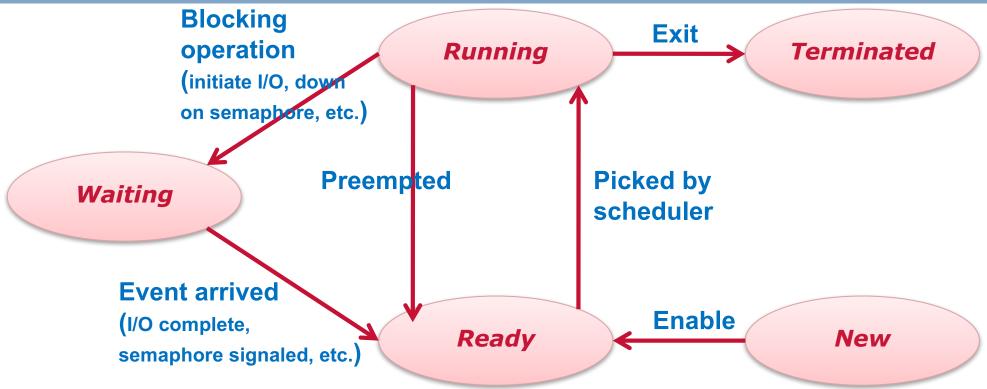


Operating Systems

Scheduling

Process States



- New: the process is being created
- Ready: runnable and waiting for processor
- Running: executing on a processor
- Waiting/Blocked: waiting for an event
- Terminated: process is being deleted

If multiple processes are ready, which one should be run?

Goals of Scheduling Algorithms

- Ensure fairness
 - Comparable processes should get comparable services
- Avoid indefinite postponement
 - No process should starve
- Enforce policy
 - E.g., priorities
- Maximize resource utilisation
 - CPU, I/O devices
- Minimize overhead
 - From context switches, scheduling decisions

Goals of Scheduling Algorithms

Batch systems:

- Throughput
 - Jobs per unit of time
- Turnaround time
 - Time between job submission and termination

Interactive systems:

- Response time crucial
 - Time between request issued and first response

Real-time systems:

- Meeting deadlines
 - Soft deadlines: e.g., leads to degraded video quality
 - Hard deadline: e.g., leads to plane crash

Preemptive vs. Non-Preemptive Scheduling

Non-preemptive

Let process run until it blocks or voluntarily releases the CPU

Preemptive:

- Let process run for a maximum amount of fixed time
- Requires clock interrupt

CPU-bound vs. I/O-bound Processes

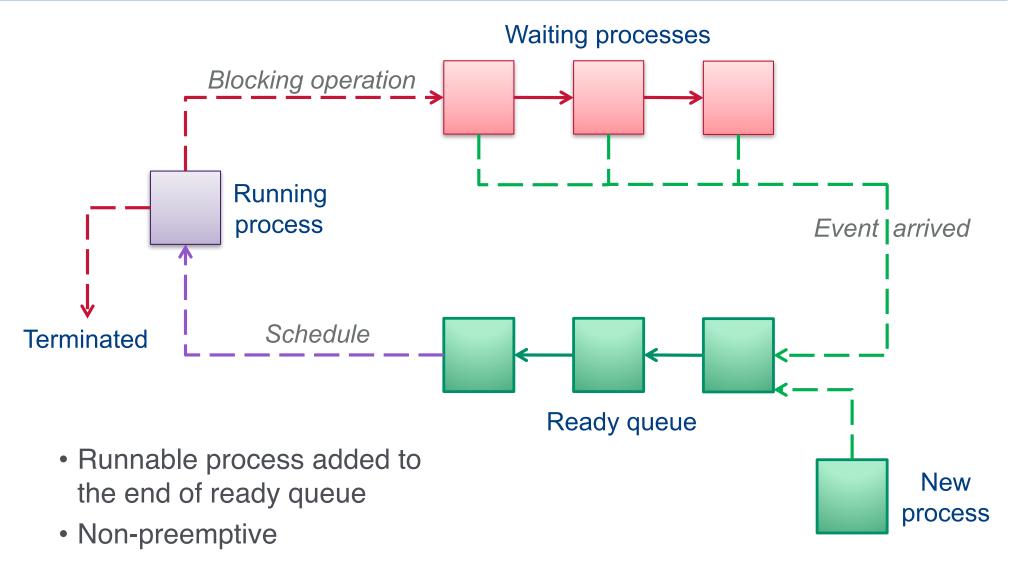
CPU-bound processes

Spend most of their time using the CPU

I/O-bound processes

- Spend most of their time waiting for I/O
- Tend to only use CPU briefly before issuing I/O request

First-Come First-Served (FCFS) (non-preemptive)



FCFS Advantages

- No indefinite postponement
 - All processes are eventually scheduled
- Really easy to implement

