Arity-Generic Datatype-Generic Programming

Stephanie Weirich Chris Casinghino
University of Pennsylvania
{sweirich,ccasin}@cis.upenn.edu

Abstract

Some programs are doubly-generic. For example, map is datatype-generic in that many different data structures support a mapping operation. A generic programming language like Generic Haskell can use a single definition to generate map for each type. However, map is also arity-generic because it belongs to a family of related operations that differ in the number of arguments. For lists, this family includes repeat, map, zipWith, zipWith3, zipWith4, etc. With dependent types or clever programming, one can unify all of these functions together in a single definition.

However, no one has explored the combination of these two forms of genericity. These two axes are not orthogonal because the idea of arity appears in Generic Haskell: datatype-generic versions of repeat, map and zipWith have different arities of kind-indexed types. In this paper, we define arity-generic datatype-generic programs by building a framework for Generic Haskell-style generic programming in the dependently-typed programming language Agda 2.

Categories and Subject Descriptors D.1.1 [Programming Techniques]: Applicative (Functional) Programming; D.3.3 [Program-

ming languages]: Language constructs and features—Data types and structures, frameworks

General Terms Design, Languages, Verification

Keywords Dependent types, Arity-generic programming, Agda, Generic Haskell

1. Introduction

This is a story about doubly-generic programming. *Datatype-generic* programming defines operations that may be instantiated at many different types, so these operations need not be redefined for each one. For example, Generic Haskell [5, 11] includes a generic map operation gmap that has instances for types such as lists, optional values, and products (even though these types have different kinds).

$$\begin{array}{lll} \mathsf{gmap} \; \langle \; [\;] \; \rangle & :: & (\mathsf{a} \to \mathsf{b}) \to [\mathsf{a}] \to [\mathsf{b}] \\ \mathsf{gmap} \; \langle \; \mathsf{Maybe} \; \rangle :: & (\mathsf{a} \to \mathsf{b}) \to \mathsf{Maybe} \; \mathsf{a} \to \mathsf{Maybe} \; \mathsf{b} \\ \mathsf{gmap} \; \langle \; (,) \; \rangle & :: & (\mathsf{a}1 \to \mathsf{b}1) \to (\mathsf{a}2 \to \mathsf{b}2) \\ & \to & (\mathsf{a}1, \mathsf{a}2) \to (\mathsf{b}1, \mathsf{b}2) \end{array}$$

Permission to make digital or hard copies of all or part of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. To copy otherwise, to republish, to post on servers or to redistribute to lists, requires prior specific permission and/or a fee.

PLPV'10, January 19, 2010, Madrid, Spain. Copyright © 2010 ACM 978-1-60558-890-2/10/01...\$10.00

Because all the instances of gmap are generated from the same definition, reasoning about that generic function tells us about map at each type.

However, there is another way to generalize map. Consider the following sequence of functions from the Haskell Prelude [20], all of which operate on lists.

$$\begin{array}{ll} \text{repeat} & :: a \to [a] \\ \text{map} & :: (a \to b) \to [a] \to [b] \\ \text{zipWith} & :: (a \to b \to c) \to [a] \to [b] \to [c] \\ \text{zipWith3} :: (a \to b \to c \to d) \to [a] \to [b] \to [c] \to [d] \\ \end{array}$$

The repeat function creates an infinite list from its argument. The zipWith function is a generalization of zip—it combines the two lists together with its argument instead of with the tupling function. Likewise, zipWith3 combines three lists.

As Fridlender and Indrika [7] have pointed out, all of these functions are instances of the same generic operation, they just have different *arities*. They demonstrate how to encode the arity as a Church numeral in Haskell and uniformly produce all of these list operations from the same definition.

Arity-genericity is not unique to the list instance of map. It is not difficult to imagine arity-generic versions of map for other types. Fridlender and Indrika's technique immediately applies to all types that are applicative functors [16]. However, one may also define arity-generic versions of map at other types.

Other functions besides map have both datatype-generic and arity-generic versions. For example, equality can be applied to

any number of arguments, all of the same type. Map has a dual operation called unzipWith that is similarly doubly-generic. Other examples include folds, enumerations, monadic maps, etc.

In this paper, we present the first *doubly-generic* definitions. For each of these examples, we can give a single definition that can be instantiated at any type or at any arity. Our methodology shows how these two forms of genericity can be combined in the same framework and demonstrates the synergy between them.

In fact, arity-genericity is not independent of datatype-genericity. Generic Haskell has its own notion of arity. and each datatype-generic function must be defined at a particular arity. Importantly, that arity corresponds to the arities in map above. For example, the Generic Haskell version of repeat has arity one, its map has arity two, and zipWith arity three.

Unfortunately, Generic Haskell does not permit generalizing over arities, so a single definition cannot produce repeat, map and zipWith. Likewise, Generic-Haskell-style libraries encoded in Haskell, such as RepLib [29] or Extensible and Modular Generics for the Masses (EMGM) [6] specialize their infrastructure to specific arities, so they too cannot write arity-generic code.

However, Altenkirch and McBride [1] and Verbruggen et al. [26] have shown how to encode Generic-Haskell-style generic programming in dependently-typed programming languages. Although they do not consider arity-genericity in their work, because of the power of dependent-types, their encodings are flexible enough to express arity-generic operations.

In this paper, we develop an analogous generic programming framework in the dependently-typed language Agda 2 [19] and demonstrate how it may be used to define doubly-generic operations. We choose Agda because it is particularly tailored to dependently-typed programming, but we could have also used a number of different languages, such as Coq [25], Epigram [15], Ω mega [23], or Haskell with recent extensions [3, 21].

Our contributions are as follows:

- 1. We develop an arity-generic version of map that reveals commonality between gmap, gzipWith and gzipWith3. This correspondence has not previously been expressed, but we find that it leads to insight into the nature of these operations. Since the definitions are all instances of the same dependently-typed function, we have shown formally that they are related.
- This example is developed on top of a reusable framework for generic programming in Agda. Although our framework has the same structure as previous work, our treatment of datatype isomorphisms is novel and requires less boilerplate.
- 3. We use our framework to develop other doubly-generic operations, such as equality and unzipWith. All of these examples shed light on arity support in a generic programming framework. In particular, there are not many operations that require arity of two or more: this work suggests what such operations must look like.
- 4. Finally, because we develop a reusable framework, this work demonstrates how a tool like Generic Haskell could be extended to arity-genericity.

We explain doubly-generic map and our generic programming infrastructure in stages. In Section 2 we start with an Agda definition of arity-generic map. Next, in Section 3, we describe a general framework for generic programming that works for all types

(of any kind) formed from unit, pairs, sums and natural numbers. We use this framework to define doubly-generic map. In Section 4 we show how datatype isomorphisms may be incorporated, so that we can specialize doubly-generic operations to inductive datatypes. We discuss other doubly-generic examples in Section 5. Finally, Sections 6 and 7 discuss related work and conclude.

All code described in this paper is available from http://www.cis.upenn.edu/~ccasin/papers/aritygen.tar.gz.

2. Arity-generic Map

We begin this section by introducing Agda and using it to define applicative functors. We show how to use applicative functors to define arity-generic map for vectors, following Fridlender and Indrika. Finally, we demonstrate why this approach does not scale to implementing datatype-generic arity-generic map.

2.1 Programming with Dependent Types in Agda

Agda is a dependently typed programming language where terms may appear in types. For example, the Agda standard library defines a type of polymorphic length-indexed vectors:

This datatype Vec is parameterized by an argument A of type Set, the analogue of Haskell's kind \star , and indexed by an argument of type \mathbb{N}^1 , the type of natural numbers. The parameter A specifies

¹ Note that Unicode symbols are valid in Agda identifiers.

the type of the objects stored in the vector and the index specifies its length. For example, the type Vec Bool 2 is a list of boolean values of length two. Note that indices can vary in the types of the constructors; for example, empty vectors [] use index 0.

The underscores in _::_ create an infix operator. Arguments to Agda functions may be made implicit by placing them in curly braces, so Agda will attempt to infer the length index by unification when applying _::_. For example, Agda can automatically determine that the term true :: false :: [] has type Vec Bool 2.

Vectors are applicative functors, familiar to Haskell programmers from the Applicative type class. Applicative functors have two operations. The first is repeat (called pure in Haskell). Given an initial value, it constructs a vector with n copies of that value.

$$\begin{array}{l} \mathsf{repeat} \,:\, \{n\,:\, \mathbb{N}\} \to \{A\,:\, \mathsf{Set}\} \to A \to \mathsf{Vec}\; A\; n \\ \mathsf{repeat}\; \{\mathsf{zero}\} \;\; \mathsf{x} \;=\; [\,] \\ \mathsf{repeat}\; \{\mathsf{suc}\; n\} \, \mathsf{x} \;=\; \mathsf{x} :: \, \mathsf{repeat}\; \{n\} \, \mathsf{x} \end{array}$$

Observe that, using curly braces, implicit arguments can be explicitly provided in a function call or matched against in a definition.

The second, $_\circledast_,$ is an infix zipping application, pronounced "zap" and defined by:

The _____ operator associates to the left. In its definition, we do not need to consider the case where one vector is empty while the other is not because the type specifies that both arguments have the

same length.

These two operations are the key to arity-generic map. The following sequence shows that the different arities of map follow a specific pattern.

```
\begin{array}{lll} \text{map0} & : \left\{\text{m} : \mathbb{N}\right\} \left\{\text{A} : \mathsf{Set}\right\} \to \mathsf{A} \to \mathsf{Vec} \ \mathsf{A} \ \mathsf{m} \\ \text{map0} & = \mathsf{repeat} \\ \\ \text{map1} & : \left\{\text{m} : \mathbb{N}\right\} \left\{\text{A} \ \mathsf{B} : \mathsf{Set}\right\} \\ & \to \left(\text{A} \to \text{B}\right) \to \mathsf{Vec} \ \mathsf{A} \ \mathsf{m} \to \mathsf{Vec} \ \mathsf{B} \ \mathsf{m} \\ \text{map1} \ \mathsf{f} \ \mathsf{x} & = \mathsf{repeat} \ \mathsf{f} \ \circledast \ \mathsf{x} \\ \\ \text{map2} & : \left\{\text{m} : \mathbb{N}\right\} \left\{\text{A} \ \mathsf{B} \ \mathsf{C} : \mathsf{Set}\right\} \\ & \to \left(\text{A} \to \text{B} \to \text{C}\right) \\ & \to \mathsf{Vec} \ \mathsf{A} \ \mathsf{m} \to \mathsf{Vec} \ \mathsf{B} \ \mathsf{m} \to \mathsf{Vec} \ \mathsf{C} \ \mathsf{m} \\ \\ \text{map2} \ \mathsf{f} \ \mathsf{x1} \ \mathsf{x2} & = \mathsf{repeat} \ \mathsf{f} \ \circledast \ \mathsf{x1} \ \circledast \ \mathsf{x2} \\ \end{array}
```

Indeed, all of these maps are defined by a simple application of repeat and n copies of _® _. Agda can express the arity-generic operation that unifies all of these maps via dependent types, as we present in the next subsection.

2.2 Arity-Generic Vector Map

The difficulty in the definition of arity-generic map is that all of the instances have different types. Given some arity n, we must generate the corresponding type in this sequence. Fridlender and Indrika, not working in a dependently typed language, do so by encoding n as a Church numeral that generates the appropriate type for map.

We prefer to use natural numbers to express the arity of the mapping operation. Therefore, we must *program* with Agda types. For

example, we can construct a vector of Agda types, Bool :: \mathbb{N} :: [], which has type Vec Set 2, and use standard vector operations (such as $_{\odot}$) with this value.²

The first step is to define arrTy, which folds the arrow type constructor \rightarrow over a non-empty vector of types. Given such a vector, this operation constructs the type of the function that will be mapped over the n data structures.

$$\begin{array}{ll} \mathsf{arrTy} \ : \ \{\mathsf{n} \ : \ \mathbb{N}\} \to \mathsf{Vec} \ \mathsf{Set} \ (\mathsf{suc} \ \mathsf{n}) \to \mathsf{Set} \\ \mathsf{arrTy} \ \{\mathsf{0}\} & (\mathsf{A} :: []) \ = \ \mathsf{A} \\ \mathsf{arrTy} \ \{\mathsf{suc} \ \mathsf{n}\} \ (\mathsf{A} :: \mathsf{As}) \ = \ \mathsf{A} \to \mathsf{arrTy} \ \mathsf{As} \end{array}$$

The function arrTyVec constructs the result type of arity-generic map for vectors. We define this operation by mapping the Vec constructor onto the vector of types, then placing arrows between them. Notice that there are two integer indices here: n determines the number of types we are dealing with (the arity), while m is the length of the vectors we map over. Recall that the curly braces in the types of arrTyVec and arrTy mark m and n as implicit arguments, so we need not always match against them in definitions nor provide them explicitly as arguments.

$$\begin{array}{ll} \mathsf{arrTyVec} \ : \ \{\mathsf{m} \ \mathsf{n} \ : \ \mathbb{N} \} \to \mathsf{Vec} \ \mathsf{Set} \ (\mathsf{suc} \ \mathsf{n}) \to \mathsf{Set} \\ \mathsf{arrTyVec} \ \{\mathsf{m} \} \ \mathsf{As} \ = \\ \mathsf{arrTy} \ (\mathsf{repeat} \ (\lambda \ \mathsf{A} \to \mathsf{Vec} \ \mathsf{A} \ \mathsf{m}) \ \circledast \ \mathsf{As}) \\ \end{array}$$

