiaobing Liu, Łukasz Kaiser, Stephan Gouws,
080	Harrison Lee, Raghav Gupta, Abhinav Rastogi, Yuan	Yoshikiyo Kato, Taku Kudo, Hideto Kazawa, Keith
081	Cao, Bin Zhang, and Yonghui Wu. 2022. Sgd-x:	Stevens, George Kurian, Nishant Patil, Wei Wang,
082	A benchmark for robust generalization in schema-	Cliff Young, Jason Smith, Jason Riesa, Alex Rud-
083	guided dialogue systems. In Proceedings of the	nick, Oriol Vinyals, Greg Corrado, Macduff Hughes,
084	AAAI Conference on Artificial Intelligence, vol-	and Jeffrey Dean. 2016. Google's neural machine
085	ume 36, pages 10938–10946.	translation system: Bridging the gap between human and machine translation.
086	Hwaran Lee, Seokhwan Jo, Hyungjun Kim, Sangkeun	
087	Jung, and Tae-Yoon Kim. 2020. Sumbt+larl: End-	Yunyi Yang, Hong Ding, Qing Liu, and Xiaojun Quan.
088	to-end neural task-oriented dialog system with rein-	2022. Ubarv2: Towards mitigating exposure bias in
089	forcement learning. <i>ArXiv</i> , abs/2009.10447.	task-oriented dialogs. ArXiv, abs/2209.07239.
	1010011011111g, 111111, 400, 2 00, 110 11, 1	Y
090	Chin-Yew Lin and FJ Och. 2004. Looking for a few	Yunyi Yang, Yunhao Li, and Xiaojun Quan. 2020.
091	good metrics: Rouge and its evaluation. In <i>Ntcir</i>	Ubar: Towards fully end-to-end task-oriented dialog
092	workshop.	systems with gpt-2. In AAAI Conference on Artifi-
002	workshop.	cial Intelligence.
093	Shikib Mehri, Tejas Srinivasan, and Maxine Eskenazi.	Jeffrey Zhao, Raghav Gupta, Yuanbin Cao, Dian Yu,
094	2019. Structured fusion networks for dialog. <i>arXiv</i>	Mingqiu Wang, Harrison Lee, Abhinav Rastogi,
095	preprint arXiv:1907.10016.	Izhak Shafran, and Yonghui Wu. 2022. Description-
033	ριεριτιί αιχίν.1907.10010.	driven task-oriented dialog modeling. ArXiv,
096	Vahid Noroozi, Yang Zhang, Evelina Bakhturina, and	abs/2201.08904.
097	Tomasz Kornuta. 2020. A fast and robust bert-based	a08/2201.06904.
098	dialogue state tracker for schema guided dialogue	A E
	dataset. ArXiv, abs/2008.12335.	A Example Appendix
099	dataset. ATAIV, a08/2006.12333.	This is a section in the sum and in
100	Paolin Dang Chunyyan Li Jinghao Li Chahin Chayan	This is a section in the appendix.
100	Baolin Peng, Chunyuan Li, Jinchao Li, Shahin Shayan-	
101	deh, Lars Lidén, and Jianfeng Gao. 2021. Soloist:	
102	Building task bots at scale with transfer learning and	
103	machine teaching. Transactions of the Association for Computational Linguistics, 9:807–824.	
104	Jor Computational Linguistics, 9.807–824.	
105	Alec Radford, Jeff Wu, Rewon Child, David Luan,	
	Dario Amodei, and Ilya Sutskever. 2019. Language	
106	models are unsupervised multitask learners.	
107	models are dissupervised mutitiask learners.	
108	Colin Raffel, Noam M. Shazeer, Adam Roberts,	
109	Katherine Lee, Sharan Narang, Michael Matena,	
110	Yanqi Zhou, Wei Li, and Peter J. Liu. 2019. Ex-	
	ploring the limits of transfer learning with a unified	
111 112	text-to-text transformer. ArXiv, abs/1910.10683.	
112	text-to-text transformer. ATAIV, abs/1910.10065.	
110	Osman Ramadan Dawat Rudzianowski and Milica Co	
113	Osman Ramadan, Paweł Budzianowski, and Milica Ga-	
114	sic. 2018. Large-scale multi-domain belief tracking with knowledge sharing. In Proceedings of the	
115	ing with knowledge sharing. In <i>Proceedings of the</i>	
116	56th Annual Meeting of the Association for Compu-	
117	tational Linguistics, volume 2, pages 432–437.	
110	Abbinay Pastagi Visayua Zang Criniyas Cuntana	
118	Abhinav Rastogi, Xiaoxue Zang, Srinivas Sunkara,	
119	Raghay Gupta, and Pranay Khaitan. 2020. Towards	
120	scalable multi-domain conversational agents: The	
121	schema-guided dialogue dataset. In <i>Proceedings of</i>	
122	the AAAI Conference on Artificial Intelligence, vol-	
123	ume 34, pages 8689–8696.	
106	Hainana Cun Iurani: Dan Var Land W. and W.	
124	Haipeng Sun, Junwei Bao, Youzheng Wu, and Xi-	
125	aodong He. 2022. Bort: Back and denoising re-	
126	construction for end-to-end task-oriented dialog. In	

NAACL-HLT.