

# CV\_Intern\_Visionlab\_IITD\_Assignment\_Sep\_2024

This report outlines the experiments and results of the assignment given by IITD. It involved the evaluation, analysis and fine tuning of the DINO object detection model on a pedestrian dataset containing 200 images.

## Ground Truth Visualization





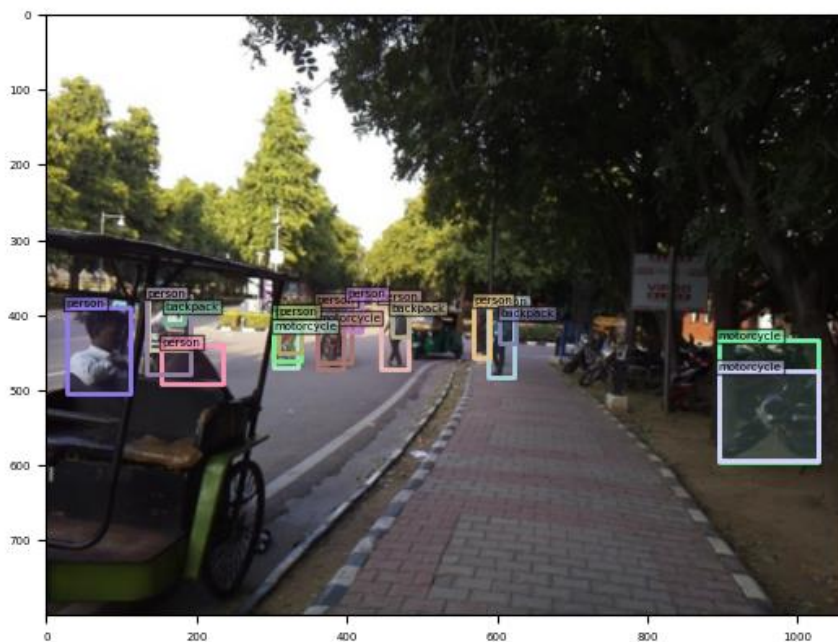
## Inference and Evaluation on pre-trained weights

Bounding box AP values with pre-trained model:

IoU metric: bbox						
Average Precision	(AP) @[	IoU=0.50:0.95	area=	all	maxDets=100	] = 0.484
Average Precision	(AP) @[	IoU=0.50	area=	all	maxDets=100	] = 0.845
Average Precision	(AP) @[	IoU=0.75	area=	all	maxDets=100	] = 0.505
Average Precision	(AP) @[	IoU=0.50:0.95	area=	small	maxDets=100	] = 0.406
Average Precision	(AP) @[	IoU=0.50:0.95	area=	medium	maxDets=100	] = 0.590
Average Precision	(AP) @[	IoU=0.50:0.95	area=	large	maxDets=100	] = 0.795
Average Recall	(AR) @[	IoU=0.50:0.95	area=	all	maxDets= 1	] = 0.100
Average Recall	(AR) @[	IoU=0.50:0.95	area=	all	maxDets= 10	] = 0.492
Average Recall	(AR) @[	IoU=0.50:0.95	area=	all	maxDets=100	] = 0.603
Average Recall	(AR) @[	IoU=0.50:0.95	area=	small	maxDets=100	] = 0.545
Average Recall	(AR) @[	IoU=0.50:0.95	area=	medium	maxDets=100	] = 0.687
Average Recall	(AR) @[	IoU=0.50:0.95	area=	large	maxDets=100	] = 0.836

