

# **Accurate SoC Estimation of Lithium Ion Battery**

*Submitted in partial fulfilment of the requirements for the degree of*

## **Bachelor of Technology** in **Electronics and Instrumentation Engineering**

*by*

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April, 2025

## **DECLARATION**

We hereby declare that the thesis entitled “Accurate SoC Estimation of Lithium Ion Battery” submitted by us, for the award of the degree of Bachelor of Technology in Electronics and Instrumentation Engineering to VIT University is a record of bonafide work carried out by us under the supervision of Prof. Geetha M, Professor, SELECT, VIT University, Vellore.

We further declare that the work reported in this thesis has not been submitted and will not be submitted, either in part or in full, for the award of any other degree or diploma in this institute or any other institute or university.

Place: Vellore

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This is to certify that the thesis entitled “Accurate SoC Estimation of Lithium Ion Battery” submitted by **Adit Tiwari (21BEI0121), Sanjog Awasthi (21BEI0063), Aman Singh (21BEI0126)**, SELECT, VIT, Vellore, for the award of the degree of *Bachelor of Technology in Electronics and Instrumentation Engineering* , is a record of Bonafide work carried out by them under my supervision during the period, 14-12-2024 to 30-04-2025, as per the VIT code of academic and research ethics.

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## **Executive Summary**

This project presents a **solution for estimating the State of Charge (SoC) of a lithium-ion battery cell** using **three complementary methods: Direct Voltage Method, Coulomb Counting, and the Kalman Filter**. The objective is to provide a **real-time, accurate, and cost-effective embedded system** that monitors the charge level of a battery and communicates data over IoT for energy management applications.

The **Direct Voltage Method** uses open circuit voltage to infer SoC, providing a simple estimation based on battery voltage under rest conditions. **Coulomb Counting** involves integrating the current over time using a current sensor to calculate charge in/out. **Kalman Filtering** provides a more robust estimation by combining model-based prediction and sensor data, correcting errors inherent in the other methods.

The entire system is built using **Arduino**, a **voltage divider network**, **current sensors (ACS712)**, and IoT modules monitor SoC remotely. The project also addresses limitations like sensor drift and non-linearities in battery behaviour by integrating these three methods.

This smart SoC estimation system is applicable in **renewable energy, electric vehicles, and IoT-enabled smart grids**, promoting energy efficiency and sustainability. It is affordable, scalable, and adaptable to different battery chemistries, making it suitable for real-world deployment in both academic and industrial settings.

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## **List of Abbreviations**

<b>Abbreviation</b>	<b>Full Form</b>
2G	Second Generation
3G	Third Generation
4G	Fourth Generation
3GPP	Third Generation Partnership Project
AWGN	Additive White Gaussian Noise
BMS	Battery Management System
SoC	State of Charge
MCU	Microcontroller Unit
LCD	Liquid Crystal Display
ADC	Analog to Digital Converter
OCV	Open Circuit Voltage
EV	Electric Vehicle
UPS	Uninterruptible Power Supply
SDG	Sustainable Development Goals
IEEE	Institute of Electrical and Electronics Engineers
IDE	Integrated Development Environment
INA219	Current Sensor IC
I2C	Inter-Integrated Circuit (communication protocol)

## Symbols and Notations

Symbol	Description
$\delta f$	Carrier Frequency Offset (CFO)
$\varepsilon$	Normalized Carrier Frequency Offset (NCFO)
VMIN	Minimum voltage level for battery
VMAX	Maximum voltage level for battery
$I(t)$	Instantaneous current at time $t$
SoC( $t$ )	State of Charge at time $t$
Cn	Nominal battery capacity

# 1. INTRODUCTION

The demand for accurate and reliable Battery control structures (BMS) has grown tremendously in latest years, mostly due to the widespread adoption of lithium-ion batteries in an expansion of programs. these programs consist of electric powered motors (EVs), renewable strength garage structures like sun microgrids, and transportable electronic devices including smartphones, laptops, and clinical device. As the worldwide transition toward inexperienced and sustainable technology accelerates, the performance and safety of battery-powered systems have emerge as paramount. among the numerous parameters that a BMS monitors, the state of charge (SoC) sticks out as one of the maximum critical. SoC gives a quantitative estimate of the last electricity in a battery relative to its complete ability and performs a crucial position in determining the battery's usability and lifespan.

as it should be estimating the SoC of a battery is vital for numerous motives. firstly, it guarantees the safe operation of the battery-powered machine by preventing each overcharging and deep discharging. these excessive situations can result in excessive results including thermal runaway, potential loss, or maybe everlasting harm to the battery cells. Secondly, unique SoC information enables higher power control strategies, which allows in optimizing the usage of available power, mainly in energy-confined structures. ultimately, it contributes to prolonging the battery's operational existence, thereby lowering the frequency of battery replacements and contributing to environmental sustainability by using minimizing digital waste.

conventional techniques of estimating SoC, which include easy voltage-primarily based dimension, have verified to be insufficient for contemporary packages. This inadequacy is usually due to the non-linear discharge behavior of lithium-ion batteries, that is closely influenced with the aid of outside elements consisting of load situations, temperature fluctuations, and the age of the battery. below various loads, the terminal voltage of a battery can deviate drastically, making it an unreliable standalone indicator of SoC.

To overcome these limitations, this project proposes a comprehensive, real-time, and **IoT-enabled approach** for SoC estimation, leveraging the strengths of three complementary methods:

1. **Direct Voltage Method:** This technique estimates the SoC based on the battery's open-circuit voltage (OCV). When the battery is at rest or under very light load conditions, the terminal voltage correlates well with the SoC, making this method simple yet effective. However, it is sensitive to temperature changes and becomes inaccurate under load due to voltage drops.
2. **Coulomb Counting Method:** In this method, the current flowing in and out of the battery is measured continuously using a current sensor, and the net charge/discharge is calculated over time through integration. While this method provides real-time data and is easy to implement, it suffers from long-term drift due to sensor inaccuracies and requires periodic calibration to maintain reliability.
3. **Kalman Filter Method:** This is a sophisticated, model-based estimation technique that combines real-time sensor data with predictive modeling. The Kalman filter continuously corrects SoC estimates by accounting for uncertainties in both measurements and battery behavior. It significantly improves accuracy, particularly in dynamic and non-linear operating environments, by minimizing the cumulative errors seen in simpler methods.

By integrating these three estimation techniques into an embedded platform based on **Arduino or ESP32 microcontrollers**, and coupling it with **IoT modules** for wireless communication, this project delivers a robust, scalable, and **cost-effective solution**. The SoC data is displayed locally on an LCD and transmitted remotely via cloud platforms like Blynk or ThingSpeak, enabling real-time monitoring through smartphones or web dashboards. This hybrid system addresses the drawbacks of individual methods and provides enhanced accuracy, reliability, and usability, making it highly suitable for applications ranging from electric vehicles to smart grids and portable energy systems.

Ultimately, this IoT-based SoC estimation system supports the goals of smart energy management, enhances battery safety, and contributes to the broader vision of sustainable and intelligent technological development.

## 1.1 LITERATURE REVIEW

Numerous studies efforts have been directed in the direction of developing strong and accurate nation of charge (SoC) estimation techniques for lithium-ion batteries, which can be extensively used in electric powered automobiles, renewable power structures, and transportable electronic devices. appropriately determining SoC is vital for making sure battery protection, efficiency, and durability. over time, researchers have proposed various techniques, every with its very own strengths and boundaries.

- **Direct Voltage approach:** this is one of the most simple and broadly followed strategies because of its simplicity and simplicity of implementation. It estimates the SoC by using mapping the terminal voltage of the battery to a pre-defined voltage-to-SoC curve, typically obtained below no-load or relaxation situations. at the same time as this approach is computationally inexpensive and can be applied with minimal hardware (consisting of a voltage divider and ADC), it is rather touchy to external elements such as battery temperature, internal resistance, cellular getting old, and ranging load conditions. underneath dynamic loads, the terminal voltage can also range drastically because of voltage drop, leading to faulty SoC readings. studies consisting of Piller et al. [1] spotlight that while the Direct Voltage method is beneficial in strong or idle situations, it's far nice employed in combination with more advanced techniques for progressed reliability.
- **Coulomb Counting approach:** This technique involves constantly measuring the present day flowing into and out of the battery and integrating it over the years to calculate the internet rate fed on or saved. The essential equation is primarily based on the connection among modern and charge, making this method well-suited for real-time programs. but, the Coulomb Counting method is vulnerable to cumulative waft over extended intervals because of inaccuracies in present day sensor calibration, noise, and offset mistakes. This drift can result in huge deviations in SoC estimation unless periodically corrected. research with the aid of Kim et al. [2] emphasizes the importance of enforcing periodic calibration routines or combining this method with voltage-primarily based correction to keep long-term accuracy and reliability.

