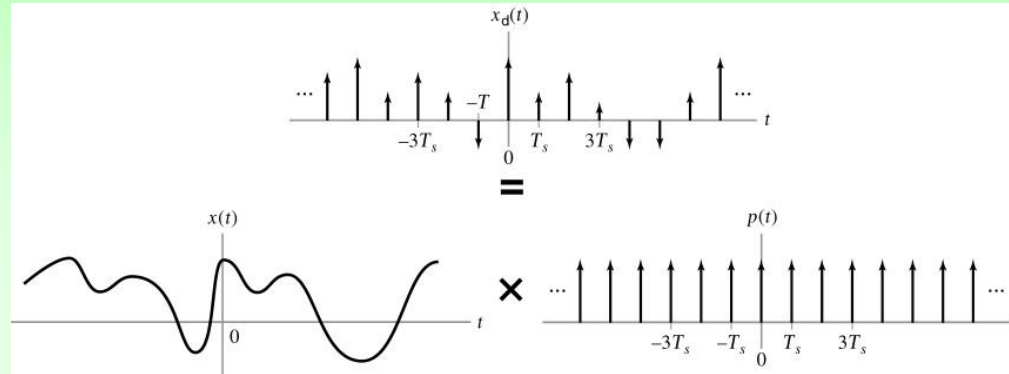

Image Interpolation

Lecturer: Sang Hwa Lee

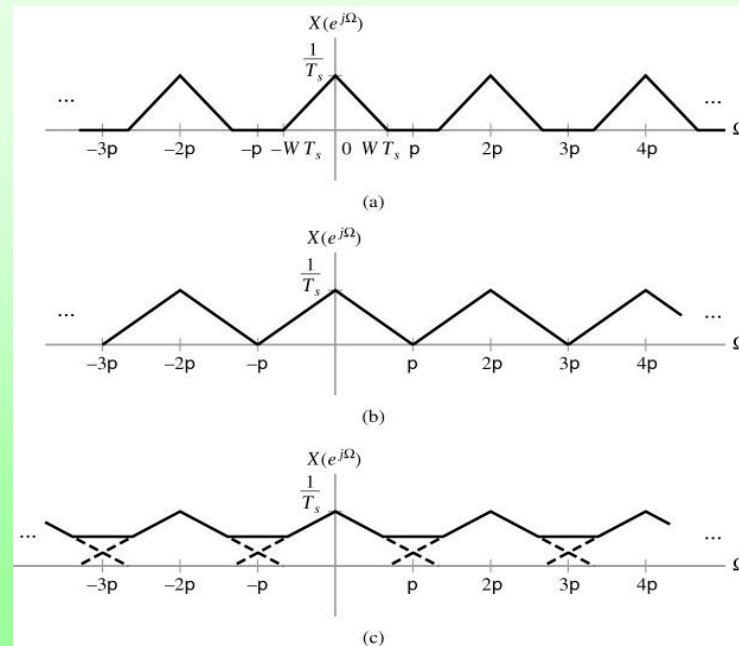
Introduction (I)

□ Sampling

Sampling
in the time domain



Sampling
in the frequency domain

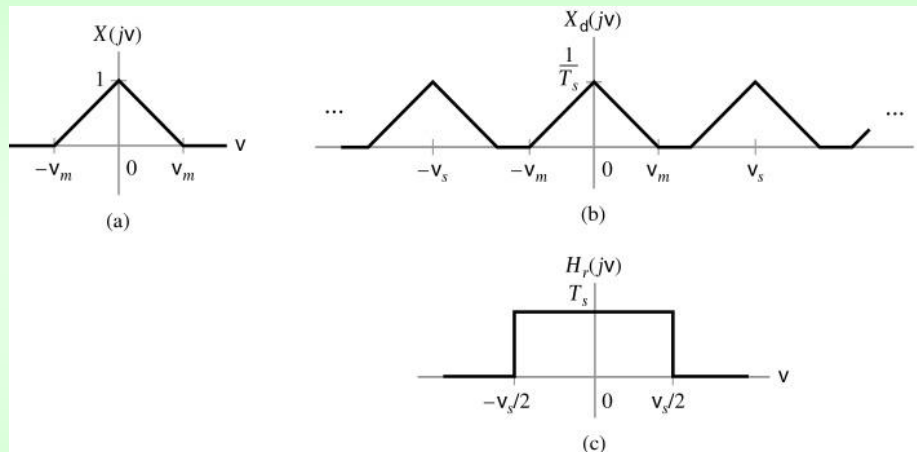


$$T=1/f$$

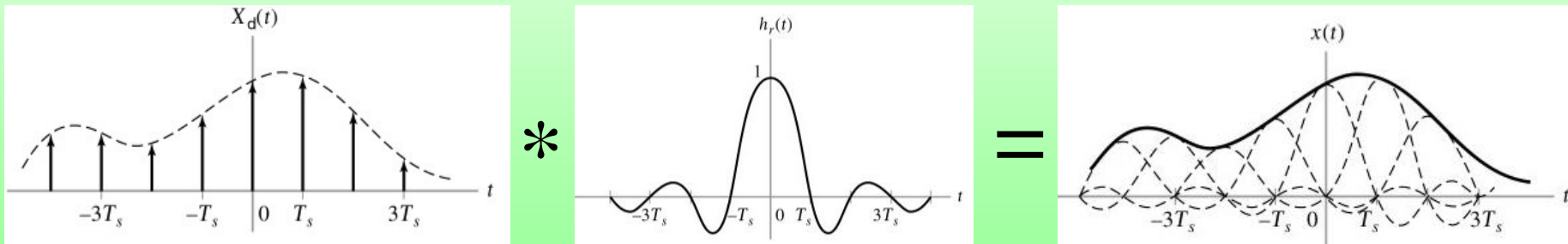
Introduction (II)