For example, we can define the sequence of types from Sec-

² This type requires Set to have type Set, enabled by Agda's --type-in-type flag. The standard type system of Agda has an infinite hierarchy of Sets, and users must resolve their code to be at the appropriate

tion 2.1 using these functions applied to lists of type variables.

```
\begin{array}{l} \mathsf{map0} : \left\{\mathsf{m} : \mathbb{N}\right\} \left\{\mathsf{A} : \mathsf{Set}\right\} \\ &\to \mathsf{arrTy} \left(\mathsf{A} :: []\right) \\ &\to \mathsf{arrTyVec} \left\{\mathsf{m}\right\} \left(\mathsf{A} :: []\right) \\ \mathsf{map1} : \left\{\mathsf{m} : \mathbb{N}\right\} \left\{\mathsf{A} \ \mathsf{B} : \mathsf{Set}\right\} \\ &\to \mathsf{arrTy} \left(\mathsf{A} :: \mathsf{B} :: []\right) \\ &\to \mathsf{arrTyVec} \left\{\mathsf{m}\right\} \left(\mathsf{A} :: \mathsf{B} :: []\right) \\ \mathsf{map2} : \left\{\mathsf{m} : \mathbb{N}\right\} \left\{\mathsf{A} \ \mathsf{B} \ \mathsf{C} : \mathsf{Set}\right\} \\ &\to \mathsf{arrTy} \left(\mathsf{A} :: \mathsf{B} :: \mathsf{C} :: []\right) \\ &\to \mathsf{arrTyVec} \left\{\mathsf{m}\right\} \left(\mathsf{A} :: \mathsf{B} :: \mathsf{C} :: []\right) \end{array}
```

Now, to define arity-generic map, we start by defining a function nvec-map. The type of this function mirrors the examples above, except that it takes in the type arguments (A, B, etc) as a vector (As). After we define nvec-map we will curry it to get the desired operation.

```
\label{eq:nvec-map} \begin{split} \mathsf{nvec\text{-}map} \, : \, \big\{ \mathsf{m} \, : \, \mathbb{N} \big\} &\to (\mathsf{n} \, : \, \mathbb{N}) \\ &\to (\mathsf{As} \, : \, \mathsf{Vec} \, \mathsf{Set} \, (\mathsf{suc} \, \mathsf{n})) \\ &\to \mathsf{arrTy} \, \mathsf{As} \to \mathsf{arrTyVec} \, \big\{ \mathsf{m} \big\} \, \mathsf{As} \end{split}
```

We define this function by recursion on n, in accumulator style. After duplicating f we have a vector of functions to zap, so we

define a helper function, g, for that more general case.

```
nvec-map n As f = g \{n\} As (repeat f) where g : \{n m : \mathbb{N}\}
\rightarrow (As : Vec Set (suc n))
\rightarrow Vec (arrTy As) m \rightarrow arrTyVec \{m\} As
g \{0\} \qquad (A :: []) \quad a = a
g \{suc n\} (A1 :: As) f =
(\lambda a \rightarrow g As (f \circledast a))
```

level. Although we have done so, in the interest of clarity we have hidden this hierarchy and its associated complexities. We discuss this choice further in Section 7.

Finally, we define two operations for currying. The first, $\forall \Rightarrow$, creates a curried version of a type which depends on a vector. The second, $\lambda \Rightarrow$, curries a corresponding function term.

```
\begin{array}{l} \forall \Rightarrow : \ \{n : \mathbb{N}\} \ \{A : \mathsf{Set}\} \to (\mathsf{Vec} \ \mathsf{A} \ \mathsf{n} \to \mathsf{Set}) \to \mathsf{Set} \\ \forall \Rightarrow \{\mathsf{zero}\} \qquad \mathsf{B} = \mathsf{B} \ [] \\ \forall \Rightarrow \{\mathsf{suc} \ \mathsf{n}\} \ \{A\} \quad \mathsf{B} = \\ \{a : A\} \to \forall \Rightarrow \{\mathsf{n}\} \ (\lambda \ \mathsf{as} \to \mathsf{B} \ (a :: \mathsf{as})) \\ \lambda \Rightarrow : \ \{\mathsf{n} : \mathbb{N}\} \ \{A : \mathsf{Set}\} \ \{\mathsf{B} : \mathsf{Vec} \ \mathsf{A} \ \mathsf{n} \to \mathsf{Set}\} \\ \to ((\mathsf{X} : \mathsf{Vec} \ \mathsf{A} \ \mathsf{n}) \to \mathsf{B} \ \mathsf{X}) \to (\forall \Rightarrow \mathsf{B}) \\ \lambda \Rightarrow \{\mathsf{zero}\} \qquad \mathsf{f} = \mathsf{f} \ [] \\ \lambda \Rightarrow \{\mathsf{suc} \ \mathsf{n}\} \ \{A\} \ \mathsf{f} = \\ \lambda \ \{\mathsf{a} : A\} \to \lambda \Rightarrow \{\mathsf{n}\} \ (\lambda \ \mathsf{as} \to \mathsf{f} \ (\mathsf{a} :: \mathsf{as})) \end{array}
```

With these operations, we can finish the definition of aritygeneric map. Again, the (implicit) argument m is the length of the vector, and the (explicit) argument n is the specific arity of map that is desired.

$$\begin{array}{l} \mathsf{nmap} \,:\, (\mathsf{n} \,:\, \mathbb{N}) \to \{\mathsf{m} \,:\, \mathbb{N}\} \\ \to \forall \Rightarrow (\lambda \; (\mathsf{As} \,:\, \mathsf{Vec} \; \mathsf{Set} \; (\mathsf{suc} \; \mathsf{n})) \\ \to \mathsf{arrTy} \; \mathsf{As} \to \mathsf{arrTyVec} \; \{\mathsf{m}\} \; \mathsf{As}) \\ \mathsf{nmap} \; \mathsf{n} \; \{\mathsf{m}\} \; = \; \lambda \Rightarrow \; (\mathsf{nvec\text{-}map} \; \{\mathsf{m}\} \; \mathsf{n}) \end{array}$$

We can use this arity-generic map just by providing the arity as an additional argument. For example, the term nmap 1 has type

and the expression

nmap 1 (
$$\lambda \times \to \times + 1$$
) (1 :: 2 :: 3 :: [])

evaluates to 2 :: 3 :: 4 :: []. Likewise, the term nmap 2 has type

and the expression

nmap 2 (
$$_$$
, $_$) (1 :: 2 :: 3 :: []) (4 :: 5 :: 6 :: []) returns (1,4) :: (2,5) :: (3,6) :: [].

2.3 Towards Type Genericity

We have shown how to define arity-generic map for vectors, but what about for other types of data, such as products of vectors or vectors of products? This should be possible, as map is a *type-generic* operation, one that is defined by type structure.

Type-generic programming in Agda is done via a technique called *universes* [13, 18]. The idea is to define an inductive datatype Tyc, called a universe, which represents types, along with an interpretation function $\lfloor _ \rfloor$ that maps elements of this universe to actual Agda types. A generic program is then an operation which manipulates this data structure.

However, there is one difficulty—what kind of types should we represent? The answer to that question determines the type of the interpretation function. For example, if the datatype Tyc represents types of kind Set then the interpretation function should have type Tyc \rightarrow Set. If the universe represents type constructors, that is, functions from types to types, then the interpretation function should have type Tyc \rightarrow (Set \rightarrow Set).

Consider the following universe of codes for type constructors.

data Tyc: Set where

Nat : Tyc Unit : Tyc

 $\begin{array}{ll} \mathsf{Prod} \; : \; \mathsf{Tyc} \to \mathsf{Tyc} \to \mathsf{Tyc} \\ \mathsf{Arr} & : \; \mathbb{N} \to \mathsf{Tyc} \to \mathsf{Tyc} \end{array}$

Var : Tyc

Each of these codes can be decoded as an Agda type constructor of kind Set \rightarrow Set. For example, \top is the unit type in Agda and \times constructs the (non-dependent) type of products.

$$| Var | a = a$$

With these two definitions, we can implement type-generic versions of the repeat and _\&_ functions.\s^3 They are implemented by recursion on the structure of the Tyc, but we elide the definitions for brevity.

$$\begin{array}{ll} \mathsf{grepeat} \ : \ (\mathsf{t} \ : \ \mathsf{Tyc}) \to \{\mathsf{a} \ : \ \mathsf{Set}\} \to \mathsf{a} \to \lfloor \, \mathsf{t} \, \rfloor \, \mathsf{a} \\ \mathsf{gzap} & : \ (\mathsf{t} \ : \ \mathsf{Tyc}) \to \{\mathsf{a} \ \mathsf{b} \ : \ \mathsf{Set}\} \\ & \to \lfloor \, \mathsf{t} \, \rfloor \, (\mathsf{a} \to \mathsf{b}) \to \lfloor \, \mathsf{t} \, \rfloor \, \mathsf{a} \to \lfloor \, \mathsf{t} \, \rfloor \, \mathsf{b} \end{array}$$

With these type-generic functions, we can generalize the definition for vectors to produce gmap, which works for all type constructors in the universe. This definition is a straightforward extension of nmap for vectors (replacing repeat and __®_ with grepeat and gzap), so we elide its definition and only show its type.

$$\begin{array}{l} \mathsf{gmap} \ : \ (\mathsf{t} \ : \ \mathsf{Tyc}) \to (\mathsf{n} \ : \ \mathbb{N}) \\ \to \forall \Rightarrow (\lambda \ (\mathsf{As} \ : \ \mathsf{Vec} \ \mathsf{Set} \ (\mathsf{suc} \ \mathsf{n})) \\ \to \mathsf{arrTy} \ \mathsf{As} \to \mathsf{arrTy} \ (\mathsf{repeat} \ | \ \mathsf{t} \ | \ \circledast \ \mathsf{As})) \end{array}$$

We use gmap by supplying a type code and arity. For example,

$$\begin{array}{l} \mathsf{example\text{-}map} \,:\, \{\mathsf{m}\,:\, \mathbb{N}\} \to \{\mathsf{A}\,\mathsf{B}\,:\, \mathsf{Set}\} \to (\mathsf{A} \to \mathsf{B}) \\ \quad \to \mathsf{Vec}\, (\mathsf{A} \times (\mathsf{A} \times \top)) \,\,\mathsf{m} \\ \quad \to \mathsf{Vec}\, (\mathsf{B} \times (\mathsf{B} \times \top)) \,\,\mathsf{m} \\ \\ \mathsf{example\text{-}map} \,=\, \\ \mathsf{gmap}\, (\mathsf{Arr}\, _\, (\mathsf{Prod}\, \mathsf{Var}\, (\mathsf{Prod}\, \mathsf{Var}\, \mathsf{Unit}))) \, \mathbf{1} \end{array}$$

We have now combined arity genericity and type genericity. However, there is a problem with this definition; it only works for type constructors of kind $Set \rightarrow Set$. Maps for other kinds are not avail-

able. Furthermore, this definition tells us nothing about how to define other arity-generic functions. We have not really gotten to the essence of arity genericity.

To extend arity-generic map to types of arbitrary kinds, we will redo our framework for type-generic programming using a kind-indexed universe. The kind determines the type of the decoding function <code>[_]</code>. With this kind-indexed universe, the concept of arity naturally shows up—following Generic Haskell, a generic function has a kind-indexed type of a particular arity. For example, generic repeat requires an arity one kind-indexed type, while generic map requires arity two, and generic zipWith requires arity three. Remarkably, but perhaps unsurprisingly, this notion of arity mirrors the arity found in arity-generic map!

What is new in this paper is that we generalize over the arities in the kind-indexed types to give a completely new definition of arity-generic type-generic map. This definition incorporates arity-genericity right from the start. In the current section we layered arity-genericity on top of type-genericity; in the next, our type-generic functions will be inherently arity-generic.

3. Arity-Generic Type-Generic Map

Next, we show how to generalize arity-generic map to arbitrary type constructors by implementing a framework for Generic

³ Because these generic functions show that all type constructors in this universe are applicative functors, we cannot include a code for sum types. We return to this issue in Section 3.3.

Haskell style kind-indexed types. We develop our framework in stages, first including only primitive type constructors in the

universe, then in Section 4, extending it to include user-defined datatypes.

3.1 Universe Definition

To write more general generic programs, we need a more expressive universe. The universe that we care about is based on the type language of F-omega [8]. It is the simply-typed lambda calculus augmented with a number of constants that form types. Therefore, to represent this language, we need datatypes for kinds, constants, and for the lambda calculus itself.

Kinds include the base kind \star and function kinds. The function kind arrow associates to the right.

data Kind : Set **where** $\star : Kind$ $\Rightarrow : Kind \rightarrow Kind \rightarrow Kind$

A simple recursive function takes a member of this datatype into an Agda kind.

