



Extending Lightweight Driver FER: A Video-Based Approach

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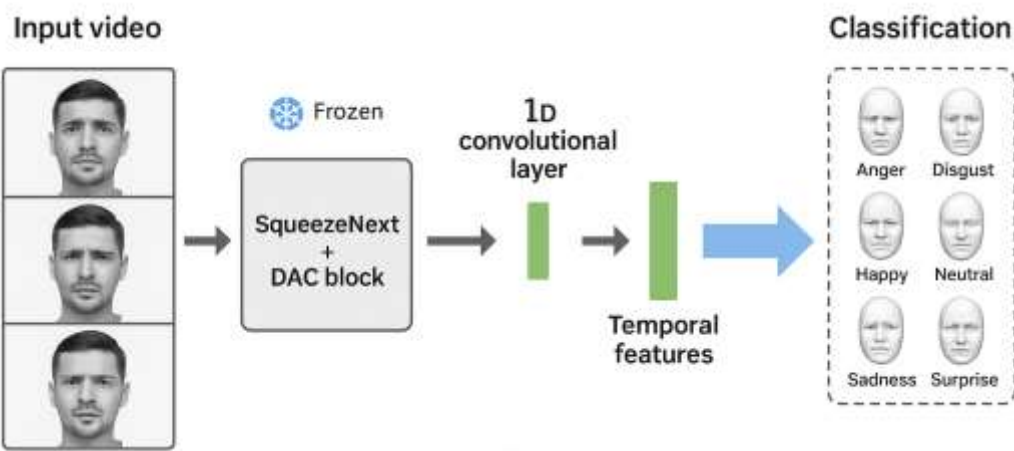
1. INTRODUCTION

Uddin (2025) [1] presents the DALDL model, optimized for efficient facial emotion recognition (FER) in real-time ADAS. This research extends DALDL by integrating temporal aggregation for video-based FER, enhancing dynamic emotion detection.

- Leverages SqueezeNext with DAC block.
- Compact: 0.75M params, 3.9ms inference.
- Handles 3-5 frame video sequences.

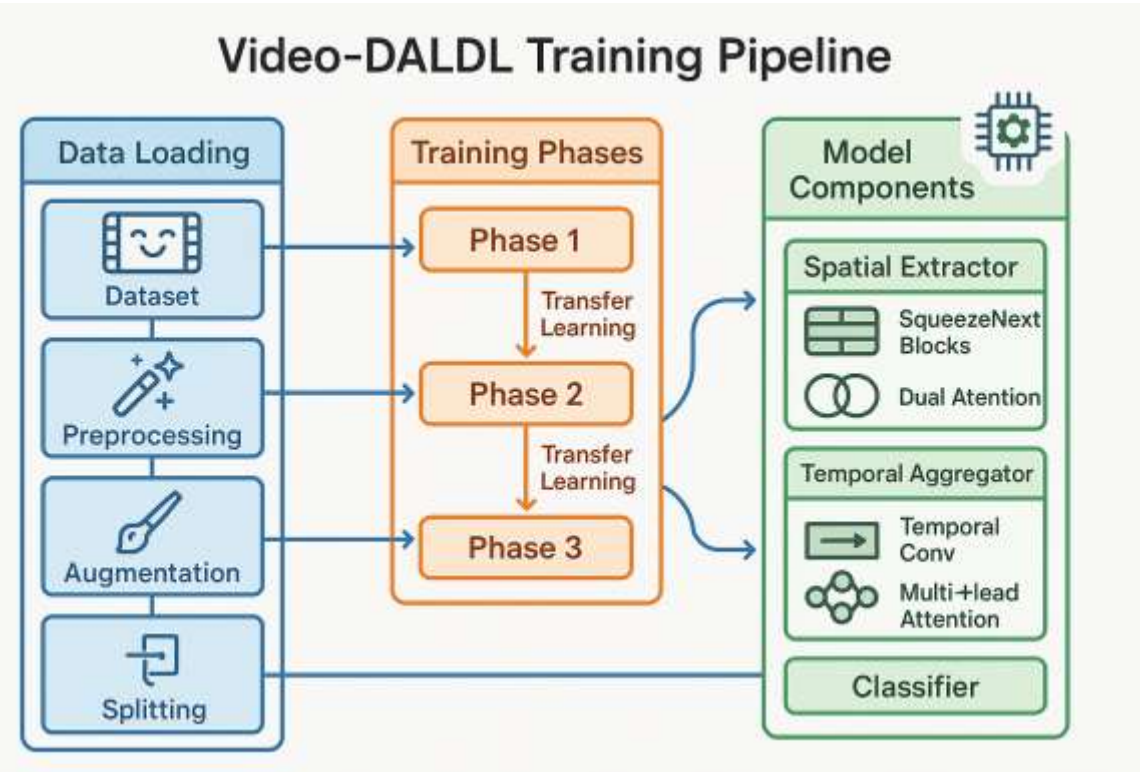
2. RESEARCH QUESTION

DALDL processes static images, missing temporal dynamics of driver emotions. Can video-based FER with temporal aggregation enhance ADAS reliability by capturing expression transitions in real-world driving scenarios?



3. METHODOLOGY

- **Objective:** Process 3-5 frame videos with DALDL.
- **Approach:** DALDL for spatial features, 1D Conv for temporal aggregation, classify 7 emotions
- **Why DALDL?** Lightweight, accurate, ADAS-fit.
- **Dataset:** KMU-FED (drivers' FEs, NIR camera).
- **Data Prep:** Group 3-5 frames into sequences; preprocess with resizing, equalization, grayscale conversion, and normalization.
- **Training:** 80-20 split, 100 epochs, Adam.