□ Reconstruction

◆ Reconstruction in the frequency domain

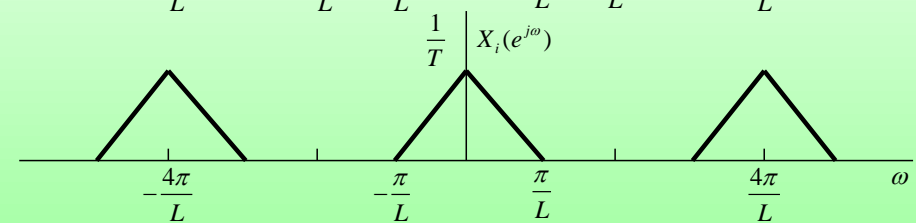
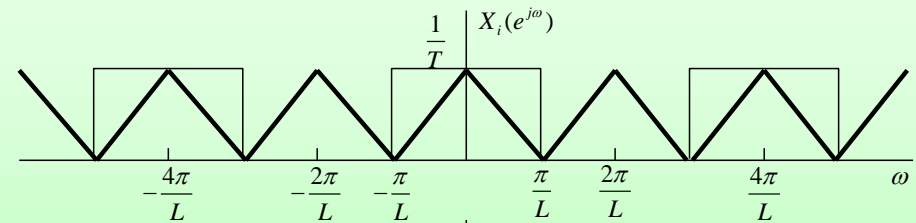
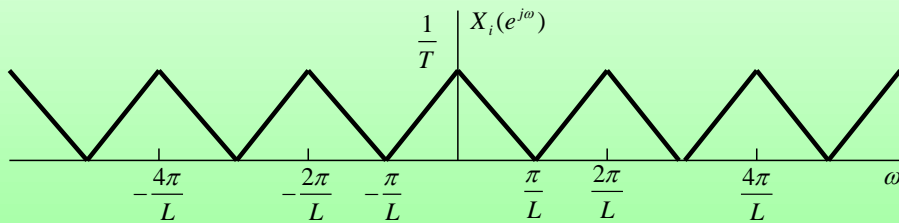
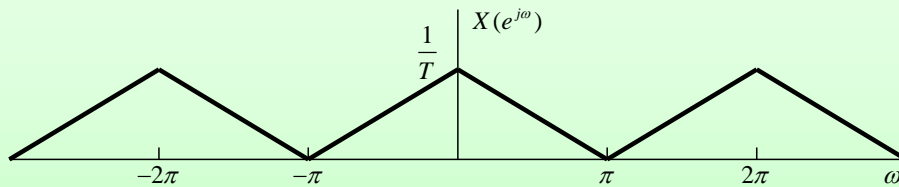
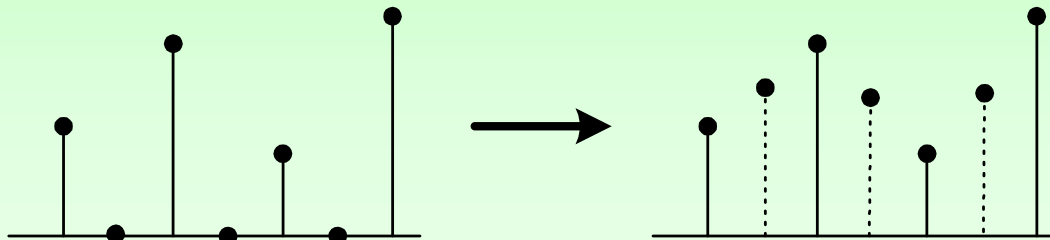


◆ Reconstruction in the time domain



Interpolation (I)

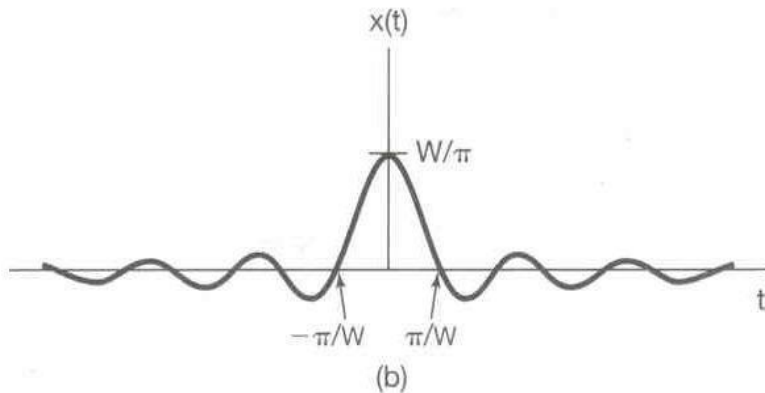
□ Interpolation in a view of DSP



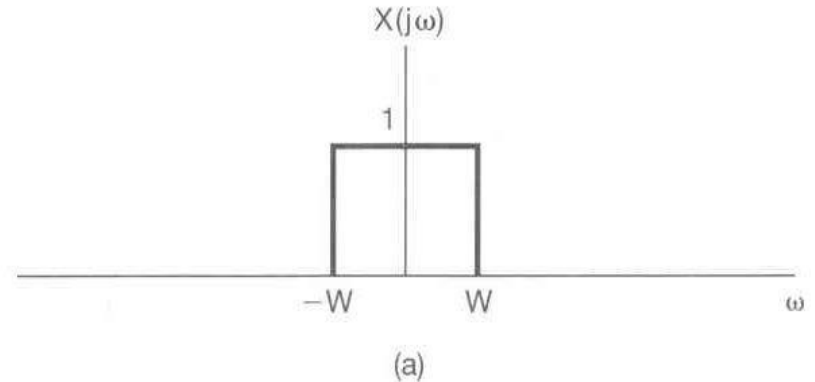
Interpolation (II)

□ Ideal LPF (sinc/rectangular function)

- Ideal interpolation when the signal is bandlimited.



