

Chapter 5 Solutions

Question 1

Firstly, let's rewrite $f(x)$ as $f(x) = 4 \log(x) \sin(x^3)$.

Then, $f'(x) = \frac{4}{x} \sin(x^3) + 12x^2 \log(x) \cos(x^3)$.

Question 2

If we rewrite our function as $f(x) = (1 + \exp(-x))^{-1}$, then we have $f'(x) = \frac{\exp(-x)}{(1+\exp(-x))^2}$.

Question 3

We have $f'(x) = \frac{\mu-x}{\sigma^2} f(x)$.

Question 4

We compute the first five derivatives of our function at 0. We have $f(0) = f'(0) = 1$, $f^{(2)}(0) = f^{(3)}(0) = -1$, and $f^{(4)}(0) = f^{(5)}(0) = 1$.

The Taylor polynomial $T_5(x) = 1 + x - \frac{1}{2}x^2 - \frac{1}{6}x^3 + \frac{1}{24}x^4 + \frac{1}{120}x^5$. The lower-order Taylor polynomials can be found by truncating this expression appropriately.

Question 5

Part a

We can see below that $\frac{\partial f_1}{\partial x}$ has dimension 1×2 ; $\frac{\partial f_2}{\partial x}$ has dimension $1 \times n$; and $\frac{\partial f_3}{\partial x}$ has dimension $n^2 \times n$.

Part b

We have $\frac{\partial f_1}{\partial x} = \begin{bmatrix} \cos(x_1) \cos(x_2) & -\sin(x_1) \sin(x_2) \end{bmatrix}$; $\frac{\partial f_2}{\partial x} = y^\top$. (Remember, y is a column vector!)

Part c

Note that xx^\top is the matrix $\begin{bmatrix} x_1^2 & x_1 x_2 & \cdots & x_1 x_n \\ x_2 x_1 & x_2^2 & \cdots & x_2 x_n \\ \vdots & \vdots & \ddots & \vdots \\ x_n x_1 & x_n x_2 & \cdots & x_n^2 \end{bmatrix}$. Thus its derivative will be a higher-order tensor.

However, if we consider the matrix to be an n^2 -dimensional object in its own right, we can compute the Jacobian. Its first row consists of $\left[2x_1 \quad x_2 \quad \cdots \quad x_n \mid x_2 \quad 0 \quad \cdots \quad 0 \mid \cdots \mid x_n \quad 0 \quad \cdots \quad 0 \right]$, where I have inserted a vertical bar every n columns, to aid readability.

Question 6

We have $\frac{df}{dt} = \cos(\log(t^\top t)) \cdot \frac{1}{t^\top t} \cdot \begin{bmatrix} 2t_1 & 2t_2 & \cdots & 2t_D \end{bmatrix} = \cos(\log(t^\top t)) \cdot \frac{2t^\top}{t^\top t}$.

For g , if we explicitly compute AXB and find its trace, we have that $g(X) = \sum_{k=1}^D \sum_{j=1}^F \sum_{i=1}^E a_{ki} x_{ij} b_{jk}$.

Thus we have, $\frac{\partial g}{\partial x_{ij}} = \sum_{k=1}^D b_{jk} a_{ki}$, and this is the (i, j) -th entry of the required derivative. Hence

$$\frac{dg}{dX} = B^\top A^\top.$$

Question 7

Part a

The chain rule tells us that $\frac{df}{dx} = \frac{df}{dz} \frac{dz}{dx}$, where $\frac{df}{dz}$ has dimension 1×1 , and $\frac{dz}{dx}$ has dimension $1 \times D$. We know $\frac{dz}{dx} = 2x^\top$ from f in Question 6. Also, $\frac{df}{dz} = \frac{1}{1+z}$.

Therefore, $\frac{df}{dx} = \frac{2x^\top}{1+x^\top x}$.

Part b

Here we have $\frac{df}{dz}$ is an $E \times E$ matrix, namely $\begin{bmatrix} \cos z_1 & 0 & \cdots & 0 \\ 0 & \cos z_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \cos z_E \end{bmatrix}$.

Also, $\frac{dz}{dx}$ is an $E \times D$ -dimensional matrix, namely A itself.

The overall derivative is obtained by multiplying these two matrices together, which will again give us an $E \times D$ -dimensional matrix.

Question 8

Part a

We have $\frac{df}{dz}$ has dimension 1×1 , and is simply $-\frac{1}{2}\exp(-\frac{1}{2}z)$.

Now, $\frac{dz}{dy}$ has dimension $1 \times D$, and is given by $y^\top(S^{-1} + (S^{-1})^\top)$.

Finally, $\frac{dy}{dx}$ has dimension $D \times D$, and is just the identity matrix.

Again, we multiply these all together to get our final derivative.

Part b

If we explicitly write out $xx^\top + \sigma^2 I$, and compute its trace, we find that $f(x) = x_1^2 + \dots + x_n^2 + n\sigma^2$.

Hence, $\frac{df}{dx} = 2x^\top$.

Part c

Here, $\frac{df}{dz} = \begin{bmatrix} \frac{1}{\cosh^2 z_1} & 0 & \dots & 0 \\ 0 & \frac{1}{\cosh^2 z_2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \frac{1}{\cosh^2 z_M} \end{bmatrix}$, while $\frac{dz}{dx} = A$, as in Question 7b.

Finally, $\frac{df}{dx}$ is given by the product of these two matrices.

Question 9

Piecing this together, replacing z with $t(\epsilon, v)$ throughout, we have that $g(v) = \log(p(x, t(\epsilon, v))) - \log(q(t(\epsilon, v), v))$.

Therefore, $\frac{dg}{dv} = \frac{p'(x, t(\epsilon, v)) \cdot t'(\epsilon, v)}{p(x, t(\epsilon, v))} - \frac{q'(t(\epsilon, v), v) \cdot t'(\epsilon, v)}{q(t(\epsilon, v), v)}$.