Week 4 – ABB Robot Teaching 9: External Axis

Advanced Robotic Systems – MANU2453

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Content

- Introduction

- Add External Mechanism

- Add Robot

- Create Robot System from Layout

- Jog Robot and Track

- Teaching Target Points

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Introduction

- Sometimes, the workpiece is too large for the robot to work on.

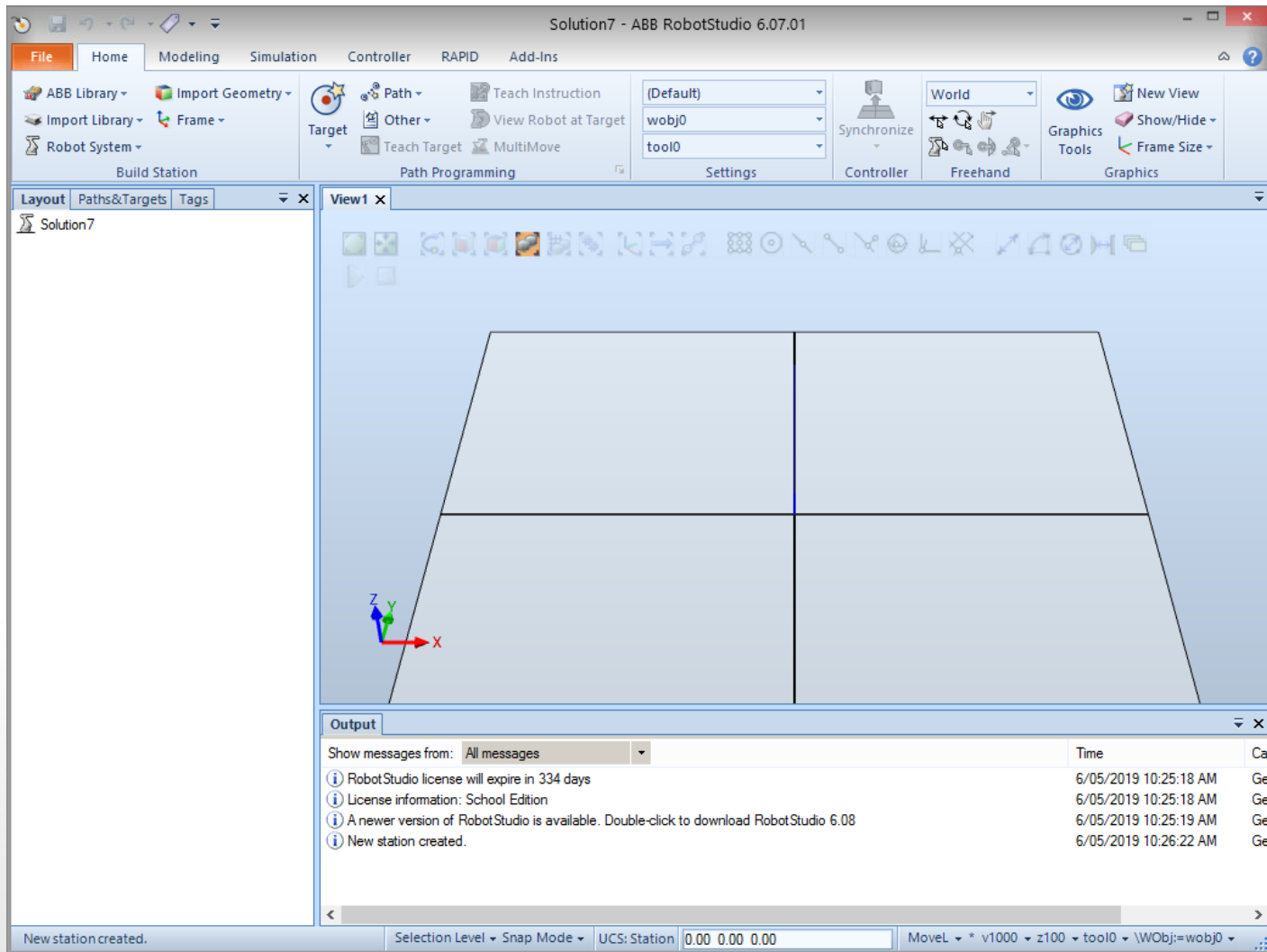 - E.g. Using a robot to polish the body of an aeroplane or ship.

- Now, if we put the robot on an external mechanism, we can increase the total workspace!

