

# Aditya Milind Deshpande

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## Education

### University of Cincinnati

PH.D. IN MECHANICAL ENGINEERING

- Research Focus: Embodied Intelligence in robots

Cincinnati, Ohio, USA

Aug. 2017 - Expected Dec. 2020

### University of Cincinnati

M.S. IN MECHANICAL ENGINEERING

- Thesis: Area Coverage Control Law for Robot Swarm inspired from Ant Colony

Cincinnati, Ohio, USA

Aug. 2015 - Jul. 2017

### Maharashtra Institute of Technology

B.E. IN MECHANICAL ENGINEERING

- Senior Design Project: Design Optimization of Heat Exchanger

Pune, India

Aug. 2010 - Jul. 2014

## Experience

### Cooperative Distributed Systems Lab, University of Cincinnati (Prof. Manish Kumar)

GRADUATE RESEARCH ASSISTANT

- Developed Non-Invasive Computer Vision Toolkit (CVT) for Legacy Machines – DMDII Grant.
- Developed Computer Vision Software to assist in road traffic monitoring using quadrotor robots – Ohio Dept. of Transportation Grant
- Developed software interface for indoor quadrotor flights with and without external position feedback – NSF Grant.

Cincinnati, Ohio, USA

May. 2017 - Present

### CEAS, University of Cincinnati

INSTRUCTOR

- Primary instructor for the large enrollment (60 students) course of Robot Control/Design comprising of Graduate and Undergraduate students in College of Engineering and Applied Sciences.

Cincinnati, Ohio, USA

Jan. 2019 - Apr. 2019

### Viaanix, Inc.

ENGINEERING INTERN

- Developed sensor fusion algorithms for wearable IMU sensors used in human motion tracking.
- Presented wearable device design solution as per the customer/chiropractor requirements and budgets.
- Collaborated with design and firmware teams for hardware-software interface testing.

Wichita, Kansas, USA

Jun. 2016 - Jul. 2016

### Dassault Systèmes (SIMULIA)

SOFTWARE ENGINEER

- Developed the graphical front-end of the next generation SIMULIA product using PolymerJS and JavaScript
- Development of web automation tools for data extraction and transfer between various applications developed in SIMULIA brand.
- Focused on website rendering time minimization and usability to improve the user experience.

Pune, Maharashtra, India

Jul. 2014 - Jul. 2015

## Skills

<b>Software</b>	Python, C/C++, Julia, MATLAB, LaTeX, Robot Operating System (ROS), OpenCV, Gazebo Sim, PyBullet, AirSim
<b>Deep Learning</b>	Pytorch, Keras, TensorFlow
<b>Hardware</b>	PixHawk Autopilot, NVIDIA Jetson, Arduino Uno, Raspberry Pi

## Publications and Presentations

### JOURNAL PUBLICATIONS

- **Deshpande, A. M.**, Ramakrishnan, S., Kumar, M. (2019) "Adaptive Switching between Brownian and Lévy Foraging Strategies for Improved Area Coverage by a Biologically Inspired Robot Swarm." Submitted to Swarm Intelligence

### CONFERENCE PUBLICATIONS

- **Deshpande, A. M.**, Kumar, R., Radmanesh, M., Veerabhadrappe, N., Kumar, M., Minai, A. A. (2018, June). Self-Organized Circle Formation around an Unknown Target by a Multi-Robot Swarm using a Local Communication Strategy. In 2018 Annual American Control Conference (ACC) (pp. 4409-4413). IEEE.

- **Deshpande, A.**, Kumar, M., Ramakrishnan, S. (2017, October). Robot swarm for efficient area coverage inspired by ant foraging: The case of adaptive switching between Brownian motion and Lévy flight. In ASME 2017 Dynamic Systems and Control Conference (pp. V002T14A009-V002T14A009). American Society of Mechanical Engineers.
- **Deshpande, A. M.**, Phatnani, G. M., Kulkarni, A. J. (2013, June). Constraint handling in firefly algorithm. In 2013 IEEE international conference on cybernetics (CYBCO) (pp. 186-190). IEEE.

