

Introduction to University Mathematics

MATH40001/MATH40009

Final Exam

**Instructions:** The **neatness, completeness and clarity of the answers** will contribute to the final mark. You must turn in handwritten solutions written on paper and scanned. You should upload your answers to this test as a single PDF via the Turnitin Assignment called *Whole exam dropbox* which you will find in the *Exam Paper and Dropbox(es)* folder.

**IMPORTANT** – Use the following naming convention for your file **AND** for the Title of your Turnitin submission: [CID]\_[ModuleCode]\_full\_submission.pdf. Your first page should be the "Maths Coversheet for Submission" (which can be download from blackboard) and be completed.

**Maths students must attempt all three questions, JMC students will only attempt the first two questions.** For this module, the module code is **MATH40001** for Maths students and **MATH40009** for JMC students.

In this test, you may assume any results from the course notes or videos, as long as you state them correctly (unless stated otherwise).

1. **Total: 20 Marks**

- (a) Let  $T$  be a set and let  $R$  be a binary relation on  $T$ . Say  $a, b, c$  are three distinct elements of  $T$ . Assume that  $R(a, b)$  is true,  $R(b, c)$  is true and  $R(c, a)$  is false. Prove that  $R$  is not an equivalence relation on  $T$ . **3 Marks**
- (b) Let  $U$  be a set, and let  $R$  be a binary relation on  $U$ . Let  $d, e, f$  be three distinct elements of  $U$ . Assume that  $R(d, e)$  is true,  $R(e, f)$  is true and  $R(f, d)$  is true. Prove that  $R$  is not a partial order on  $U$ . **3 Marks**
- (c) Let  $X$  be a set, and let  $R$  and  $S$  be two binary relations on  $X$ .  
Now define two new binary relations  $A$  and  $B$  on  $X$ , by  $A(x, y) = R(x, y) \wedge S(x, y)$ , and  $B(x, y) = R(x, y) \vee S(x, y)$ .
  - i. Proof or counterexample: If  $R$  and  $S$  are equivalence relations, then  $A$  must be an equivalence relation. **4 Marks**
  - ii. Proof or counterexample: If  $R$  and  $S$  are equivalence relations, then  $B$  must be an equivalence relation. **4 Marks**
  - iii. Proof or counterexample: If  $R$  and  $S$  are antisymmetric, then  $A$  must be antisymmetric. **3 Marks**
  - iv. Proof or counterexample: if  $R$  and  $S$  are antisymmetric, then  $B$  must be antisymmetric. **3 Marks**

2. **Total: 20 Marks**

- (a) For this part assume the Peano axioms only!
  - i. Show that for all  $n, m$ ,  $\nu(n + m) = \nu(n) + m$ . **3 Marks**
  - ii. Show that for all  $n, m$  in  $\mathbb{N}$ ,  $n \neq n + \nu(m)$ . **4 Marks**
- (b) Let  $p_n$  be the  $n$ -th prime number, so  $p_1 = 2$ ,  $p_2 = 3$ , ...
  - i. Show that  $p_{n+1} \leq p_1 \cdots p_n + 1$ , for  $n \geq 1$ . **4 Marks**

ii. Show that  $p_n \leq 2^{2^{n-1}}$ . 3 Marks

(c) Let  $S$  be a field and  $x \neq 0$  be in  $S$ . Show that there exists no element  $y \neq 0$  in  $S$  such that  $x \cdot y = 0$ . 3 Marks

(d) Prove that, for every positive real number  $r \in \mathbb{R}$ , there exists a function  $f : \mathbb{N} \rightarrow \mathbb{N}$  such that the set  $S := \{f(n) \cdot n^{-1} | n \geq 1, n \in \mathbb{N}\}$  has infimum equal to  $r$ . Show that, if  $r$  is not a rational number, then the supremum cannot also equal  $r$ . 3 Marks

3. Total: 20 Marks

(a) For each of the following statements, state without proof whether they are TRUE or FALSE:

i. The equation  $ax + by + cz + d = 0$  represents a line in space. 1 Mark

ii. The cross product of two unit vectors is a unit vector. 1 Mark

iii. If  $|\mathbf{r}(t)| = 1$  for all  $t$ , then  $\mathbf{r}'(t)$  is orthogonal to  $\mathbf{r}(t)$  for all  $t$ . 1 Mark

iv. If  $\mathbf{r}(t)$  is a differentiable vector function, then  $\frac{d}{dt}|\mathbf{r}(t)| = |\mathbf{r}'(t)|$ . 1 Mark