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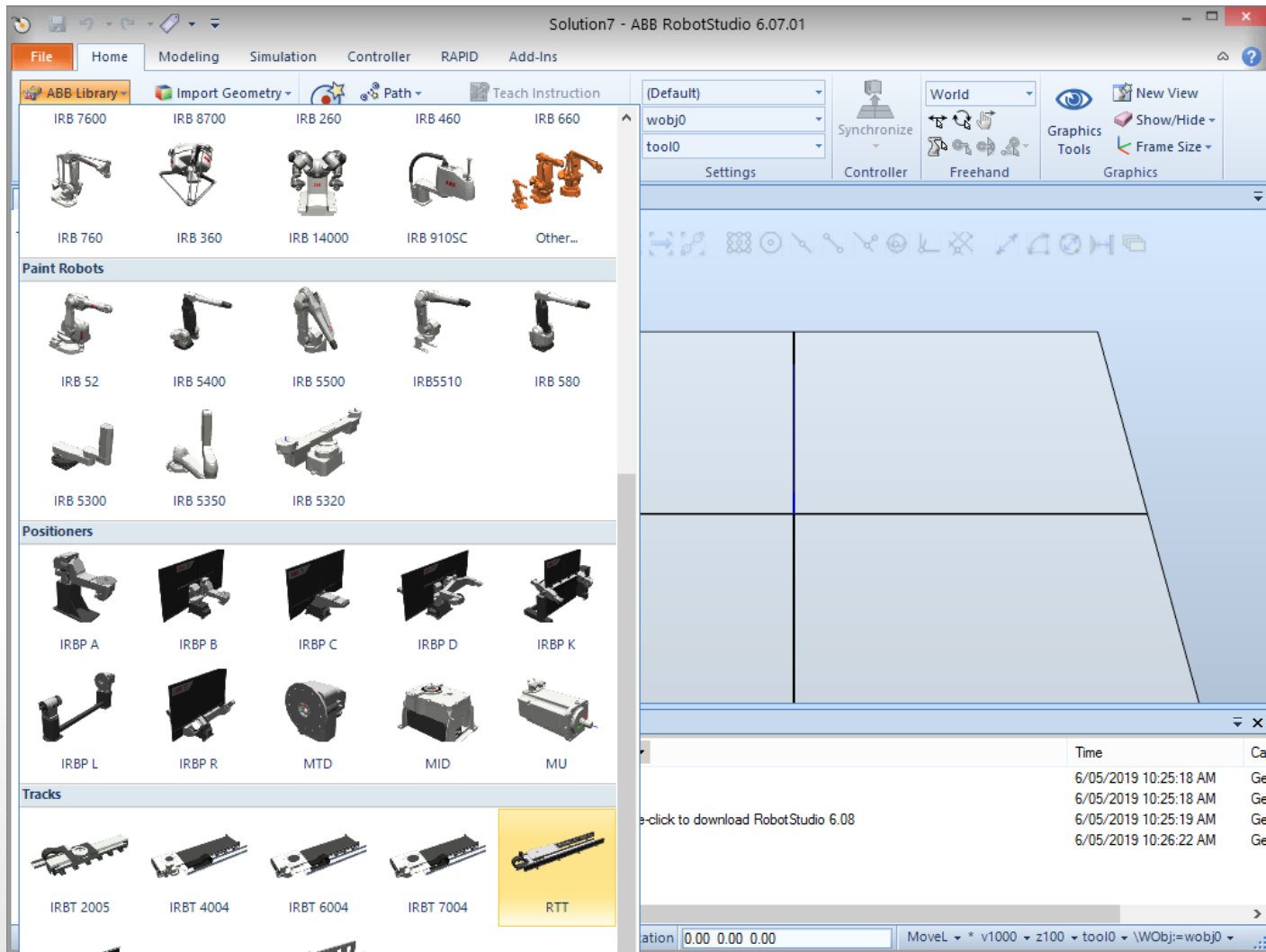- Jog Robot and Track
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Add External Mechanism
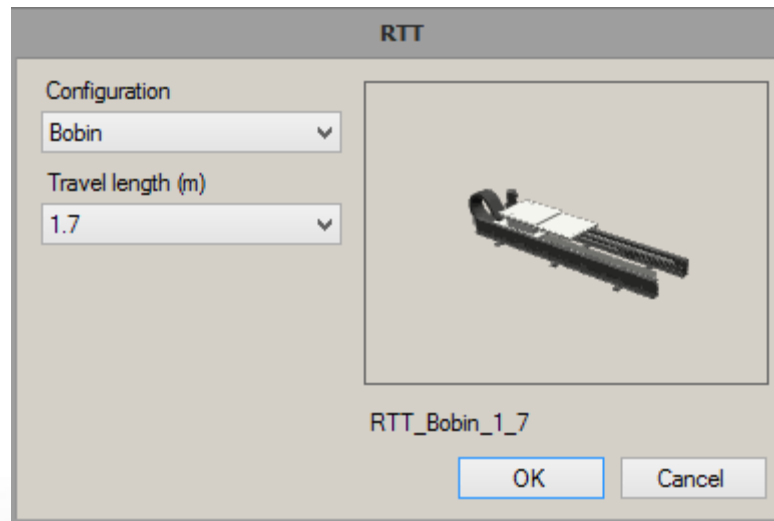
- First of all, start ABB Robotstudio as usual.

