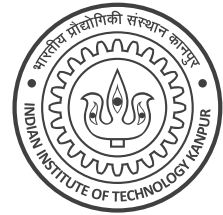


**Instructions:**

1. This question paper contains 2 pages (4 sides of paper). Please verify.
2. Write your name, roll number, department in **block letters** with **ink** on **each page**.
3. Write your final answers neatly **with a blue/black pen**. Pencil marks may get smudged.
4. Don't overwrite/scratch answers especially in MCQ – ambiguous cases may get 0 marks.



**Q1. (Total confusion)** The *confusion matrix* is a very useful tool for evaluating classification models. For a  $C$ -class problem, this is a  $C \times C$  matrix that tells us, for any two classes  $c, c' \in [C]$ , how many instances of class  $c$  were classified as  $c'$  by the model. In the example below,  $C = 2$ , there were  $P + Q + R + S$  points in the test set where  $P, Q, R, S$  are strictly positive integers. The matrix tells us that there were  $Q$  points that were in class  $+1$  but (incorrectly) classified as  $-1$  by the model,  $S$  points were in class  $-1$  and were (correctly) classified as  $-1$  by the model, etc. **Give expressions for the specified quantities in terms of  $P, Q, R, S$ .** No derivations needed. Note that  $y$  denotes the true class of a test point and  $\hat{y}$  is the predicted class for that point. **(5 x 1 = 5 marks)**

		Predicted class $\hat{y}$	
		+1	-1
True class $y$	+1	$P$	$Q$
	-1	$R$	$S$

**Confusion Matrix**

Accuracy (**ACC**)  $\mathbb{P}[\hat{y} = y]$

Precision (**PRE**)  $\mathbb{P}[y = 1 | \hat{y} = 1]$

Recall (**REC**)  $\mathbb{P}[\hat{y} = 1 | y = 1]$

False discovery rate (**FDR**)  $\mathbb{P}[y = -1 | \hat{y} = 1]$

False omission rate (**FOR**)  $\mathbb{P}[y = 1 | \hat{y} = -1]$


**Q2. (Kernel Smash)** Melbi has created two Mercer kernels  $K_1, K_2: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  with the feature map for the kernel  $K_i$  being  $\phi_i: \mathbb{R} \rightarrow \mathbb{R}^2$ . Thus, for any  $x, y \in \mathbb{R}$ , we have  $K_i(x, y) = \langle \phi_i(x), \phi_i(y) \rangle$  for  $i \in \{1, 2\}$ . Melbi knows that  $\phi_1(x) = (x, x^3)$  and  $\phi_2(x) = (1, x^2)$ . Melbo has created a new kernel  $K_3$  using Melbi's kernels so that for any  $x, y \in \mathbb{R}$ ,  $K_3(x, y) = (K_1(x, y) + 3 \cdot K_2(x, y))^2$ . Design a feature map  $\phi_3: \mathbb{R} \rightarrow \mathbb{R}^7$  for the kernel  $K_3$ . Write your answer only in the pace given below. No derivation needed. **Note that  $\phi_3$  must not use more than 7 dimensions. If your solution does not require 7 dimensions leave the rest of the dimensions blank.** **(5 marks)**

$\phi_3(x) =$

()

**Q3 (Opt to Prob)** Melbo enrolled in an advanced ML course and learnt an unsupervised learning technique called support vector data description (SVDD). Given a set of data points, say in 2D for sake of simplicity,  $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathbb{R}^2$ , SVDD solves the following optimization problem:

$$\min_{\mathbf{c} \in \mathbb{R}^2, r \geq 0} r^2 \text{ s.t. } \|\mathbf{x}_i - \mathbf{c}\|_2^2 \leq r^2 \text{ for all } i \in [n]$$

Melbo's friend Melba saw this and exclaimed that this is just an MLE solution. To convince Melbo, create a likelihood distribution  $\mathbb{P}[\mathbf{x} \mid \mathbf{c}, r]$  over the 2D space  $\mathbb{R}^2$  with parameters  $\mathbf{c} \in \mathbb{R}^2, r \geq 0$  s.t.

$$\left[ \arg \max_{\mathbf{c} \in \mathbb{R}^2, r \geq 0} \left\{ \prod_{i \in [n]} \mathbb{P}[\mathbf{x}_i \mid \mathbf{c}, r] \right\} \right] = \left[ \arg \min_{\mathbf{c} \in \mathbb{R}^2, r \geq 0} r^2 \text{ s.t. } \|\mathbf{x}_i - \mathbf{c}\|_2^2 \leq r^2 \text{ for all } i \in [n] \right]. \text{ Your solution}$$

**must be a proper distribution i.e.,**  $\mathbb{P}[\mathbf{x} \mid \mathbf{c}, r] \geq 0$  and  $\int_{\mathbf{x} \in \mathbb{R}^2} \mathbb{P}[\mathbf{x} \mid \mathbf{c}, r] d\mathbf{x} = 1$ . Give calculations to show why your distribution is correct. *Hint: area of a circle of radius  $r$  is  $\pi r^2$ .* **(4 + 6 = 10 marks)**

Write down the density function of your likelihood distribution here.