Time domain (Sinc function)



Frequency domain (Rectangular function)

Interpolation (III)

□ Why is the interpolation required ?

- The sampled signal is not bandlimited.
 - An image usually consists of all frequency components.
- Ideal low pass filter can't be implemented
 - Non-causal, infinite length (IIR)

□ Interpolation problem

- Design of FIR filter which approximate the ideal LPF
 - The interpolators approach sinc function in spatial domain.
- Spatially adaptive filter design
 - Spatially varying frequency components
- Anti-aliasing filtering

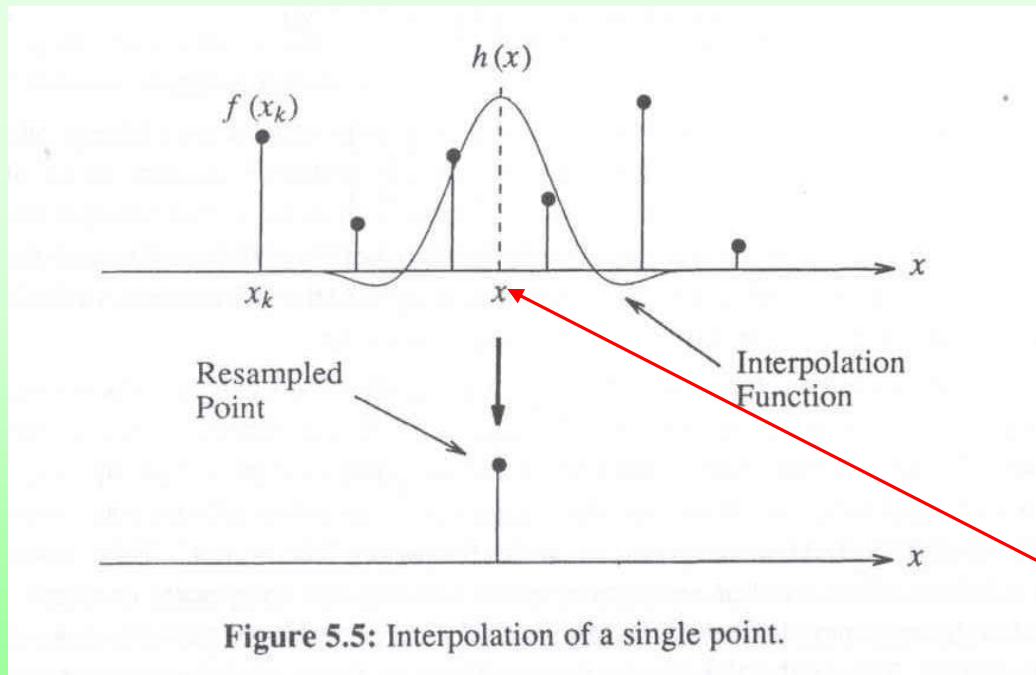
□ Two aspects in interpolation

- Restoration vs Enhancement

Interpolation (IV)

□ What is the interpolation ?

- Convert discrete signals to continuous ones
- Filling with weighted sum of the neighboring samples
 - Weight function: interpolation filter



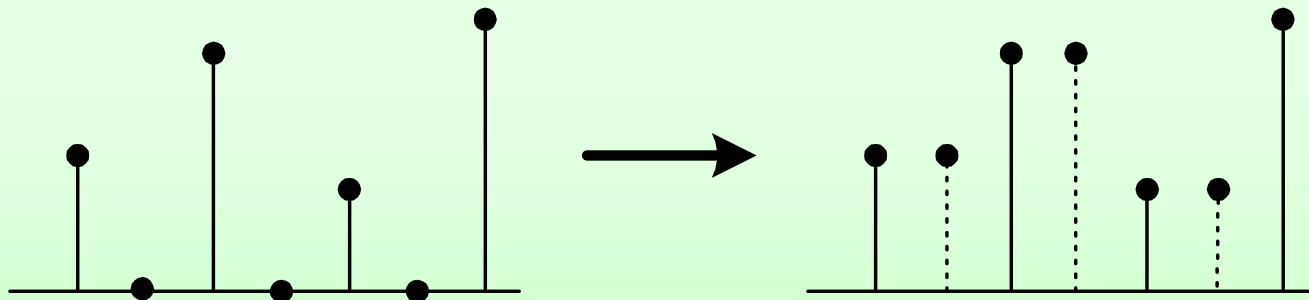
$$f(x) = \sum_{k=0}^{K-1} c_k h(x - x_k)$$

Interpolated site

Nearest neighbor (1)

□ Nearest neighbor

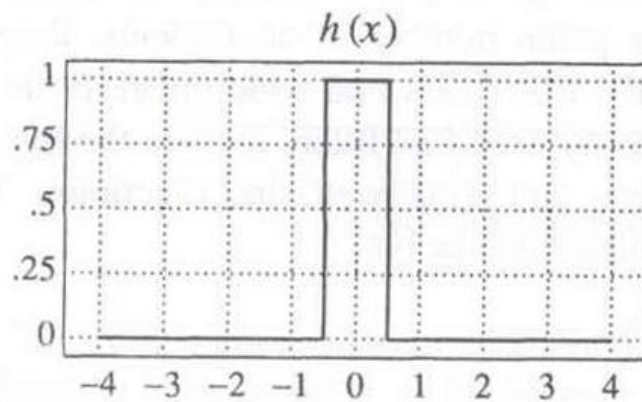
- zero order interpolator
- Assign the value of the nearest sample point