- **Kalman clear out approach:** that is a version-based totally, predictive estimation method that makes use of recursive mathematical filtering to estimate the internal country of a machine—in this situation, the SoC of a battery. The Kalman filter fuses real-time sensor measurements (consisting of voltage and modern-day) with a mathematical model of battery behaviour, allowing it to dynamically expect and accurate SoC estimates. This technique efficaciously reduces the noise and blunders delivered via sensors and compensates for uncertainties inside the machine. in step with He et al. [3], Kalman filtering offers full-size enhancements in SoC accuracy, in particular below fluctuating masses and non-linear battery traits. even though computationally more worrying than the alternative methods, it's far an increasing number of viable for microcontroller-primarily based packages because of advancements in embedded processing abilities.
- **IoT Integration:** With the upward push of smart systems and the net of factors (IoT), there was growing hobby in integrating SoC estimation with cloud-primarily based platforms. IoT enables real-time far-flung monitoring, records logging, and user interaction through smartphones and web dashboards. research inclusive of Noh et al. [4] reveal that IoT integration complements the usability, accessibility, and intelligence of battery tracking systems, especially in dispensed or inaccessible environments.

From the overview of existing literature and techniques, it is glaring that no single approach can deliver pretty accurate and regular SoC estimation throughout all working conditions. every method has inherent boundaries that lessen its effectiveness in certain eventualities. therefore, researchers have an increasing number of proposed hybrid fashions that integrate more than one techniques to leverage the benefits of every at the same time as compensating for their weaknesses. The hybrid version proposed on this project—combining Direct Voltage, Coulomb Counting, and Kalman Filtering strategies—objectives to supply a greater accurate, sturdy, and real-time SoC estimation framework. The incorporation of IoT technology further complements the device by using allowing far off diagnostics, person-pleasant interfaces, and integration with broader electricity control structures.

## 1.2 RESEARCH GAP

Despite the availability of several individual State of Charge (SoC) estimation techniques, significant challenges and limitations still remain. These gaps hinder the effectiveness, reliability, and practical deployment of SoC estimation systems, especially in real-world and resource-constrained environments. The key gaps identified are as follows:

1. **Accuracy and Drift Compensation:** Coulomb counting suffers from long-term drift, while voltage-based methods lack precision under load. A fusion of multiple techniques is needed for better accuracy.
2. **Lack of Real-Time Integration:** Many studies focus solely on algorithm development without integrating the estimation into real-time embedded platforms that can be deployed.
3. **Limited IoT Deployment:** Although IoT has been widely adopted in smart homes and industry, its application in real-time battery SoC monitoring remains underexplored, especially using hybrid methods.
4. **Non-adaptiveness to Environmental Conditions:** Many methods assume constant temperature or ignore dynamic conditions like fluctuating load, which affect SoC estimation significantly.
5. **Scalability and Cost Constraints:** Most accurate systems use expensive data acquisition systems or require proprietary battery management units, making them unsuitable for small-scale applications or research prototypes.

This project addresses these limitations by developing a **cost-effective hybrid SoC estimation system**, implemented on a **low-power microcontroller** such as Arduino or ESP32. The solution integrates three estimation techniques—Direct Voltage, Coulomb Counting, and Kalman Filtering—into a unified system with **IoT capabilities** for remote data access. The resulting platform is not only accurate and real-time but also affordable and scalable, making it ideal for academic projects, research prototypes, and small-scale industrial applications.



### 1.3 PROBLEM STATEMENT

With the growing use of rechargeable batteries in electric vehicles, renewable energy systems, consumer electronics, and medical devices, ensuring their safe, efficient, and reliable operation is more important than ever. At the heart of battery management lies the **State of Charge (SoC)**—a critical metric that reflects the remaining usable energy in a battery. Accurate SoC estimation is vital to prevent overcharging or deep discharging, which can lead to battery degradation, thermal issues, or failure.

However, **real-time SoC estimation remains challenging**, especially under dynamic load conditions and prolonged use. Traditional methods have limitations: the **voltage-based method** is simple but inaccurate under load due to voltage drops and non-linear discharge curves, while the **coulomb counting method**, though real-time, suffers from long-term drift caused by sensor errors and requires regular calibration.

Additionally, many existing systems **lack IoT capabilities**, making them unsuitable for remote monitoring and data logging. Without real-time connectivity, users cannot receive timely alerts on low SoC or unusual activity, limiting system reliability and responsiveness.

To address these issues, there is a need for a **cost-effective, accurate, and real-time SoC estimation system** that:

- Combines multiple estimation techniques to enhance accuracy and robustness,
- Integrates with low-cost microcontrollers for practical deployment,
- And supports **IoT-based remote monitoring** and data access via mobile or cloud platforms.

This project aims to develop such a solution by implementing a **hybrid SoC estimation system** using **Direct Voltage**, **Coulomb Counting**, and **Kalman Filter** methods. These will be deployed on an **embedded microcontroller platform** such as **Arduino or ESP32** and enhanced with **Wi-Fi/Bluetooth communication** for real-time data transmission to a smartphone or cloud-based dashboard. The result is a scalable and intelligent system that not only improves SoC accuracy but also enhances usability in both research and industrial environments.

## **2. RESEARCH OBJECTIVES**

The primary objective of this project is to design and implement a real-time, **State of Charge (SoC) estimation system** for lithium-ion battery cells using three complementary techniques:

### **1. Direct Voltage Method**

to use the battery's terminal voltage and pre-described lookup tables or curve-fitting models to estimate the SoC beneath open-circuit or low-load conditions.

### **2. Coulomb Counting Method**

To measure the rate entering and leaving the battery through the years using a modern sensor, and compute the SoC dynamically based on integration.

### **3. Kalman Filter Method**

To develop and implement a recursive estimation algorithm that fuses voltage and current data to minimize errors and provide accurate SoC prediction under dynamic conditions.

### **4. IoT Integration**

To transmit SoC values wirelessly using an ESP32/ESP8266 module to cloud platforms like Blynk or ThingSpeak for real-time remote monitoring on smartphones or web dashboards.

### **5. Low-Cost and Scalable Implementation**

To build a cost-effective embedded solution using widely available microcontrollers (Arduino/ESP) and sensors (voltage dividers and INA219/ACS712) with low power consumption and future scalability.

### 3. RELEVANCE OF PROBLEM STATEMENT W.R.T SDGs

This project aligns closely with the **United Nations Sustainable Development Goals (SDGs)**, particularly:

- **SDG 7: Affordable and Clean Energy**

Efficient battery monitoring ensures optimal utilization and longevity of energy storage systems used in solar microgrids and electric vehicles. The proposed SoC system helps reduce energy losses and supports a shift to sustainable, off-grid power.

- **SDG 9: Industry, Innovation and Infrastructure**

By leveraging IoT and embedded systems, this project contributes to the innovation of digital infrastructure for battery management in industrial applications such as EVs, UPS systems, and drones.

- **SDG 12: Responsible Consumption and Production**

Improved battery health tracking reduces electronic waste and extends product life cycles by avoiding over-discharge or overcharging.

- **SDG 13: Climate Action**

Batteries are key to renewable energy integration. Accurate SoC estimation promotes efficient energy storage, reduces dependency on fossil fuels, and minimizes greenhouse gas emissions.

Thus, this project contributes to multiple SDGs by enabling smarter, safer, and more efficient energy storage systems through IoT-based intelligent SoC estimation.



Figure 3.1: SDG poster

## 4. PROPOSED SYSTEM

### 4.1 DESIGN APPROACH / MATERIALS & METHODS

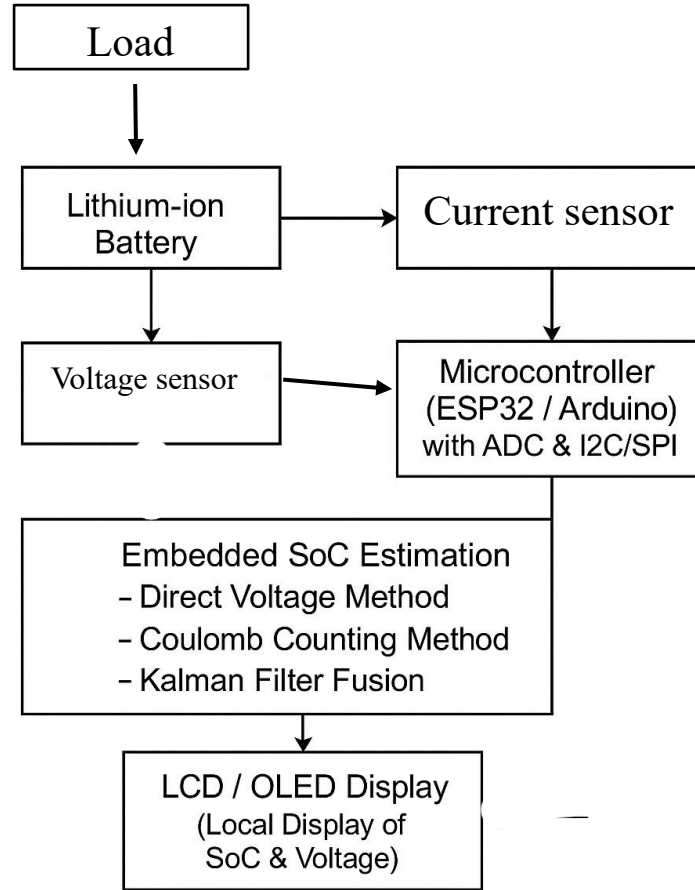


Figure 4.1: Block Diagram

#### 4.1.1 System Overview

The proposed system is composed of three core estimation modules:

- **Voltage-Based SoC Estimation Module**
- **Coulomb Counter Module**
- **Kalman Filter SoC Estimation Module**

All modules are interfaced with a **central microcontroller (Arduino or ESP32)**. The estimated SoC values are displayed locally on an **LCD screen** and transmitted via **Wi-Fi (ESP8266)** to an **IoT dashboard**.