4. Results

Progressive Training Results

Phase 1 (Binary): Achieved 54.29% accuracy.
Phase 2 (Four emotions): Achieved 84.51% accuracy.
Phase 3 (All emotions): Achieved 98.99% accuracy (10.09% above 88.9% baseline).

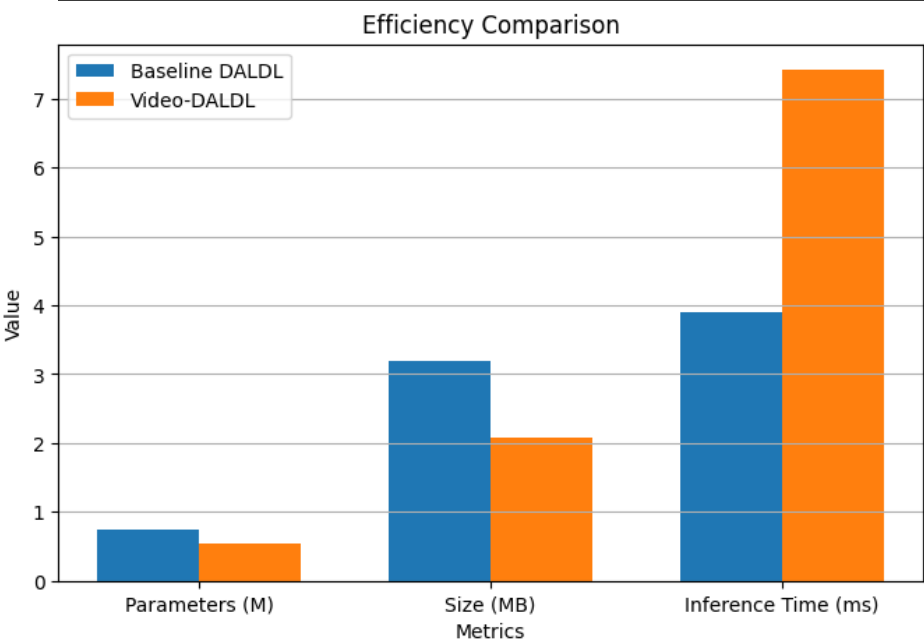
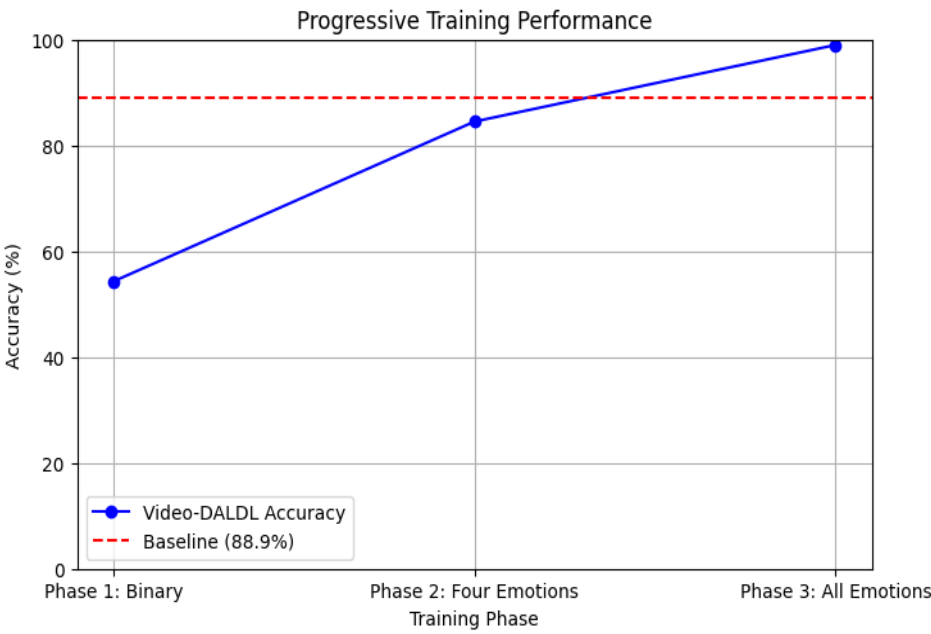
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GPU Memory: 0.02 GB
Early stopping at epoch 42
Phase completed. Best validation accuracy: 98.99%

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FINAL RESULTS - Memory-Optimized Video-DALDL Extension
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Phase 1: 54.29% ✓
Phase 2: 84.51% ✓
Phase 3: 98.99% ✓

Final Model Statistics:
Total Parameters: 543,749
Model Size: 2.07 MB
Final GPU Memory Usage: 0.02 GB

Inference Speed Test:
Average Inference Time: 7.42 ± 1.09 ms

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TARGET ASSESSMENT vs Uddin (2025) Baseline
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Final Accuracy: 98.99% (Target: >88.9%)
Model Size: 2.07 MB (Target: <3.3 MB)
Inference Time: 7.42 ms (Target: <5 ms)
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5. Conclusion and Future Work

- **Conclusion:** This demonstrates the effectiveness of combining video-based temporal processing with lightweight deep learning architectures for robust performance in dynamic driving environments.
- **Future Work:** Optimize the model's inference time through techniques like quantization and pruning to meet real-time ADAS requirements under 5ms.