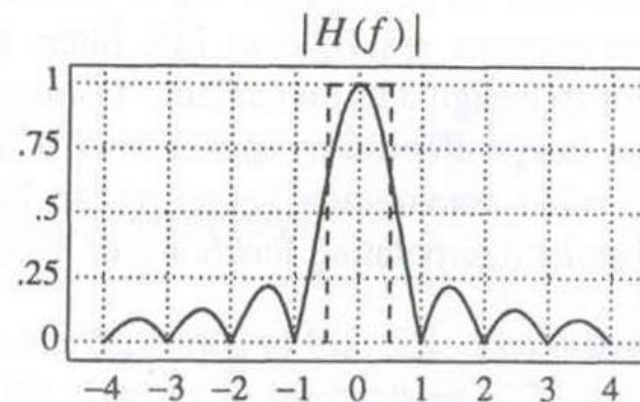
Nearest neighbor (2)

□ Nearest neighbor

- prominent side lobes
- Poor low pass filter
- Blocky artifact



(a)

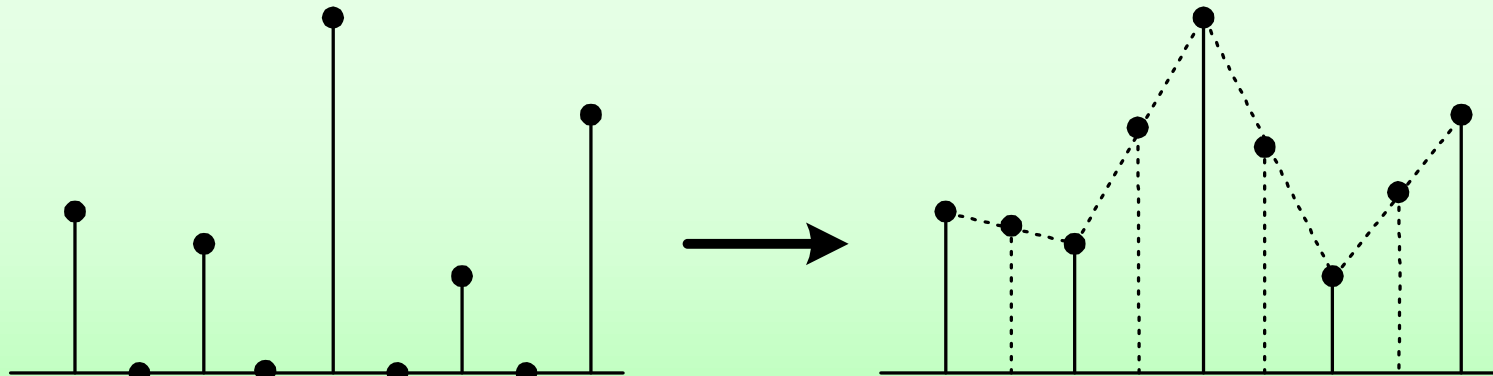


(b)

Linear interpolation (1)

□ Linear interpolation

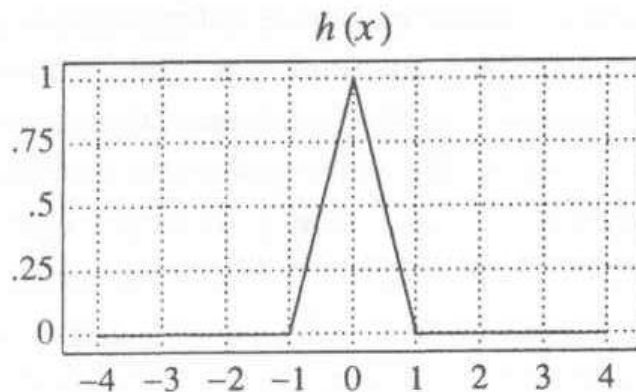
- First order interpolator
- Passes a line through two consecutive points



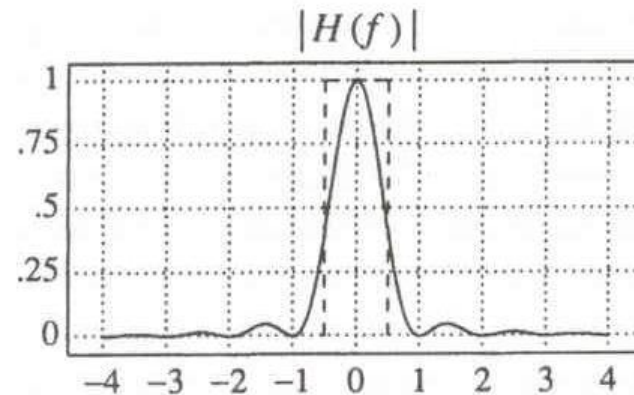
Linear interpolation (2)

□ Linear interpolation

- Superior to nearest neighbor, but insufficient
- Widely used since reasonably good results at moderate costs



(a)



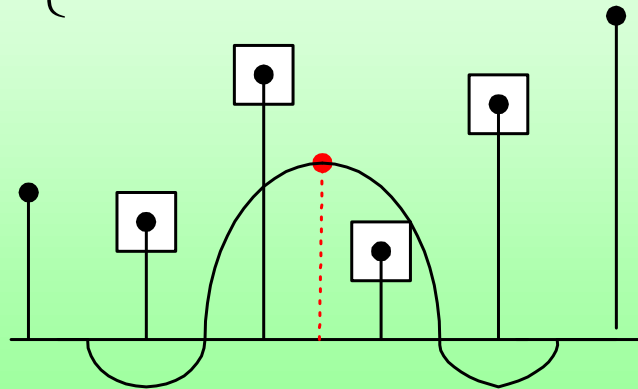
(b)