Add External Mechanism

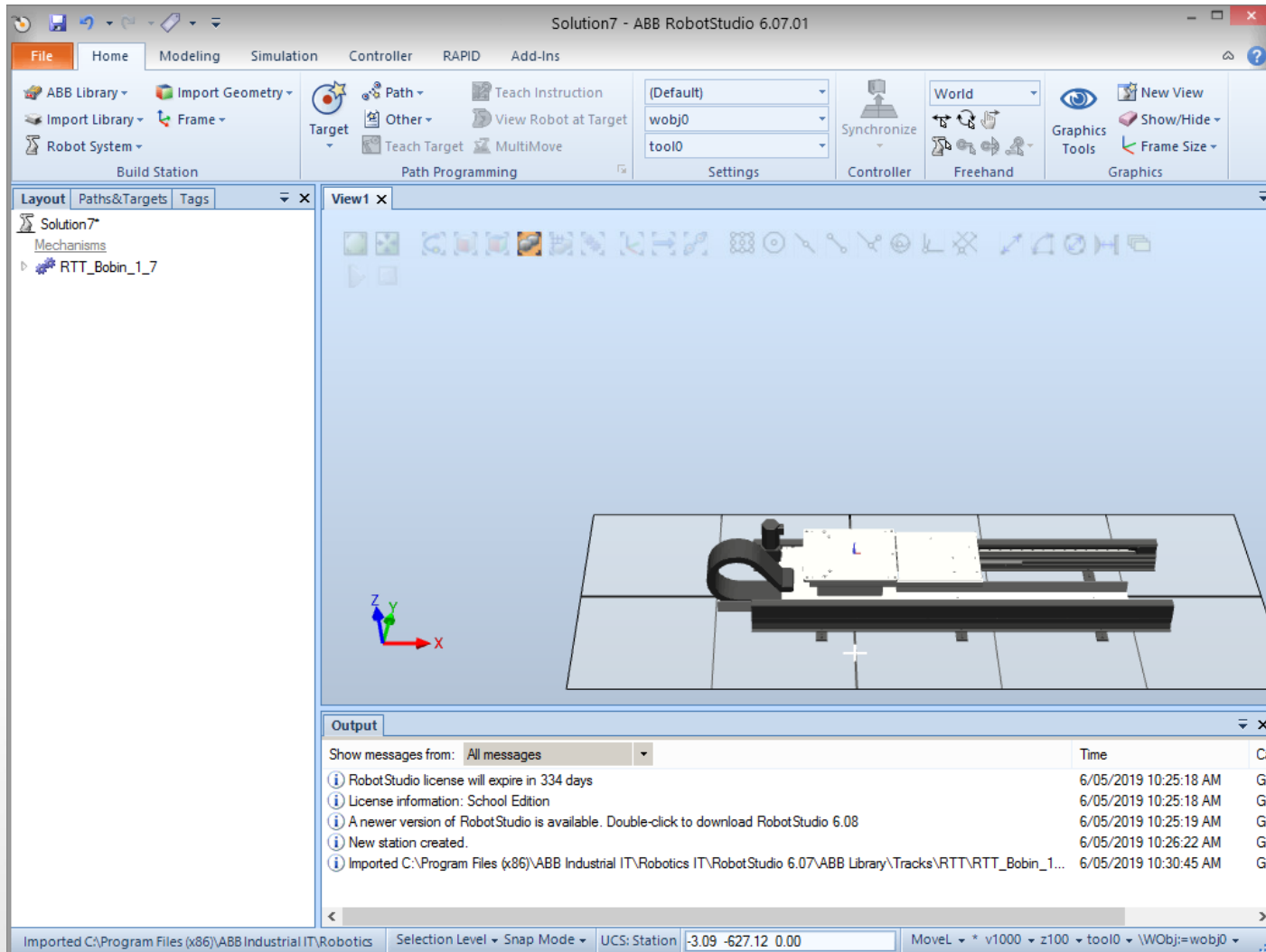- Under ABB Library, choose any of the tracks, e.g. "RTT".

Add External Mechanism

- Then choose any of the options suitable for your application.