(b) Find a parametric equation for the line  $\mathcal{L}$  through the points  $A(1, 2, 1)$  and  $B(2, 1, 2)$ . Compute the distance between line  $\mathcal{L}$  and the point  $C(2, 3, 4)$ . 4 Marks

(c) The Frenet–Serret formulas are given by

$$\begin{cases} d\mathbf{T}/ds = \kappa\mathbf{N} \\ d\mathbf{N}/ds = -\kappa\mathbf{T} + \tau\mathbf{B} \\ d\mathbf{B}/ds = -\tau\mathbf{N} \end{cases}$$

where  $\mathbf{T}$ ,  $\mathbf{N}$  and  $\mathbf{B}$  are respectively the tangent, normal and binormal vectors to a curve parametrized by a vector function  $\mathbf{r}$ . In writing these formulas, we introduced two important quantities:  $\kappa$  the curvature and  $\tau$  the torsion of the curve. In this question, we will provide an explicit expression for the torsion. You can use the Frenet–Serret formulas without further proof.

i. First, show that

$$\mathbf{r}'' = s''\mathbf{T} + \kappa(s')^2\mathbf{N}$$

where the primes denote derivatives with respect to  $t$  and the notation  $(s')^n$  means  $(ds/dt)^n$ . 2 Marks

ii. Then, show that

$$\mathbf{r}' \times \mathbf{r}'' = \kappa(s')^3\mathbf{B}$$

2 Marks

iii. Further, show that

$$\mathbf{r}''' = [s''' - \kappa^2(s')^3]\mathbf{T} + [3\kappa s' s'' + \kappa'(s')^2]\mathbf{N} + \kappa\tau(s')^3\mathbf{B}$$

2 Marks

iv. Finally, deduce that the torsion of a curve parametrized by vector function  $\mathbf{r}$  can be explicitly expressed as

$$\tau = \frac{(\mathbf{r}' \times \mathbf{r}'') \cdot \mathbf{r}'''}{|\mathbf{r}' \times \mathbf{r}''|^2}$$

2 Marks

v. The DNA molecule has the structure of a double helix. One of the helices can be parametrized by the vector function  $\mathbf{r}(t) = (a \cos t, a \sin t, bt)$ , where  $a$  and  $b$  are positive real constants. Show that this curve has constant curvature and constant torsion. 4 Marks

