

PCA sketch of the proof

CSCI 347

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Let the data D consist of n points over d attributes, i.e., it is an $n \times d$ matrix, given as

$$D = \begin{matrix} & X_1 & X_2 & \cdots & X_d \\ \begin{matrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{matrix} & \begin{matrix} x_{11} \\ x_{21} \\ \cdots \\ x_{n1} \end{matrix} & \begin{matrix} x_{12} \\ x_{22} \\ \cdots \\ x_{n2} \end{matrix} & \begin{matrix} \cdots \\ \cdots \\ \ddots \\ \cdots \end{matrix} & \begin{matrix} x_{1d} \\ x_{2d} \\ \cdots \\ x_{nd} \end{matrix} \end{matrix}$$

$x_i = (x_{i1}, x_{i2}, \dots, x_{id})^T$ spanned by d standard basis vectors

$$e_1, e_2, e_3, \dots, e_d$$

Standard basis vectors are **orthonormal**.

$$e_i^T e_j = 0 \text{ and } \|e_i\| = 1$$

If we are given any other set of d **orthonormal** vectors

u_1, u_2, \dots, u_d with $u_i^T u_j = 0$ and $\|u_i\| = 1$

We can re-express each point x as the linear combination

$$x = a_1 u_1 + a_2 u_2 + \dots + a_d u_d$$

$a = (a_1, a_2, \dots, a_d)^T$ represents the coordinates of the x in the new basis.

The above combination can be represented as a matrix multiplication as well.

$$x = Ua$$

Where U is the $d \times d$ matrix, whose i -th column comprises the i -th basis vector u_i

$$U = \begin{pmatrix} | & | & \cdots & | \\ u_1 & u_2 & \cdots & u_d \\ | & | & \cdots & | \end{pmatrix}$$

Where U is an orthogonal matrix, where columns are orthonormal

$$U = \begin{pmatrix} | & | & \cdots & | \\ u_1 & u_2 & \cdots & u_d \\ | & | & \cdots & | \end{pmatrix}$$

$$u_i^T u_j = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

Since U is an orthogonal matrix,

$$U^{-1} = U^T$$

$$U^{-1} = U^T \rightarrow U^T U = I$$

$$x = Ua$$

$$U^T x = U^T Ua$$

$$U^T x = a$$

$$a = U^T x$$

Let's look at an example.

$$x = (-0.343, -0.754, 0.241)^T$$

$$e_1 = (1, 0, 0)^T, e_2 = (0, 1, 0)^T, e_3 = (0, 0, 1)^T$$

$$u_i^T u_j = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

New basis vectors

$$u_1 = (-0.390, 0.089, -0.916)^T, u_2 = (-0.639, -0.742, 0.200)^T, u_3 = (-0.663, 0.664, 0.346)^T$$

$$\|u_1\| = \sqrt{0.39^2 + 0.089^2 + 0.916^2} \approx 1$$

$$u_1^T u_3 = -0.39 * -0.663 + 0.089 * 0.664 - 0.916 * 0.346 \approx 0$$

$$a = U^T x = \begin{pmatrix} -0.39 & 0.089 & -0.916 \\ -0.639 & -0.742 & 0.2 \\ -0.663 & 0.664 & 0.346 \end{pmatrix} \begin{pmatrix} -0.343 \\ -0.754 \\ 0.241 \end{pmatrix} = \begin{pmatrix} -0.154 \\ 0.828 \\ -0.190 \end{pmatrix}$$

$$x = -0.15u_1 + 0.828u_2 - 0.19u_3$$

There are potentially infinite choices for the set of orthonormal basis vectors.

Example: Think about 3-dimension space. Take the 3-basis vector and rotate it in the space.

Let's look at projection of x into r basis vectors.

$$x = a_1u_1 + a_2u_2 + \cdots + a_du_d$$

We pick first r basis vectors from this.

$$x' = a_1u_1 + a_2u_2 + \cdots + a_ru_r, r \ll d$$

Note that x and x' are not the same.

Here x' is the projection of x onto the first r basis vectors.

We can write this in matrix notation as well.

$$x' = \begin{pmatrix} | & | & \cdots & | \\ u_1 & u_2 & \cdots & u_r \\ | & | & \cdots & | \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_r \end{pmatrix} = U_r a_r$$

U_r is the matrix comprising of the first r basis vectors, and a_r is the vector comprising the first r coordinates.