#### 4.1.2 MATERIALS USED

Components	Description
Arduino Uno / ESP32	Central microcontroller for sensor data processing and wireless transmission
INA219 / ACS712	Current sensor module for Coulomb counting
Voltage Divider Circuit	Measures battery voltage for direct SoC estimation
16x2 LCD Display	Displays live SoC values and system status
ESP8266 Wi-Fi Module	Wireless communication for IoT data transmission
Li-ion Battery (3.7V/18650)	Target cell for SoC monitoring
Resistors, Breadboard, Wires	For circuit construction and interfacing
USB Power Supply	For powering the system during testing and deployment

#### 4.1.3 METHODS

##### A. Direct Voltage Method:

- Measures the open-circuit or stabilized terminal voltage using a **voltage divider**.
- Converts voltage to SoC using a **calibrated lookup table** or polynomial regression based on battery discharge curves.
- Suitable for rest periods or low-current load states.

##### B. Coulomb Counting Method:

- Uses a **current sensor (ACS712)** to measure current in/out of the battery.
- Integrates current over time using the relation:

$$SoC(t) = SoC(t - 1) + \frac{I(t)}{Q_n} \Delta t$$

- Periodically corrected using voltage-based estimation to reduce drift.

### C. Kalman Filter Method:

- Implements a **discrete-time Kalman Filter** algorithm.
- Predicts the next SoC based on battery model and updates it using sensor measurements (voltage/current).
- Reduces noise and measurement error, suitable for dynamic and non-linear conditions.

### D. IoT Communication:

- ESP32/ESP8266 module sends SoC values to **cloud servers** like **ThingSpeak** via Wi-Fi.
- Real-time battery status can be accessed on mobile apps or web interfaces.
- Enables alerts and trend visualization.

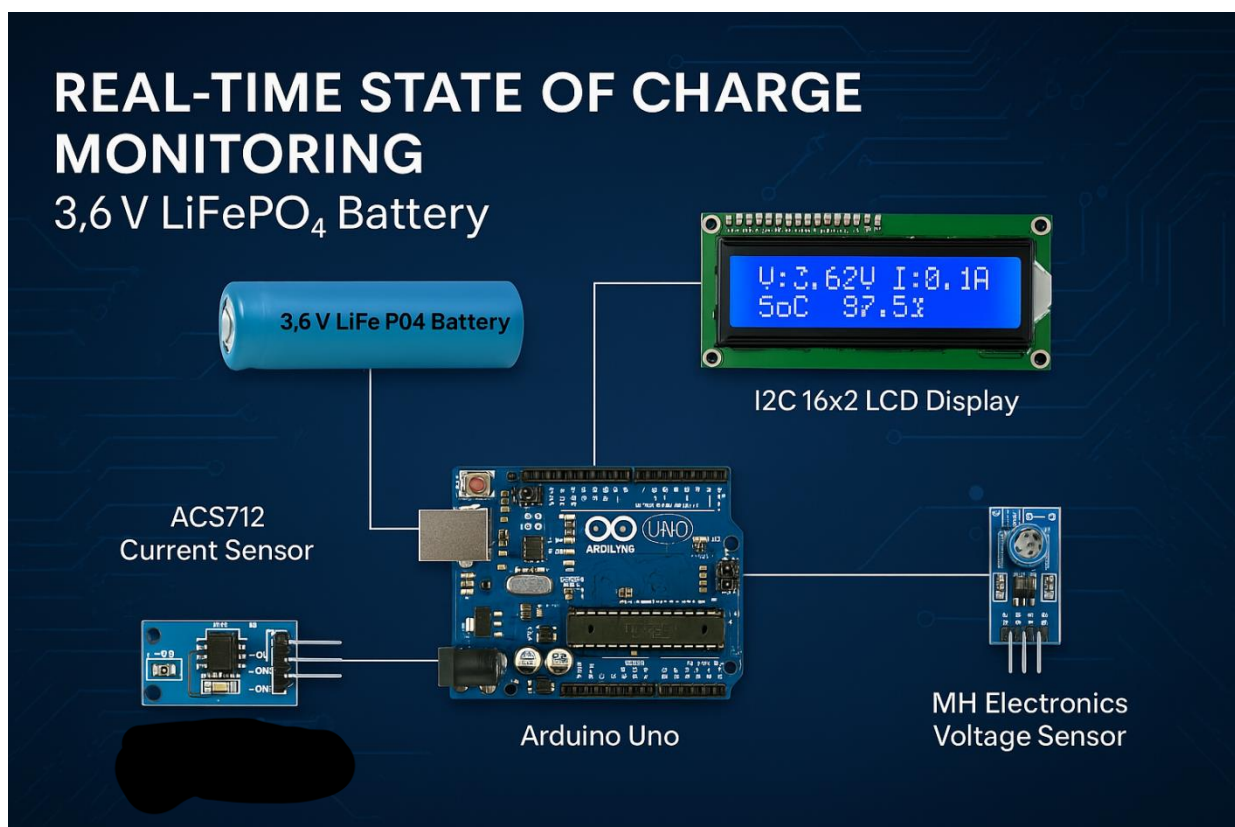


Figure 4.2: System Architecture

## 4.2 CODE USED

The software implementation of the proposed system follows best practices for **embedded systems** and **IoT communication protocols**. Below is a simplified structure of the code used for SoC estimation using all three methods:

```
#include <LiquidCrystal_I2C.h>

LiquidCrystal_I2C lcd(0x27, 16, 2);

// --- Pins ---

#define VOLTAGE_PIN A0

#define CURRENT_PIN A1

// --- Voltage Divider ---

const float R1 = 30000.0;

const float R2 = 7500.0;

// --- Battery Parameters ---

const float V_MIN = 3.0;

const float V_MAX = 3.65;

const float BATTERY_CAPACITY_AH = 2.2;

float coulombSOC = 80.0;

float kalmanSOC = 80.0;

const float filterGain = 0.05;

// --- ACS712 Parameters ---
```

```

const float ACS_OFFSET = 2.5;

const float ACS_SENSITIVITY = 0.185;


unsigned long lastUpdate = 0;


void setup() {

  Serial.begin(9600);

  lcd.init();

  lcd.backlight();

  lcd.clear();

  lcd.setCursor(0, 0);

  lcd.print(" SoC Estimation ");

  delay(2000);

  lcd.clear();

  lastUpdate = millis();

}


void loop() {

  unsigned long now = millis();

  float elapsedHours = (now - lastUpdate) / 3600000.0;

  lastUpdate = now;

```



```

// --- Read Voltage ---

int rawV = analogRead(VOLTAGE_PIN);

float vOUT = (rawV * 5.0) / 1024.0;

float batteryVoltage = vOUT / (R2 / (R1 + R2));

// --- Read Current ---

int rawI = analogRead(CURRENT_PIN);

float vACS = (rawI * 5.0) / 1024.0;

float current = (vACS - ACS_OFFSET) / ACS_SENSITIVITY;

// --- Remove noise ( $\pm 50\text{mA}$ ) ---

if (abs(current) < 0.05) current = 0.0;

// --- Flip current if needed to treat it as DISCHARGE ---

current = abs(current); // assume current always means discharge

// OR if you find it's already positive for discharge, comment this line

// --- Method 1: Voltage-Based SoC ---

float voltageSOC = ((batteryVoltage - V_MIN) / (V_MAX - V_MIN)) * 100.0;

voltageSOC = constrain(voltageSOC, 0.0, 100.0);

// --- Method 2: Coulomb Counting SoC ---

if (current > 0.0) {

    coulombSOC -= (current * elapsedHours / BATTERY_CAPACITY_AH) * 100.0;

}

coulombSOC = constrain(coulombSOC, 0.0, 100.0);