FCFS Disadvantages

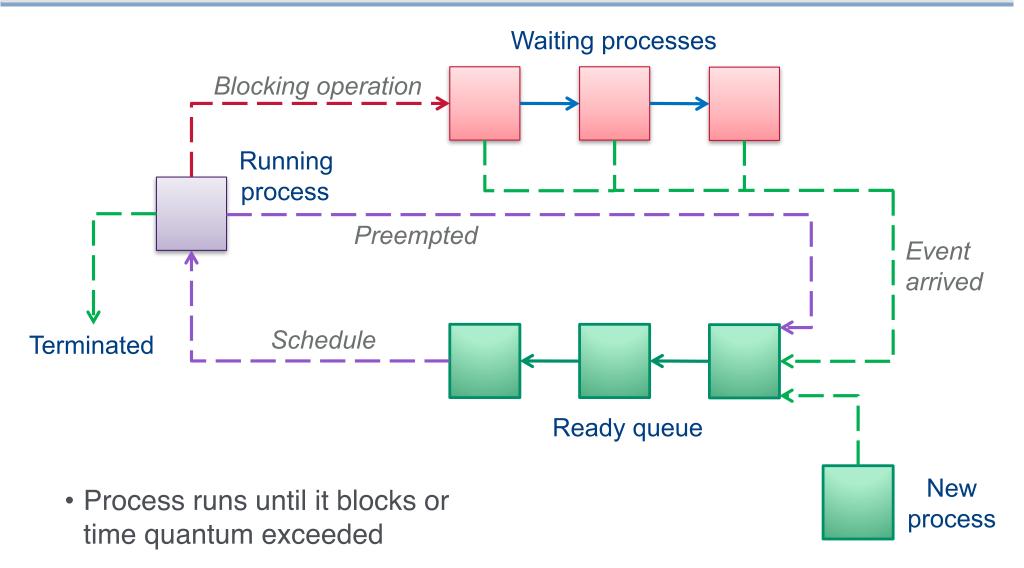
- What happens if a long job is followed by many short jobs?
 - E.g., 1h, 1s, 1s, 1s, with jobs 2-4 submitted just after job 1

- Throughput?
- Average turnaround time?

```
1s 1s 1s 3600s
```

- Throughput?
- Average turnaround time?

Round-Robin Scheduling (RR)



Round-Robin

- Fairness
 - Ready jobs get equal share of the CPU
- Response time
 - Good for small number of jobs
- Average turnaround time:
 - Low when run-times differ
 - Poor for similar run-times

RR Quantum (Time Slice)

- RR Overhead:
 - 4ms quantum, 1ms context switch time: 20% of time → overhead
 - 1s quantum, 1ms context switch time: only 0.1% of time → overhead
- Large quantum:
 - Smaller overhead
 - Worse response time
 - Quantum = ∞ \rightarrow FCFS
- Small quantum:
 - Larger overhead
 - Better response time

RR Quantum

- Choosing a quantum value:
 - Should be much larger than context switch cost
 - But provide decent response time
- Typical values: 10-200ms
- Some example values for standard processes (values vary depending on process type and behaviour, priority, etc.):
 - Linux: 100ms
 - Windows client: 20ms
 - Windows server: 180ms

Shortest Job First (SJF)

- Non-preemptive scheduling with run-times known in advance
- Pick the shortest job first
 - Process with shortest CPU burst

8	4	4	4
А	В	C	D

FCFS turnaround time:

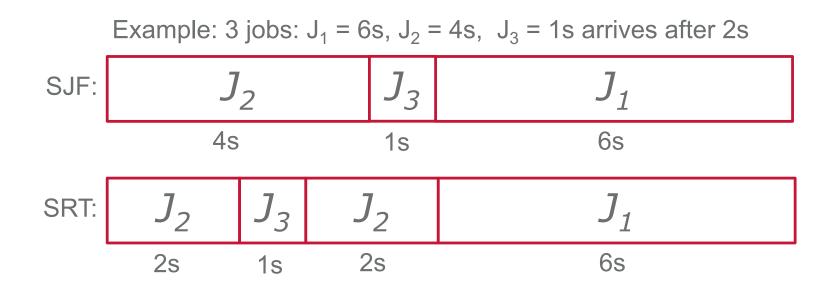
4	4	4	8
В	O	D	A

SJF turnaround time:

Provably optimal when all jobs are available simultaneously

Shortest Remaining Time (SRT)

- Preemptive version of shortest job first
 - Again, runtimes have to be known in advance
- Choose process whose remaining time is shortest
 - When new process arrives with execution time less than the remaining time for the running process, run it
- Allows new short jobs to get good service



Shortest Remaining Time (SRT)

- What if a running process is almost complete and a shorter job arrives?
 - Might want to disallow preemption when remaining run-time reaches a low threshold to avoid indefinite postponement
 - What if context switch overhead is greater than the difference in remaining run-times for the two jobs?