Cubic convolution (I)

□ Cubic convolution

- Third order interpolator
- Symmetry property of two points on each side
- kernel

$$h(x) = \begin{cases} a_{30} |x|^3 + a_{20} |x|^2 + a_{10} |x| + a_{00} & 0 \leq |x| < 1 \\ a_{31} |x|^3 + a_{21} |x|^2 + a_{11} |x| + a_{01} & 1 \leq |x| < 2 \\ 0 & 2 \leq |x| \end{cases}$$



Cubic convolution (II)

□ Cubic convolution

■ Constraints

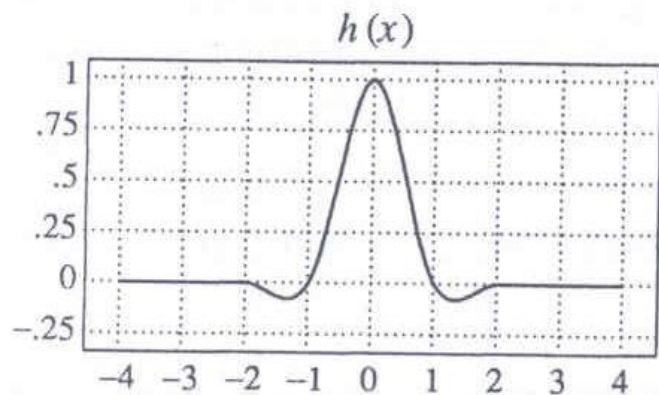
- $h(0) = 1$ and $h(x) = 0$ for $|x| = 1$ and 2 .
- h must be continuous at $|x| = 0, 1$, and 2 .
- h must have a continuous first derivative at $|x| = 0, 1$, and 2 .

$$h(x) = \begin{cases} (a+2)|x|^3 - (a+3)|x|^2 + 1, & 0 \leq |x| < 1 \\ a|x|^3 - 5a|x|^2 + 8a|x| - 4a, & 1 \leq |x| < 2 \\ 0 & , 2 \leq |x| \end{cases}$$

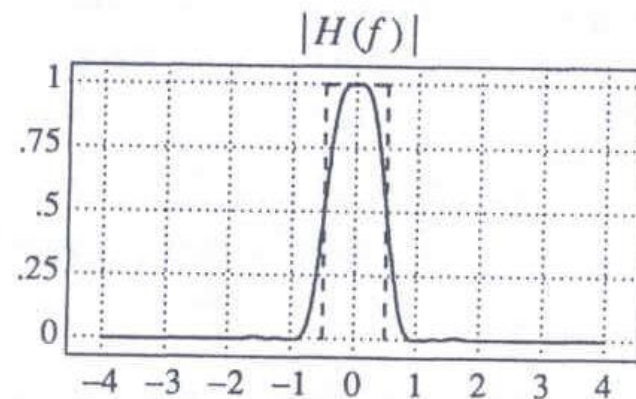
Cubic convolution (III)

□ Cubic convolution

- $a = -1$: preferable if visually enhanced results
- $a = -0.5$: mathematically precise



(a)

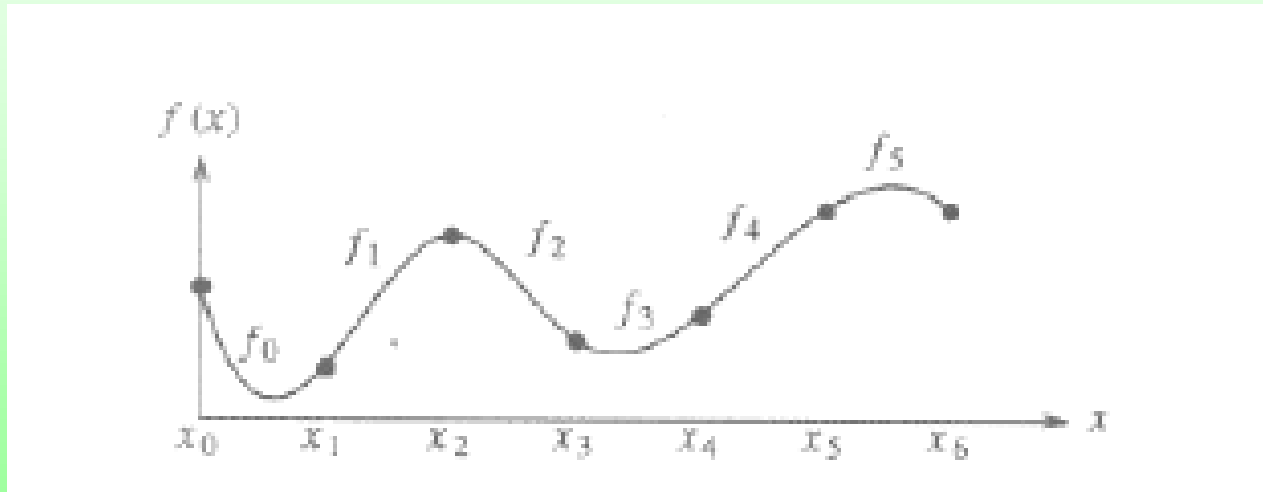
 $a = -1$ 

(b)

Cubic splines

□ Cubic spline

- Piecewise continuous third-degree polynomials
- Curve fitting using polynomials
- N points $\rightarrow (N-1)$ th polynomials (# of variables: N)
- Polynomials, f_k are joined at each point x_k such that f_k , f_k' and f_k'' are continuous.