## Solutions to Final Exam

### 1. Total: 20 Marks

- (a) We prove it by contradiction. Assume  $R$  is an equivalence relation. Then  $R(a, b)$  is true and  $R(b, c)$  is true. By transitivity we deduce that  $R(a, c)$  is true. By symmetry we deduce that  $R(c, a)$  is true. But  $R(c, a)$  is false, a contradiction. Hence  $R$  is not an equivalence relation. I would also be happy if people argue with equivalence classes (" $R(a, b)$  is true so  $cl(a) = cl(b)$ " etc etc).
- (b) Again by contradiction. Assume  $R$  is a partial order. We know  $R(d, e)$  is true and  $R(e, f)$  is true, so by transitivity  $R(d, f)$  is true. We know  $R(f, d)$  is true as well, so by antisymmetry we deduce that  $d = f$ . But  $d$  and  $f$  are assumed to be distinct, a contradiction. Hence  $R$  is not a partial order.
- (c) i. This is true. First,  $R$  and  $S$  are reflexive, so  $A$  is reflexive, because for all  $x \in X$  we have  $A(x, x) = R(x, x) \wedge S(x, x) = \text{true} \wedge \text{true} = \text{true}$ . Next,  $R$  and  $S$  are symmetric, so  $A$  is symmetric, because if  $x, y \in X$  and  $A(x, y)$  is true, then  $R(x, y)$  and  $S(x, y)$  are true, so  $R(y, x)$  and  $S(y, x)$  are true by symmetry of  $R$  and  $S$ , so  $A(y, x)$  is true. Finally,  $R$  and  $S$  are transitive, so  $A$  is transitive, because if  $x, y, z \in X$  with  $A(x, y)$  and  $A(y, z)$ , then  $R(x, y)$  and  $S(x, y)$  and  $R(y, z)$  and  $S(y, z)$  are all true, so by transitivity of  $R$  and  $S$  we deduce  $R(x, z)$  and  $S(x, z)$  are true, and thus  $A(x, z)$  is true.
- ii. This is false, although a counterexample is slightly tricky to find. Let  $X = \{1, 2, 3\}$ . Recall from the course videos that we can make an equivalence relation on  $X$  by partitioning it into nonempty disjoint subsets. So let's let  $R$  be the equivalence relation corresponding to the partition of  $X$  into  $\{1, 2\}$  and  $\{3\}$ , and let  $S$  be the equivalence relation corresponding to the partition  $\{1\}$  and  $\{2, 3\}$  (the point of doing it this way is that we don't need to check the axioms for an equivalence relation, we know  $R$  and  $S$  will satisfy them).  
Because 1 and 2 are in the same partition for  $R$ , we have that  $R(1, 2)$  is true, but because 1 and 3 are in different partitions for  $R$ , we have that  $R(1, 3)$  is false. Similarly  $S(2, 3)$  is true, but  $S(1, 3)$  is false.  
Hence  $B(1, 2)$  is true, because  $R(1, 2)$  is true, and  $B(2, 3)$  is true, because  $S(2, 3)$  is true, but  $B(1, 3)$  is not true, because  $R(1, 3)$  and  $S(1, 3)$  are both false.  
Thus  $B$  is not transitive, and hence not an equivalence relation.
- iii. This is true. Assume  $x, y \in X$  and  $A(x, y)$  and  $A(y, x)$  are both true; we want to prove that  $x = y$ . However  $A(x, y)$  implies  $R(x, y)$  and  $A(y, x)$  implies  $R(y, x)$ , so antisymmetry of  $R$  tells us that  $x = y$ , which is what we wanted.
- iv. This is not true. Let  $X = \{1, 2\}$  and define a binary relation  $R$  on  $X$  by  $R(1, 2)$  is true and  $R(x, y)$  is false otherwise. This relation is antisymmetric because if we assume  $R(x, y)$  and  $R(y, x)$  are true, we must have  $x = 1, y = 2$  and  $y = 1, x = 2$ , but these together prove a contradiction, so we have assumed something false and can deduce  $x = y$  as false statements imply anything.  
Similarly if  $S$  is defined by  $S(2, 1)$  is true and  $S(x, y)$  is false otherwise, then  $S$  is also antisymmetric (the same proof as above works, just switch 1 and 2). However  $B(1, 2)$  and  $B(2, 1)$  will both be true (because  $\text{false} \vee \text{true} = \text{true}$ ), so  $B$  is not antisymmetric because  $2 \neq 1$ .

### 2. Total: 20 Marks

- (a) i. Show that for all  $n, m$ ,  $\nu(n + m) = \nu(n) + m$ .

*Proof.* Define the set

$$A = \{m \in \mathbb{N} \mid \nu(n + m) = \nu(n) + m\}.$$

0 is obviously in the set by definition of addition. Now assume  $m$  is in the set. We want to show  $\nu(n + \nu(m)) = \nu(n) + \nu(m)$ . But again by definition of addition, induction hypothesis and again definition of addition (in this order)  $\nu(n + \nu(m)) = \nu(\nu(n + m)) = \nu(\nu(n) + m) = \nu(n) + \nu(m)$ , which shows the statement.  $\square$

- ii. Show that for all  $n, m$  in  $\mathbb{N}$ ,  $n \neq n + \nu(m)$ .

*Proof.* Fix  $m \in \mathbb{N}$ . Define the set

$$A = \{n \in \mathbb{N} \mid n \neq n + \nu(m)\}.$$

We first show that  $0 \in A$ , or equivalently  $0 \neq 0 + \nu(m)$ . We have  $0 + \nu(m) = \nu(m)$ , which cannot be 0 by (P3). Now suppose that  $n \in A$ . Then by (P4),  $\nu(n) \neq \nu(n + \nu(m)) = \nu(n) + \nu(m)$ . So  $\nu(n) \in A$  as well. By (P5),  $A = \mathbb{N}$ .  $\square$

- (b) Let  $p_n$  be the  $n$ -th prime number.

- i. Show that  $p_{n+1} \leq p_1 \cdot \dots \cdot p_n + 1$ , where  $n \geq 1$ .

*Proof.* Let  $x := p_1 \cdot \dots \cdot p_n + 1$ . None of the primes  $p_i$  with  $0 < i \leq n$  is a factor of  $x$ . Indeed assume  $q = p_i$  for some  $i$ , then  $q \mid p_1 \cdot \dots \cdot p_n$ . But then  $q \mid x - p_1 \cdot \dots \cdot p_n = 1$ , which is a contradiction. Therefore  $q$  has to be a prime numbers which is not in the list  $p_1, \dots, p_n$ , and therefore  $q = p_k$ , with  $k \geq n + 1$  and consequently  $p_{n+1} \leq q \leq p_1 \cdot \dots \cdot p_n + 1$ .  $\square$

- ii. Show that  $p_n \leq 2^{2^{n-1}}$ .