## POSTERS

- Anand, S., Kumar, M., Deshpande, A., Jakkali, V., Telikicherla, A. K., Non-Invasive Computer Vision Toolkit (CVT) using MT Connect<sup>®</sup>. Future Factory Technology Showcase, UI Labs, Chicago, Illinois, Nov. 13, 2018.

## PRESENTATIONS

- James Wells, **Aditya M. Deshpande**, Runit Kumar, Anuj Saxena, Bryan Brown, Dieter Vanderelst, and Manish Kumar. "Autonomous Indoor Flight in GPS Denied, Degraded Environments." 44th Dayton-Cincinnati Aerospace Sciences Symposium. March 2019.
- Runit Kumar, **Aditya M. Deshpande**, Siddharth Sridhar, Kelly Cohen, Manish Kumar. "Quaternion Feedback Based Full Pose Control of a Quadcopter UAV with Thrust Vectoring Capabilities." 44th Dayton-Cincinnati Aerospace Sciences Symposium. March 2019.
- Oyindamola Omotuyi, James Wells, **Aditya M. Deshpande**, Runit Kumar, Manish Kumar. "Laser Based EKF Localization on TurtleBot3 Robot." 44th Dayton-Cincinnati Aerospace Sciences Symposium. March 2019.
- **Aditya M. Deshpande**, Manish Kumar, Subramanian Ramakrishnan. "Robot Swarm inspired by Ant Colony for Augmented Search and Retrieval." 43rd Dayton-Cincinnati Aerospace Sciences Symposium. February 2018
- **Aditya M. Deshpande**, Manish Kumar, Ali A. Minai. "Self-Organized Circle Formation around an Unknown Target by a Multi-Robot Swarm using a Local Communication Strategy." 43rd Dayton-Cincinnati Aerospace Sciences Symposium. February 2018.
- **Aditya M. Deshpande**, Manish Kumar, Subramanian Ramakrishnan. "Area Coverage Based On Levy Foraging Hypothesis Applied to Robot Swarm Emulating Ant Foraging Behavior." 42nd Dayton-Cincinnati Aerospace Sciences Symposium. March 2017.

## THESIS

- **Deshpande, A.** (2017). Robot Swarm Based On Ant Foraging Hypothesis With Adaptive Levy Flights. (Electronic Thesis or Dissertation). Retrieved from <https://etd.ohiolink.edu/>

# Affiliations and Professional Activities

## AFFILIATIONS

- 2017-Present **American Society of Mechanical Engineers (ASME), Student Member**
- 2019-Present **American Association for the Advancement of Science (AAAS), Student Member**

## PROFESSIONAL ACTIVITIES

- 2017 **Dynamic Systems and Control Conference, Reviewer**
- 2017 **American Control Conference, Reviewer**
- 2018 **Dynamic Systems and Control Conference, Reviewer**
- 2018 **American Control Conference, Reviewer**

# Honors & Awards

- 2019 **Video in Science Award**, 44th Dayton-Cincinnati Aerospace Sciences Symposium *Dayton, Ohio*
- 2018 **"UC researchers team up with ODOT to study traffic with drones"**, WCPO-TV, Channel 9 *Cincinnati, Ohio*  
Cincinnati, July 10, 2018
- 2018 **University Research Council (URC) Award, \$5000**, Principal Investigator (PI) for the research on "Deep Intelligence for Complex Learning in Robots" *Cincinnati, Ohio*
- 2015-19 **University Graduate Scholarship**, University of Cincinnati *Cincinnati, Ohio*
- 2012 **3rd Place**, Designer Pro (AutoCAD) Competition in "Axlerate" (Technical Festival, Maharashtra Institute of Technology) *Pune, India*