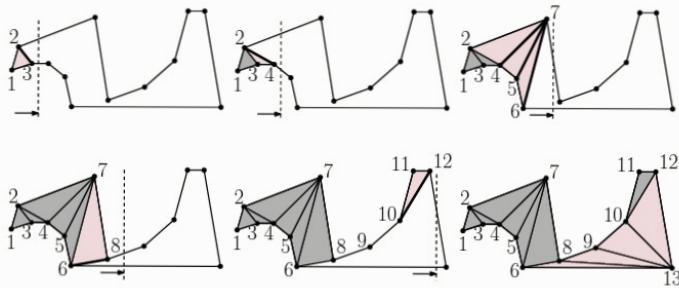


Polygon Division pt 2

State x -monotone polygon

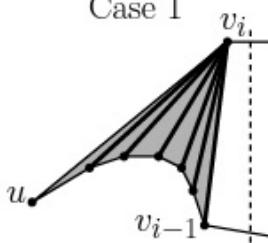


Key idea:

- 1 untriangulated region to left of the sweepline has "nice" structure allowing for fast division
- 2 polygon has $n-3$ diagonal(s) $\Rightarrow O(n)$ time

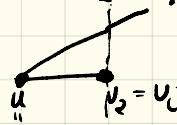
Lemma: (Main Invariant) For $i \geq 2$, let v_i be the vertex just processed by the triangulation algorithm. The untriangulated region lying to the left of v_i consists of two x -monotone chains, a lower chain and an upper chain each containing at least one edge. If the chain from v_i to u has two or more edges, then these edges form a reflex chain (that is, a sequence of vertices with interior angles all at least 180 degrees). The other chain consists of a single edge whose left endpoint is u and whose right endpoint lies to the right of v_i (see Fig. 32(a)).

Case 1

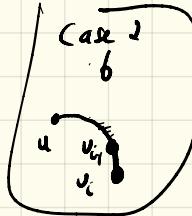
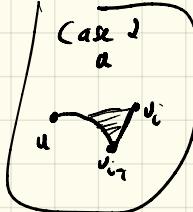
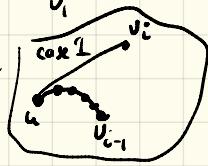


Pf (Main invariant) by induction

base case consider v_2 w/ $u = v_1$



Induction step:



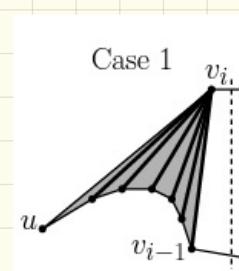
Case 1: v_i is on the opposite chain
of v_{i-1}

- add diagonals from
 v_i to v_{i-1}, \dots , vertex
before u

u_{left} is visible to v_i by assumption
→ chain is x -monotone

reflex and to the left of v_i
⇒ any vertex "after" v_i cannot sneak back to block visibility

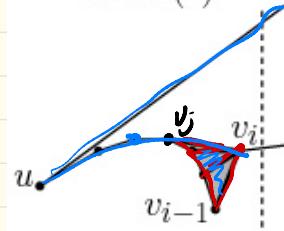
- set u to be v_{i-1} (restore invariant)
reflex chain is now v_{i-1}, v_i



(2a) v_i is on the same chain as v_{i-1} ,
and is non-reflex

- walk backwards on the reflex chain
to the vertex visible to v_i
- add diag from v_i to v_{i-1}, \dots, v_j
- remove v_{i-1}, \dots, v_j from
the reflex chain
- add v_i to the reflex chain
(restored invariant)

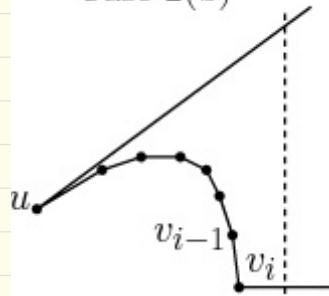
Case 2(a)



(2b) v_i is on same chain as v_{i-1}
and is reflex

- add v_i to reflex chain
(restore invariant)

Case 2(b)



How to implement

- store the reflex chain on a stack
- store if the chain is lower or upper chain
- check visibility by orientation tests

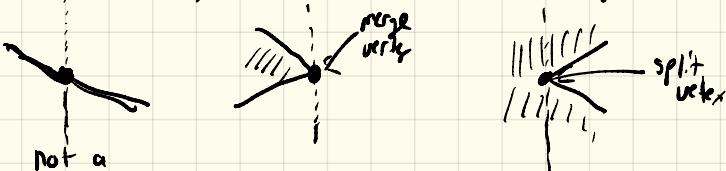
Analysis: Chain $O(n)$ time

- monotone polygon \Rightarrow sorted list of verts in $O(n)$ -time
- check for diag is $O(1)$ orientation tests $\Rightarrow O(1)$ time
- adding diag takes $O(1)$ time
- and $O(n)$ diags $\Rightarrow O(n)$ -time to Δ monotone polygon of n -verts

