# An introduction to Bayesian statistics

Sensor fusion & nonlinear filtering

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# WHAT IS BAYESIAN STATISTICS?

A statistical inference framework.

 Can be used for estimation, classification, detection, model selection, etc.

 Key characteristic: unknown quantities are described as random.

#### APPLICATIONS OF BAYESIAN STATISTICS

- A medical application: analyze the disease of a patient.
  - Quantity of interest: the disease,  $\theta$ .
  - Observations: blood samples, temperature, comments by patient, etc.



- In Bayesian statistics  $\theta$  is described as random
  - → we can make statements like: "based on our observations, patient has disease X with 97% probability".
- Possible concern: is the disease random?

#### **APPLICATIONS OF BAYESIAN STATISTICS**

- Self-driving vehicles rely on the ability to position surrounding vehicles.
- This enables the system safely navigate its surroundings without causing accidents with other road users.
  - Quantity of interest: relative position and velocity of other vehicles at the current time.
  - Observations: wheel speeds, INS measurements, radar detections (distance and angle), Lidar point clouds, camera images, etc.
- Bayesian statistics: vehicle motions are modelled statistically 
   → helps us to rule out unrealistic trajectories.
- Possible concern: are the vehicle motions random?

#### **COMPARISON: BAYES VS FREQUENTIST**

- There are two main strategies to decision making: Bayesian and frequentist statistics.
- In frequenstist statistics, the quantities of interest are described as unknown and deterministic.

# **Bayes vs Frequentist**

We wish to estimate the height of the Eiffel tower. Is the height random or not?

- Frequentist perspective: the tower has a certain height and is therefore not random.
- Bayesian perspective: we describe our uncertainties in the height stochastically
  height is described as random!



### **OVERVIEW OF THE BAYESIAN STRATEGY**

Suppose we wish to estimate  $\theta$  given measurements y.

## Key steps in a Bayesian method:

- 1. **Modeling.** Model what we know about  $\theta$  (using a prior  $p(\theta)$ ) and the how the measurements y relate to  $\theta$  (using a density  $p(y|\theta)$ ).
- 2. **Measurement update.** Combine what we knew before (the prior) with our measurement (with  $p(y|\theta)$ , also called the likelihood) to summarize what we know about  $\theta$  ( $p(\theta|y)$ ).
- 3. **Decision making.** Given what we know about  $\theta$  (described by  $p(\theta|y)$ ) and a loss function, we compute an optimal decision.

## **SELF-ASSESSMENT QUESTIONS**

Which of the following statements are correct:

- Bayesian methods can be used to solve many types of decision making problems including estimation, detection and classification.
- We can model the height of the Eiffel tower as random only if we think that there are many similar towers with different heights.
- In Bayesian statistics we describe what we know about  $\theta$  (the quantity of interest) before observing any measurements.

Check all that apply.