M20580 L.A. and D.E. Tutorial Worksheet 8

Sections 6.1, 6.2, 6.3, 6.4

1,

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

Denote
$$\alpha_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$
, $\alpha_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}$, $\alpha_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$, these are the three columns of A . Let

 $W = Span\{\alpha_1, \alpha_2, \alpha_3\}.$

(a) Find a basis for W^{\perp} .

According to THM 3 in b.1. W1 is the null space of AT, i.e. the

$$A^{\mathsf{T}} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_1 - \mathbb{R}_2} \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_1 - \mathbb{R}_2} \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbb{R}_2 - \mathbb{R}_3} \begin{bmatrix} 1 & 0$$

(b) Check your answer in (a), i.e. each vector in your basis for W^{\perp} is perpendicular to every α_i (i = 1, 2, 3). Let $\alpha_4 = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$ then $\alpha_4 = \begin{bmatrix} -1$ every α_i (i = 1, 2, 3).

Let
$$04 = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$$
 then $W = Span \{ 04 \}$. $04 \cdot 04$

(c) Use Gram-Schmidt process to find an orthogonal basis for $W = Span\{\alpha_1, \alpha_2, \alpha_3\}$. You need not normalize your basis. (-1)·0+1·1 +(-1)-1

$$X_1 = \alpha_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\mathcal{C}_{2} = \alpha_{2} - \frac{\alpha_{2} \cdot \alpha_{1}}{\alpha_{1} \cdot \alpha_{1}} \stackrel{\alpha_{1}}{=} \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 0 \end{bmatrix}$$

$$\begin{aligned}
\chi_3 &= \alpha_3 - \frac{\alpha_3 \cdot \gamma_2}{\gamma_2 \cdot \gamma_2} \gamma_2 - \frac{\alpha_3 \cdot \gamma_1}{\gamma_1 \cdot \gamma_1} \gamma, & Foy the convenience of further calculation, we may \\
&= \begin{bmatrix} 0 \\ 1 \end{bmatrix} - \frac{1}{3} \cdot \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} - \frac{0}{\gamma_1 \cdot \gamma_1} \cdot \gamma, & take \begin{bmatrix} 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \\
&= \begin{bmatrix} 0 \\ 1 \end{bmatrix} + \begin{bmatrix} -\frac{1}{3} \\ -\frac{1}{3} \end{bmatrix} - 0 = \begin{bmatrix} -\frac{1}{3} \\ \frac{1}{3} \end{bmatrix} \cdot 0 = \begin{bmatrix} -\frac{1}{3}$$

= 0

(d) Let $\beta = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$. Find the orthogonal projection of β onto W, i.e. $proj_W \beta$, using the orthogonal basis you've found in (c).

proj w
$$\beta = \frac{\beta \cdot \beta_1}{\beta_1 \cdot \beta_2} \beta_1 + \frac{\beta \cdot \beta_2}{\beta_2 \cdot \beta_2} \beta_2 + \frac{\beta \cdot \beta_3}{\beta_3 \cdot \beta_3} \beta_3$$
.

where $\left\{\beta_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \beta_2 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}, \beta_3 = \begin{bmatrix} -1 \\ -1 \end{bmatrix} \right\}$ is the ovthogonal basis we've found in (c).

Calculate:
$$\beta = \frac{1}{2} \beta_1 + \frac{-1}{6} \beta_2 + \frac{1}{12} \begin{bmatrix} \beta_3 \\ \frac{1}{2} \end{bmatrix} + \begin{bmatrix} \frac{1}{6} \\ -\frac{1}{6} \end{bmatrix} + \begin{bmatrix} \frac{1}{12} \\ \frac{1}{12} \end{bmatrix} = \begin{bmatrix} \frac{3}{4} \\ \frac{1}{4} \end{bmatrix}$$

(e) Find the orthogonal projection of β onto W^{\perp} , i.e. $proj_{W^{\perp}}\beta$, using an orthogonal basis for W^{\perp} .

We know that $proj_{W^{\perp}}\beta = \beta - proj_{W}\beta$, so you may solve this part using (d). But I suggest you to calculate $proj_{W^{\perp}}\beta$ by again using orthogonal projection formula, so that you can practice the formula again.

$$\operatorname{proj}_{W}\beta = \frac{\beta \cdot \alpha_{4}}{\alpha_{4} \cdot \alpha_{4}} \cdot \alpha_{4}$$

$$= \frac{1}{4} \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{4} \end{bmatrix}$$

(f) Using your results of (d) and (e), check that $\beta = proj_W \beta + proj_{W^{\perp}} \beta$. Thus, we get a decomposition of β into two parts, one part is in W, the other part is in W^{\perp} .