Knowing Run-times in Advance

- Run-times are usually not available in advance
- Compute CPU burst estimates based on various heuristics?
 - E.g., based on previous history
 - Not always applicable
- User-supplied estimates?
 - Need to counteract cheating to get higher priority
 - E.g., terminate or penalise processes after they exceed their estimated run-time

Fair-Share Scheduling

- Users are assigned some fraction of the CPU
 - Scheduler takes into account who owns a process before scheduling it
- E.g., two users each with 50% CPU share
 - User 1 has 4 processes: A, B, C, D
 - User 2 has 2 processes: E, F
- What does a fair-share RR scheduler do?
 - A, E, B, F, C, E, D, F, A, E, B, F...

Priority Scheduling

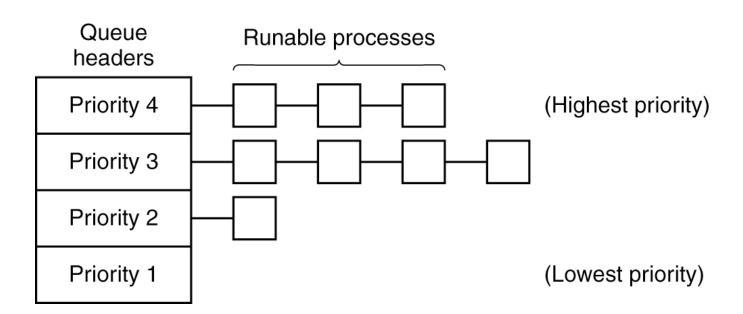
- Jobs are run based on their priority
 - Always run the job with the highest priority
- Priorities can be externally defined (e.g., by user) or based on some process-specific metrics (e.g., their expected CPU burst)
- Priorities can be static (i.e. they don't change) or dynamic (they may change during execution)
- Example: consider three processes arriving at essentially the same time with externally defined static priorities A = 4, B = 7, C = 1, where a higher value means higher priority.
 - Processes are run to completion in the order B, A, C.

General-Purpose Scheduling

- Favour short and I/O-bound jobs
 - Get good resource utilisation
 - And short response times
- Quickly determine the nature of the job and adapt to changes
 - Processes have periods when they are I/O-bound and periods when they are CPU-bound

- A form of priority scheduling
 - Shortest remaining time also a form of priority scheduling!
- Implemented by many OSs:
 - Windows Vista, Windows 7
 - Mac OS X
 - Linux 2.6 2.6.23
 - Pintos!

- One queue for each priority level
 - Run job on highest non-empty priority queue
 - Each queue can use different scheduling algorithm
 - Usually round-robin



- Need to determine current nature of job
 - I/O-bound? CPU-bound?
- Need to worry about starvation of lower-priority jobs

- Feedback mechanism:
 - Job priorities recomputed periodically, e.g., based on how much CPU they have recently used
 - Exponentially-weighted moving average
 - Aging: increase job's priority as it waits

- Not very flexible
 - Applications basically have no control
 - Priorities make no guarantees
 - What does priority 15 mean?
- Does not react quickly to changes
 - Often needs warm-up period
 - Running system for a while to get better results
 - Problem for real-time systems, multimedia apps
- Cheating is a concern
 - Add meaningless I/O to boost priority?
- Can't donate priority

Lottery Scheduling [Waldspurger and Weihl 1994]

- Jobs receive lottery tickets for various resources
 - E.g., CPU time
- At each scheduling decision, one ticket is chosen at random and the job holding that ticket wins

Example: 100 lottery tickets for CPU time, P1 has 20 tickets

- Chance of P1 running during the next CPU quantum: 20%
- In the long run, P1 gets 20% of the CPU time

Lottery Scheduling

- Number of lottery tickets meaningful
 - Job holding p% of tickets, gets p% of resource
 - Unlike priorities
- Highly responsive:
 - New job given p% of tickets has the p% chance to get the resource at the *next* scheduling decision
- No starvation
- Jobs can exchange tickets
 - Allows for priority donation
 - Allows cooperating jobs to achieve certain goals
- Adding/removing jobs affect remaining jobs proportionally
- Unpredictable response time
 - What if interactive process is unlucky for a few lotteries?

Summary

- Scheduling algorithms often need to balance conflicting goals
 - E.g., ensure fairness, enforce policy, maximize resource utilisation
- Different scheduling algorithms appropriate in different contexts
 - E.g., batch systems vs interactive systems vs real-time systems
- Well-studied scheduling algorithms include
 - First-Come First-Served FCFS, Round Robin, Shortest Job First (SJF), Shortest Remaining Time (SRT), Multilevel Feedback Queues and Lottery Scheduling