Constants are indexed by their kinds. For now, we will concentrate on types formed from natural numbers, unit, binary sums, and binary products. Note that these definitions include a code for sum types. Although doubly-generic map is partial for sums, many doubly-generic operations are not. On the other hand, most generic functions are partial for function types, so we do not include a code for them. Furthermore, because vectors are representable in terms

of the other constructors, we do not include a code for them in this universe. This keeps the definitions of arity-generic functions simple. In Section 4, we discuss how our generic programming framework can interface directly with Agda datatypes like Vec.

data Const: Kind → Set where

 $\begin{array}{lll} \mathsf{Nat} & : \; \mathsf{Const} \; \star \\ \mathsf{Unit} & : \; \mathsf{Const} \; \star \end{array}$

Sum : Const $(\star \Rightarrow \star \Rightarrow \star)$ Prod : Const $(\star \Rightarrow \star \Rightarrow \star)$

Again, each of these constants can be decoded as an Agda type constructor.

```
\begin{array}{lll} \text{interp-c} & : \; \forall \; \{k\} \rightarrow \mathsf{Const} \; k \rightarrow \llbracket \; k \; \rrbracket \\ \text{interp-c} \; \mathsf{Unit} & = \; \top \\ \text{interp-c} \; \mathsf{Nat} & = \; \mathbb{N} \\ \text{interp-c} \; \mathsf{Sum} & = \; \_ \uplus \_ \\ \text{interp-c} \; \mathsf{Prod} & = \; \_ \times \_ \end{array}
```

To represent other types (of arbitrary kinds), we now define an indexed datatype called Typ. A Typ may be a variable, a lambda, an application, or a constant. The datatype is indexed by the kind of the type and a typing context which indicates the kinds of variables. We use de Bruijn indices for variables, so we represent the typing context as a list of Kinds. The nth Kind in the list is the kind of variable n.

 $\begin{array}{ll} \mathsf{Ctx} \,:\, \mathsf{Set} \\ \mathsf{Ctx} \,=\, \mathsf{List} \; \mathsf{Kind} \\ \\ \textbf{data} \; \mathsf{TyVar} \,:\, \mathsf{Ctx} \to \mathsf{Kind} \to \mathsf{Set} \; \textbf{where} \end{array}$

```
\begin{array}{lll} \mathsf{VZ} & : \ \forall \ \{G\ k\} \to \mathsf{TyVar}\ (k::G)\ k \\ \mathsf{VS} & : \ \forall \ \{G\ k'\ k\} \to \mathsf{TyVar}\ G\ k \to \mathsf{TyVar}\ (k'::G)\ k \\ \\ \textbf{data}\ \mathsf{Typ} & : \ \mathsf{Ctx} \to \mathsf{Kind} \to \mathsf{Set}\ \textbf{where} \\ \mathsf{Var} & : \ \forall \ \{G\ k\} \to \mathsf{TyVar}\ G\ k \to \mathsf{Typ}\ G\ k \\ \mathsf{Lam} & : \ \forall \ \{G\ k1\ k2\} \to \mathsf{Typ}\ (k1::G)\ k2 \\ & \to \mathsf{Typ}\ G\ (k1 \Rightarrow k2) \\ \mathsf{App} & : \ \forall \ \{G\ k1\ k2\} \to \mathsf{Typ}\ G\ (k1 \Rightarrow k2) \to \mathsf{Typ}\ G\ k1 \\ & \to \mathsf{Typ}\ G\ k2 \\ \mathsf{Con} & : \ \forall \ \{G\ k\} \to \mathsf{Const}\ k \to \mathsf{Typ}\ G\ k \\ \end{array}
```

We use the notation Ty for closed types—those that can be checked in the empty typing context.

$$\begin{array}{ll} \mathsf{Ty} \; : \; \mathsf{Kind} \to \mathsf{Set} \\ \mathsf{Ty} \; = \; \mathsf{Typ} \; [\;] \end{array}$$

Now that we can represent type constructors, we need a mechanism to decode them as Agda types. To do so, we must have an environment to decode the variables. We index the datatype for the environment with the typing context to make sure that each variable is mapped to an Agda type of the right kind. Note that this definition overloads the [] and _::_ constructors, but Agda can infer which we mean.

```
\begin{array}{lll} \textbf{data} \; \mathsf{Env} \; : \; \mathsf{List} \; \mathsf{Kind} \; \to \; \mathsf{Set} \; \textbf{where} \\ [\,] & : \; \mathsf{Env} \; [\,] \\ & : : \; : \; \forall \; \{k \; G\} \; \to \; \llbracket \; k \; \rrbracket \; \to \; \mathsf{Env} \; \mathsf{G} \; \to \; \mathsf{Env} \; (k :: \; \mathsf{G}) \\ \mathsf{sLookup} \; : \; \forall \; \{k \; G\} \; \to \; \mathsf{TyVar} \; \mathsf{G} \; k \; \to \; \mathsf{Env} \; \mathsf{G} \; \to \; \llbracket \; k \; \rrbracket \\ \mathsf{sLookup} \; \mathsf{VZ} \qquad (\mathsf{v} :: \; \mathsf{G}) \; = \; \mathsf{v} \\ \mathsf{sLookup} \; (\mathsf{VS} \; \mathsf{x}) \; (\mathsf{v} :: \; \mathsf{G}) \; = \; \mathsf{sLookup} \; \mathsf{x} \; \mathsf{G} \end{array}
```

Finally, with the help of the environment, we can decode a Typ as an Agda type of the appropriate kind. We use the $\lfloor _ \rfloor$ notation for decoding closed types in the empty environment.

```
\begin{array}{lll} \text{interp} \ : \ \forall \ \{k \ G\} \rightarrow \mathsf{Typ} \ G \ k \rightarrow \mathsf{Env} \ G \rightarrow \llbracket \ k \ \rrbracket \\ \text{interp} \ (\mathsf{Var} \ x) \ e &= \ \mathsf{sLookup} \ x \ e \\ \text{interp} \ (\mathsf{Lam} \ t) \ e &= \ \lambda \ \mathsf{y} \rightarrow \mathsf{interp} \ t \ (\mathsf{y} :: e) \\ \text{interp} \ (\mathsf{App} \ t1 \ t2) \ e &= \ (\mathsf{interp} \ t1 \ e) \ (\mathsf{interp} \ t2 \ e) \\ \text{interp} \ (\mathsf{Con} \ c) \ e &= \ \mathsf{interp-c} \ c \\ \ \lfloor \_ \rfloor \ : \ \forall \ \{k\} \rightarrow \mathsf{Ty} \ k \rightarrow \llbracket \ k \ \rrbracket \\ \ \lfloor \ t \ \rfloor &= \ \mathsf{interp} \ t \ [ \ ] \end{array}
```

For example, the following type constructor Option (isomorphic to the standard Maybe datatype)

Option : Set
$$\rightarrow$$
 Set Option = $\lambda A \rightarrow \top \uplus A$

is represented with the following code:

```
\begin{array}{ll} {\sf option} \ : \ {\sf Ty} \ (\star \Rightarrow \star) \\ {\sf option} \ = \\ {\sf Lam} \ ({\sf App} \ ({\sf App} \ ({\sf Con} \ {\sf Sum}) \ ({\sf Con} \ {\sf Unit})) \ ({\sf Var} \ {\sf VZ})) \end{array}
```

The Agda type checker can see that [option] normalizes to Option, so it considers these two expressions equal.

3.2 Framework for Doubly-Generic Programming

Next, we give the signature of a framework for defining aritygeneric type-generic programs. For space reasons, we do not give the implementation of this framework here. The interested reader may consult Altenkirch and McBride [1], Verbruggen et al. [26], or our source code for more details.

As with Generic Haskell, the behavior of a generic program defined using this framework is fixed for applications, lambdas and variables. Therefore, to define an arity-generic type-generic operation, we need only supply the behavior of the generic program for the type constants.

Datatype-generic operations have different types when instantiated at different kinds, so they are described by *kind-indexed types* [11]. For example, consider the type of the standard map function for the Option type constructor, of kind $\star \Rightarrow \star$:

$$\begin{array}{c} \mathsf{option\text{-}map1} \,:\, \forall \, \left\{ \mathsf{A} \; \mathsf{B} \right\} \to \left(\mathsf{A} \to \mathsf{B} \right) \\ \to \left(\mathsf{Option} \; \mathsf{A} \to \mathsf{Option} \; \mathsf{B} \right) \end{array}$$

And map for the type constructor $_\times_$, of kind $\star \Rightarrow \star \Rightarrow \star$

$$\begin{array}{c} \mathsf{pair\text{-}map1} \ : \ \forall \ \{\mathsf{A1} \ \mathsf{A2} \ \mathsf{B1} \ \mathsf{B2}\} \\ \quad \to (\mathsf{A1} \to \mathsf{B1}) \to (\mathsf{A2} \to \mathsf{B2}) \\ \quad \to (\mathsf{A1} \times \mathsf{A2}) \to (\mathsf{B1} \times \mathsf{B2}) \end{array}$$

Though different, the types of option-map1 and pair-map1 are instances of the same kind-indexed type. In Generic Haskell, kind-indexed types are defined by recursion on the kind of the type arguments. For example, here is the Generic Haskell definition of map's type [12]:

type Map
$$\langle \star \rangle$$
 t₁ t₂ = t₁ \rightarrow t₂
type Map $\langle k_1 \Rightarrow k_2 \rangle$ t₁ t₂ = \forall a₁ a₂, Map $\langle k_1 \rangle$ a₁ a₂ \rightarrow Map $\langle k_2 \rangle$ (t₁ a₁) (t₂ a₂)

Readers new to Generic Haskell-style generic programming may

find it instructive to verify that Map $\langle \star \Rightarrow \star \rangle$ Option Option and Map $\langle \star \Rightarrow \star \Rightarrow \star \rangle$ _×_ _×_ simplify to the types given above for option-map and pair-map (modulo notational differences).

For arity-genericity, we must generalize kind-indexed types in another way. We want not only pair-map1, but also pair-map at other arities to be instances as well:

$$\begin{array}{l} \mathsf{pair\text{-}map0} \,:\, \forall \, \left\{ \mathsf{A} \,\, \mathsf{B} \,:\, \mathsf{Set} \right\} \to \mathsf{A} \to \mathsf{B} \to \mathsf{A} \times \mathsf{B} \\ \mathsf{pair\text{-}map2} \,:\, \forall \, \left\{ \mathsf{A1} \,\, \mathsf{B1} \,\, \mathsf{C1} \,\, \mathsf{A2} \,\, \mathsf{B2} \,\, \mathsf{C2} \right\} \\ \to \left(\mathsf{A1} \to \mathsf{B1} \to \mathsf{C1} \right) \to \left(\mathsf{A2} \to \mathsf{B2} \to \mathsf{C2} \right) \\ \to \mathsf{A1} \times \mathsf{A2} \to \mathsf{B1} \times \mathsf{B2} \to \mathsf{C1} \times \mathsf{C2} \end{array}$$

We compute the type of a generic function instance from four pieces of information: the arity of the operation (given with an implicit argument n), a function b to construct the type in the base case, the kind k itself and a vector v of n Agda types, each of kind k. Reminiscent of Generic Haskell, our kind-indexed type is written b $\langle \ k \ \rangle$ v:

The primary difference between our definition and the Generic

Haskell definition of kind-indexed type is that because the arity is a parameter, we deal with the type arguments as a vector rather than as individuals. For higher kinds the polymorphic type produced takes n arguments of kind [k1] (the vector As) and a kind-indexed type for those arguments and produces a result where each higher kinded type in the vector Vs has been applied to each argument in vector As.

We use the $\forall \Rightarrow$ function (from Section 2) to curry the type so that the user may provide n individual [k1]'s rather than a vector. The $_$ in Vec [k1] $_$ instructs Agda to infer the length of the vector (convenient since we did not give a name to the arity).

We do not allow these vectors to be empty because few generic functions make sense at arity zero. If we had allowed empty vectors we would have to add a degenerate zero case for the majority of generic functions. It would be straightforward, but tedious, to remove this restriction. As a result, the number provided here as an arity (n) is one less than the corresponding Generic Haskell arity. We refer to this reduced number as the arity for convenience.