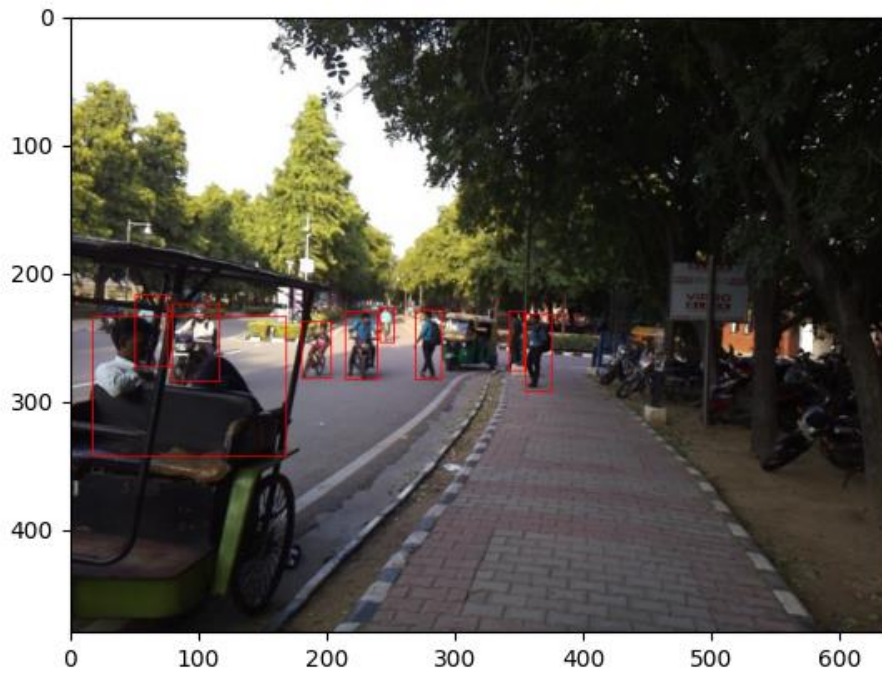
## Analysis

Inference with pre-trained model (checkpoint0033\_4scale.pth):





Ground truth:



- Results are fairly consistent with the ground truth. Larger objects are detected with more average precision while smaller objects with lesser AP.
- False negatives for people who are sitting and are farther away (see middle left)



## **Errors encountered**

- DINO\_train.sh and DINO\_eval.sh needed specific versions of numpy and yapf to work. Solved it by “pip install numpy==1.23.5 yapf==0.40.1”
- While setup, test.py gave CUDA out of memory error for dimensions higher than 71 in the following code:

```
for channels in [30, 32, 64, 71, 1025, 2048, 3096]:
    check_gradient_numerical(channels, True, True, True)
```