Remember:

$$a = U^T x$$

Restricting it to first r basis vectors,

$$a_r = U_r^T x$$

$$x' = \begin{pmatrix} | & | & \cdots & | \\ u_1 & u_2 & & u_r \\ | & | & & | \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_r \end{pmatrix} = U_r a_r$$

$$a_r = U_r^T x$$

$$x' = U_r a_r = U_r U_r^T x$$

$P_r = U_r U_r^T$ is the orthogonal projection matrix for the subspace spanned by the first r basis vectors.

$$x' = U_r a_r = U_r U_r^T x = P_r x$$

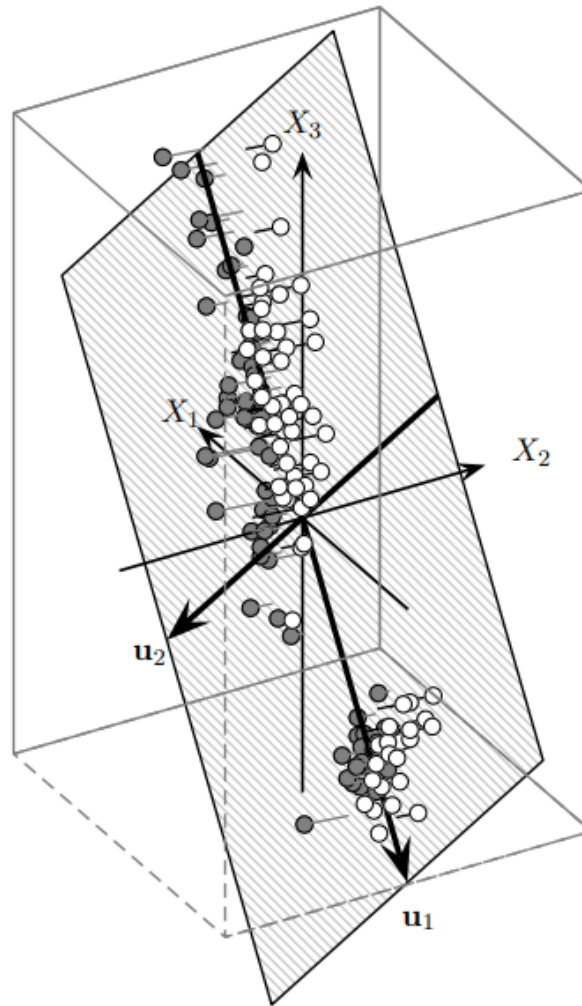
P_r is **symmetric** and **idempotent**, i.e.,

$$P_r = P_r^T \text{ and } P_r^2 = P_r$$

$$P_r = U_r U_r^T = \sum_{i=1}^r u_i u_i^T$$

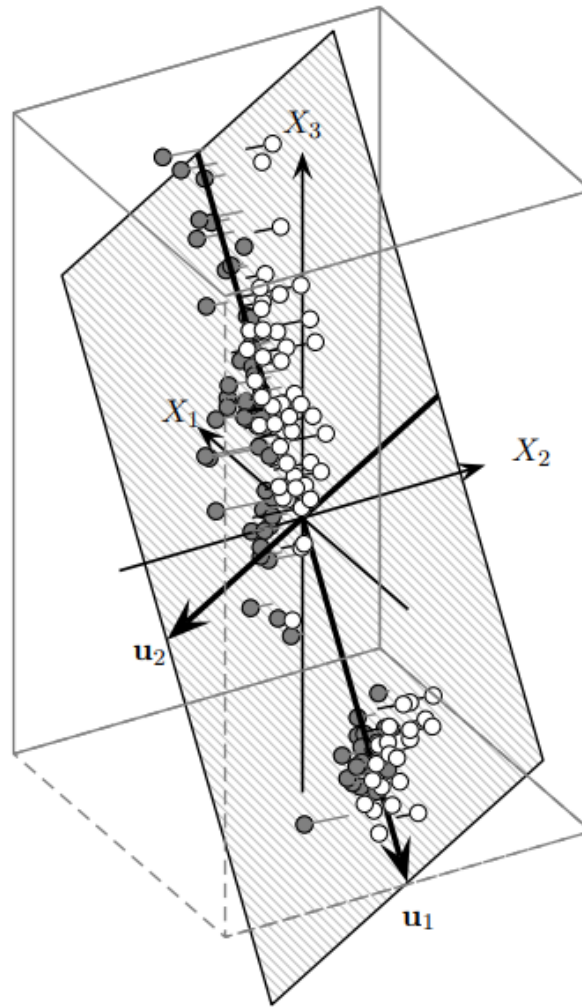
$$\epsilon = \sum_{i=r+1}^d a_i u_i = x - x'$$

We can get an expression for the error of the projection.