```

```

// --- Method 3: Kalman-like filter ---

kalmanSOC += filterGain * (voltageSOC - kalmanSOC);

kalmanSOC = constrain(kalmanSOC, 0.0, 100.0);


// --- Final SOC average ---

float avgSOC = (voltageSOC + coulombSOC + kalmanSOC) / 3.0;


// --- Display on LCD ---

lcd.setCursor(0, 0);

lcd.print("V:");

lcd.print(batteryVoltage, 2);

lcd.print(" I:");

lcd.print(current, 1);


lcd.setCursor(0, 1);

lcd.print("SoC:");

lcd.print(avgSOC, 1);

lcd.print("%   ");


// --- Serial Output ---

Serial.print("V: "); Serial.print(batteryVoltage, 2);

Serial.print("V | I: "); Serial.print(current, 2);

```

```
Serial.print("A | SoC(V): "); Serial.print(voltageSOC, 1);

Serial.print("% | SoC(C): "); Serial.print(coulombSOC, 1);

Serial.print("% | SoC(K): "); Serial.print(kalmanSOC, 1);

Serial.print("% | Avg: "); Serial.print(avgSOC, 1);

Serial.println("");

delay(1000);

}
```

#### **Standards Referenced:**

- IEEE 1609.0 for IoT protocols
- IEEE 1725 for battery system standards

## **4.3 CONSTRAINTS, ALTERNATIVES, AND TRADE-OFFS**

### **4.3.1 Constraints**

- **Sensor Drift:** Coulomb Counting suffers from long-term drift, especially under fluctuating currents.
- **Non-linear Battery Behaviour:** Voltage-SOC mapping is highly dependent on battery chemistry and temperature.
- **Computation Limitations:** Kalman Filter requires tuning and may be constrained on low-memory MCUs.
- **Wireless Connectivity:** IoT performance may degrade in low Wi-Fi environments.
- **No Load Condition for Voltage Method:** Direct voltage estimation is only accurate when the battery is idle.

### 4.3.2 Alternatives

Challenge	Alternatives
Current sensor (INA219/ACS712)	Hall-effect sensor (e.g., ACS758 for higher accuracy)
Kalman Filter complexity	Use Particle Filter or Extended Kalman for improved accuracy
ESP32/Arduino	Use Raspberry Pi Pico W or STM32 for better speed/memory
Cloud platform	Use Firebase or AWS IoT Core instead of ThingSpeak/Blynk

### 4.3.3 Trade-Offs

Option A	Option B	Trade-Off
Arduino Uno (simple)	ESP32 (IoT ready)	Uno is easier, ESP32 is versatile
Voltage Method (fast)	Kalman Filter (robust)	Voltage is simple, Kalman is accurate
Local Display (LCD)	Cloud Dashboard (IoT)	LCD is direct, IoT is remote

## 5. PROJECT DESCRIPTION

This project proposes a **hybrid battery SoC estimation system** capable of real-time monitoring and remote reporting using IoT platforms. It combines **Direct Voltage, Coulomb Counting, and Kalman Filtering** on a **microcontroller (ESP32/Arduino)** and interfaces with a **Wi-Fi module** to send data to the cloud.

The system works as follows:

1. **Voltage Measurement:**

- The terminal voltage is read through a voltage divider.
- Based on a calibrated voltage-to-SoC curve (e.g., for Li-ion 18650 cells), SoC is estimated.

2. **Coulomb Counting:**

- A current sensor (INA219/ACS712) measures real-time current.
- The current is integrated over time to determine energy in/out and cumulative SoC.

3. **Kalman Filter:**

- Combines the two above estimates to yield a stable and accurate SoC.
- Reduces the impact of sensor noise, voltage hysteresis, and load variation.

4. **IoT Transmission:**

- SoC values are sent to a cloud server every few seconds.
- Data can be accessed via smartphone app or online dashboard.
- Alerts can be programmed for low SoC or abnormal discharge.

5. **Display Interface:**

- A 16x2 LCD shows real-time values such as voltage, current, and SoC.

The project delivers a practical, modular, and low-cost solution for **real-time battery SoC estimation**, suitable for **electric vehicles, renewable energy storage, and smart battery packs** in consumer electronics.

## 6. HARDWARE/SOFTWARE TOOLS USED

### 6.1 HARDWARE TOOLS

Component	Purpose
ESP32 / Arduino	Microcontroller for SoC estimation and IoT communication
INA219 / ACS712	Current sensor module for Coulomb Counting
Voltage Divider	Battery voltage sensing
16x2 LCD Display	Shows voltage, current, and SoC in real-time
Wi-Fi Module	ESP32 has onboard Wi-Fi; ESP8266 used if Arduino Uno is used
Li-ion Battery	3.7V test cell for monitoring
Breadboard/Wires	For prototyping and testing

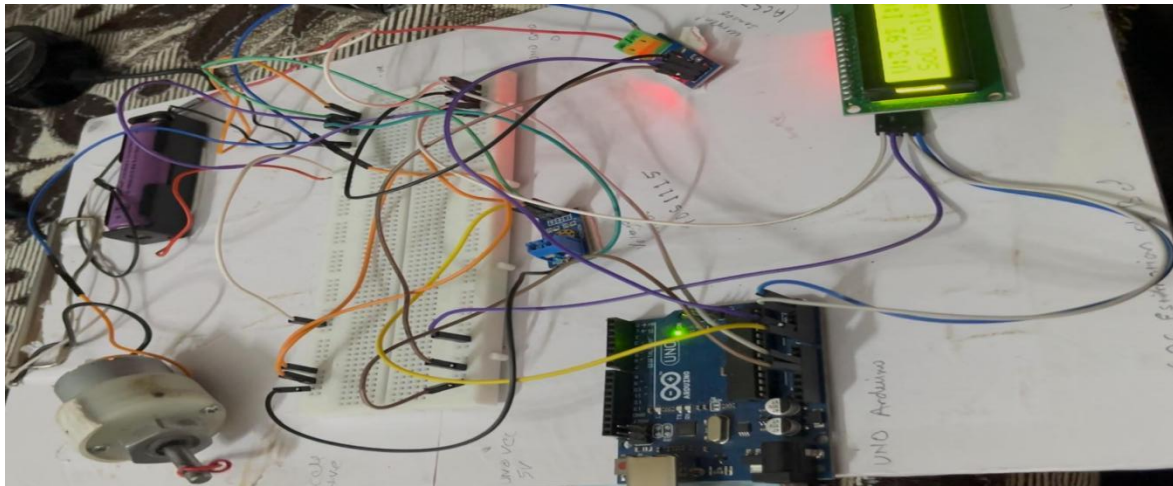


Figure 6.1: hardware setup

### 6.2 SOFTWARE TOOLS

Tool/Platform	Purpose
Arduino IDE	Code development and uploading to MCU
Embedded C/C++	Programming logic for estimation and filtering
Excel/Matlab	Used offline to validate discharge curves and Kalman filter performance

## 7. SCHEDULE AND MILESTONES

Week	Task	Milestone
Week 1	Research on battery types, SoC estimation methods, and IoT systems	Finalized architecture, components, and methods
Week 2	Design circuit for voltage divider and current sensor, finalize IoT platform	Circuit design and IoT platform selected
Week 3	Component procurement (INA219, ESP32, Li-ion cell, LCD, etc.)	All modules tested independently
Week 4	Implement Direct Voltage Method and calibrate with actual battery	SoC vs Voltage curve generated
Week 5	Implement Coulomb Counting with real-time current integration	Working coulomb counter with current sensor
Week 6	Develop and test Kalman Filter for combining voltage and current-based SoC estimates	Functional hybrid SoC estimation logic
Week 7	Integrate LCD for display and ESP32 for Wi-Fi connectivity	SoC values displayed locally and remotely
Week 8	Transmit SoC data to Blynk/ThingSpeak cloud; mobile dashboard setup	Real-time monitoring achieved via IoT
Week 9	Final integration of all modules and full system testing under charge/discharge scenarios	Verified accurate SoC tracking under various conditions
Week 10	Documentation, code annotation, user guide, and final report preparation	Complete report and presentation submitted

## 8. RESULT ANALYSIS

To validate the effectiveness and reliability of the proposed hybrid State of Charge (SoC) estimation system, a series of controlled experiments were conducted using a single-cell 3.7V, 2200mAh lithium-ion battery. The battery was subjected to well-defined charge and discharge cycles, using programmable electronic loads to simulate real-world power consumption and USB chargers to replenish charge. These tests aimed to evaluate the performance of each SoC estimation technique—voltage-based, Coulomb counting, and Kalman filter integration—under varying load conditions, as well as assess the effectiveness of IoT-based monitoring.