Add External Mechanism
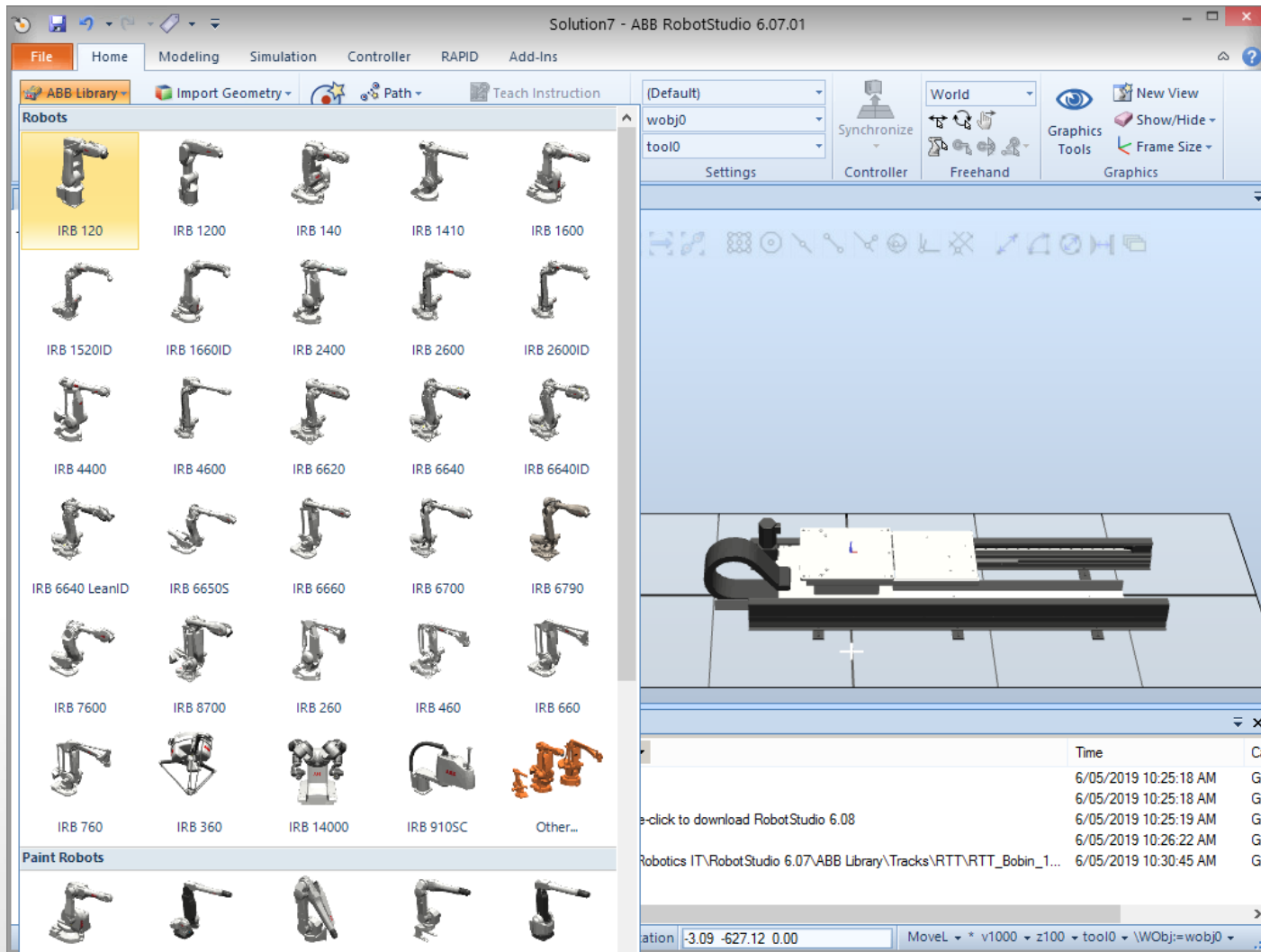
- The external mechanism is now added to your workcell.
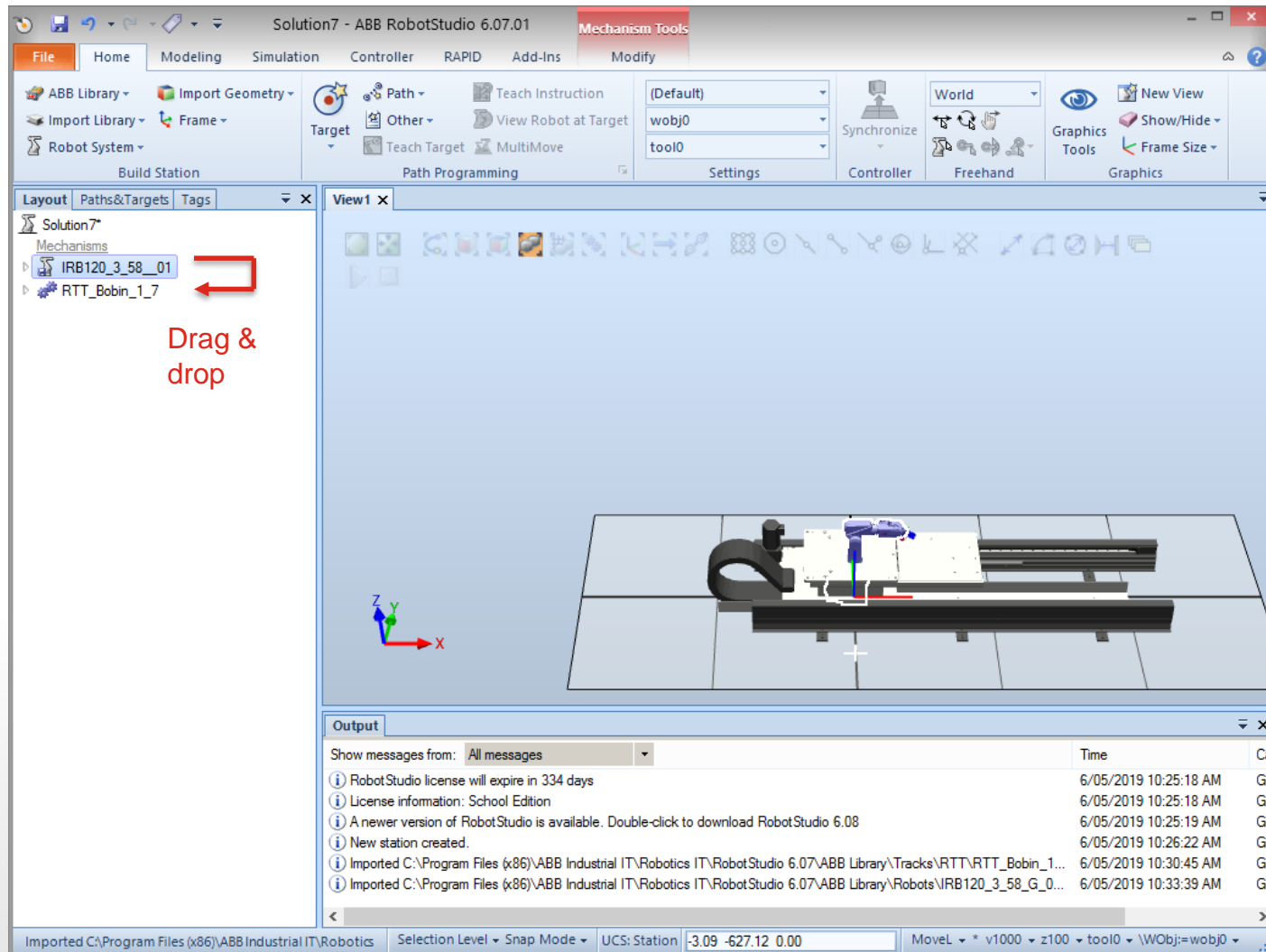
Content