*Proof.* This is a proof by strong induction.  $p_1 = 2$ , hence  $2 \leq 2^1 = 2^{2^{1-1}}$  and the base case is done.

Assume now that  $p_j \leq 2^{2^{j-1}}$  for all  $1 \leq j \leq k$ . We get using i)

$$p_{k+1} \leq p_1 \cdot \dots \cdot p_k + 1 \leq 2 \cdot 2^{2^1} \cdot 2^{2^2} \dots 2^{2^{k-1}} + 1 \leq 2^{2^k - 1} + 1 \leq 2^{2^k}.$$

This proves the results.  $\square$

- (c) Let  $S$  be a field and  $x \neq 0$  be in  $S$ . Show that there exists no element  $y \neq 0$  in  $S$  such that  $x \cdot y = 0$ .

*Proof.* Since  $S$  is a field and  $x \neq 0$ , there exists an element  $x^{-1}$ , such that  $x \cdot x^{-1} = 1$ . Assume now that there exists a  $y \neq 0$  in  $S$  such that  $x \cdot y = 0$ . We have

$$0 = x^{-1} \cdot 0 = x^{-1} \cdot (x \cdot y) = (x^{-1} \cdot x) \cdot y = 1 \cdot y = y,$$

which is a contradiction.  $\square$

- (d) Prove that, for every positive real number  $r \in \mathbb{R}$ , there exists a function  $f : \mathbb{N} \rightarrow \mathbb{N}$  such that the set  $S := \{f(n) \cdot n^{-1} \mid n \geq 1, n \in \mathbb{N}\}$  has infimum equal to  $r$ . Show that the supremum cannot also equal  $r$  unless  $r$  is a rational number.

*Proof.* For every  $n$ , let  $f(n)$  be the unique natural number such that  $f(n) - 1 < r \cdot n \leq f(n)$ : this can be defined as the minimum natural number greater than or equal to  $r \cdot n$ , and in this case  $f(n) - 1 < r \cdot n$  because  $r \cdot n \geq 0$ . If  $n \geq 1$ , by division,  $f(n) \cdot n^{-1} \geq r$ , so that  $r$  is indeed a lower bound of the set  $S$ . We claim that it is the greatest lower bound. Suppose for a contradiction that  $r'$  is another lower bound of  $S$ , and  $r' > r$ . Then, by the Archimedean property, there exists  $n$  such that  $n(r' - r) \geq 1$ . By definition,  $f(n) - 1 < r \cdot n \leq f(n)$ . Since  $r'$  is also a lower bound, we have  $f(n) \cdot n^{-1} \geq r'$ , i.e.,  $f(n) \geq r' \cdot n$ . Now by assumption,  $r' \cdot n \geq r \cdot n + 1$ , so that  $f(n) \geq r \cdot n + 1$ , i.e.,  $f(n) - 1 \geq r \cdot n$ , a contradiction.

For the final question, if  $r$  were also the supremum, then it would be both a lower bound and an upper bound, which would imply that  $S = \{r\}$ . As  $S \subseteq \mathbb{Q}$  by definition, this would require that  $r$  be rational. (Remark: actually, one can see that  $r$  would have to be an integer, since it can be represented as fractions  $p \cdot q^{-1}$  and  $p' \cdot (q')^{-1}$  with  $\gcd(q, q') = 1$ .)  $\square$

3. **Total: 20 Marks**

(a) Consider the following statements:

- i. The equation  $ax + by + cz + d = 0$  represents a line in space. **FALSE** 1 Mark
- ii. The cross product of two unit vectors is a unit vector. **FALSE** 1 Mark
- iii. If  $|\mathbf{r}(t)| = 1$  for all  $t$ , then  $\mathbf{r}'(t)$  is orthogonal to  $\mathbf{r}(t)$  for all  $t$ . **TRUE** 1 Mark
- iv. If  $\mathbf{r}(t)$  is a differentiable vector function, then  $\frac{d}{dt}|\mathbf{r}(t)| = |\mathbf{r}'(t)|$ . **FALSE** 1 Mark