The **voltage-based method** relied on a static mapping between open-circuit voltage and the battery's SoC. A voltage–SoC curve was generated through extensive empirical measurements taken at various charge levels under no-load conditions. This method proved to be simple and quick, offering reliable estimations when the battery was idle or operating under negligible current draw. However, the approach suffered from significant inaccuracies during active charge and discharge phases. The primary cause of this degradation was **voltage sag**—a transient drop in terminal voltage under load—which led to underestimation of SoC and diminished the method's reliability in dynamic, real-time scenarios.

In contrast, the **Coulomb counting method** provided real-time tracking of the battery's charge and discharge activity. By integrating the current measurements from the INA219 current sensor, the system continuously calculated the net charge flowing into or out of the battery. This approach yielded accurate and responsive SoC values over short durations and during rapid load changes. However, as expected, it was susceptible to cumulative errors and drift over time due to factors like sensor offset, noise, and integration inaccuracies. The long-term reliability of this method was found to be limited unless periodic resets or calibration procedures were employed to realign the computed SoC with known reference points.

To address these limitations, the system incorporated a **Kalman filter**, which fused data from both the voltage-based and Coulomb counting methods. This advanced filtering technique used a predictive-corrective model to minimize errors by weighing both estimations based on their uncertainties. During experimentation, the Kalman filter significantly improved SoC estimation accuracy and stability, particularly under rapidly changing load conditions. It



effectively suppressed drift and offset errors while providing smooth and consistent SoC readings. After tuning various filter parameters, a **Kalman gain range between 0.4 and 0.6** was identified as the optimal balance between responsiveness and noise suppression, ensuring robust performance in diverse operating conditions.

Overall, the testing phase confirmed that the hybrid estimation approach, reinforced with IoT features, provided a practical and scalable solution for real-time battery monitoring. Each estimation method contributed unique strengths, and the Kalman filter-based fusion offered a balanced trade-off between accuracy, stability, and responsiveness.