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Add Robot

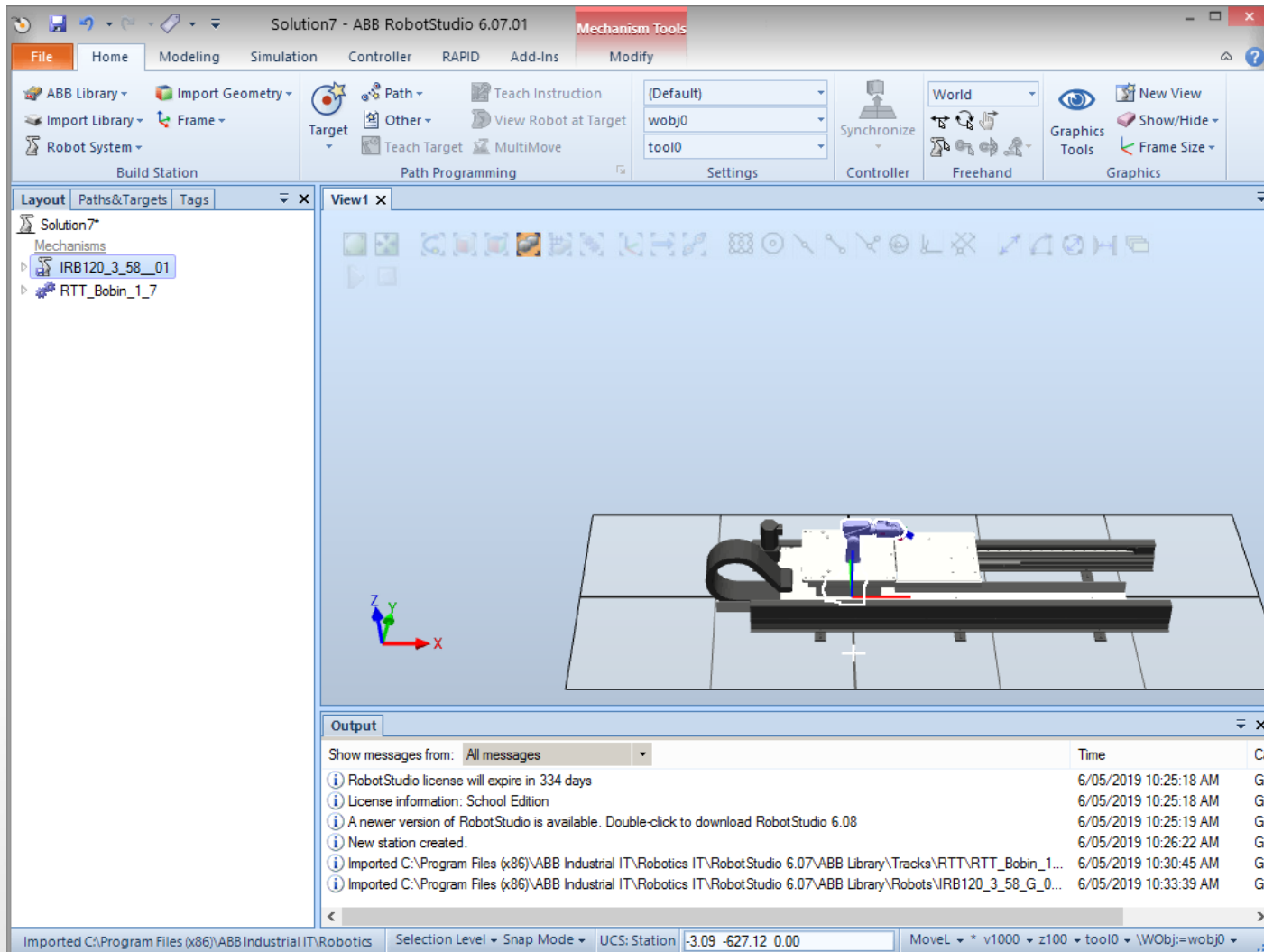- Next, add robot to the workcell.

Add Robot
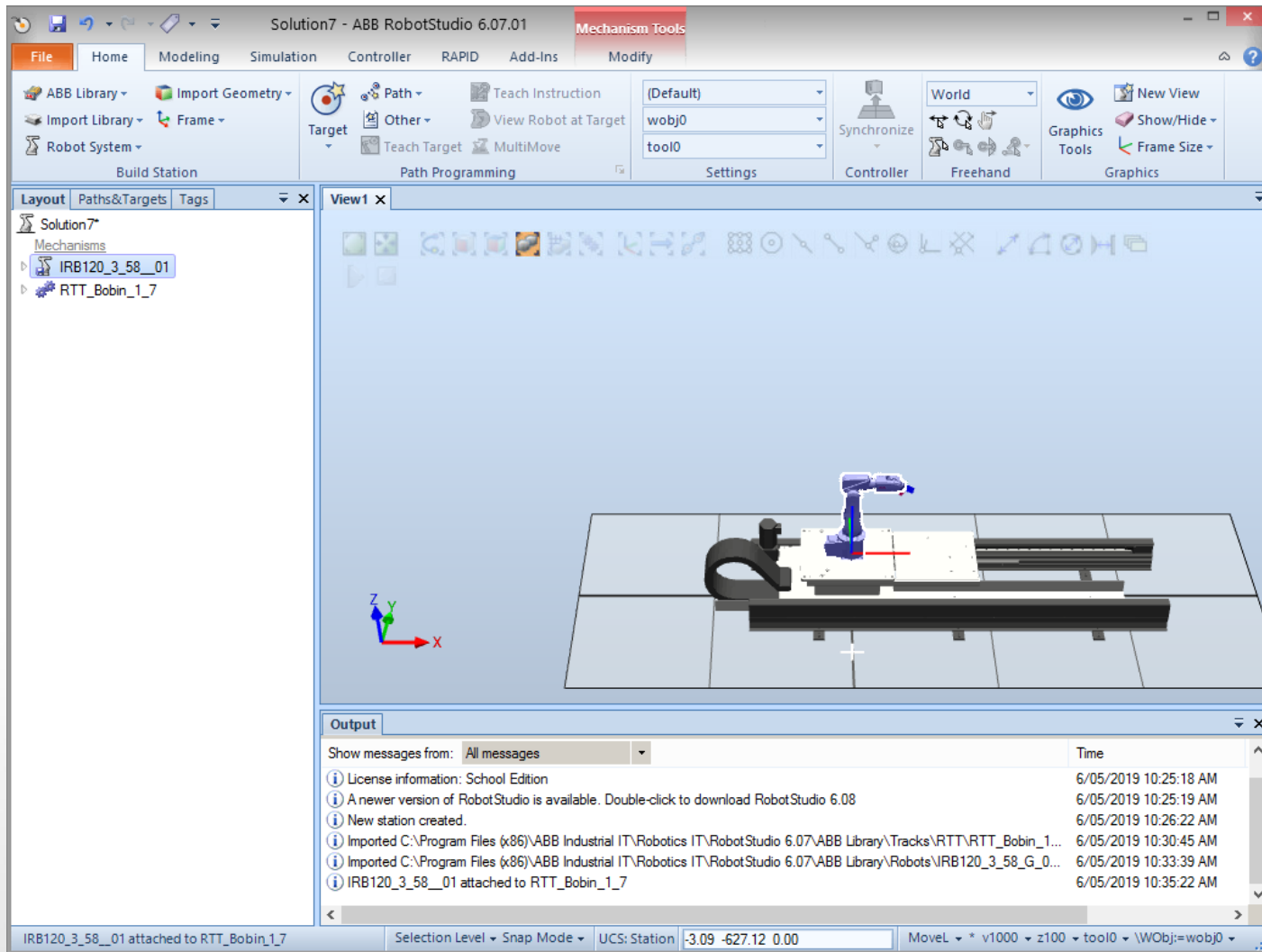
- Attach robot onto the track.

