

Appendix A

FSP Quick Reference

A.1 Processes

A process is defined by a one or more local processes separated by commas. The definition is terminated by a full stop. `STOP` and `ERROR` are primitive local processes.

Example

```
Process = (a -> Local) ,
Local   = (b -> STOP) .
```

Action Prefix <code>-></code>	If x is an action and P a process then $(x \rightarrow P)$ describes a process that initially engages in the action x and then behaves exactly as described by P .
Choice <code> </code>	If x and y are actions then $(x \rightarrow P \mid y \rightarrow Q)$ describes a process which initially engages in either of the actions x or y . After the first action has occurred, the subsequent behavior is described by P if the first action was x and Q if the first action was y .
Guarded Action when	The choice (when $B \ x \rightarrow P \mid y \rightarrow Q$) means that when the guard B is true then the actions x and y are both eligible to be chosen, otherwise if B is false then the action x cannot be chosen.
Alphabet Extension <code>+</code>	The alphabet of a process is the set of actions in which it can engage. $P + S$ extends the alphabet of the process P with the actions in the set S .

Table A.1 – Process operators

A.2 Composite Processes

A composite process is the parallel composition of one or more processes. The definition of a composite process is preceded by `||`.

Example

```
||Composite = (P || Q) .
```

Parallel	If P and Q are processes then $(P \parallel Q)$ represents the
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Composition $ $	concurrent execution of P and Q .
Replicator forall	forall $[i:1..N]$ $P(i)$ is the parallel composition $(P(1) \dots P(N))$
Process Labeling :	$a:P$ prefixes each label in the alphabet of P with a .
Process Sharing ::	$\{a_1, \dots, a_x\}::P$ replaces every label n in the alphabet of P with the labels $a_1.n, \dots, a_x.n$. Further, every transition $(n \rightarrow Q)$ in the definition of P is replaced with the transitions $(\{a_1.n, \dots, a_x.n\} \rightarrow Q)$.
Priority High $<<$	$ C = (P Q) << \{a_1, \dots, a_n\}$ specifies a composition in which the actions a_1, \dots, a_n have higher priority than any other action in the alphabet of $P Q$ including the silent action τ . In any choice in this system which has one or more of the actions a_1, \dots, a_n labeling a transition, the transitions labeled with lower priority actions are discarded.
Priority Low $>>$	$ C = (P Q) >> \{a_1, \dots, a_n\}$ specifies a composition in which the actions a_1, \dots, a_n have lower priority than any other action in the alphabet of $P Q$ including the silent action τ . In any choice in this system which has one or more transitions not labeled by a_1, \dots, a_n , the transitions labeled by a_1, \dots, a_n are discarded.

Table A.2 – Composite Process Operators

A.3 Common Operators

The operators in Table A.3 may be used in the definition of both processes and composite processes.

Conditional if then else	The process if B then P else Q behaves as the process P if the condition B is true otherwise it behaves as Q . If the else Q is omitted and B is false, then the process behaves as STOP .
Re-labeling /	Re-labeling is applied to a process to change the names of action labels. The general form of re-labeling is: $/\{newlabel_1/oldlabel_1, \dots, newlabel_n/oldlabel_n\}$.
Hiding \backslash	When applied to a process P , the hiding operator $\backslash \{a_1..a_x\}$ removes the action names $a_1..a_x$ from the alphabet of P and makes these concealed actions "silent". These silent actions are labeled τ . Silent actions in different processes are not shared.

Interface @	When applied to a process P , the interface operator $@\{a_1..a_x\}$ hides all actions in the alphabet of P not labeled in the set $a_1..a_x$.
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Table A.3 – Common Process Operators

A.4 Properties

Safety property	A safety property P defines a deterministic process that asserts that any trace including actions in the alphabet of P , is accepted by P .
Progress progress	progress $P = \{a_1, a_2..a_n\}$ defines a progress property P which asserts that in an infinite execution of a target system, at least one of the actions $a_1, a_2..a_n$ will be executed infinitely often.

Table A.4 – Safety and Progress Properties

A.5 FLTL – Fluent Linear Temporal Logic

Fluent fluent	fluent $FL = \langle \{s_1, \dots, s_n\}, \{e_1..e_n\} \rangle$ initially B defines a fluent FL that is initially true if the expression B is true and initially false if the expression B is false. FL becomes true immediately any of the initiating actions $\{s_1, \dots, s_n\}$ occur and false immediately any of the terminating actions $\{e_1..e_n\}$ occur. If the term initially B is omitted then FL is initially false.
Assertion assert	assert $PF = \text{FLTL_Expression}$ defines an FLTL property.
&&	conjunction (<i>and</i>)
 	disjunction (<i>or</i>)
!	negation (<i>not</i>)
->	implication $((A \rightarrow B) \circ (!A \ \ B))$
<->	equivalence $((A \leftrightarrow B) \circ (A \rightarrow B) \ \&\& \ (B \rightarrow A))$
next time x F	iff F holds in the next instant.
always []F	iff F holds now and always in the future.
eventually <>F	iff F holds at some point in the future.
until P U Q	iff Q holds at some point in the future and P holds until

	then.
weak until $P \text{ W } Q$	iff P holds indefinitely or $P \text{ U } Q$
forall	forall $[i:R] \text{ FL}(i)$ conjunction of $\text{FL}(i)$
exists	exists $[i:R] \text{ FL}(i)$ disjunction of $\text{FL}(i)$

Table A.5 – Fluent Linear Temporal Logic