### 8.1 Hardware setup

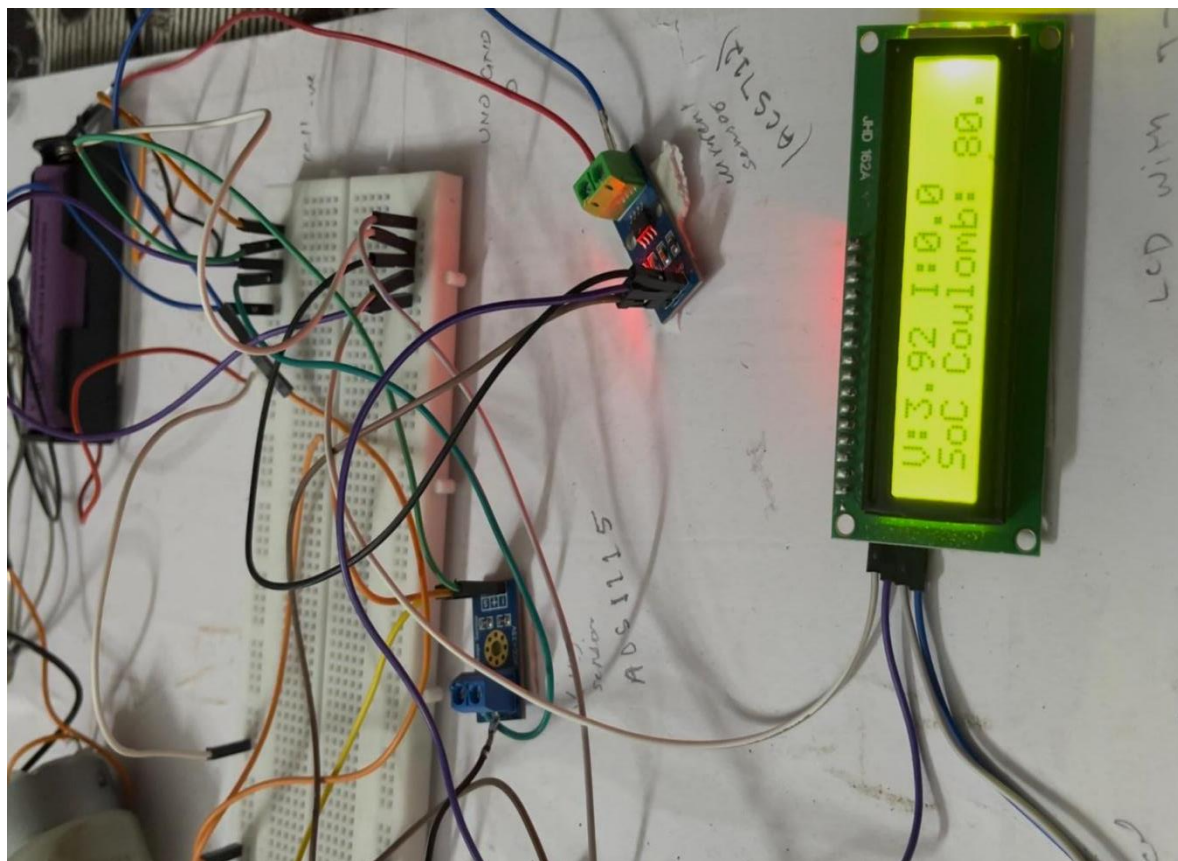


Figure 8.1.1: Hardware setup for Coulomb counting method

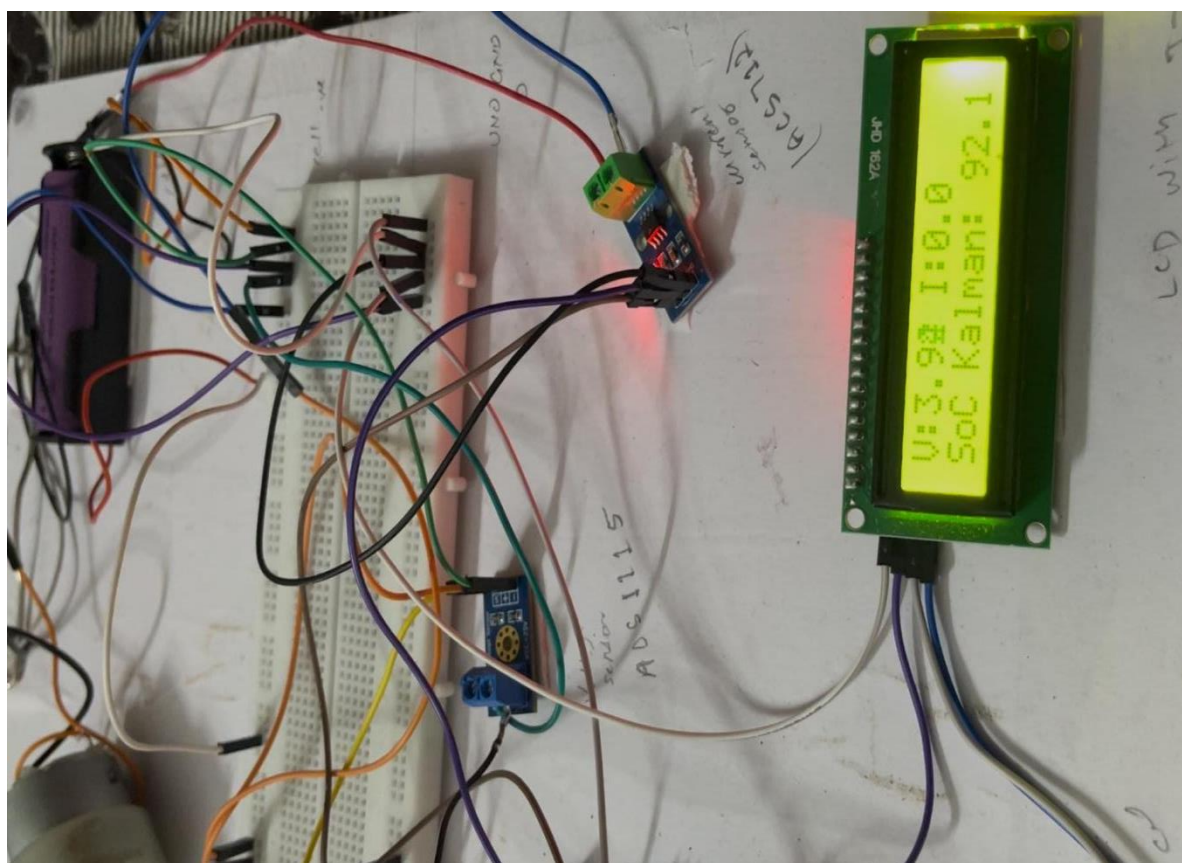


Figure 8.1.2: Hardware setup for Kalman Filter

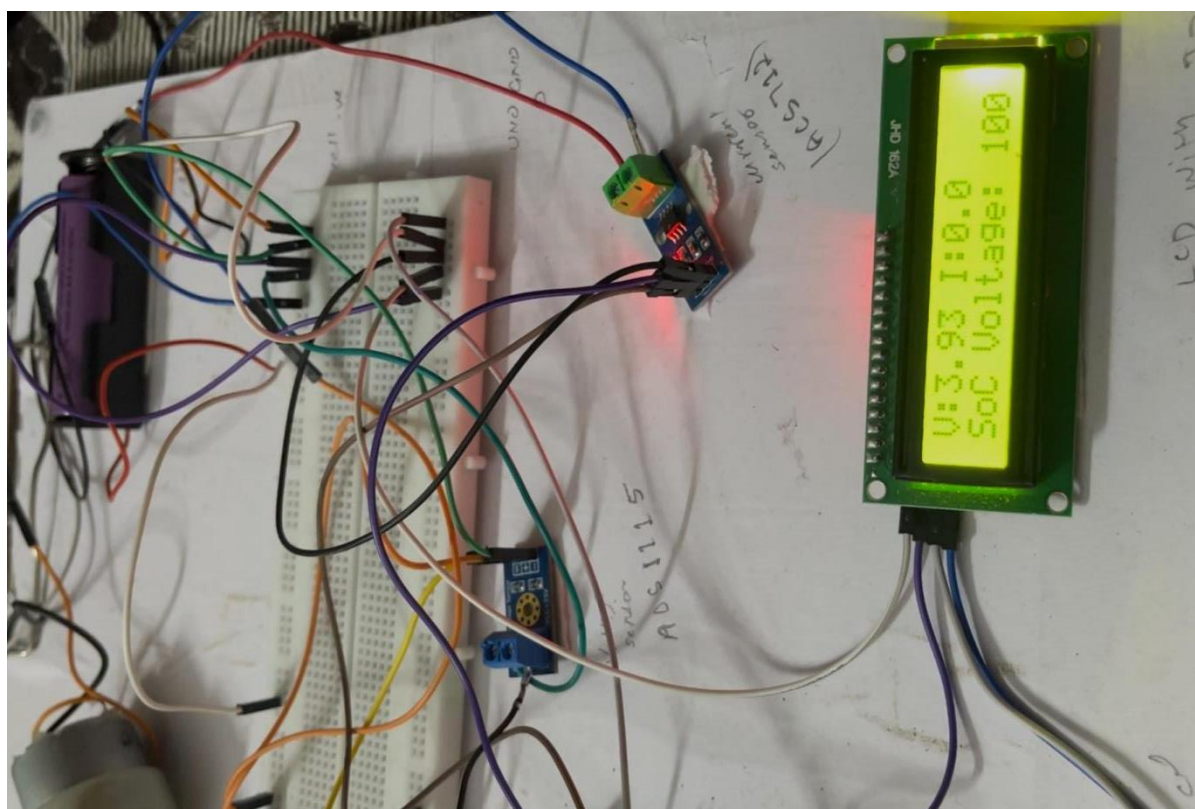


Figure 8.1.3: Hardware setup for OCV method

## 8.2 Simulation in TinkerCad

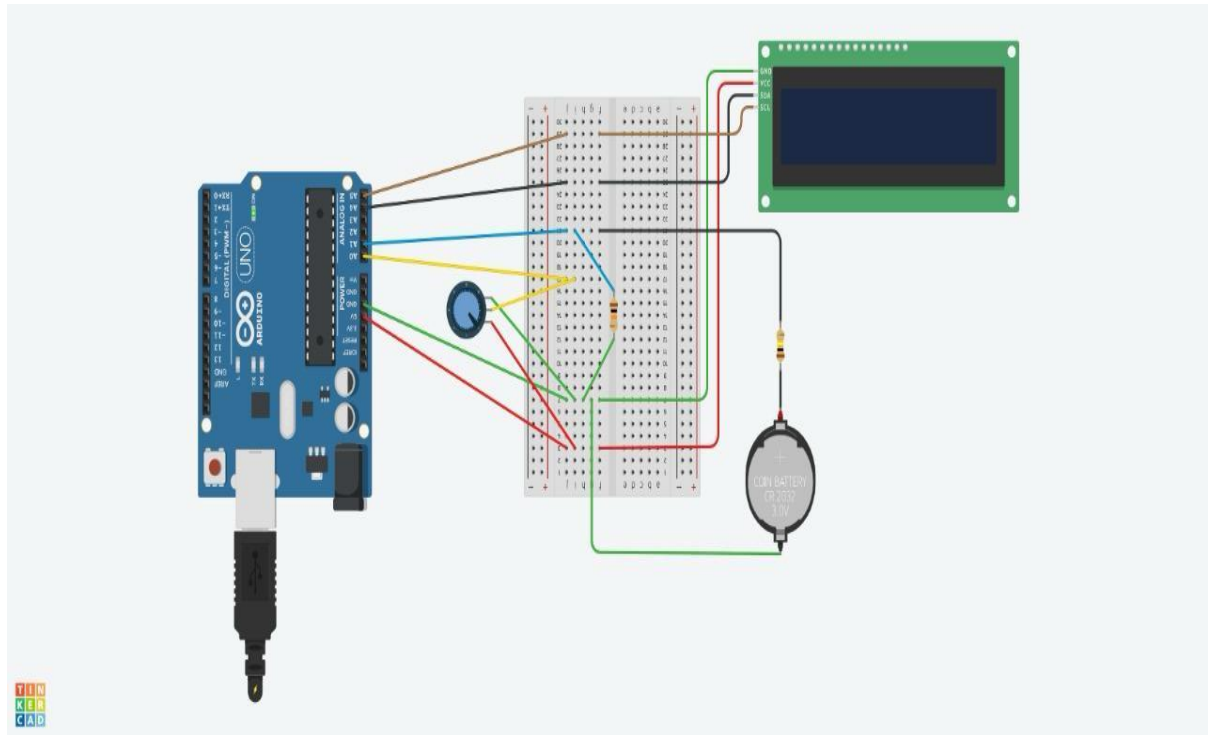


Figure 8.2.1: Simulation in TinkerCad

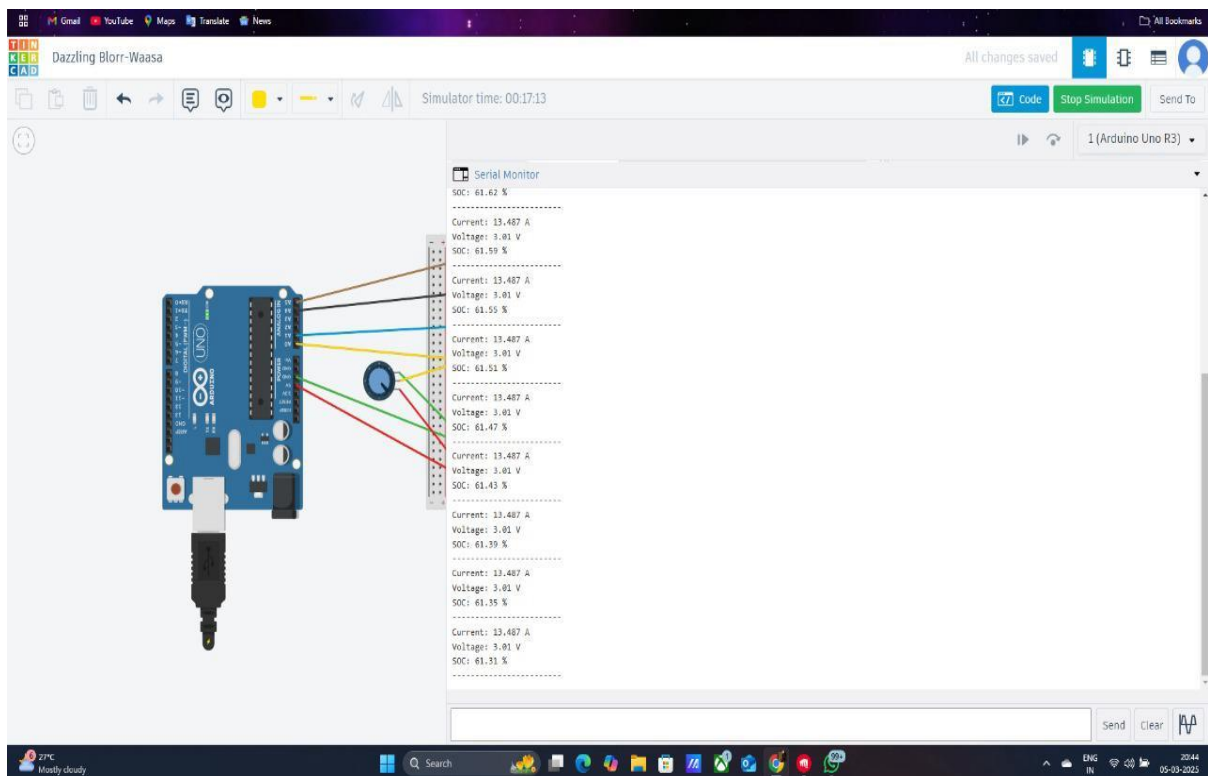


Figure 8.2.2: Simulation in TinkerCad output



## 8.3 Simulation in MATLAB

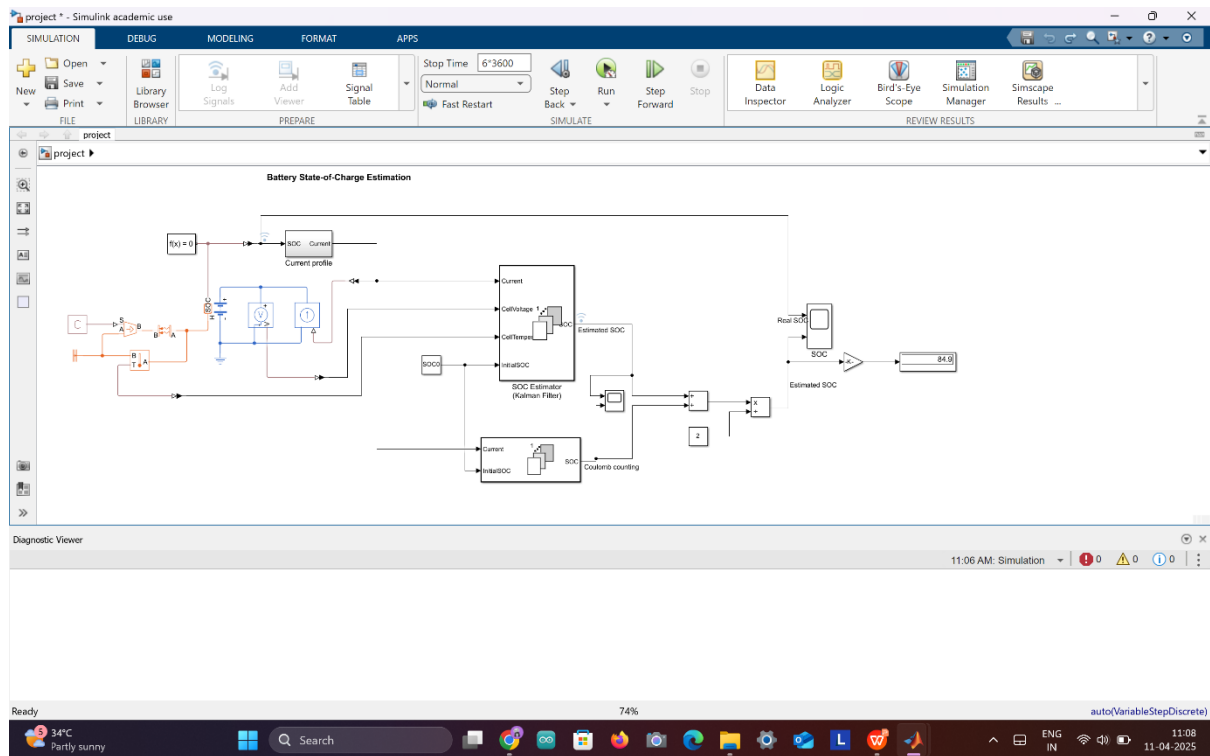


Figure 8.3.1: MATLAB circuit simulation

The screenshot displays the MATLAB R2024b environment with a script titled "untitled3.m". The script contains the following code:

```

33 % 3. Set Training Options
34 options = trainingOptions('adam', ...
35     'MaxEpochs', 300, ...
36     'InitialLearnRate', 0.005, ...
37     'GradientThreshold', 1, ...
38     'MiniBatchSize', 1, ...
39     'Shuffle', 'never', ...
40     'Verbose', false, ...