We define generic functions with ngen, whose type is shown below. This operation produces a value of a kind-indexed type given ce, a mapping from constants to appropriate definitions.

```
\begin{array}{l} \mathsf{ngen} \ : \ \{\mathsf{n} \ : \ \mathsf{N}\} \ \{\mathsf{b} \ : \ \mathsf{Vec} \ \mathsf{Set} \ (\mathsf{suc} \ \mathsf{n}) \to \mathsf{Set}\} \ \{\mathsf{k} \ : \ \mathsf{Kind}\} \\ \to (\mathsf{t} \ : \ \mathsf{Ty} \ \mathsf{k}) \\ \to (\mathsf{ce} \ : \ \mathsf{TyConstEnv} \ \mathsf{n} \ \mathsf{b}) \\ \to \mathsf{b} \ \langle \ \mathsf{k} \ \rangle \ (\mathsf{repeat} \ | \ \mathsf{t} \ |) \end{array}
```

The type of ce is a function which maps each constant to a value of the kind-indexed type associated with that constant.

$$\mathsf{TyConstEnv} \,:\, \{\, n \,:\, \mathbb{N} \,\} \to (b \,:\, \mathsf{Vec} \, \mathsf{Set} \,\, \mathsf{n} \to \mathsf{Set}) \to \mathsf{Set}$$

```
\label{eq:total_const_noise} \begin{split} \mathsf{TyConstEnv} \ b \ = \\ \{ k \ : \ \mathsf{Kind} \} \ (\mathsf{c} \ : \ \mathsf{Const} \ \mathsf{k}) \to \mathsf{b} \ \langle \ \mathsf{k} \ \rangle \ (\mathsf{repeat} \ \lfloor \ \mathsf{Con} \ \mathsf{c} \ \rfloor) \end{split}
```

We can already use this framework for non-arity-generic programming. For example, suppose we wished to define the standard generic map. In this case, we would provide the following definition for b.

```
\begin{array}{ll} \mathsf{Map} \,:\, \mathsf{Vec}\,\,\mathsf{Set}\,\, 2 \to \mathsf{Set} \\ \mathsf{Map}\,\,(\mathsf{A}::\mathsf{B}::[\,]) \,=\, \mathsf{A} \to \mathsf{B} \end{array}
```

Next, we define the type-constant environment for this particular b. The mapping function for natural numbers and unit is an identity function. For products and sums, the mapping function takes those arguments apart, maps the subcomponents and then puts them back together.

```
\begin{array}{lll} \mathsf{gmap\text{-}const} \, : \, \mathsf{TyConstEnv} \, \mathsf{GMap} \\ \mathsf{gmap\text{-}const} \, \mathsf{Nat} & = \, \lambda \, \mathsf{x} \to \mathsf{x} \\ \mathsf{gmap\text{-}const} \, \mathsf{Unit} & = \, \lambda \, \mathsf{x} \to \mathsf{x} \\ \mathsf{gmap\text{-}const} \, \mathsf{Prod} & = \, \lambda \, \mathsf{f} \, \mathsf{g} \, \mathsf{x} \to (\mathsf{f} \, (\mathsf{proj}_1 \, \mathsf{x}), \mathsf{g} \, (\mathsf{proj}_2 \, \mathsf{x})) \\ \mathsf{gmap\text{-}const} \, \mathsf{Sum} & = \, \mathsf{g} \\ & \mathsf{where} \\ & \mathsf{g} \, : \, \{ \mathsf{A1} \, \mathsf{B1} \, \mathsf{A2} \, \mathsf{B2} \, : \, \mathsf{Set} \} \\ & \to \, (\mathsf{A1} \to \mathsf{B1}) \to (\mathsf{A2} \to \mathsf{B2}) \\ & \to \, \mathsf{A1} \, \uplus \, \mathsf{A2} \to \mathsf{B1} \, \uplus \, \mathsf{B2} \\ & \mathsf{g} \, \mathsf{fa} \, \mathsf{fb} \, (\mathsf{inj}_1 \, \mathsf{xa}) \, = \, \mathsf{inj}_1 \, (\mathsf{fa} \, \mathsf{xa}) \\ & \mathsf{g} \, \mathsf{fa} \, \mathsf{fb} \, (\mathsf{inj}_2 \, \mathsf{xb}) \, = \, \mathsf{inj}_2 \, (\mathsf{fb} \, \mathsf{xb}) \end{array}
```

Generic map then calls ngen with this argument.

```
gmap : \{k : Kind\} \rightarrow (t : Ty k)
```

$$\label{eq:map_def} \begin{array}{ll} & \rightarrow \mathsf{Map} \; \langle \; \mathsf{k} \; \rangle \; (\; \lfloor \; \mathsf{t} \; \rfloor \; :: \; [\;]) \\ \mathsf{gmap} \; \mathsf{t} \; = \; \mathsf{ngen} \; \mathsf{t} \; \mathsf{gmap\text{-}const} \end{array}$$

Providing the type code instantiates generic map at particular types. For example, using the code for the Option type of the previous section, we can define:

$$\begin{array}{c} \mathsf{option\text{-}map1} \,:\, \{\mathsf{A}\;\mathsf{B}\,:\, \mathsf{Set}\} \to (\mathsf{A} \to \mathsf{B}) \\ \quad \to \mathsf{Option}\;\mathsf{A} \to \mathsf{Option}\;\mathsf{B} \\ \mathsf{option\text{-}map1} \,=\, \mathsf{gmap}\;\mathsf{option} \end{array}$$

3.3 Doubly-generic Map

To use ngen to implement a doubly-generic function, we must also supply b and ce to ngen, but this time both of those arguments must generalize over the arity. For doubly-generic map, we call these pieces NGmap and ngmap-const. NGmap is simply the arrTy function from Section 2.2, which takes the arity as an implicit argument.

$$\begin{array}{ll} \mathsf{NGmap} \ : \ \{\mathsf{n} \ : \ \mathbb{N}\} \to \mathsf{Vec} \ \mathsf{Set} \ (\mathsf{suc} \ \mathsf{n}) \to \mathsf{Set} \\ \mathsf{NGmap} \ = \ \mathsf{arrTy} \end{array}$$

We are simplifying the example somewhat because generic zips (which are generic maps at arities greater than one) are partial functions—they may fail if instantiated at a sum type and passed mismatched injections. To account for this possibility in Generic Haskell, the library function zipWith returns a Maybe. However, we would like to keep our presentation as simple as possible, so we use an error term to indicate failure. A version of doubly-generic map that returns a Maybe is included with our sources. Because

Agda lacks Haskell's error function, we use a postulate:

```
postulate error : (A : Set) \rightarrow A
```

Next, we define the behavior of arity-generic type-generic map at the constant types. We do this by writing a term that dispatches to cases for the various constants (defined below). Each case takes the arity as an argument.

```
\begin{array}{lll} ngmap\text{-}const : \{n : \mathbb{N}\} & \rightarrow \mathsf{TyConstEnv} \; \mathsf{NGmap} \\ ngmap\text{-}const \, \{n\} \; \mathsf{Nat} & = \; \mathsf{defNat} \; \mathsf{n} \\ ngmap\text{-}const \, \{n\} \; \mathsf{Unit} & = \; \mathsf{defUnit} \; \mathsf{n} \\ ngmap\text{-}const \, \{n\} \; \mathsf{Prod} & = \; \mathsf{defPair} \; \mathsf{n} \\ ngmap\text{-}const \, \{n\} \; \mathsf{Sum} & = \; \mathsf{defSum} \; \mathsf{n} \end{array}
```

Recalling the definition of NGmap, for the first two cases, we must return arity-n functions with the types $\mathbb{N} \to \mathbb{N} \to ... \to \mathbb{N}$ and $\top \to \top \to ... \to \top$. For \mathbb{N} , when n is zero, we pick a default element to return arbitrarily. When n is one, we return the argument. For larger arities, we check that the inputs are identical. We choose to reject unequal nats to mirror the behavior of map at sum types.

```
defNat : (n : \mathbb{N}) \to \mathsf{NGmap} \langle \star \rangle (repeat \{\mathsf{suc}\, n\} \, \mathbb{N}) defNat zero = zero -- arbitrary \mathbb{N} defNat (suc zero) = \lambda \times \to \times -- return what was given defNat (suc (suc n)) = \lambda \times \to \lambda \ \mathsf{y} \to \mathsf{if} \ \mathsf{eqNat} \times \mathsf{y} \ \mathsf{then} \ \mathsf{defNat} \ (\mathsf{suc}\, \mathsf{n}) \ \mathsf{y} else error _ defUnit : (\mathsf{n} : \mathbb{N}) \to \mathsf{NGmap} \ \langle \star \rangle \ (\mathsf{repeat} \ \{\mathsf{suc}\, \mathsf{n}\} \, \top)
```

 $\begin{array}{ll} \mathsf{defUnit} \ : \ (\mathsf{n} \ : \ \mathbb{N}) \to \mathsf{NGmap} \ \langle \ \star \ \rangle \ (\mathsf{repeat} \ \{\mathsf{suc} \ \mathsf{n} \} \ \top) \\ \mathsf{defUnit} \ \mathsf{zero} & = \ \mathsf{tt} \end{array}$

```
\mathsf{defUnit}\;(\mathsf{suc}\;\mathsf{n})\;=\;\lambda\;\mathsf{x}\to(\mathsf{defUnit}\;\mathsf{n})
```

The Prod and Sum cases remain. Because these constants have higher kinds, the return type of ngmap-const changes. Consider Prod first. The desired type of defPair n is:

```
\begin{array}{l} \mathsf{NGmap} \; \langle \star \Rightarrow \star \Rightarrow \star \rangle \; (\mathsf{repeat} \; \{ \mathsf{suc} \; \mathsf{n} \} \; \_\times \_) \; = \\ \forall \Rightarrow \lambda \; (\mathsf{As} \; : \; \mathsf{Vec} \; \mathsf{Set} \; \mathsf{n}) \to \mathsf{arrTy} \; \mathsf{As} \to \\ \forall \Rightarrow \lambda \; (\mathsf{Bs} \; : \; \mathsf{Vec} \; \mathsf{Set} \; \mathsf{n}) \to \mathsf{arrTy} \; \mathsf{Bs} \to \\ \mathsf{arrTy} \; ((\mathsf{repeat} \; \times) \; \circledast \; \mathsf{As} \; \circledast \; \mathsf{Bs}) \end{array}
```

If we imagine writing out As as A1 :: A2 :: ... :: An :: [] and Bs as B1 :: B2 :: ... :: Bn :: [] the type simplifies to:

$$\begin{array}{l} \mathsf{NGmap} \; \langle \star \Rightarrow \star \Rightarrow \star \rangle \; (\mathsf{repeat} \; \{\mathsf{suc} \; \mathsf{n}\} \; _{\times} _) \; = \\ \; \; \{ \mathsf{A1} \; \mathsf{A2} \; ... \; \mathsf{An} \; \colon \; \mathsf{Set} \} \to (\mathsf{A1} \to \mathsf{A2} \to ... \to \mathsf{An}) \\ \to \{ \mathsf{B1} \; \mathsf{B2} \; ... \; \mathsf{Bn} \; \colon \; \mathsf{Set} \} \to (\mathsf{B1} \to \mathsf{B2} \to ... \to \mathsf{Bn}) \\ \to (\mathsf{A1} \times \mathsf{B1}) \to (\mathsf{A2} \times \mathsf{B2}) \to ... \to (\mathsf{An} \times \mathsf{Bn}) \end{array}$$

However, it is easier to define the case where the A1 ... An arguments are uncurried, and then curry the resulting function.

```
\begin{array}{l} \mathsf{defPairAux} \,:\, (\mathsf{n} \,:\, \mathbb{N}) \\ \to (\mathsf{As} \,:\, \mathsf{Vec} \, \mathsf{Set} \, (\mathsf{suc} \, \mathsf{n})) \to \mathsf{arrTy} \, \mathsf{As} \\ \to (\mathsf{Bs} \,:\, \mathsf{Vec} \, \mathsf{Set} \, (\mathsf{suc} \, \mathsf{n})) \to \mathsf{arrTy} \, \mathsf{Bs} \\ \to \mathsf{arrTy} \, (\mathsf{repeat} \, \underline{\quad} \times \underline{\quad} \otimes \, \mathsf{As} \, \otimes \, \mathsf{Bs}) \\ \mathsf{defPairAux} \, \mathsf{zero} \quad (\mathsf{A} :: []) \quad \mathsf{a} \, (\mathsf{B} :: []) \quad \mathsf{b} \, = \, (\mathsf{a}, \mathsf{b}) \\ \mathsf{defPairAux} \, (\mathsf{suc} \, \mathsf{n}) \, (\mathsf{A1} :: \, \mathsf{As}) \, \mathsf{a} \, (\mathsf{B1} :: \, \mathsf{Bs}) \, \mathsf{b} \, = \\ \lambda \, \mathsf{p} \to \\ (\mathsf{defPairAux} \, \mathsf{n} \, \mathsf{As} \, (\mathsf{a} \, (\mathsf{proj}_1 \, \mathsf{p})) \, \mathsf{Bs} \, (\mathsf{b} \, (\mathsf{proj}_2 \, \mathsf{p}))) \end{array}
```

In the zero case of defPairAux, a and b are arguments of type A

and B respectively—the function must merely pair them up. In the successor case, a and b are functions with types A1 \rightarrow arrTy As and B1 \rightarrow arrTy Bs. We want to produce a result of type A1 \times B1 \rightarrow arrTy (repeat $_\times_$ \circledast As \circledast Bs). Therefore, this case takes an argument p and makes a recursive call, passing in a applied to the first component of p and b applied to the second component of p. We use a kind-directed currying function k-curry, whose definition has been elided, to define the final version.

```
\begin{array}{ccc} \mathsf{defPair} \, : \, (\mathsf{n} \, : \, \mathbb{N}) \\ & \to \mathsf{NGmap} \, \langle \, \star \Rightarrow \star \Rightarrow \star \, \rangle \, (\mathsf{repeat} \, \{\mathsf{suc} \, \mathsf{n}\} \, \_\times \_) \\ \mathsf{defPair} \, \mathsf{n} \, = \, \mathsf{k-curry} \, (\star \Rightarrow \star \Rightarrow \star) \, (\mathsf{defPairAux} \, \mathsf{n}) \end{array}
```

Sum also has kind $\star \Rightarrow \star \Rightarrow \star$, so the type of its ngmap-const case is similar. However, for sums, we must check that the terms provided have the same structure (are either all inj₁ or all inj₂). Otherwise, we signal an error. Again, we first define defSumAux and then curry the result.