Add Robot

- Click YES to the subsequent 2 questions.

Add Robot

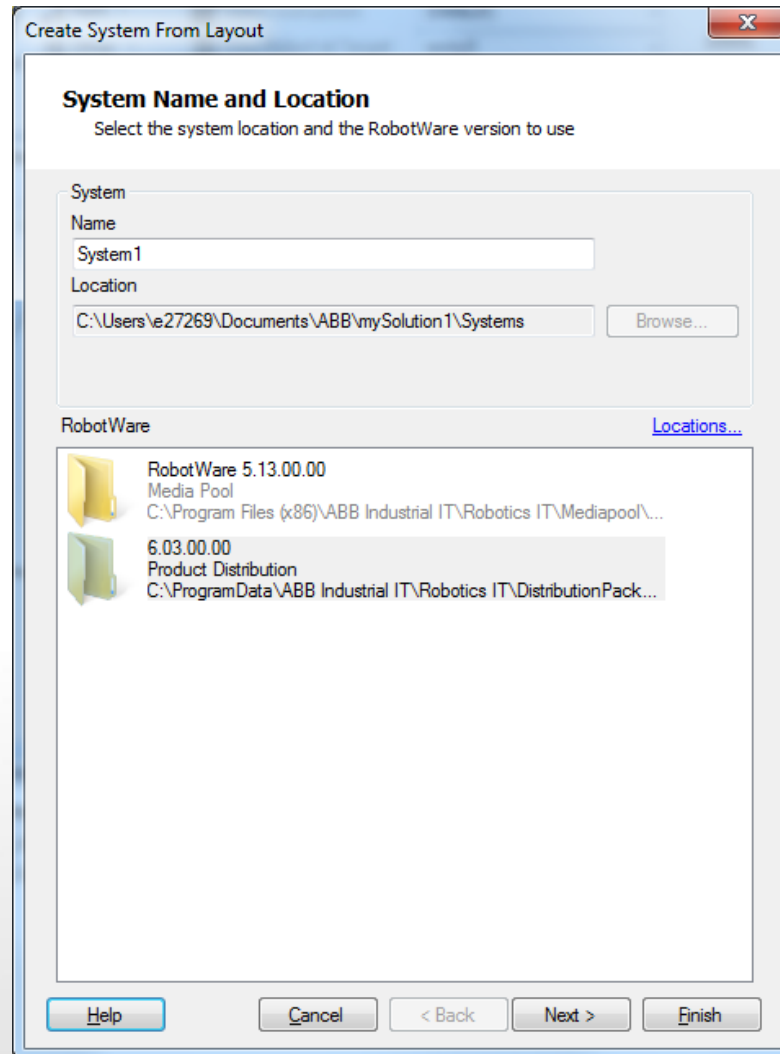- The robot is now attached to the track.