Monotone Subdivision

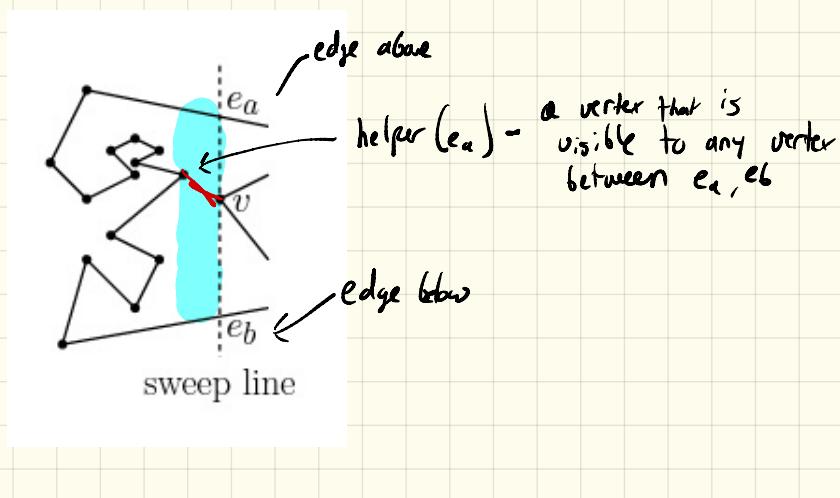
- turn a polygon into multiple monotone polygons

Observations

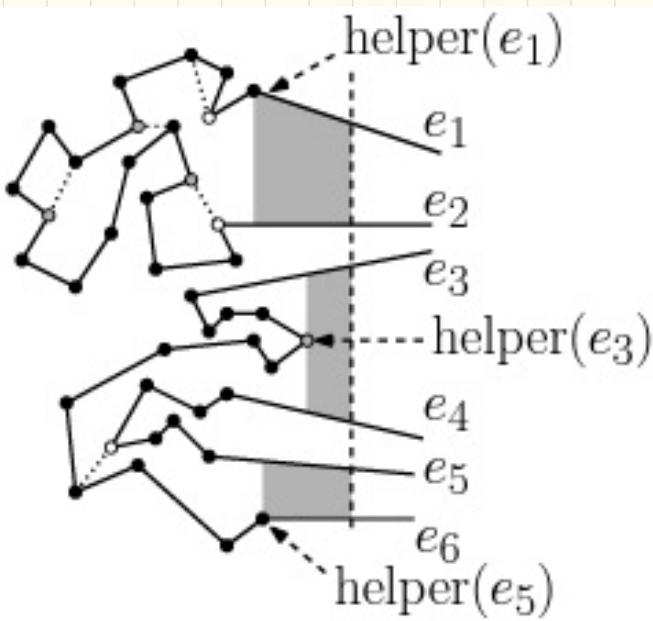
- x -monotonicity is violated when both edges are to left or right^{of jet}
- 

Idea:

- plane sweep, add diagonals at split and merge vrtx
- store some info to add diag quickly



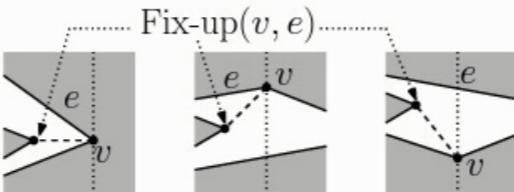
helper(e_a): Let e_b be the edge of the polygon lying just below e_a on the sweep line. The helper is the rightmost vertically visible vertex on or below e_a on the polygonal chain between e_a and e_b . This vertex may either be on e_a, e_b , or it may lie between them.



Events: events of the polygon
 (no new events are created during algo)

Sweeping status:

- list of edges intersecting sweep line
 sorted top to bottom
- $\text{Fixup}(v, e)$: if $\text{helper}(e)$ is a merge vertex
 add a diag from v to the merge vertex



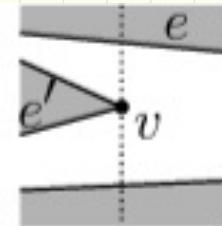
Processing events:

Event types for vertex v

- v is a split vertex
- v is a merge vertex
- v is a start vertex
- v is an end vertex
- v is part of an upper chain
- v is part of a lower chain

merge vertex:

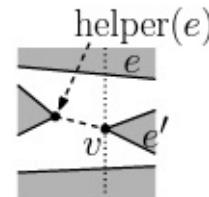
- find edges in the sweepline incident to v
- delete both edges
- e the edge above v
- fixup(v, e)
- fixup(v, e')



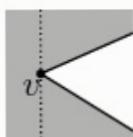
Merge

split vertex:

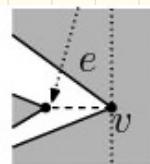
- search sweepline status for edge e above v
- add diag from v to helper(e)
- add 2 edges incident to v to the sweepline status
- label e' the lower of the 2 edges
- set v as the helper for e and e'



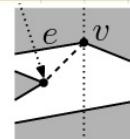
Split



Start



End



Upper

Analysis:

each event performs a const # of searches on the sweepline
⇒ each event takes $O(\log n)$ time
of events is n

⇒ $O(n \log n)$ for decompose

Action analysis

$O(n \log n)$ to decompose
 k monotone polygons
of size n_1, n_2, \dots, n_k

each monotone polygon of size n_i takes $O(n_i)$ to slate

$$\sum_{i=1}^k n_i = n \Rightarrow O(n) \text{ to slate all monotone polygons}$$

⇒ $O(n \log n)$ for Action