Since it was only a testing code, I removed dimensions  $\geq 1025$

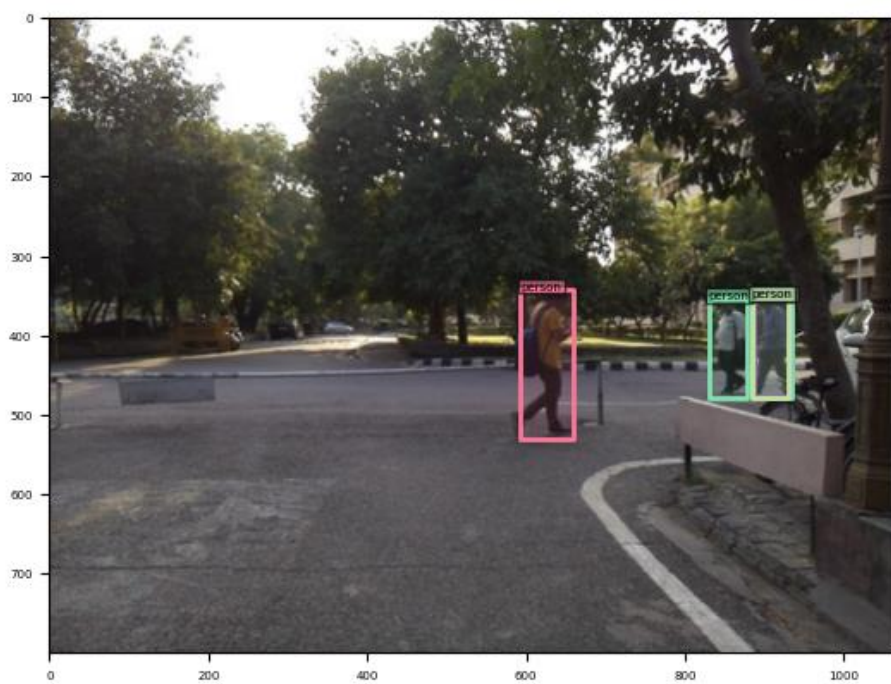
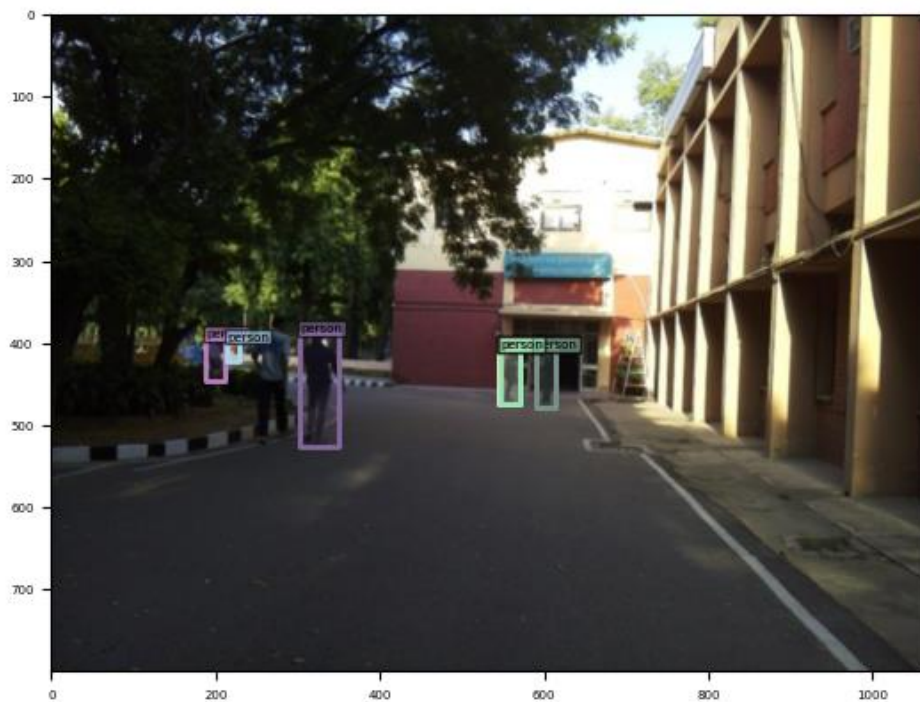
- Few config errors that were resolved by correcting the params (num\_classes, dn\_labelbook\_size, etc)
- When trying to add the `--save_results` flag in DINO\_train.sh and DINO\_eval.sh, it threw a `RuntimeError: Sizes of tensors must match except in dimension 1. This error was caused in engine.py within the “if arg.save_results:” block. Couldn’t resolve it in time.`

## Inference and Evaluation on fine-tuned weights

- lr=0.00025
- epochs=30

```
IoU metric: bbox
Average Precision (AP) @[ IoU=0.50:0.95 | area= all | maxDets=100 ] = 0.305
Average Precision (AP) @[ IoU=0.50 | area= all | maxDets=100 ] = 0.628
Average Precision (AP) @[ IoU=0.75 | area= all | maxDets=100 ] = 0.248
Average Precision (AP) @[ IoU=0.50:0.95 | area= small | maxDets=100 ] = 0.247
Average Precision (AP) @[ IoU=0.50:0.95 | area=medium | maxDets=100 ] = 0.447
Average Precision (AP) @[ IoU=0.50:0.95 | area= large | maxDets=100 ] = 0.252
Average Recall (AR) @[ IoU=0.50:0.95 | area= all | maxDets= 1 ] = 0.076
Average Recall (AR) @[ IoU=0.50:0.95 | area= all | maxDets= 10 ] = 0.368
Average Recall (AR) @[ IoU=0.50:0.95 | area= all | maxDets=100 ] = 0.548
Average Recall (AR) @[ IoU=0.50:0.95 | area= small | maxDets=100 ] = 0.480
Average Recall (AR) @[ IoU=0.50:0.95 | area=medium | maxDets=100 ] = 0.680
Average Recall (AR) @[ IoU=0.50:0.95 | area= large | maxDets=100 ] = 0.571
```