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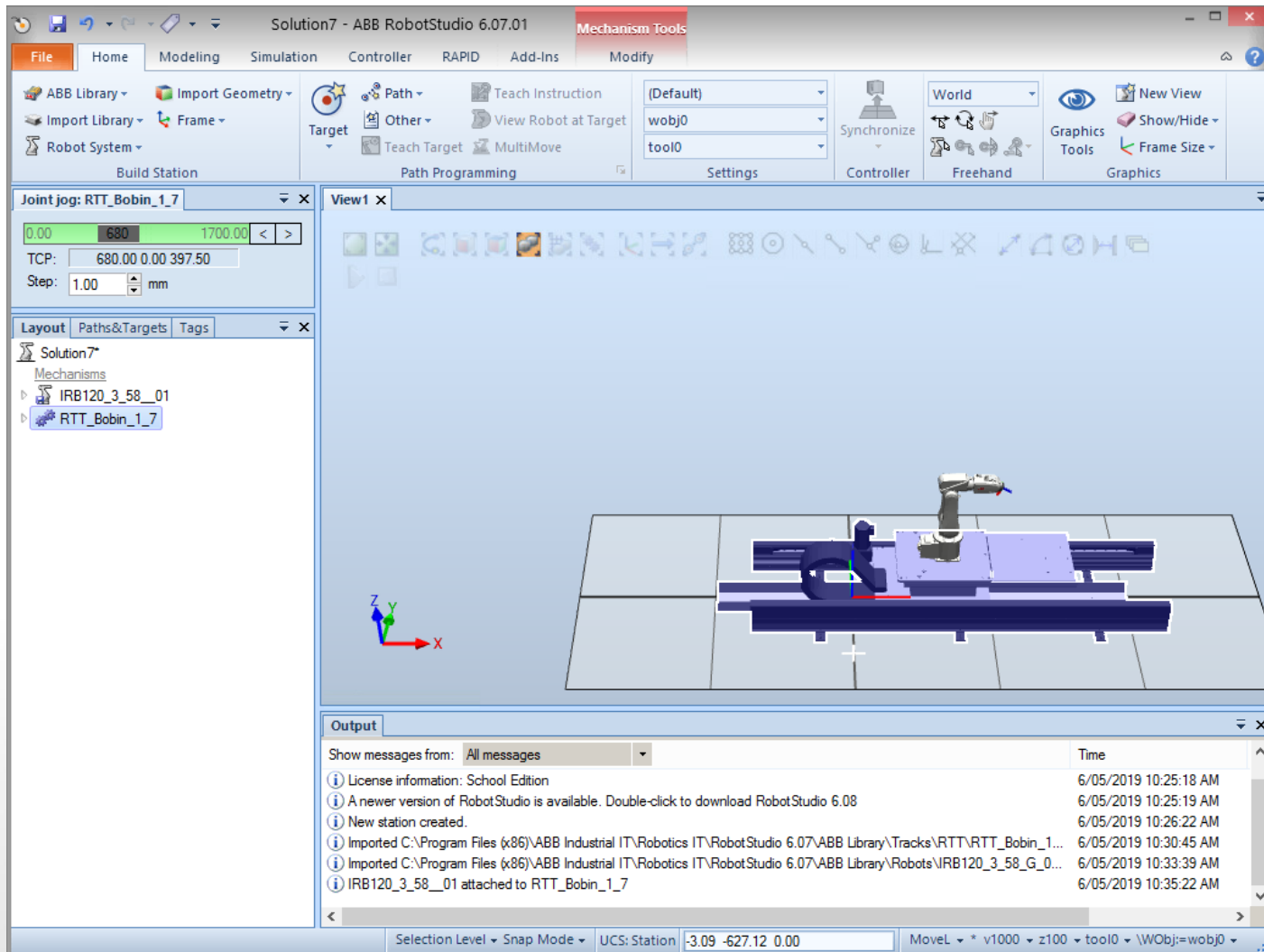# Create Robot System from Layout

- Click Robot System → From Layout.

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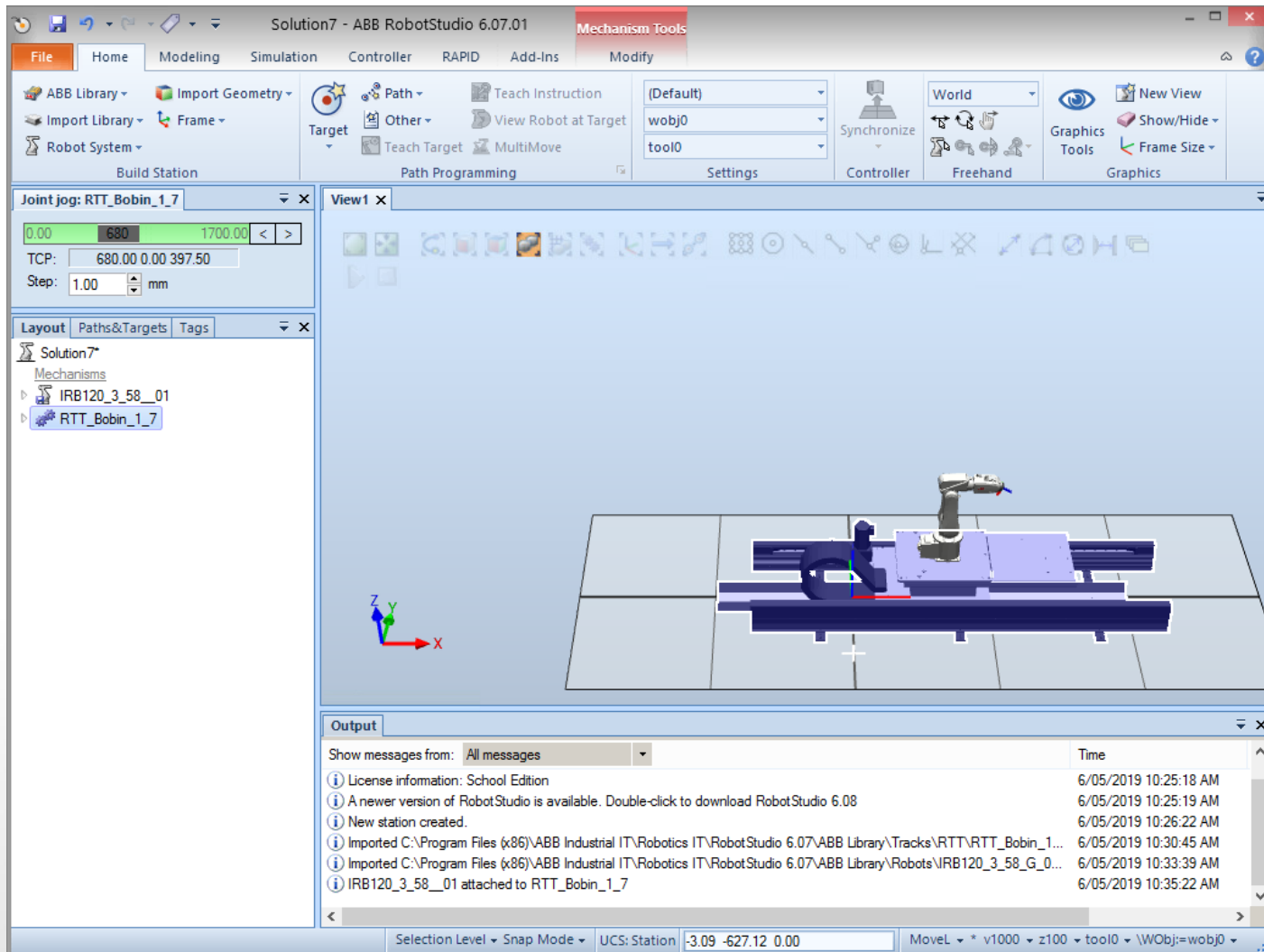# Jog Robot and Track