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Note that x' and ϵ are orthogonal vectors.

Let's look at an example.

$$\mathbf{x} = (-0.343, -0.754, 0.241)^T$$

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New basis vectors

$$\mathbf{u}_1 = (-0.390, 0.089, -0.916)^T, \mathbf{u}_2 = (-0.639, -0.742, 0.200)^T, \mathbf{u}_3 = (-0.663, 0.664, 0.346)^T$$

Let's pick only one new basis \mathbf{u}_1 vector and project the data.

$$\begin{aligned} P_1 &= \mathbf{u}_1 \mathbf{u}_1^T = \begin{pmatrix} -0.39 \\ 0.089 \\ -0.916 \end{pmatrix} \begin{pmatrix} -0.39 & 0.089 & -0.916 \end{pmatrix} \\ &= \begin{pmatrix} 0.152 & -0.035 & 0.357 \\ -0.035 & 0.008 & -0.082 \\ 0.357 & -0.082 & 0.839 \end{pmatrix} \end{aligned}$$

$$\mathbf{x}' = P_1 \mathbf{x} = \begin{pmatrix} \mathbf{0.060} \\ \mathbf{-0.014} \\ \mathbf{0.141} \end{pmatrix}$$

$$\boldsymbol{\epsilon} = \mathbf{x} - \mathbf{x}' = a_2 \mathbf{u}_2 + a_3 \mathbf{u}_3 = \begin{pmatrix} \mathbf{-0.40} \\ \mathbf{-0.74} \\ \mathbf{0.10} \end{pmatrix}$$

Let's look at an example.

$$\mathbf{x}' = \mathbf{P}_1 \mathbf{x} = \begin{pmatrix} 0.060 \\ -0.014 \\ 0.141 \end{pmatrix}$$

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We can check that \mathbf{x}' and $\boldsymbol{\epsilon}$ are orthogonal.

$$\mathbf{x}'^T \boldsymbol{\epsilon} = (0.06 \quad -0.014 \quad 0.141) \begin{pmatrix} -0.40 \\ -0.74 \\ 0.10 \end{pmatrix} = 0$$

Proof of PCA

- Assume that the data is centered.
- Let's think about projecting data onto one line.
- Projection of x_i on the vector u is:

$$x'_i = \left(\frac{u^T x_i}{u^T u} \right) u = (u^T x_i) u = a_i u$$

- Let's get an expression for the variance of the projected data points.
- $\sigma_u^2 = \frac{1}{n} \sum_{i=1}^n (a_i - \mu_u)^2$
- $\sigma_u^2 = \frac{1}{n} \sum_{i=1}^n (a_i)^2$ since $\mu_u = 0$

$$\sigma_u^2 = \frac{1}{n} \sum_{i=1}^n (a_i - \mu_u)^2$$

$$\sigma_u^2 = \frac{1}{n} \sum_{i=1}^n (u^T x_i)^2$$

$$\sigma_u^2 = \frac{1}{n} \sum_{i=1}^n (u^T x_i)^2 = \frac{1}{n} \sum_{i=1}^n (u^T x_i)(u^T x_i) = \frac{1}{n} \sum_{i=1}^n (u^T x_i)(x_i^T u)$$

$$\sigma_u^2 = u^T \left(\frac{1}{n} \sum_{i=1}^n x_i x_i^T \right) u$$

(using associative and distributive properties)

$$\sigma_u^2 = u^T \Sigma u$$

We want to maximize σ_u^2 and find u that achieves that objective.

$$\sigma_u^2 = u^T \Sigma u$$

We want to maximize σ_u^2 and find u that achieves that objective while keeping the constraints $u^T u = 1$.

We can use Lagrangian multiplier.

$$\max_a J(u) = u^T \Sigma u - \alpha(u^T u - 1)$$

We take the derivative of $J(u)$ with respect to u and set it to zero.

$$\begin{aligned} \frac{\partial J(u)}{\partial u} &= 0 \\ 2\Sigma u - 2\alpha u &= 0 \\ \Sigma u &= \alpha u \end{aligned}$$

This implies that α is an eigenvalue of the covariance matrix Σ .

$$\sigma_u^2 = u^T \Sigma u = u^T \alpha u = \alpha u^T u = \alpha$$

This means to maximize the variance choose the largest eigenvalue.