Below, defSumAux checks if the first argument is an inj₁ or an inj₂, then calls defSumLeft or defSumRight which require that all subsequent arguments match. In the degenerate case, where there are no arguments, we arbitrarily choose the right injection. Because defSumRight is analogous to defSumLeft, we elide its definition below.

```
\begin{array}{c} \mathsf{defSumLeft} \; : \; (\mathsf{n} \; : \; \mathbb{N}) \\ \qquad \to (\mathsf{As} \; : \; \mathsf{Vec} \; \mathsf{Set} \; (\mathsf{suc} \; \mathsf{n})) \to \mathsf{arrTy} \; \mathsf{As} \\ \qquad \to (\mathsf{Bs} \; : \; \mathsf{Vec} \; \mathsf{Set} \; (\mathsf{suc} \; \mathsf{n})) \\ \qquad \to \mathsf{arrTy} \; (\mathsf{repeat} \; \_ \uplus \_ \circledast \; \mathsf{As} \; \circledast \; \mathsf{Bs}) \\ \mathsf{defSumLeft} \; \mathsf{zero} \quad (\mathsf{A} :: [\,]) \quad \mathsf{a} \; (\mathsf{B} :: [\,]) \quad = \; \mathsf{inj_1} \; \mathsf{a} \end{array}
```

```
defSumLeft (suc n) (A1 :: As) a (B1 :: Bs) = f
  where
     f: A1 \uplus B1 \rightarrow arrTy (repeat \ \uplus \ \circledast As \circledast Bs)
     f(inj_1 a1) = defSumLeft n As (a a1) Bs
     f(inj_2 b1) = defSumLeft n As (a (error A1)) Bs
defSumAux : (n : \mathbb{N})
  \rightarrow (As : Vec Set (suc n)) \rightarrow arrTy As
  \rightarrow (Bs : Vec Set (suc n)) \rightarrow arrTy Bs
  defSumAux zero (A :: []) a (B :: []) b =
  (inj_2 b)
defSumAux (suc n) (A1 :: As) a (B1 :: Bs) b = f
  where
     f: A1 \uplus B1 \rightarrow arrTy (repeat \ \uplus \ \circledast As \circledast Bs)
     f(ini_1 a1) = defSumLeft n As (a a1) Bs
     f(inj_2 b1) = defSumRight n As Bs (b b1)
```

Finally, we also curry defSumAux to get the desired branch.

```
defSum : (n : \mathbb{N})
                    \rightarrow NGmap \langle \star \Rightarrow \star \Rightarrow \star \rangle (repeat \{ \text{suc n} \} \quad \uplus \quad )
\mathsf{defSum} \ \mathsf{n} \ = \ \mathsf{k\text{-}curry} \ (\star \Rightarrow \star \Rightarrow \star) \ (\mathsf{defSumAux} \ \mathsf{n})
```

We can then define ngmap by instantiating ngen.

```
ngmap : (n : \mathbb{N}) \rightarrow \{k : Kind\} \rightarrow (e : Ty k)
          \rightarrow NGmap \langle k \rangle (repeat \{ suc n \} \mid e \mid \}
ngmap n e = ngen e ngmap-const
```

If we had included vectors in our universe, we could simply use

nmap from Section 2.2 for that case.

Just as datatype-generic functions are instantiated at a type, doubly generic functions are instantiated at an arity and a type. For example, given the definitions Option and option from the last section, we can define various maps for this type constructor:

$$\begin{array}{c} \text{option-map1} \,:\, \{A \ B \,:\, \mathsf{Set}\} \to (\mathsf{A} \to \mathsf{B}) \\ & \to \mathsf{Option} \ \mathsf{A} \to \mathsf{Option} \ \mathsf{B} \\ \text{option-map1} \,=\, \mathsf{ngmap} \ \mathsf{1} \ \mathsf{option} \\ \text{option-map2} \,:\, \{A \ B \ C \,:\, \mathsf{Set}\} \to (\mathsf{A} \to \mathsf{B} \to \mathsf{C}) \\ & \to \mathsf{Option} \ \mathsf{A} \to \mathsf{Option} \ \mathsf{B} \to \mathsf{Option} \ \mathsf{C} \\ \text{option-map2} \,=\, \mathsf{ngmap} \ \mathsf{2} \ \mathsf{option} \end{array}$$

Of course, pair map functions are also instances of ngmap. We only show the definition of pair-map2 below.

$$\begin{array}{l} \mathsf{pair\text{-}map2} \,:\, \big\{ \mathsf{A1} \; \mathsf{B1} \; \mathsf{C1} \; \mathsf{A2} \; \mathsf{B2} \; \mathsf{C2} \,:\, \mathsf{Set} \big\} \\ \quad \to \; (\mathsf{A1} \to \mathsf{B1} \to \mathsf{C1}) \to (\mathsf{A2} \to \mathsf{B2} \to \mathsf{C2}) \\ \quad \to \; \mathsf{A1} \times \; \mathsf{A2} \to \mathsf{B1} \times \; \mathsf{B2} \to \mathsf{C1} \times \mathsf{C2} \\ \mathsf{pair\text{-}map2} \; \mathsf{f1} \; \mathsf{f2} \; = \; \mathsf{ngmap} \; \mathsf{2} \; (\mathsf{Con} \; \mathsf{Prod}) \; \mathsf{f1} \; \mathsf{f2} \end{array}$$

4. Datatype Isomorphisms

The infrastructure described so far permits us to instantiate arity-generic functions at different types based on their structure. However, to complete the story and generate versions of n-ary map for datatypes like Vec, we must must make a connection between arbitrary datatypes and their structure. In this section, we describe modifications to the implementation necessary to support generic functions on arbitrary datatypes through datatype isomorphisms.

4.1 Representing Datatypes

There are at least two ways to support datatypes. The current system already can encode datatypes on an ad hoc basis, in a manner described by Verbruggen et al. [26]. However, this encoding requires some tedious applications of coercions between the datatype and its isomorphism for each datatype instance of the generic operation. Instead, we move that boilerplate to the generic function itself by adding a new constructor to the Typ universe. This new constructor, Data, contains information about a particular datatype.

```
data Typ : Ctx \rightarrow Kind \rightarrow Set where ... Data : \forall {G} \rightarrow DT G \rightarrow Typ G \star
```

The DT data structure contains four pieces of information about a datatype: its Typ representation t, the actual Agda datatype that this code represents s, and two functions for coercing between values of type t and values of type s.

```
\begin{array}{lll} \textbf{data} \ \mathsf{DT} \ (\mathsf{G} \ : \ \mathsf{Ctx}) \ : \ \mathsf{Set} \ \textbf{where} \\ \mathsf{mkDT} \ : \ (\mathsf{t} & : \ \mathsf{Typ} \ \mathsf{G} \ \star) \\ & \to (\mathsf{s} & : \ \mathsf{Env} \ \mathsf{G} \to \mathsf{Set}) \\ & \to (\mathsf{to} & : \ (\{\mathsf{e} \ : \ \mathsf{Env} \ \mathsf{G}\} \to \mathsf{interp} \ \mathsf{t} \ \mathsf{e} \to \mathsf{s} \ \mathsf{e})) \\ & \to (\mathsf{from} \ : \ (\{\mathsf{e} \ : \ \mathsf{Env} \ \mathsf{G}\} \to \mathsf{s} \ \mathsf{e} \to \mathsf{interp} \ \mathsf{t} \ \mathsf{e})) \\ & \to \mathsf{DT} \ \mathsf{G} \end{array}
```

Note that we can only represent datatypes of kind Set. Other kinds do not support the coercion functions to and from as their interpretations have the wrong type. To create isomorphisms of type constructors like Vec, the DT datatype is parameterized by a context G, and s may depend on an environment for that context.

We describe this mechanism in more detail below.

We define a number of accessor functions for retrieving the parts of a DT, called DT-s, DT-t, DT-from and DT-to (here elided). ⁴ Because interp is mentioned by the components of DT, it must be defined mutually with Env, sLookup, Typ, DT, and its accessors.

Finally, we extend the interpretation function for codes by looking up the Agda type and giving it the current environment.

```
\begin{array}{ll} \text{interp} \; : \; \forall \; \{ \, k \; G \, \} \; \rightarrow \; \text{Typ} \; G \; k \; \rightarrow \; \text{Env} \; G \; \rightarrow \; [\![ \; k \; ]\!] \\ \dots \\ \text{interp} \; (\mathsf{Data} \; \mathsf{dt}) \; \mathsf{e} \; = \; \mathsf{DT-s} \; \mathsf{dt} \; \mathsf{e} \end{array}
```

For example, suppose we have a simple datatype definition that identifies natural numbers as Oranges.

data Orange : Set where to Orange : $\mathbb{N} \to \text{Orange}$

We can form the code for this datatype as below.

```
\begin{array}{lll} \text{fromOrange} \,:\, \text{Orange} \to \mathbb{N} \\ \text{fromOrange} \, (\text{toOrange} \, \text{x}) \, = \, \text{x} \\ \text{orange} \, : \, \left\{ \text{G} \, : \, \text{Ctx} \right\} \to \text{Typ G} \, \star \\ \text{orange} \, = \, \text{Data} \, (\text{mkDT} \\ \text{(Con Nat)} & -- \, \text{t} \\ \text{($\lambda$ e} \to \text{Orange)} & -- \, \text{s} \\ \text{($\lambda$ $\{e\}$ $\to $toOrange)} & -- \, \text{to} \\ \text{($\lambda$ $\{e\}$ $\to $fromOrange)}) & -- \, \text{from} \\ \end{array}
```

Even though the kind of a datatype isomorphism must be \star , we

⁴ Unfortunately, Agda does not support record definitions in a mutual block.

can still create isomorphisms for datatypes with higher kinds, such as Maybe and Vec. This works by creating an isomorphism with a "hole" (exploiting the fact that the environment need not be empty), then wrapping it in a lambda.

Instead of defining the structure of the Maybe type as a code with higher kind (i.e., something of type Ty $(\star \Rightarrow \star)$, such as option from Section 3.1), we instead define its structure as a function from codes to codes.

```
\begin{array}{ll} \mathsf{maybeDef} \,:\, \{\mathsf{G} \,:\, \mathsf{Ctx}\} \to \mathsf{Typ} \; \mathsf{G} \star \to \mathsf{Typ} \; \mathsf{G} \star \\ \mathsf{maybeDef} \; t \,=\, (\mathsf{App} \; (\mathsf{App} \; (\mathsf{Con} \; \mathsf{Sum}) \; (\mathsf{Con} \; \mathsf{Unit})) \; t) \end{array}
```

The conversions to and from the Maybe type are also parameterized by the code of the argument to Maybe.

```
 \begin{array}{l} \text{toMaybe} : \left\{ \mathsf{G} : \mathsf{Ctx} \right\} \left\{ \mathsf{e} : \mathsf{Env} \, \mathsf{G} \right\} \\ & \to (\mathsf{t} : \mathsf{Typ} \, \mathsf{G} \, \star) \\ & \to (\mathsf{interp} \, (\mathsf{maybeDef} \, \mathsf{t}) \, \mathsf{e}) \to \mathsf{Maybe} \, (\mathsf{interp} \, \mathsf{t} \, \mathsf{e}) \\ \mathsf{toMaybe} \, \mathsf{t} \, (\mathsf{inj}_1 \, \bot) & = \; \mathsf{nothing} \\ \mathsf{toMaybe} \, \mathsf{t} \, (\mathsf{inj}_2 \, \mathsf{x}) & = \; \mathsf{just} \, \mathsf{x} \\ \mathsf{fromMaybe} \, \mathsf{t} \, \left\{ \mathsf{G} : \, \mathsf{Ctx} \right\} \left\{ \mathsf{e} : \, \mathsf{Env} \, \mathsf{G} \right\} \to (\mathsf{t} : \, \mathsf{Typ} \, \mathsf{G} \, \star) \\ & \to \; \mathsf{Maybe} \, (\mathsf{interp} \, \mathsf{t} \, \mathsf{e}) \\ & \to (\mathsf{interp} \, (\mathsf{maybeDef} \, \mathsf{t}) \, \mathsf{e}) \\ \mathsf{fromMaybe} \, \mathsf{t} \, (\mathsf{just} \, \mathsf{x}) & = \; \mathsf{inj}_2 \, \mathsf{x} \\ \mathsf{fromMaybe} \, \mathsf{t} \, \mathsf{nothing} & = \; \mathsf{inj}_1 \, \mathsf{tt} \\ \end{array}
```

Finally, we form the code of the datatype itself by wrapping the Data constructor in a Lam and using variable zero for the parameter. The environments supplied to s, to and from allow us to specify the type this variable corresponds to.

```
\begin{array}{ll} \mathsf{maybe} \,:\, \{\mathsf{G}\,:\, \mathsf{Ctx}\} \to \mathsf{Typ}\; \mathsf{G}\; (\star \Rightarrow \star) \\ \mathsf{maybe}\; \{\mathsf{G}\} \,=\, \mathsf{Lam}\; (\mathsf{Data}\\ (\mathsf{mkDT}\; (\mathsf{maybeDef}\; (\mathsf{Var}\; \mathsf{VZ})) \\ (\lambda\; \mathsf{e} \quad \to \mathsf{Maybe}\; (\mathsf{interp}\; (\mathsf{Var}\; \mathsf{VZ})\; \mathsf{e})) \\ (\lambda\; \{\mathsf{e}\} \to \mathsf{toMaybe} \quad \{\star ::\; \mathsf{G}\}\; \{\mathsf{e}\}\; (\mathsf{Var}\; \mathsf{VZ})) \\ (\lambda\; \{\mathsf{e}\} \to \mathsf{fromMaybe}\; \{\star ::\; \mathsf{G}\}\; \{\mathsf{e}\}\; (\mathsf{Var}\; \mathsf{VZ})))) \end{array}
```