- You can now jog both the robot and track.

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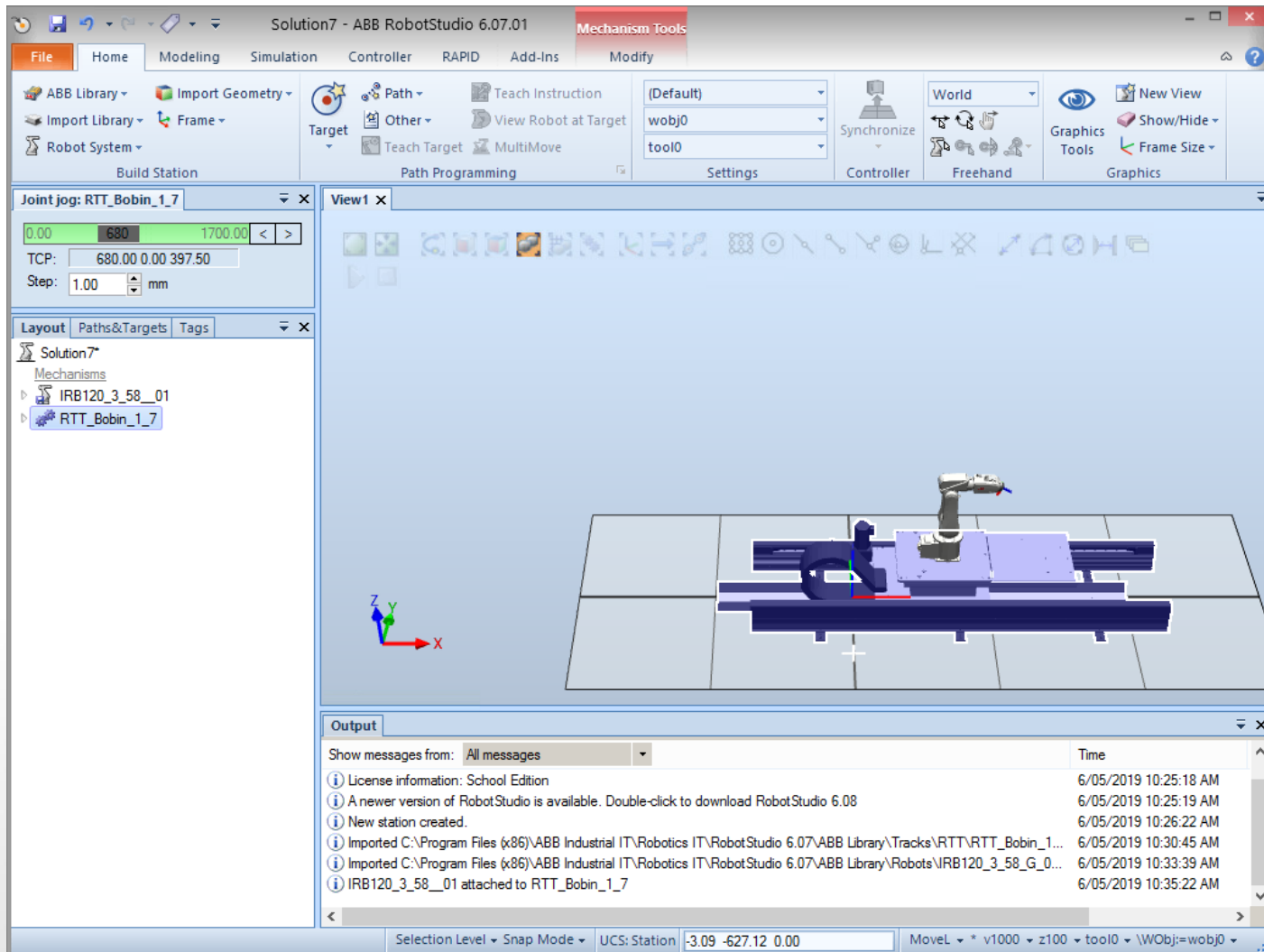- Jog Robot and Track

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Teaching Target Points

- Note: jog the track to a feasible position first, before hitting "create target".

Teaching Target Points

- After that, follow same procedure → create path → auto configure etc.

Thank you!

Have a good evening.

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