(b) We consider the line  $\mathcal{L}$  going through the points  $A = (1, 2, 1)$  and  $B = (2, 1, 2)$ . The vector  $\mathbf{u} = (2 - 1, 1 - 2, 2 - 1) = (1, -1, 1)$  and we can take the reference point  $A = (1, 2, 1)$ . So a parametric equation for  $\mathcal{L}$  is given by

$$\mathbf{r} = A + \lambda \mathbf{u}, \text{ with } \lambda \in \mathbb{R}$$

i.e.

$$\begin{cases} x = 1 + \lambda \\ y = 2 - \lambda \\ z = 1 + \lambda \end{cases}$$

2 Marks

The distance between line  $\mathcal{L}$  and point  $C$  is by definition

$$d(\mathcal{L}, C) = \frac{|\mathbf{AC} \times \mathbf{u}|}{|\mathbf{u}|}$$

We have  $|\mathbf{u}| = \sqrt{1^2 + (-1)^2 + 1^2} = \sqrt{3}$ . Further,  $\mathbf{AC} = (1, 1, 3)$  so that  $\mathbf{AC} \times \mathbf{u} = (4, 2, -2)$ . Finally, we have

$$d(\mathcal{L}, C) = \frac{\sqrt{4^2 + 2^2 + (-2)^2}}{\sqrt{3}} = \frac{2\sqrt{6}}{\sqrt{3}} = 2\sqrt{2}$$

2 Marks

(c) In this problem, we assume that we can use without further proof Frenet–Serret formulas

$$\begin{cases} \text{(FS1): } d\mathbf{T}/ds = \kappa\mathbf{N} \\ \text{(FS2): } d\mathbf{N}/ds = -\kappa\mathbf{T} + \tau\mathbf{B} \\ \text{(FS3): } d\mathbf{B}/ds = -\tau\mathbf{N} \end{cases}$$

i. The definition of the tangent vector gives us

$$\mathbf{r}'(t) = |\mathbf{r}'(t)|\mathbf{T}$$

but we know that  $|\mathbf{r}'(t)| = ds/dt$ . Said differently, we have

$$\mathbf{r}' = s'\mathbf{T} \Rightarrow \mathbf{r}'' = s'\mathbf{T}' + s''\mathbf{T} \Rightarrow \mathbf{r}'' = s''\mathbf{T} + (s')^2 \frac{d\mathbf{T}}{ds} \Rightarrow \mathbf{r}'' = s''\mathbf{T} + \kappa(s')^2\mathbf{N} \quad \text{by (FS1).}$$

2 Marks

ii. Using the result of part (i), we have  $\mathbf{r}'' = s''\mathbf{T} + \kappa(s')^2\mathbf{N}$  and so

$$\begin{aligned} \mathbf{r}' \times \mathbf{r}'' &= (s'\mathbf{T}) \times [s''\mathbf{T} + \kappa(s')^2\mathbf{N}] \\ &= s's''(\mathbf{T} \times \mathbf{T}) + \kappa(s')^3(\mathbf{T} \times \mathbf{N}) \\ &= \kappa(s')^3\mathbf{B} \end{aligned}$$

where we have used the linearity of the cross product and the fact that by definition  $\mathbf{B} = \mathbf{T} \times \mathbf{N}$ . 2 Marks

- iii. Using once again the result of part (i), we have  $\mathbf{r}'' = s''\mathbf{T} + \kappa(s')^2\mathbf{N}$  which we can differentiate to write

$$\begin{aligned}
 \mathbf{r}''' &= \frac{d}{dt} [s''\mathbf{T} + \kappa(s')^2\mathbf{N}] \\
 &= s'''\mathbf{T} + s''\mathbf{T}' + \kappa'(s')^2\mathbf{N} + 2\kappa s' s''\mathbf{N} + \kappa(s')^2\mathbf{N}' \\
 &= s'''\mathbf{T} + s' s'' \frac{d\mathbf{T}}{ds} + \kappa'(s')^2\mathbf{N} + 2\kappa s' s''\mathbf{N} + \kappa(s')^3 \frac{d\mathbf{N}}{ds} \\
 &= s'''\mathbf{T} + \kappa s' s''\mathbf{N} + \kappa'(s')^2\mathbf{N} + 2\kappa s' s''\mathbf{N} + \kappa(s')^3 \frac{d\mathbf{N}}{ds} \quad (\text{by FS1}) \\
 &= s'''\mathbf{T} + \kappa s' s''\mathbf{N} + \kappa'(s')^2\mathbf{N} + 2\kappa s' s''\mathbf{N} + \kappa(s')^3 [-\kappa\mathbf{T} + \tau\mathbf{B}] \quad (\text{by FS2})
 \end{aligned}$$

and finally, we obtain as requested

$$\mathbf{r}''' = [s''' - \kappa^2(s')^3] \mathbf{T} + [3\kappa s' s'' + \kappa'(s')^2] \mathbf{N} + \kappa(s')^3 \tau \mathbf{B}$$