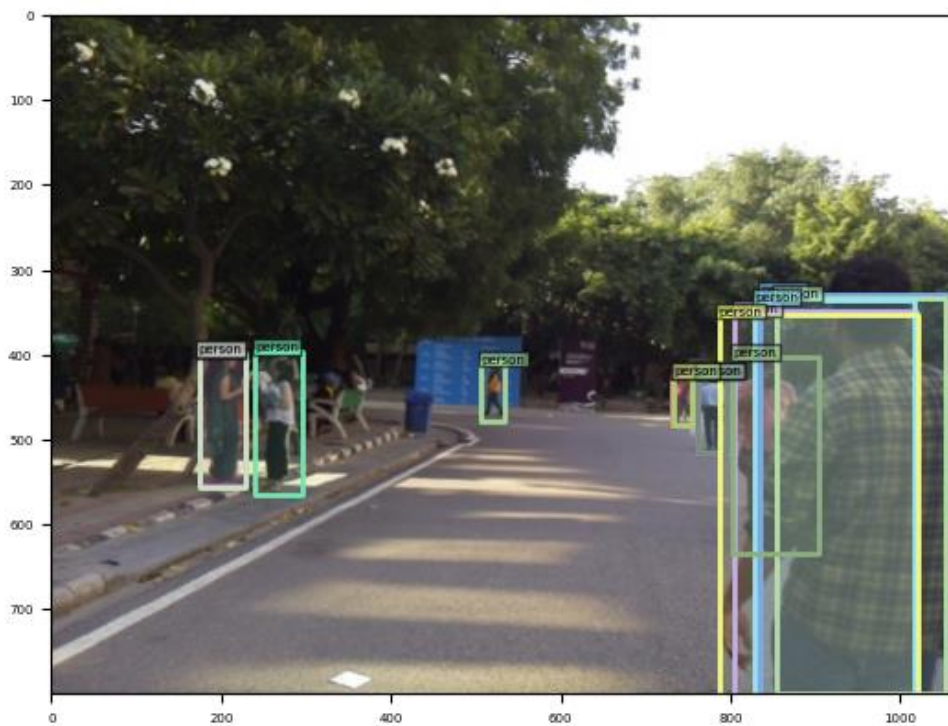






## Observations:

- Lots of false positives (overlapping bounding boxes) for small and large objects. Possibly, due to IOU threshold value.





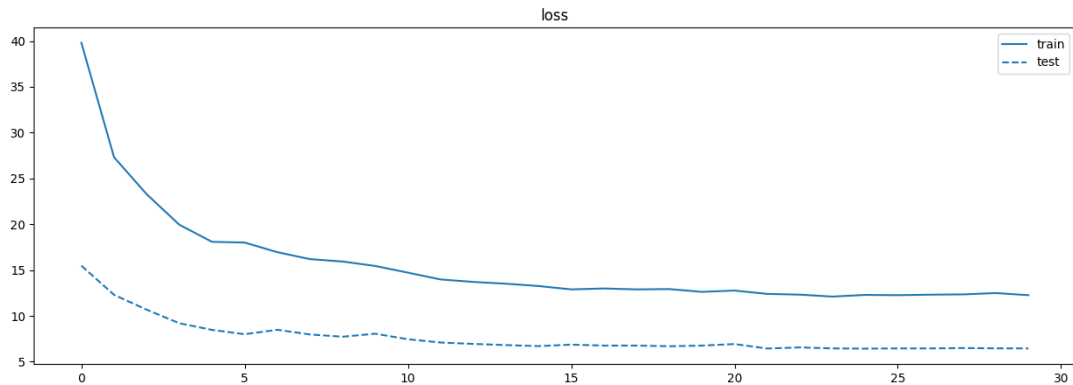
- Low sample size but occlusion handled well in this case:



- False negative for sitting people



Loss plot:



Due to time constraints (practical exam on 23<sup>rd</sup> Sept), I wasn't able to experiment more. If I could, I would've experimented by doing the following:

- Lower learning rate, around 0.0001 (I used 0.00025)
- If I had access to more GPU memory, I would have increased batch size (I used batch size of 2)
- Since the dataset is smaller, I would have run it for more epochs (I ran it for 30 epochs)
- In DETR based models, num\_queries generally refers to the number of object queries used in the model. It correlates to the number of objects the model can detect in a single image. Default value is 900. I would've tried with a smaller value (200-500)
- Since it's a small dataset which I'm running for more epochs, I would slightly increase weight decay to prevent overfitting. Weight decay adds a penalty term to the loss function that is proportional to the sum of the squared weights in the model.