Cubic B splines

■ Cubic B splines

- B-spline: N convolutions of the box filter
- Guarantee the positivity of the interpolated image
- Undergoes considerable smoothing
- Parzen window
- Not interpolation filter
 - $h(0)=4/6$
 - An approximation function near the point

$$h(x) = \frac{1}{6} \begin{cases} 3|x|^2 - 6|x| + 4 & 0 \leq |x| < 1 \\ -|x|^3 + 6|x|^2 - 12|x| + 8 & 1 \leq |x| < 2 \\ 0 & 2 \leq |x| \end{cases}$$

Windowed sinc function (I)

□ Windowed sinc function (in spatial domain)

- Signal truncation: FIR
- Sinc function: ideal LPF, IIR \rightarrow FIR filter (by window)
- multiplication by window \rightarrow convolution with spectrum of window

□ Rectangular window

- Truncation of sinc function
- Bad performance in step edges
 - ringing artifacts (Gibbs phenomena)
 - Because of the convolution of sinc function in frequency domain, the stopband has non-zero ripples.

□ We need some weighted windows to reduce the ripples

Windowed sinc function (II)

☐ Rectangular (zero-order)

☐ Bartlett (first order)

☐ Hanning (a=0.5)

☐ Hamming (a=0.54)

$$\begin{cases} a + (1-a) \cos \frac{2\pi x}{M-1} & |x| < \frac{M-1}{2} \\ 0 & \text{otherwise} \end{cases}$$

☐ Blackman window

$$\begin{cases} 0.42 + 0.5 \cos \frac{2\pi x}{M-1} + 0.08 \cos \frac{4\pi x}{M-1}, & |x| < \frac{M-1}{2} \\ 0 & \text{otherwise} \end{cases}$$

☐ Kaiser window :

$$\frac{I_0[\beta \sqrt{1 - (1 - \frac{2n}{M-1})^2}]}{I_0[\beta]}, \quad 0 \leq n \leq M-1$$

Windowed sinc function (III)

□ Lanczos window (I)

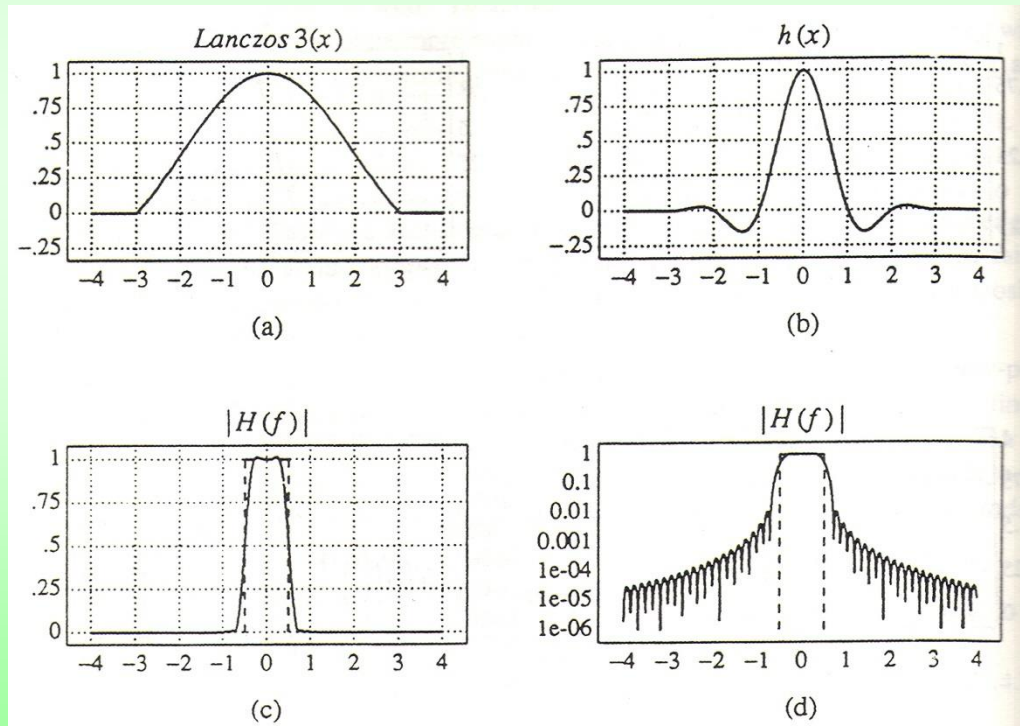
- Reducing ringing artifacts in the windowed sinc functions by constraints on the frequency response
 - Unity gain in passband
 - Zero gain in stopband
 - Linear transition
- Convolution of two box filters in frequency domain
 - Multiplication of two sinc functions in spatial domain
- Example: $\text{sinc}(x)\text{sinc}(x/2)\text{Rect}(x/4)$
 - $\text{Rect}(f)*\text{Rect}(2f)*\text{sinc}(4f)$

Windowed sinc function (IV)

□ Lanczos window (II)

- N-lobed window function
 - Determine the extent of non-zero sinc function

$$LanczosN(x) = \begin{cases} \frac{\sin(\pi x / N)}{\pi x / N} & 0 \leq |x| < N \\ 0 & |x| > N \end{cases}$$



Windowed sinc function (VI)

