

## 1 Matroids

Assume  $(E, \mathcal{I})$  is not a matroid. Then either the subset property does not hold, or the subset property does hold, but the augmentation property does not hold. We will argue these two cases separately.

**Subset property does not hold:** We know that there exists  $J \in \mathcal{I}$  and  $I \subset J$  such that  $I \notin \mathcal{I}$ . Give all elements of  $I$  weight 2, all elements of  $J \setminus I$  weight 1, and all other elements weight 0. The greedy algorithm will consider the elements of  $I$ , then the remaining elements of  $J$ , and then the remaining elements of  $E$ . Because the greedy algorithm maintains feasibility, it will not take all the elements of  $I$ . But then the greedy algorithm cannot take all the elements of  $J$  either. This means that greedy isn't optimal, as every optimal solution must contain every element of  $J$ .

**Subset property does hold, but augmentation property does not:** Then there exist  $I, J \in \mathcal{I}$  such that  $|I| < |J|$  but there is no  $j \in J \setminus I$  such that  $I \cup \{j\} \in \mathcal{I}$ . Assign all elements of  $I$  weight  $1 + \epsilon$ , and all elements of  $J$  weight 1. Assign all other elements of  $E$  weight 0. The greedy algorithm will consider all elements of  $I$  first, and will add them all, by downward closure. However, it will not add any elements of  $J \setminus I$ , as the augmentation property is violated for  $I$  and  $J$ . It follows that greedy will return a set with total weight  $|I|(1 + \epsilon)$ . For sufficiently small values of  $\epsilon$ , the optimal solution will be  $J$ , with total weight  $|J| > |I|(1 + \epsilon)$ . It follows that greedy is not optimal in this case.

## 2 Travel Time

modDijkstra( $G, f, s$ )

$S = \{\}$ .

for all  $v$ , insert( $v, \infty$ ).

decreasekey( $s, 0$ )

While  $Q$  not empty

    ( $v, d$ ) = deletemin()

    add  $v$  to  $S$

    dist( $v$ ) =  $d$

    for each  $u$  adjacent to  $v$

        decreasekey( $u, f_{(v,u)}(d)$ )

We'll show two things by induction. These claims together imply correctness.

1. On the  $j$ th iteration of the while loop, dist( $v$ ) is the travel time from  $s$  to  $v$  for all  $v \in S$ .

2. In addition, for all pairs in  $Q$  at that time, the key is the one-hop distance from  $s$ , where one-hop distance is the shortest travel time along one-hop paths.

Proof:

**Base Case** Before the first iteration, the claim is clearly true.

**Inductive Hypothesis** Assume the claim holds for all  $j \leq k$

**Inductive Case** Let  $(v, d)$  be the  $k+1$ st pair removed from  $Q$ .

- Assume there's path  $P$  from  $s$  to  $v$  with travel time less than  $d$ .
- It can't be a one-hop path, by IH.
- Let  $u$  be first vertex where  $P$  leaves  $S$ .
- Let  $P'$  be  $P$  truncated at  $u$ 
  - \*  $P'$  is the shortest path from  $s$  to  $u$ .
  - \* It is one-hop.
  - \* Hence  $u$  would be returned by `deletemin()`
- Contradiction
- To see part 2 of our claim, note that by the induction hypothesis,  $d$  is the one-hop distance of  $v$ , so if any vertex  $u$  has its key changed to  $f_{(v,u)}(d)$  it is precisely because there is a one-hop path through  $v$  with that length.

Runtime:  $O(m \log n)$ . Initializing and filling the priority queue costs  $O(n \log n)$ . The remaining work comes from calls to `decreasekey()`. There are  $O(m)$  such calls, resulting in a runtime of  $O(m \log n)$ . (This requires the assumption of strong connectivity, in which case  $n = O(m)$ ).