We can use this same idea to encode vectors. Because we know the length of given vector, it is isomorphic to an n-tuple—a sequence of products terminated by unit. The code for the vector type then abstracts both the code for the type of the elements of the vector and a natural number for its length.

```
\mathsf{vecDef} \,:\, \{\mathsf{G} \,:\, \mathsf{Ctx}\} \to \mathsf{Typ}\; \mathsf{G} \star \to (\mathsf{n} \,:\, \mathbb{N}) \to \mathsf{Typ}\; \mathsf{G} \star
vecDef = 0 = Con Unit
vecDef t (suc n) =
   (App (App (Con Prod) t) (vecDef t n))
from Vec : \{n : \mathbb{N}\} \{G : Ctx\}
                  \{t : Typ G \star\} \{e : Env G\}
               \rightarrow Vec (interp t e) n \rightarrow (interp (vecDef t n) e)
fromVec {0}
from Vec \{suc n\} (x :: xs) = (x, from Vec xs)
to Vec: \{n : \mathbb{N}\} \{G : Ctx\} \{t : Typ G \star\} \{e : Env G\}
         \rightarrow interp (vecDef t n) e \rightarrow Vec (interp t e) n
toVec {0} _
                            = []
toVec {suc n} (x, xs) = (x :: toVec xs)
\mathsf{vec} \ : \ \{\mathsf{G} \ : \ \mathsf{Ctx}\} \to \{\mathsf{n} \ : \ \mathbb{N}\} \to \mathsf{Typ} \ \mathsf{G} \ (\star \Rightarrow \star)
vec \{G\} \{n\} = Lam (Data)
   (mkDT (vecDef (Var VZ) n)
```

$$\begin{array}{l} (\lambda \; e \; \rightarrow \; Vec \; (interp \; (Var \; VZ) \; e) \; n) \\ to Vec \\ from Vec)) \end{array}$$

Lists are somewhat trickier to represent. The type of a list does not tell us its length, so the direct recursive representation of List is an infinite structure. Agda's termination checker will be unable to prove that uses of this representation terminate. Another option is to encode dependent pairs of lists and proofs they have finite lengths, rather than encoding lists directly. Examples of both these encodings are included with our source code.

4.2 Adding Data Support to ngen

Although Data provides a mechanism for coding datatypes, we cannot use it to define generic functions until we extend ngen to handle Data. However, there is a complication—it is not clear how to do so. Without getting too much into the technicalities, the issue is that in this definition we need to produce a result of type⁵

but we only have a value of type

We would like to coerce the latter to the former using to and from, but we know nothing about b. Therefore, we require an additional argument to ngen, to be supplied when the generic operation is defined (i.e., when b is supplied).

$$\begin{array}{l} \mathsf{ngen} \,:\, \{\mathsf{n} \,:\, \mathbb{N}\} \, \{\mathsf{b} \,:\, \mathsf{Vec} \, \mathsf{Set} \, (\mathsf{suc} \, \mathsf{n}) \to \mathsf{Set} \} \, \{\mathsf{k} \,:\, \mathsf{Kind} \} \\ & \to (\mathsf{t} \,:\, \mathsf{Ty} \, \mathsf{k}) \end{array}$$

```
\rightarrow TyConstEnv n b

\rightarrow DataGen b

\rightarrow b \langle k \rangle (repeat | t |)
```

This argument, of type DataGen, shown below, is exactly the coercion function necessary.

```
\begin{array}{l} \mathsf{Data}\mathsf{Gen} \ : \ \{\mathsf{n} \ : \ \mathbb{N}\} \to (\mathsf{b} \ : \ \mathsf{Vec} \ \mathsf{Set} \ (\mathsf{suc} \ \mathsf{n}) \to \mathsf{Set}) \to \mathsf{Set} \\ \mathsf{Data}\mathsf{Gen} \ \{\mathsf{n}\} \ \mathsf{b} \ = \\ \qquad \qquad \{\mathsf{G} \ : \ \mathsf{Ctx}\} \\ \to (\mathsf{dt} \ : \ \mathsf{DT} \ \mathsf{G}) \\ \to (\mathsf{envs} \ : \ \mathsf{Vec} \ (\mathsf{Env} \ \mathsf{G}) \ (\mathsf{suc} \ \mathsf{n})) \\ \to \mathsf{b} \ (\mathsf{repeat} \ (\mathsf{interp} \ (\mathsf{DT-t} \ \mathsf{dt})) \ \circledast \ \mathsf{envs}) \\ \to \mathsf{b} \ (\mathsf{repeat} \ (\mathsf{DT-s} \ \mathsf{dt}) \ \circledast \ \mathsf{envs}) \end{array}
```

As an example of an instance of DataGen, recall the definition of ngmap and its base type NGmap from Section 3.3.

```
\begin{array}{ll} \mathsf{arrTy} \,:\, \{ \, \mathsf{n} \,:\, \mathbb{N} \} \to \mathsf{Vec} \, \mathsf{Set} \, (\mathsf{suc} \, \mathsf{n}) \to \mathsf{Set} \\ \mathsf{arrTy} \, \{ \mathsf{0} \} & (\mathsf{A} ::[]) &= \, \mathsf{A} \\ \mathsf{arrTy} \, \{ \mathsf{suc} \, \mathsf{n} \} \, (\mathsf{A1} ::\, \mathsf{As}) &= \, \mathsf{A1} \to \mathsf{arrTy} \, \mathsf{As} \\ \mathsf{NGmap} \,:\, \{ \mathsf{n} \,:\, \mathbb{N} \} \to \mathsf{Vec} \, \mathsf{Set} \, (\mathsf{suc} \, \mathsf{n}) \to \mathsf{Set} \\ \mathsf{NGmap} \,=\, \mathsf{arrTy} \end{array}
```

The definition of the DataGen coercion for the case where b is NGmap, called ngmap-data below, proceeds by induction on

the arity. In the base case of n=0, ngmap-data must coerce a result from the representation type to the Agda type using the to

⁵ Here b : Vec Set (suc n) \rightarrow Set describes the type of the generic operation and envs : Vec (Env G) (suc n) is a vector of environments for the free variables.

component.

For higher n, ngmap-data is provided with a vector of environments e1 :: es and a function of type:

$$\begin{array}{l} \text{interp (DT-t dt) e1} \\ \rightarrow \text{arrTy (repeat (interp (DT-t dt))} \ \circledast \ \text{es)} \end{array}$$

Its result type is:

$$(\mathsf{DT}\text{-}\mathsf{s}\;\mathsf{dt})\;\mathsf{e}\mathsf{1}\to\mathsf{arr}\mathsf{Ty}\;(\mathsf{repeat}\;(\mathsf{DT}\text{-}\mathsf{s}\;\mathsf{dt})\;\;\circledast\;\;\mathsf{es})$$

This case takes in a (DT-s dt) e1, uses the from function to convert it to an interp (DT-t dt) e1, then coerces the result of the provided function by calling ngmap-data recursively.

```
\begin{array}{ll} \mathsf{ngmap\text{-}data} \,:\, \left\{\mathsf{n} \,:\, \mathbb{N}\right\} \to \mathsf{DataGen} \; (\mathsf{NGmap} \; \left\{\mathsf{n}\right\}) \\ \mathsf{ngmap\text{-}data} \; \left\{\mathsf{0}\right\} & \mathsf{dt} \; (\mathsf{e} :: []) \; \; \mathsf{bt} \; = \; \mathsf{DT\text{-}to} \; \mathsf{dt} \; \mathsf{bt} \\ \mathsf{ngmap\text{-}data} \; \left\{\mathsf{suc} \; \mathsf{n}\right\} \; \mathsf{dt} \; (\mathsf{e1} :: \mathsf{es}) \; \mathsf{bt} \; = \\ \lambda \; \mathsf{x} \to \mathsf{ngmap\text{-}data} \; \left\{\mathsf{n}\right\} \; \mathsf{dt} \; \mathsf{es} \; (\mathsf{bt} \; (\mathsf{DT\text{-}from} \; \mathsf{dt} \; \mathsf{x})) \end{array}
```

4.3 Using ngen at Datatypes

With the ngmap-data function from the previous section, we may instantiate the updated ngen for NGmap.

```
ngmap : (n : \mathbb{N}) \rightarrow \{k : Kind\} \rightarrow (e : Typ [] k) \rightarrow NGmap \{n\} \langle k \rangle \text{ (repeat (interp e []))}ngmap n e = ngen e ngmap-const ngmap-data
```

This new ngmap adds support for datatypes. For example, we may use it with the maybe and vec representations of Section 4.1. Note that vec-map0 is precisely the repeat function we have used throughout this paper.

```
\begin{array}{lll} \mathsf{maybe\text{-}map1} \,:\, \{\mathsf{A}\;\mathsf{B}\;\colon \mathsf{Set}\} \to (\mathsf{A} \to \mathsf{B}) \\ & \to \mathsf{Maybe}\;\mathsf{A} \to \mathsf{Maybe}\;\mathsf{B} \\ \mathsf{maybe\text{-}map1} &= \mathsf{ngmap}\;\mathsf{1}\;\mathsf{maybe} \\ \mathsf{vec\text{-}map0} &:\, \{\mathsf{A}\;\colon \mathsf{Set}\}\; \{\mathsf{n}\;\colon \mathbb{N}\} \to \mathsf{A} \to \mathsf{Vec}\;\mathsf{A}\;\mathsf{n} \\ \mathsf{vec\text{-}map0} &= \mathsf{ngmap}\;\mathsf{0}\;\mathsf{vec} \\ \mathsf{vec\text{-}map1} &:\, \{\mathsf{A}\;\mathsf{B}\;\colon \mathsf{Set}\}\; \{\mathsf{n}\;\colon \mathbb{N}\} \\ & \to (\mathsf{A} \to \mathsf{B}) \to \mathsf{Vec}\;\mathsf{A}\;\mathsf{n} \to \mathsf{Vec}\;\mathsf{B}\;\mathsf{n} \\ \mathsf{vec\text{-}map1} &= \mathsf{ngmap}\;\mathsf{1}\;\mathsf{vec} \end{array}
```

Observe that instantiating ngmap at a datatype is no different than any other type we have seen. The codes for Maybe and Vec work for any generic operation. Although the definition of ngmap needed the DataGen argument, this argument must be implemented once per generic operation, just like TyConstEnv. In contrast, previous work [26] could not define a general code for datatypes like Maybe and Vec, and required significant boilerplate at every instantiation of a generic function with a specific datatype.

5. Other Doubly-Generic Operations

Mapping is not the only arity-generic function. In this section, we examine two others.

5.1 Equality

We saw in Section 3.3 that doubly-generic map must check that its arguments have the same structure. We can define doubly-generic equality in a similar manner. This function takes n arguments, returning true if they are all equal, and false otherwise. Unlike map, equality is not partial for sums as it returns false in the case that the

injections do not match.

In the specific case of vectors, arity-generic equality looks a lot like arity-generic map. Each instance of this function follows the same pattern. Given an n-ary equality function for the type argument, we can define n-ary equality for vectors as:

$$\begin{array}{l} \mathsf{nvec\text{-}eq} \,:\, \left\{\mathsf{m} \,:\, \mathbb{N}\right\} \, \left\{\mathsf{A} \,:\, \mathsf{Set}\right\} \\ \quad \to \left(\mathsf{A} \to \dots \to \mathsf{A} \to \mathsf{Bool}\right) \\ \quad \to \mathsf{Vec} \, \mathsf{A} \, \mathsf{m} \to \dots \to \mathsf{Vec} \, \mathsf{A} \, \mathsf{m} \to \mathsf{Bool} \\ \mathsf{nvec\text{-}eq} \, \mathsf{f} \, \mathsf{v1} \, \dots \, \mathsf{vn} \,=\, \mathsf{all} \, (\mathsf{repeat} \, \mathsf{f} \, \circledast \, \mathsf{v1} \, \circledast \, \dots \, \circledast \, \mathsf{vn}) \end{array}$$

However, again this definition does not help us make equality type-generic as well as arity-generic. For type-genericity, the type of the equality function depends on the kind of the type constructor.