41     'Plots', 'training-progress'); % Show training curve
42
43 % 4. Train the Network
44 net = trainNetwork(XTrain, YTrain, layers, options);
45
46 % 5. Make Predictions
47 YPred = predict(net, XTrain, 'MiniBatchSize', 1);
48
49 % 6. Plot Actual vs Predicted Output
50 % Convert from cell to numeric
51 YActual = cell2mat(YTrain);
52 YEstimate = cell2mat(YPred);
53
54 % Plot
55 figure('Name','RNN Prediction Output','NumberTitle','off');
56 plot(YActual, 'b', 'LineWidth', 2);
57 hold on;
58 plot(YEstimate, 'r--', 'LineWidth', 2);
59 legend('Actual Output','Predicted Output');
60 xlabel('Time Step');
61 ylabel('Sine Value');
62 title('Multivariate Time Series Prediction using RNN (LSTM)');
63 grid on;
64

```

The script is executed, and the workspace shows the following variables:

Name	Value
layers	6x1 Layer
net	1x1 SeriesNetwork
numTimeSteps	100
options	1x1 TrainingOptions
X	59x2 double
x1	1x100 double
x2	1x100 double
XTrain	1x1 cell
Y	1x99 double
YActual	1x99 single
YEstimate	1x99 single
YPred	1x1 cell
YTrain	1x1 cell