Check:
$$\text{proj}_{W}\beta + \text{proj}_{W}\beta = \begin{bmatrix} \frac{1}{4} \\ \frac{1}{4} \end{bmatrix} + \begin{bmatrix} \frac{1}{4} \\ \frac{1}{4} \end{bmatrix} = \begin{bmatrix} \frac{1}{6} \\ \frac{1}{6} \end{bmatrix} = \beta$$

2. Find a least squares solution to the system

$$\begin{bmatrix} 1 & 1 & 3 \\ 2 & -1 & 1 \\ 1 & 1 & -2 \\ 3 & 0 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 2 \end{bmatrix}.$$

Note that the columns a_1, a_2, a_3 of the coefficient matrix A form an **orthogonal** basis for Col A.

$$A^{T}A = \begin{bmatrix} 1 & 2 & 13 \\ 1 & -1 & 10 \\ 3 & 1 & -2 & -1 \end{bmatrix}$$

$$A^{T} \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 13 \\ 0 & -1 & 10 \\ 3 & 1 & -2 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 2 \end{bmatrix}$$

$$A^{T}Ax = \begin{bmatrix} 0 \\ 0 \\ -2 \end{bmatrix}$$

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$$A^{T}Ax = \begin{bmatrix} 0 \\ 0 \\ -2 \end{bmatrix}$$

$$X_{1} = \begin{bmatrix} 0 \\ 0 \\ -2 \end{bmatrix}$$

$$X_{2} = \begin{bmatrix} 0 \\ 0 \\ -2 \end{bmatrix}$$

$$X_{3} = \begin{bmatrix} 0 \\ 0 \\ -2 \end{bmatrix}$$

3. Let

$$A = \begin{bmatrix} 2 & 3 \\ 2 & 4 \\ 1 & 1 \end{bmatrix}$$

Use Gram-Schmidt process to find a orthogonal basis for Col A, and use the orthogonal basis you get to find the QR factorization of A.

$$\alpha_1 = \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$$
 $\alpha_2 = \begin{bmatrix} 3 \\ 4 \\ 1 \end{bmatrix}$

Firstly, we orthogonalize fx, x;]:

Take
$$\beta_1 = \begin{bmatrix} \frac{2}{2} \\ \frac{1}{2} \end{bmatrix}$$

$$\beta_{2} = \beta_{1} = \begin{bmatrix} \frac{3}{4} \\ -\frac{15}{9} \end{bmatrix} = \begin{bmatrix} \frac{3}{4} \\ \frac{1}{9} \end{bmatrix} = \begin{bmatrix} \frac{3}{4} \\ \frac{1}{3} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{3}{4} \\ -\frac{1}{3} \end{bmatrix} = \begin{bmatrix} \frac{1}{3} \\ \frac{1}{3} \end{bmatrix} = \begin{bmatrix} \frac{3}{4} \\ \frac{1}{3} \end{bmatrix}$$

$$So, Q = \begin{bmatrix} \beta_{1} : \beta_{2} \end{bmatrix} = \begin{bmatrix} \frac{2}{4} \\ \frac{3}{3} \end{bmatrix}$$

Suppose
$$A = QR$$
, then $Q^TA = Q^TQR$.

$$Q^{T}A = \begin{bmatrix} 2 & 2 & 1 \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & 3 \\ 2 & 4 \end{bmatrix} = \begin{bmatrix} 0 & 15 \\ 0 & 1 \end{bmatrix}$$

$$Q^{T}Q = \begin{bmatrix} 2 & 2 & 1 \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{2}{3} \end{bmatrix} \cdot \begin{bmatrix} 2 & \frac{2}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}$$

$$\Rightarrow R = (Q^TQ)^{-1} \cdot (Q^TA) = \begin{cases} e^{-\frac{1}{2}} & 0 \\ 0 & 1 \end{cases} \cdot \begin{bmatrix} 9 & 15 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & \frac{3}{3} \\ 0 & 1 \end{bmatrix}.$$