□ Comparison of windowed sinc functions

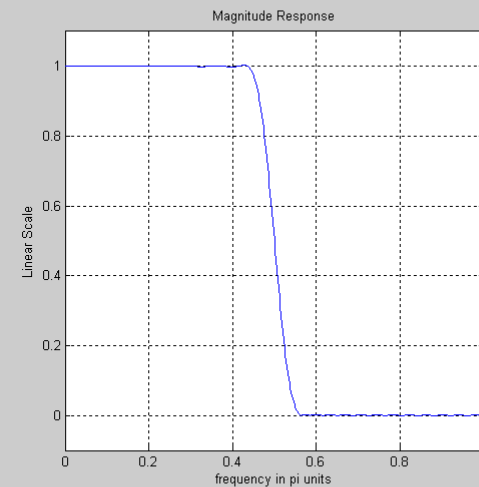
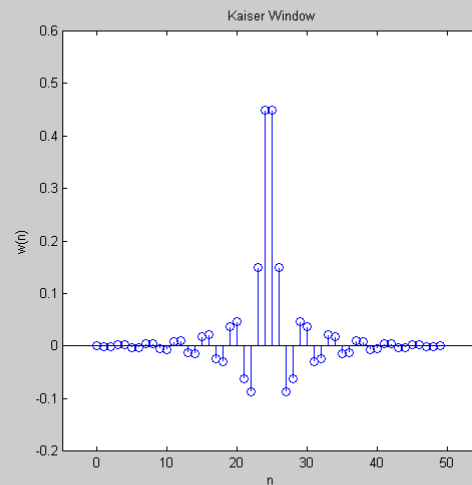
Blackman

Bartlett

Hamming

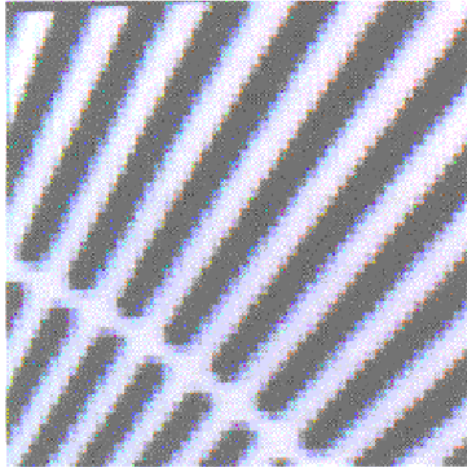
Hanning

Kaiser



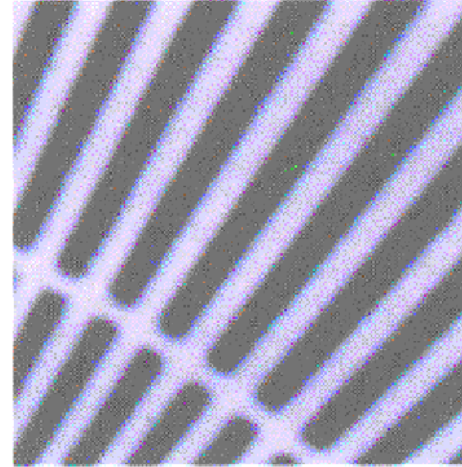
Comparisons of interpolation filters (I)

Nearest
neighbor



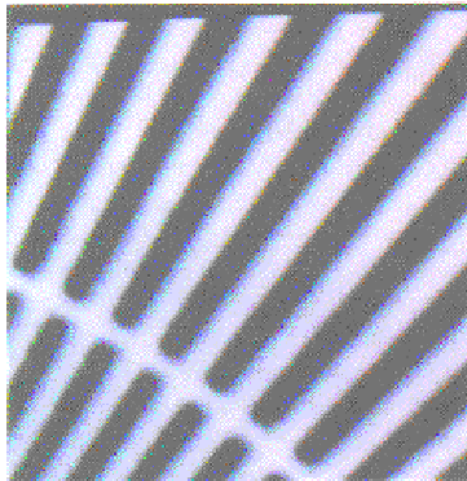
(a)

Linear
interpolation

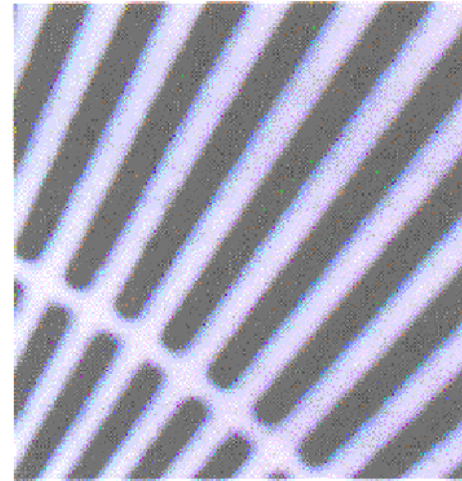


(b)

Cubic convo-
Lution ($a=-1$)

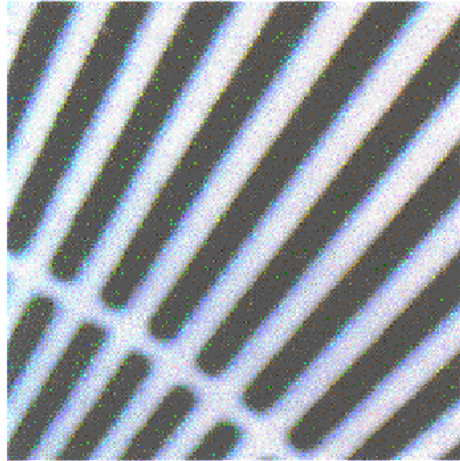


Cubic convo-
Lution ($a=-0.5$)



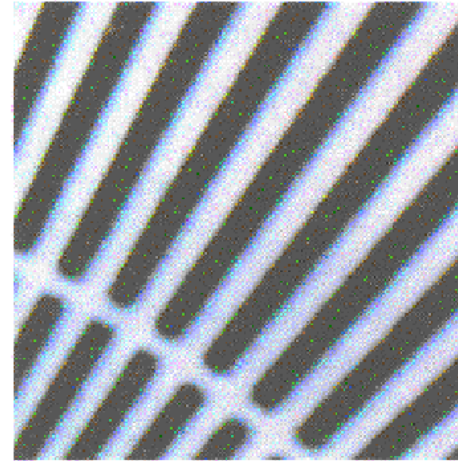
Comparisons of interpolation filters (II)