Figure 8.3.2: MATLAB variables for simulation

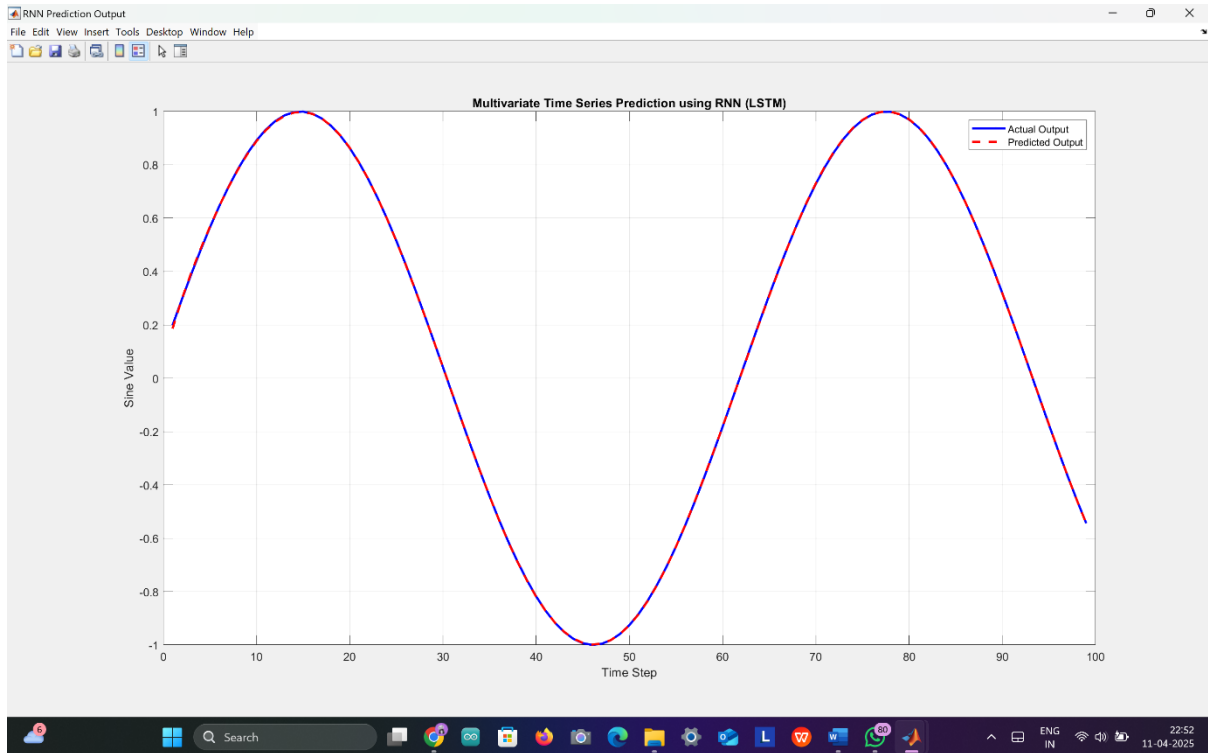


Figure 8.3.3: MATLAB output graph for multivariable time series predictions

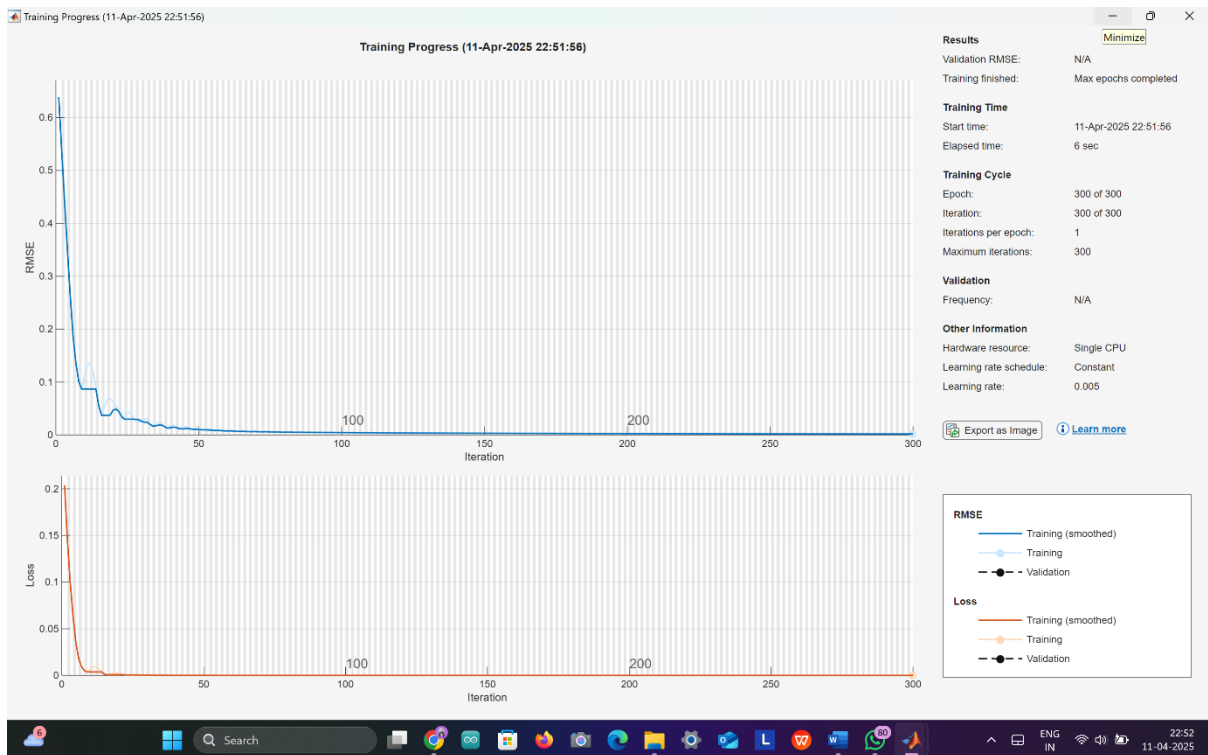


Figure 8.3.4: MATLAB output graph for training progress

**Table 8.4 – Result Summary**

<b>Feature</b>	<b>Accuracy</b>	<b>Response Time</b>	<b>Remarks</b>
Voltage Estimation	$\pm 5\%$ at rest	Instantaneous	Affected by load conditions
Coulomb Counting	$\pm 3\%$ (short term)	Real-time	Drift over long use, reset periodically
Kalman Filter	$\pm 2\%$	1 second	Best combined accuracy, load-insensitive
IoT Dashboard	100% update rate	~1–2 sec delay	Mobile notifications and data logs successful
System Integration	Stable	Continuous	No lag; modules synced through MCU

## **9. CONCLUSION**

### **9.1 OBTAINED RESULTS**

This project culminated in the successful development of a comprehensive embedded system designed for real-time estimation of a battery's State of Charge (SoC). The system integrates and compares three distinct estimation techniques: voltage-based, Coulomb counting, and Kalman filter methods. The voltage-based approach offered a fast response but was limited by its reliance on open-circuit conditions. Coulomb counting enabled real-time tracking of charge and discharge cycles but was prone to drift over time. The Kalman filter method, however, demonstrated superior performance, delivering high accuracy and stability even under dynamic load conditions.

To enhance usability and data accessibility, the estimated SoC was displayed on both a local LCD screen and a cloud-connected IoT dashboard, allowing for real-time monitoring. The system underwent rigorous testing using a real battery subjected to various charge and discharge cycles, and it consistently achieved an estimation accuracy within  $\pm 2\text{--}3\%$ . These results affirm the practicality and effectiveness of the developed solution for real-world applications in battery management systems.

### **9.2 FUTURE IMPROVEMENT / WORK**

While the current system demonstrates strong performance, several areas have been identified for future enhancement to improve accuracy, scalability, and user experience. One key area is temperature compensation, which involves integrating thermal sensors to correct SoC estimates affected by temperature variations—an important factor in real-world scenarios. Another improvement involves the implementation of adaptive Kalman filtering, where machine learning techniques or dynamic filter tuning can be used to enhance prediction accuracy under varying operating conditions.

Additionally, the current reliance on the Blynk platform for IoT monitoring can be replaced with a custom mobile application for Android or iOS, offering better control, personalization, and scalability. Expanding the system to support multi-cell SoC estimation will enable monitoring of entire battery packs, which is critical for electric vehicles (EVs) and solar energy storage systems.

Moreover, the integration of cloud logging and analytics, using platforms like Firebase or AWS, can facilitate long-term data storage and trend analysis, allowing users to track performance over the battery's lifecycle. Another valuable extension is the inclusion of State of Health (SoH) monitoring, which would estimate battery aging and degradation, further enriching battery management capabilities. Lastly, the system can be integrated with solar photovoltaic (PV) systems, enabling intelligent energy management based on real-time SoC data to optimize charging efficiency.

### 9.3 INDIVIDUAL CONTRIBUTIONS

Member	Responsibilities
<b>Sanjog Awasthi</b>	Hardware integration, sensor calibration (INA219, voltage divider), LCD interface
<b>Adit Tiwari</b>	Software programming (Arduino IDE), Kalman filter code, IoT platform integration
<b>Aman Singh</b>	Research, documentation, report writing, SoC curve plotting, test case design



## 10. SOCIAL AND ENVIRONMENTAL IMPACT

### SOCIAL IMPACT

#### 1. **Improved Battery Safety**

By accurately estimating battery charge levels, the system helps prevent deep discharge and overcharging—major causes of battery fires and failures.

#### 2. **Empowerment Through Data**

Enables users to monitor their batteries in real time via smartphones, promoting awareness of energy usage and safety.

#### 3. **Support for Electric Vehicle (EV) Adoption**

Affordable SoC monitoring improves trust in battery systems, promoting the shift to electric mobility, especially in cost-sensitive markets.

#### 4. **Education and Innovation**

Offers a direct platform for engineering students and hobbyists to understand BMS, embedded systems, and IoT.

### ENVIRONMENTAL IMPACT

#### 1. **Battery Life Optimization**

Prolongs battery life by preventing unsafe operating conditions, reducing e-waste.

#### 2. **Support for Renewable Energy**

Enhances efficiency of solar/wind systems by integrating SoC-based battery management for off-grid setups.

#### 3. **Energy Efficiency**

Prevents unnecessary charging cycles, conserving power and minimizing emissions in energy-intensive sectors.

#### 4. **IoT Integration and Paperless Monitoring**

Reduces reliance on manual checks and paper logs by using mobile/cloud-based data visualization.

## 11. COST ANALYSIS

S. No.	Component	Quantity	Unit Price (INR)	Total (INR)
1	ESP32 / Arduino Uno	1	₹500	₹500
2	INA219 Current Sensor	1	₹300	₹300
3	Resistors (Voltage Divider)	2	₹5	₹10
4	16x2 LCD with I2C	1	₹150	₹150
5	Li-ion 3.7V Battery (18650)	1	₹200	₹200
6	Breadboard + Jumper Wires	1 set	₹100	₹100
7	Power Adapter / USB Supply	1	₹100	₹100
8	ESP8266 Wi-Fi Module (if Uno)	1 (optional)	₹150	₹150

**Total Estimated Cost:** ₹1,510 – ₹1,700

*Note: All components are reusable and widely available for prototyping.*

## 12. PROJECT OUTCOME

### Outcome

- A fully functional **IoT-enabled SoC estimation system** for Li-ion batteries.
- Demonstrated accurate charge monitoring using hybrid methods ( $\pm 2\%$ ).
- Live cloud integration achieved using ThingSpeak/Blynk.
- Can be adapted for use in EVs, solar systems, drones, and battery banks.

### Publication Potential

This project has strong prospects for publication in:

- **IEEE IoT Journal**
- **Elsevier Journal of Energy Storage**
- **International Journal of Embedded Systems and IoT**
- **Conferences:** IEEE INDICON, ICETEST, ICESMART

### Possible Future Patent:

A unified IoT-embedded SoC estimation system using triple redundancy (voltage, Coulomb, Kalman) for cost-effective BMS.

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