2 Marks

- iv. Using the results from part (ii) and part (iii), we write

$$(\mathbf{r}' \times \mathbf{r}'') \cdot \mathbf{r}''' = (\kappa(s')^3 \mathbf{B}) \cdot ([s''' - \kappa^2(s')^3] \mathbf{T} + [3\kappa s' s'' + \kappa'(s')^2] \mathbf{N} + \kappa(s')^3 \tau \mathbf{B})$$

Using the linearity of the scalar product, we can expand this expression. Using the fact that  $\mathbf{B} \cdot \mathbf{T} = \mathbf{B} \cdot \mathbf{N} = 0$  as these three vectors are orthogonal to each other, we find that

$$(\mathbf{r}' \times \mathbf{r}'') \cdot \mathbf{r}''' = \tau \kappa^2(s')^6 \mathbf{B} \cdot \mathbf{B}$$

But we know that by definition  $\mathbf{B}$  is a unit vector and so  $\mathbf{B} \cdot \mathbf{B} = 1$ . Finally, we can isolate  $\tau$  and write

$$\tau = \frac{(\mathbf{r}' \times \mathbf{r}'') \cdot \mathbf{r}'''}{\kappa^2(s')^6}$$

which is also

$$\tau = \frac{(\mathbf{r}' \times \mathbf{r}'') \cdot \mathbf{r}'''}{|\mathbf{r}' \times \mathbf{r}''|^2}$$

according to part (ii). 2 Marks

- v. Finally, we want to calculate the curvature and the torsion of the circular helix parametrized by  $\mathbf{r} = (a \cos t, a \sin t, bt)$ . We know that

$$\text{Curvature: } \kappa(t) = \frac{|\mathbf{r}'(t) \times \mathbf{r}''(t)|}{|\mathbf{r}'(t)|^3}$$

$$\text{Torsion: } \tau(t) = \frac{(\mathbf{r}'(t) \times \mathbf{r}''(t)) \cdot \mathbf{r}'''(t)}{|\mathbf{r}'(t) \times \mathbf{r}''(t)|^2}$$

For this curve, we have

$$\begin{aligned}
 \mathbf{r}'(t) &= (-a \sin t, a \cos t, b) \Rightarrow |\mathbf{r}'(t)| = \sqrt{a^2 + b^2} \\
 \mathbf{r}''(t) &= (-a \cos t, -a \sin t, 0) \\
 \mathbf{r}'''(t) &= (a \sin t, -a \cos t, 0)
 \end{aligned}$$

which leads to

$$\mathbf{r}' \times \mathbf{r}'' = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ -a \sin t & a \cos t & b \\ -a \cos t & -a \sin t & 0 \end{vmatrix} = ab \sin t \hat{\mathbf{i}} - ab \cos t \hat{\mathbf{j}} + a^2 \hat{\mathbf{k}}$$

leading to

$$|\mathbf{r}' \times \mathbf{r}''| = a\sqrt{a^2 + b^2}$$

and finally

$$(\mathbf{r}' \times \mathbf{r}'') \cdot \mathbf{r}''' = a^2 b \sin^2 t + a^2 b \cos^2 t = a^2 b$$

We thus conclude that

$$\text{Curvature: } \kappa(t) = \frac{|\mathbf{r}'(t) \times \mathbf{r}''(t)|}{|\mathbf{r}'(t)|^3} = \frac{a\sqrt{a^2 + b^2}}{(a^2 + b^2)^{3/2}} = \frac{a}{a^2 + b^2}$$

$$\text{Torsion: } \tau(t) = \frac{(\mathbf{r}'(t) \times \mathbf{r}''(t)) \cdot \mathbf{r}'''(t)}{|\mathbf{r}'(t) \times \mathbf{r}''(t)|} = \frac{a^2 b}{a^2(a^2 + b^2)} = \frac{b}{a^2 + b^2}$$

which shows that both only depend on  $a$  and  $b$ ; they are thus constant.

4 Marks
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