For example, the definition of arity-two equality for natural numbers returns true only if all three match:

$$\mathsf{nat}\text{-}\mathsf{eq2}\,:\,\mathbb{N}\to\mathbb{N}\to\mathbb{N}\to\mathsf{Bool}$$

Likewise, the arity-two equality for pairs requires equalities for all of the components of the pair. Furthermore, the type arguments need not be the same. We can pass any sort of comparison functions in to examine the values carried by the three products.

$$\begin{array}{c} \mathsf{pair\text{-}eq2} \,:\, \big\{\mathsf{A1}\;\mathsf{B1}\;\mathsf{C1}\;\mathsf{A2}\;\mathsf{B2}\;\mathsf{C2}\,:\,\,\mathsf{Set}\big\} \\ \quad \to \big(\mathsf{A1}\to\mathsf{B1}\to\mathsf{C1}\to\mathsf{Bool}\big) \\ \quad \to \big(\mathsf{A2}\to\mathsf{B2}\to\mathsf{C2}\to\mathsf{Bool}\big) \to \\ \quad \to \big(\mathsf{A1}\times\mathsf{A2}\big) \to \big(\mathsf{B1}\times\mathsf{B2}\big) \to \big(\mathsf{C1}\times\mathsf{C2}\big) \to \mathsf{Bool} \end{array}$$

The definition of ngeq, which can define all of these operations, is similar to that of ngmap, so we will only highlight the differences.⁶ One occurs in the definition of the arity-indexed type, NGeq. This function returns a boolean value rather than one of

the provided types, which means that ngeq makes sense even for n = 0. In that case its type is simply Bool.

```
\begin{array}{lll} \mathsf{NGeq} \ : \ \{\mathsf{n} \ : \ \mathbb{N}\} \to (\mathsf{v} \ : \ \mathsf{Vec} \ \mathsf{Set} \ \mathsf{n}) \to \mathsf{Set} \\ \mathsf{NGeq} \ \{\mathsf{zero}\} \ \ [\ ] & = \ \mathsf{Bool} \\ \mathsf{NGeq} \ \{\mathsf{suc} \ \mathsf{n}\} \ (\mathsf{A1} :: \mathsf{As}) \ = \ \mathsf{A1} \to \mathsf{NGeq} \ \mathsf{As} \end{array}
```

Next we must define a TyConstEnv for NGeq. For simplicity, we only show the cases for Unit and Nat. The cases for Prod and Sum are straightforward variations of ngmap. As there is only a single member of the \top type, the case for unit is just a function that takes n arguments and returns true.

```
\begin{array}{ll} \mathsf{defUnit} \,:\, (\mathsf{n} \,:\, \mathbb{N}) \to \mathsf{NGeq} \; (\mathsf{repeat} \; \top) \\ \mathsf{defUnit} \; \mathsf{zero} &= \; \lambda \; \mathsf{x} \to \mathsf{true} \\ \mathsf{defUnit} \; (\mathsf{suc} \; \mathsf{n}) &= \; \lambda \; \mathsf{x} \to \mathsf{defUnit} \; \mathsf{n} \end{array}
```

For natural numbers, ngeq should compare each number and return true only when they all match (or when n is less than 2). We implement this by checking each argument for equality with the next. If a mismatch is found, ngeq uses constFalse, which consumes a given number of arguments and returns false.

```
\begin{array}{l} \mathsf{constFalse} \,:\, \{\,\mathsf{n}\,:\,\mathbb{N}\,\} \to (\mathsf{v}\,:\,\mathsf{Vec}\,\mathsf{Set}\,\mathsf{n}) \to \mathsf{NGeq}\,\mathsf{v} \\ \mathsf{constFalse}\, \{\mathsf{zero}\}\,[\,] \,=\, \mathsf{false} \\ \mathsf{constFalse}\, \{\mathsf{suc}\,\mathsf{m}\}\,(\mathsf{A1}::\,\mathsf{As}) \,=\, \lambda\,\,\mathsf{a} \to \mathsf{constFalse}\,\mathsf{As} \\ \mathsf{defNat}\, :\, (\mathsf{n}\,:\,\mathbb{N}) \to \mathsf{NGeq}\, (\mathsf{repeat}\, \{\mathsf{n}\}\,\mathbb{N}) \\ \mathsf{defNat}\, \mathsf{zero} \,=\, \mathsf{true} \\ \mathsf{defNat}\, (\mathsf{suc}\, \mathsf{zero}) \,=\, \lambda\,\mathsf{x} \to \mathsf{true} \\ \mathsf{defNat}\, (\mathsf{suc}\, \mathsf{zero}) \,=\, \lambda\,\mathsf{x} \to \mathsf{true} \\ \mathsf{defNat}\, (\mathsf{suc}\, (\mathsf{suc}\,\mathsf{n})) \,=\, \\ \lambda\,\mathsf{x} \to \lambda\,\,\mathsf{y} \to \mathsf{if}\, \mathsf{eqNat}\,\mathsf{x}\,\mathsf{y}\, \mathsf{then}\, \mathsf{defNat}\, (\mathsf{suc}\,\mathsf{n})\,\mathsf{y} \\ \qquad \qquad \qquad \mathsf{else}\, \mathsf{constFalse}\, (\mathsf{repeat}\,\,\mathbb{N}) \\ \end{array}
```

Finally, because we wish to use ngeq at various Agda datatypes, we must define an instance of DataGen from Section 4. As before, we go by recursion on the arity. Since NGeq is an n-ary function of representable types, we simply take in each argument, use the provided DT isomorphism to coerce it to the appropriate type, and recurse:

```
\begin{array}{ll} \mathsf{ngeq\text{-}data} \ : \ \{\mathsf{n} \ : \ \mathbb{N}\} \to \mathsf{Data}\mathsf{Gen} \ (\mathsf{NGeq} \ \{\mathsf{suc} \ \mathsf{n}\}) \\ \mathsf{ngeq\text{-}data} \ \{\mathsf{0}\} & \mathsf{dt} \ (\mathsf{e} :: []) \ \mathsf{bt} \ = \end{array}
```

```
\begin{array}{l} \lambda \; \mathsf{s} \to \mathsf{bt} \; (\mathsf{DT\text{-}from} \; \mathsf{dt} \; \mathsf{s}) \\ \mathsf{ngeq\text{-}data} \; \{ \mathsf{suc} \; \mathsf{n} \} \; \mathsf{dt} \; (\mathsf{e} :: \mathsf{es}) \; \mathsf{bt} \; = \\ \lambda \; \mathsf{s} \to \mathsf{ngeq\text{-}data} \; \mathsf{dt} \; \mathsf{es} \; (\mathsf{bt} \; (\mathsf{DT\text{-}from} \; \mathsf{dt} \; \mathsf{s})) \end{array}
```

With these pieces defined, the definition of ngeq is a straightforward application of ngen:

```
ngeq : (n : \mathbb{N}) \rightarrow \{k : Kind\} \rightarrow (e : Ty k) \rightarrow NGeq \langle k \rangle (repeat \{suc n\} (\lfloor e \rfloor))ngeq n e = ngen e ngeq-const ngeq-data
```

5.2 Splitting

The Haskell prelude and standard library include the functions

```
\begin{array}{lll} unzip & :: [(a,b)] & \to ([a],[b]) \\ unzip3 :: [(a,b,c)] & \to ([a],[b],[c]) \\ unzip4 :: [(a,b,c,d)] & \to ([a],[b],[c],[d]) \\ unzip5 :: [(a,b,c,d,e)] & \to ([a],[b],[c],[d],[e]) \\ unzip6 :: [(a,b,c,d,e,f)] & \to ([a],[b],[c],[d],[e],[f]) \end{array}
```

⁶ The complete definition may be found in ngeq.agda with our sources.

suggesting that there should be an arity-generic version of unzip that unifies all of these definitions.

Furthermore, it makes sense that we should be able to unzip data structures other than lists, such as Maybes or Trees.

```
unzipMaybe :: Maybe (a, b) \rightarrow (Maybe \ a, Maybe \ b)
unzipTree :: Tree (a, b) \rightarrow (Tree \ a, Tree \ b)
```

Indeed, unzip is also datatype-generic, and Generic Haskell includes the function gunzipWith that can generate arity-one unzips for any type constructor.

Here, we describe the definition of ngsplit, which generates unzips for arbitrary data structures at arbitrary arities. In some sense, ngsplit is the dual to ngmap. Instead of taking in n arguments (with the same structure) and combining them together to a single result, split takes a single argument and distributes it to n results, all with the same structure.

For example, here is an instance of ngsplit, specialized to the Option type and arity 2. Note that this function is more general than unzipMaybe above, the Maybes need not contain pairs so long as we have some way to split the data.

```
unzipWithMaybe2 : \{A \ B \ C : Set\} \rightarrow (A \rightarrow B \times C)
 \rightarrow (Maybe \ A \rightarrow Maybe \ B \times Maybe \ C)
unzipWithMaybe2 = ngsplit 2 maybe
```

The definition of unzipWith gives us unzip when applied to the identity function.

$$\begin{array}{l} \mathsf{unzipMaybe2} \,:\, \{\mathsf{A}\;\mathsf{B}\,:\, \mathsf{Set}\} \to \mathsf{Maybe}\; (\mathsf{A}\times\mathsf{B}) \\ \to (\mathsf{Maybe}\;\mathsf{A}\times\mathsf{Maybe}\;\mathsf{B}) \end{array}$$

```
unzipMaybe2 = unzipWith2 (\lambda \times \rightarrow x)
```

The function NGsplit gives the type of ngsplit at base kinds. The first type in the vector passed to NGsplit is the type to split. The subsequent types are those the first type will be split into. If there is only one type, the function returns unit. The helper function prodTy folds the \times constructor across a vector of types.

```
\begin{array}{lll} \mathsf{prodTy} \,:\, \{\mathsf{n}\,:\, \mathbb{N}\} \to (\mathsf{As}\,:\, \mathsf{Vec}\,\,\mathsf{Set}\,\,\mathsf{n}) \to \mathsf{Set} \\ \mathsf{prodTy}\, \{\mathsf{0}\} & \_ & = \, \top \\ \mathsf{prodTy}\, \{\mathsf{1}\} & (\mathsf{A}::\, [\,]) & = \, \mathsf{A} \\ \mathsf{prodTy}\, \{\mathsf{suc}\,\,(\mathsf{suc}\,\,\_)\}\,\, (\mathsf{A}::\, \mathsf{As}) & = \, (\mathsf{A}\times\mathsf{prodTy}\,\,\mathsf{As}) \end{array}
```

NGsplit :
$$\{n : \mathbb{N}\} \rightarrow (v : Vec Set (suc n)) \rightarrow Set$$

NGsplit $(A1 :: As) = A1 \rightarrow prodTy As$

The cases for Nat and Unit are straightforward, so we do not show them. They simply make n copies of the argument.

To split a product (x,y), we first split x and y, then combine together the results. For this combination, product takes arguments of types $(A1 \times A2 \times ... \times An)$ and $(B1 \times B2 \times ... \times Bn)$ and forms a result of type $(A1 \times B1) \times (A2 \times B2) \times ... \times (An \times Bn)$.

```
\begin{array}{lll} \mathsf{prodn} \, : \, \big\{ \mathsf{n} \, : \, \mathbb{N} \big\} \, \to \, (\mathsf{As} \, \mathsf{Bs} \, : \, \mathsf{Vec} \, \mathsf{Set} \, \mathsf{n}) \\ & \to \mathsf{prod} \mathsf{Ty} \, \mathsf{As} \, \to \mathsf{prod} \mathsf{Ty} \, \mathsf{Bs} \\ & \to \mathsf{prod} \mathsf{Ty} \, (\mathsf{repeat} \, \_ \times \_ \, \circledast \, \, \mathsf{As} \, \circledast \, \, \mathsf{Bs}) \\ \mathsf{prodn} \, \big\{ \mathsf{0} \big\} \, \_ \, & = \, \mathsf{a} \, \mathsf{b} \, = \, \mathsf{tt} \\ \mathsf{prodn} \, \big\{ \mathsf{1} \big\} \, \big( \mathsf{A} :: \, [\,] \big) \, \big( \mathsf{B} :: \, [\,] \big) \, \mathsf{a} \, \mathsf{b} \, = \, (\mathsf{a}, \mathsf{b}) \\ \mathsf{prodn} \, \big\{ \mathsf{suc} \, (\mathsf{suc} \, \mathsf{n}) \big\} \, \big( \mathsf{A} :: \, \mathsf{As} \big) \, \big( \mathsf{B} :: \, \mathsf{Bs} \big) \, \big( \mathsf{a}, \mathsf{as} \big) \, \big( \mathsf{b}, \mathsf{bs} \big) \, = \\ & \big( (\mathsf{a}, \mathsf{b}), \mathsf{prodn} \, \big\{ \mathsf{suc} \, \mathsf{n} \big\} \, \_ \, \_ \, \mathsf{as} \, \mathsf{bs} \big) \end{array}
```

```
\begin{array}{c} \mathsf{defPair} \,:\, (\mathsf{n} \,:\, \mathbb{N}) \\ \qquad \to (\mathsf{As} \,:\, \mathsf{Vec} \, \mathsf{Set} \, (\mathsf{suc} \, \mathsf{n})) \to (\mathsf{NGsplit} \, \mathsf{As}) \\ \qquad \to (\mathsf{Bs} \,:\, \mathsf{Vec} \, \mathsf{Set} \, (\mathsf{suc} \, \mathsf{n})) \to (\mathsf{NGsplit} \, \mathsf{Bs}) \\ \qquad \to \mathsf{NGsplit} \, (\mathsf{repeat} \, \_ \times \_ \, \circledast \, \mathsf{As} \, \circledast \, \mathsf{Bs}) \\ \mathsf{defPair} \, \mathsf{n} \, (\mathsf{A} :: \mathsf{As}) \, \mathsf{a} \, (\mathsf{B} :: \, \mathsf{Bs}) \, \mathsf{b} \, = \\ \qquad \lambda \, \mathsf{p} \to \mathsf{prodn} \, \{\mathsf{n}\} \, \_ \, (\mathsf{a} \, (\mathsf{proj}_1 \, \mathsf{p})) \, (\mathsf{b} \, (\mathsf{proj}_2 \, \mathsf{p})) \end{array}
```

The case for sums scrutinizes the argument to see if it is a left or right injection, and uses the appropriate provided function to split the inner expression. Then we use either injLeft or injRight (elided), which simply map inj_1 or inj_2 onto the members of the resulting tuple.