Cubic
Spline



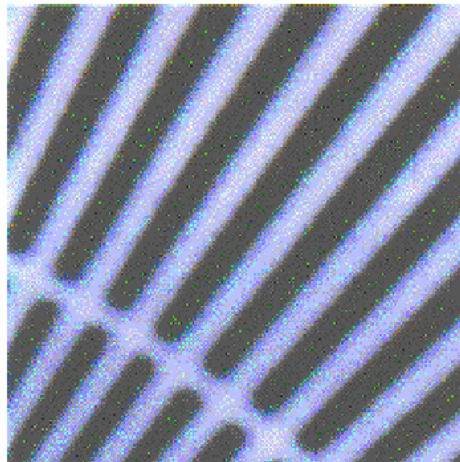
(a)

Lanczos2
window

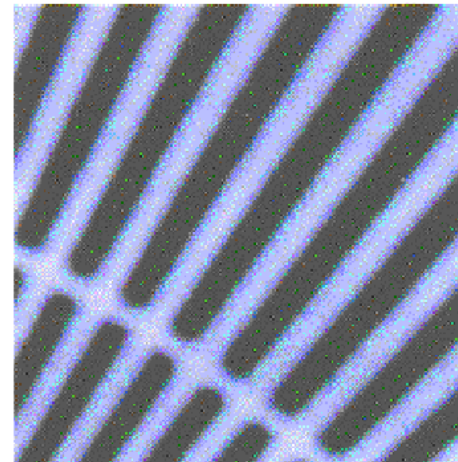


(b)

Hamming



Exponential
filter



Comparisons of interpolation filters (III)

Nearest neighbor

Bilinear

Cubic B spline

Cubic ($a=-0.5$)

Lanczos window

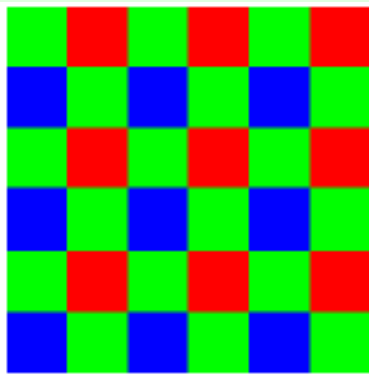


Image Demosaic

Digital Color Imaging

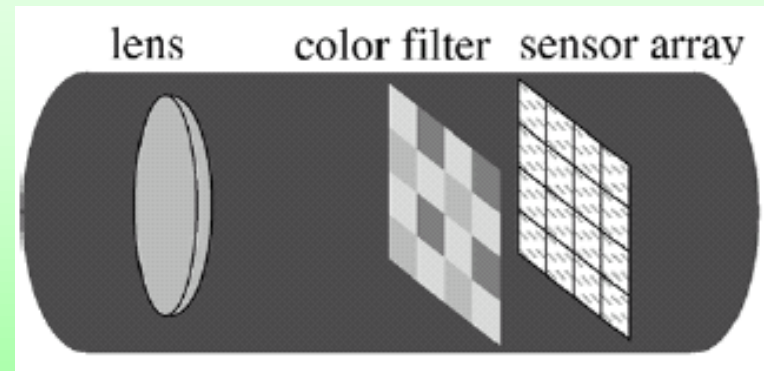
□ Bayar CFA (color filter array) pattern in digital camera

- Each CCD cell takes only one color component via mosaiced CFA pattern.
- Color components (RGB) are mosaiced like tiles due to color filter array.
- Green is sampled at a higher rate than red and blue



Bayar CFA pattern

G	R	G	R	G	R
B	G	B	G	B	G
G	R	G	R	G	R
B	G	B	G	B	G
G	R	G	R	G	R
B	G	B	G	B	G



Color image acquisition

Demosaic (1)

❑ For full resolution color images

- Interpolation is required for each color component.
- Inverse process of mosaiced CFA pattern
- Demosaicing

❑ Interpolating each color component, (R,G,B)

- Independent interpolation
- Using correlations between color components

❑ Artifacts generated from

- Image contents (high frequency)
- Interpolation algorithms
- CFA pattern: zippering
- More serious in color images than gray ones

Demosaic Examples (1)

- ❑ Some exemplary results (IEEE IP, March, 2005)
 - “Adaptive homogeneity-directed demosaicing algorithm”



Horizontal interpolation

Vertical interpolation

Directional interpolation

Demosaic Examples (2)

□ Some exemplary results

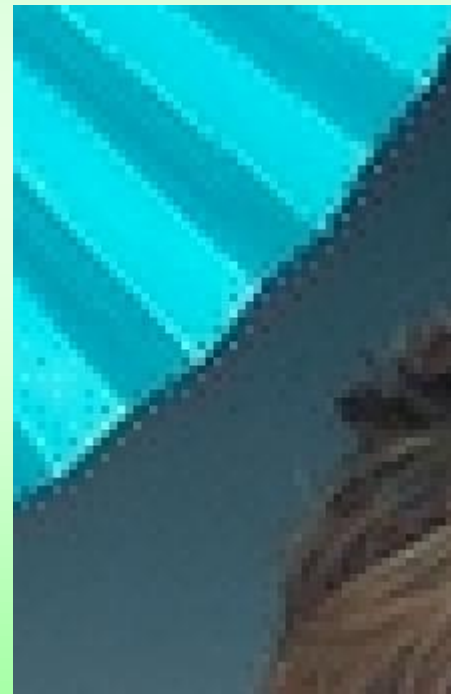
- [1] “Color plane interpolation using alternating projections,” (IP, 2002.9)
- [2] “Demosaicing using optimal recovery” (IP, 2005.2)



Result in [1]



Result in [2]



magnified part in [1]



in [2]