Cx.1.

a) i)
$$S-X=\begin{bmatrix} -101\\ -202\\ -101 \end{bmatrix}$$
, $S-Y=\begin{bmatrix} 121\\ 000\\ -1-2-1 \end{bmatrix}$

$$S-X=flip(S-X)=\begin{bmatrix} 1 & 0-1 \\ 2 & 0-2 \\ 1 & 0-1 \end{bmatrix}$$
, $S-Y=flip(S-Y)=\begin{bmatrix} -1-2-1 \\ 0 & 0 \\ 1 & 2 \end{bmatrix}$

at the central pixel we have:
$$6.1 + 7.0 + 5.-1$$
 = $27.2 + 0.15 + 10.-2$
= $6 - 5 + 44 - 20 + 32 - 18 = 39$ w. r.t x

and
$$-6-7.2-5$$
 +32+2.21+18=67 wirty

= 0 edge strength= $\sqrt{38^2+67^2}=\sqrt{1521}+4489=\sqrt{6010}=77.52$

ii) I guess they are acting again for the central pixeless 0 = arctan(99 lyx)= arctan($67/38$), this is the direction I guess. Not sale the.

ii) mask =
$$flip([0,10]) = [0,10]$$

convolve at the center of the image putch:
-30+28=-2 - snot an edge, so edges this should
be 0

C) fiorizontal
$$\sqrt{-1-1-1}$$
, vertical $-\frac{1}{-1} = -\frac{1}{-1} = -\frac{1}{-1}$
Diagonal $-\frac{1}{-1} = -\frac{1}{-1} = -\frac{1}{-1} = -\frac{1}{2} =$

b) step 1-10 convert the images to grayscale (6/004) and white)

step 2-buse SIFT to find the interesting points in both images
step 3) Match their verpoint by using for exa-

mple brute force matcher.

Reasoning: SIFT has a good performance.

- c) i) I will truck the balloons using edges. We can extract Edges with Sobel operator.

 ii) The edges of the balloons will be a lot smoother iii) we can use sift, which will defect more keypoints from just the edges, so the probability to lose the balloon for some fromes will decreuse
- ex. 3
 - i) We can use the face as a template and then elide this template through the picture, coloulating cross-correlation.
 - ii) we can use discriminants seech as area of the nose,
 - (iii) No, the results for continuous space doesn't generalise to discrete space very well
- i) we can use convolutional neural network and frain it to classify each pixel of our image.
 - ii) area, perimeter, direction
 - representation by plotting the radial distance w.r.t Arclength. Then we find the frequency

components of that periodic function. We can use this to classify the shape

that for circular object the function recording that for circular object the function reached in general the deviation in the rulue will be smaller than for a non-circular shape.

circular

are length

non-circular

Qrc-rength