Give calculations showing why your likelihood distribution does indeed result in the optimization problem as MLE.

**Q4. (A one-class SVM?)** For anomaly detection tasks, the “one-class” approach is often used. Given a set of data points  $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathbb{R}^d$ , the 1CSVM solves the following problem:

$$\min_{\mathbf{w} \in \mathbb{R}^d, \xi \in \mathbb{R}^n, \rho \in \mathbb{R}} \left\{ \frac{1}{2} \|\mathbf{w}\|_2^2 - \rho + \sum_{i \in [n]} \xi_i \right\} \text{ s.t. } \mathbf{w}^\top \mathbf{x}_i \geq \rho - \xi_i \text{ and } \xi_i \geq 0 \text{ for all } i \in [n]$$

1. Write down the Lagrangian for this optimization problem by introducing dual variables.
2. Write down the dual problem as a max-min problem (no need to simplify it at this stage).
3. Now simplify the dual problem (eliminate  $\mathbf{w}, \xi, \rho$ ). Show major steps. **(3 + 2 + 5 = 10 marks)**

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Write down the Lagrangian here (you will need to introduce dual variables and give them names)

Derive and simplify the dual for this problem. Show major calculations steps.

**Q5 (Kernelized Anomaly Detection?)** Let's kernelize the 1CSVM. Suppose  $d$  is large and instead of receiving  $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathbb{R}^d$ , we receive pairwise dot products of the features as an  $n \times n$  matrix  $G = [g_{ij}] \in \mathbb{R}^{n \times n}$  where  $g_{ij} \stackrel{\text{def}}{=} \langle \mathbf{x}_i, \mathbf{x}_j \rangle$  for all  $i, j \in [n]$ . Rewrite **the (simplified) dual that you derived in Q4** but using only the dot products  $g_{ij}$ . No derivations required – just rewrite the dual using the dot products. **Note: your rewritten dual must not use feature vectors  $\mathbf{x}_i$  at all.** (2 marks)

**Q6 (Delta Likelihood)** Melbo has  $n$  data points  $\{\mathbf{x}_i, y_i\}$  with  $\mathbf{x}_i \in \mathbb{R}^d, y_i \in \{-1, +1\}$ . The likelihood of a model  $\mathbf{w} \in \mathbb{R}^d$  w.r.t. data point  $i$  is  $s_i \stackrel{\text{def}}{=} 1/(1 + \exp(-y_i \cdot \mathbf{w}^T \mathbf{x}_i))$  and w.r.t. the entire data is  $\mathcal{L}(\mathbf{w}) \stackrel{\text{def}}{=} \prod_{i \in [n]} s_i$ . Notice that if the label of the  $j$ -th point is flipped (for any single  $j \in [n]$ ), then the likelihood of the same model  $\mathbf{w}$  changes to  $\tilde{\mathcal{L}}_j(\mathbf{w}) \stackrel{\text{def}}{=} 1/(1 + \exp(y_j \cdot \mathbf{w}^T \mathbf{x}_j)) \cdot (\prod_{i \neq j} s_i)$ .

- i. Given a **fixed** model  $\mathbf{w}$ ,  $j \in [n]$ , give an expression for  $\Delta_j(\mathbf{w}) \stackrel{\text{def}}{=} \tilde{\mathcal{L}}_j(\mathbf{w})/\mathcal{L}(\mathbf{w})$ , i.e., the factor by which likelihood of  $\mathbf{w}$  changes if  $j$ -th label is flipped. Give brief derivation.
- ii. If  $n = 5$  and  $s_1 = 0.1, s_2 = 0.3, s_3 = 0.9, s_4 = 0.6, s_5 = 0.2$ , find the point  $j^* \in [5]$  for which  $\Delta_{j^*}(\mathbf{w})$  is the largest and value of  $\Delta_{j^*}(\mathbf{w})$ . Give brief justification.
- iii. If  $n = 5$  and  $s_1 = 0.4, s_2 = 0.6, s_3 = 0.2, s_4 = 0.7, s_5 = 0.8$ , find  $k^* \in [5]$  for which  $\Delta_{k^*}(\mathbf{w})$  is the smallest and value of  $\Delta_{k^*}(\mathbf{w})$ . Give brief justification. **(2 + 3 + 3 = 8 marks)**

$\Delta_j(\mathbf{w}) =$

$j^* = \underline{\hspace{2cm}} \quad \Delta_{j^*}(\mathbf{w}) = \underline{\hspace{2cm}} \quad k^* = \underline{\hspace{2cm}} \quad \Delta_{k^*}(\mathbf{w}) = \underline{\hspace{2cm}}$

Give brief derivation for part i and justification for parts ii and iii below.