The definition of split-const (elided) dispatches to the branches above in the standard way, delegating to a trivial case when n is 0. Finally, we must define an instance of DataGen so that we may use ngsplit at representable Agda datatypes. Since NGsplit is defined in terms of prodTy, we must also convert instances of that type. These (elided) functions are similar to previous examples, except that we are converting a pair instead of an arrow. With split-const

and split-data, we can define ngsplit as usual.

Splitting is a good example of datatype-generic programming's potential to save time and eliminate errors. Defining a separate instance of split for vectors is not simple. For example, we would need a function to transpose vectors of products, transforming Vec m (A1 \times A2 \times ... \times An) into (Vec A1 m \times Vec A2 m \times ... \times Vec An m). This code is slightly tricky and potentially error-prone, but with generic programming we get the vector split for free. Moreover, we may reason once about the correctness of the general definition of split rather than reasoning individually about each of its arity and type instances.

5.3 More Operations

Mapping, equality and splitting provide three worked out examples of doubly generic functions. We know of a few others, such as a monadic map, a map that returns a Maybe instead of an error when the Sum injections do not match, a comparison function, and an equality function that returns a proof that the arguments are all equal. Furthermore, there are arity-generic versions of standard Generic Haskell functions like crushes or enumerations. For example, an arity-generic gsum adds together all of the numbers found in n data structures. Such examples seem less generally useful than arity-generic map or unzip, but are not difficult to define.

Compared to the space of datatype-generic functions, the space of doubly generic operations is limited. This is unsurprising, as there already were not many examples of Generic Haskell functions with arities greater than one. However, this work has given us new insight into what other doubly-generic functions might look like. Furthermore, though the collection of doubly-generic functions is small, this is no reason not to study it. Indeed, it includes some of

the most fundamental operations of functional programming, and it makes sense that we should learn as much as we can about these operations.

6. Related Work

Only a few sources discuss arity-generic programming. Fridlender and Indrika [7] show how to encode n-ary list map in Haskell, using a Church encoding of numerals to reflect the necessary type dependencies. They remark that a generic programming language could provide a version of zipWith that works for arbitrary datatypes, but that no existing language provides such functionality. They also mention a few other arity-generic programs: taut which determines whether a boolean expression of n variables is a tautology, and variations on liftM, curry and uncurry from the Haskell prelude. It is not clear whether any of these functions could be made datatype-generic. McBride [14] shows an alternate encoding of arity-generic list map in Haskell using type classes to achieve better safety properties. He examines several other families of operations, like crush and sum, but does not address type genericity.

Many Scheme functions, such as map, are arity-generic (or variable-arity, in Scheme parlance). Strickland et al. [24] extend Typed Scheme with support for variable-arity polymorphism by adding new forms for variable-arity functions to the type language. They are able to check many examples, but do not consider datatype-genericity.

Sheard [22] translates Fridlender and Indrika's example to the Ω mega programming language, using that language's native indexed datatypes instead of the Church encoding. He also demonstrates one other arity-generic program, n-ary addition. Although

the same work also includes an implementation of datatype-generic programming in Ω mega, the two ideas are not combined.

Several researchers have used dependent types (or their encodings) to implement Generic-Haskell-style datatype-genericity. In previous work, we encoded representations of types using Church encodings [28] and GADTs [29] and showed how to implement a number of datatype-generic operations such as map. Hinze [10], inspired by this approach, gave a similar encoding based on type classes. In those encodings, doubly-generic programming is not possible because datatype-generic programs of different arities require different representations or type classes.

The most closely related encoding of Generic Haskell to this one is by Verbruggen et al. [26]. They use the Coq programming language to define a framework for generic programming, but do not consider arity-genericity. Altenkirch and McBride [1] show a similar development in Oleg. This work extends those developments by considering examples not possible in Generic Haskell and showing a technique for writing generic programs which work on source-language datatypes.

The idea of generic programming in dependent type theory via universes has seen much attention since it was originally proposed [13, 18]. While demonstrating a new form of double genericity, this paper covers only one part of what is possible in a dependently typed language. In particular, our codes do not extend to all inductive families and so we cannot represent all types that are available (see Benke et al. [2] and Morris et al. [17] for more expressive universes). A dependently-typed language also permits the definition of generic proofs about generic programs. Chlipala [4] uses this technique in the Coq proof assistant to generically define and prove substitution properties of programming languages. Ver-

bruggen et al. [27] use Coq's dependent types to develop a framework for proving properties about generic programs.

7. Discussion

Generic programming in a dependently-typed language As we mentioned in the introduction, there are several dependently-typed languages that we could have used for this development. We selected Agda because the focus of its design has been this sort of programming. Like Coq, Agda is a full-spectrum dependently typed language. That has allowed us the flexibility to use universes to directly implement generic programming. We had the full power of the computational language available to express the relationships between values and types. A phase-sensitive language, such as Ω mega or Haskell, would have required singletons to reflect computation to the type level, and would have permitted type-level computation only in a restricted language.

Compared to Coq, Agda has more vigorous type inference, especially combined with pattern matching. Although Coq can also infer implicit arguments, if we had written the functions in Coq we would have had to add many more type annotations. Additionally, developing in Agda allowed us to deal with non-termination more conveniently—while Coq must be able to see that a definition terminates before moving on, Agda shows the user where it can not prove termination and allows other work to continue.

On the other hand, using Coq would have lead to two advantages. Coq's tactic language can be used to automate some of the reasoning. Tactics would have been particularly useful in proving some of the equalities needed to typecheck the (elided) implementation of ngen. However, we did not see any need for tactics in any

of the *uses* of ngen to define doubly-generic operations. More importantly, as discussed below, differences in the way Coq and Agda handle type levels forced us to use Agda's --type-in-type flag to clarify the presentation.

Type levels in Agda Although we have hidden it, Agda actually has an infinite hierarchy of type levels. Set, also known as Set0, is the lowest level in the type hierarchy. Terms like Set0 and Set0 \rightarrow Set0 have type Set1, which itself has type Set2, etc.

To simplify our exposition, we collapsed all of these levels to the type Set, with the help of the --type-in-type flag. This flag makes Agda's logic inconsistent, so to demonstrate that we are not using it in an unsound way, we have also implemented a version of the code that may be compiled without the flag. That version can be found in the notypeintype subdirectory of our source tarball.

Three differences between Coq and Agda make this explicit version more complicated than the one presented here. First, Agda currently lacks *universe polymorphism* [9], a feature which allows definitions to work on multiple type levels. As a result, many of the data structures in this paper must actually be duplicated at the level of Set1, creating significant clutter. Second, since Set is not impredicative in Agda, many definitions that could live at the level of Set in Coq must be at the level of Set1 instead. Finally, because Set0 is not a subtype of Set1 in Agda, we found it necessary to explicitly lift types from Set0 to Set1.

Future work and Conclusions Because we are working in the flexible context of a dependently-typed programming language, our work here will allow us to adapt and extend orthogonal results in generic programming to this framework. For example, we would like to use Agda as a proof assistant to reason about the properties

of the generic programs that we write. We would also like to extend our universe so that it may encode more of Agda's type system, such as arbitrary indexed datatypes. Finally, we would like to gain more experience with doubly-generic programming by creating and analyzing additional examples.

In this paper, we have combined arity-generic and datatypegeneric programming into a single framework. Crucially, this combination takes advantage of the natural role that arities play in the definition of kind-indexed types. This framework has provided us with new understanding of the definition and scope of doublygeneric programs.

Acknowledgments Thanks to Andres Löh and Tim Sheard for discussion, and to the anonymous reviewers for many helpful comments. This paper was generated from literate Agda sources using lhs2TeX

References

- [1] Thorsten Altenkirch and Conor McBride. Generic programming within dependently typed programming. In *Proceedings of the IFIP TC2 Working Conference on Generic Programming*, Dagstuhl, Germany, July 2003.
- [2] Marcin Benke, Peter Dybjer, and Patrik Jansson. Universes for generic programs and proofs in dependent type theory. *Nordic Journal of Computing*, 10(4):265–289, 2003.
- [3] Manuel M. T. Chakravarty, Gabriele Keller, and Simon Peyton Jones. Associated type synonyms. In *ICFP '05: Proceedings of the Tenth ACM SIGPLAN International Conference on Functional Programming*, pages 241–253, New York, NY, USA, 2005. ACM.
- [4] Adam Chlipala. A certified type-preserving compiler from lambda

- calculus to assembly language. In *PLDI '07: Proceedings of the 2007 ACM SIGPLAN Conference on Programming Language Design and Implementation*, pages 54–65, New York, NY, USA, 2007. ACM.
- [5] Dave Clarke, Ralf Hinze, Johan Jeuring, Andres Löh, and Jan de Wit. The Generic Haskell user's guide. Technical Report UU-CS-2001-26, Utrecht University, 2001.
- [6] Bruno C. d. S. Oliveira, Ralf Hinze, and Andres Loeh. Extensible and modular generics for the masses. In Henrik Nilsson, editor, *Trends in Functional Programming (TFP 2006)*, April 2007.
- [7] Daniel Fridlender and Mia Indrika. Do we need dependent types? *Journal of Functional Programming*, 10(4):409–415, July 2000.
- [8] Jean-Yves Girard. Interprétation fonctionelle et élimination des coupures de l'arithmétique d'ordre supérieur. PhD thesis, Université Paris VII, 1972.
- [9] Robert Harper and Robert Pollack. Type checking with universes. *Theoretical Computer Science*, 89:107–136, 1991.
- [10] Ralf Hinze. Generics for the masses. *Journal of Functional Programming*, 16(4-5):451–483, 2006.
- [11] Ralf Hinze. Polytypic values possess polykinded types. *Science of Computer Programming*, 43(2–3):129–159, 2002. MPC Special Issue.
- [12] Ralf Hinze and Johan Jeuring. Generic Haskell: Practice and theory. In Roland Backhouse and Jeremy Gibbons, editors, Generic Programming, Advanced Lectures, volume 2793 of Lecture Notes in Computer Science, pages 1–56. Springer-Verlag, 2003.
- [13] Per Martin-Löf. Intuitionistic Type Theory. Bibliopolis-Napoli, 1984.
- [14] Conor McBride. Faking it: Simulating dependent types in haskell. *Journal of Functional Programming*, 12(5):375–392, 2002.
- [15] Conor McBride and James McKinna. The view from the left. *Journal of Functional Programming*, 14(1):69–111, 2004.

- [16] Conor McBride and Ross Paterson. Applicative programming with effects. *Journal of Functional Programming*, 18(1):1–13, 2008.
- [17] Peter Morris, Thorsten Altenkirch, and Neil Ghani. Constructing strictly positive families. In CATS '07: Proceedings of the Thirteenth Australasian Symposium on Theory of Computing, pages 111–121, Darlinghurst, Australia, Australia, 2007. Australian Computer Society, Inc.
- [18] B. Nordström, K. Petersson, and J. Smith. *Programming in Martin-Löf's Type Theory: an introduction*. Oxford University Press, 1990.
- [19] Ulf Norell. Towards a practical programming language based on dependent type theory. PhD thesis, Department of Computer Science and Engineering, Chalmers University of Technology, SE-412 96 Göteborg, Sweden, September 2007.
- [20] Simon Peyton Jones et al. The Haskell 98 language and libraries: The revised report. *Journal of Functional Programming*, 13(1):0-255, Jan 2003. http://www.haskell.org/definition/.
- [21] Simon L. Peyton Jones, Dimitrios Vytiniotis, Stephanie Weirich, and Geoffrey Washburn. Simple unification-based type inference for GADTs. In *ICFP '06: Proceedings of the Eleventh ACM SIGPLAN International Conference on Functional Programming*, pages 50–61, Portland, OR, USA, September 2006.
- [22] Tim Sheard. Generic programming programming in omega. In Roland Backhouse, Jeremy Gibbons, Ralf Hinze, and Johan Jeuring, editors, *Datatype-Generic Programming*, volume 4719 of *Lecture Notes in Computer Science*, pages 258–284. Springer, 2006.
- [23] Tim Sheard. Putting Curry-Howard to work. In Proceedings of the ACM SIGPLAN 2005 Haskell Workshop. ACM Press, September 2005.
- [24] T. Stephen Strickland, Sam Tobin-Hochstadt, and Matthias Felleisen. Practical variable-arity polymorphism. In ESOP '09: Proceedings of

- the Eighteenth European Symposium On Programming, pages 32–46, March 2009.
- [25] The Coq Development Team. The Coq Proof Assistant Reference Manual, Version 8.1. LogiCal Project, 2006. Available from http://coq.inria.fr/V8.1beta/refman/.
- [26] Wendy Verbruggen, Edsko de Vries, and Arthur Hughes. Polytypic programming in Coq. In WGP '08: Proceedings of the ACM SIGPLAN Workshop on Generic Programming, pages 49–60, New York, NY, USA, 2008. ACM.
- [27] Wendy Verbruggen, Edsko de Vries, and Arthur Hughes. Polytypic properties and proofs in Coq. In WGP '09: Proceedings of the 2009 ACM SIGPLAN Workshop on Generic Programming, pages 1–12, New York, NY, USA, 2009. ACM.
- [28] Stephanie Weirich. Type-safe run-time polytypic programming. *Journal of Functional Programming*, 16(10):681–710, November 2006.
- [29] Stephanie Weirich. RepLib: A library for derivable type classes. In Haskell Workshop, pages 1–12, Portland, OR, USA, September 2006.