

Group Theory and Homotopy Groups

A quick, equation-heavy reference for physics

February 22, 2026

Abstract

This is a standalone collection of group theory and homotopy material (Lie groups and Lie algebras, representations, exact sequences, and standard computations of π_n) with a focus on the formulas most often used in gauge theory, defects, and topological terms in QFT.

Contents

1	Groups, actions, and representations	2
1.1	Groups and homomorphisms	2
1.2	Group actions	2
1.3	Representations	3
2	Lie groups and Lie algebras	3
2.1	Lie algebra from matrices	3
2.2	Adjoint and coadjoint actions	3
2.3	Structure constants and normalization	3
3	Exact sequences and covering spaces	3
3.1	Short exact sequences	3
3.2	Universal covers (example)	4
4	Homotopy groups: definitions	4
4.1	Based homotopy groups	4

4.2	Relative homotopy and pairs	4
5	Fibrations and the long exact sequence	4
5.1	Example: $U(1) \hookrightarrow SU(2) \twoheadrightarrow S^2$	4
6	Standard computations and facts	5
6.1	Spheres	5
6.2	Lie groups (selected low homotopy)	5
6.3	Homogeneous spaces and defects	5
7	A minimal “physics bridge” appendix	5
7.1	Gauge fields and characteristic classes (one page)	5
7.2	A quick picture: maps at infinity	5

1 Groups, actions, and representations

1.1 Groups and homomorphisms

A group (G, \cdot) has identity e and inverses. A homomorphism $\varphi : G \rightarrow H$ satisfies

$$\varphi(g_1 g_2) = \varphi(g_1) \varphi(g_2).$$

Kernel and image:

$$\ker(\varphi) = \{g \in G : \varphi(g) = e\}, \quad \text{im}(\varphi) = \varphi(G).$$

1.2 Group actions

A (left) action of G on X is $G \times X \rightarrow X$, $(g, x) \mapsto g \cdot x$, with

$$e \cdot x = x, \quad (g_1 g_2) \cdot x = g_1 \cdot (g_2 \cdot x).$$

Orbits and stabilizers:

$$G \cdot x = \{g \cdot x\}, \quad G_x = \{g \in G : g \cdot x = x\}.$$

1.3 Representations

A representation is a homomorphism $\rho : G \rightarrow GL(V)$. For Lie groups, differentiating at the identity gives a Lie algebra representation

$$\rho_* : \mathfrak{g} \rightarrow \mathfrak{gl}(V), \quad \rho_*([X, Y]) = [\rho_*(X), \rho_*(Y)].$$

2 Lie groups and Lie algebras

2.1 Lie algebra from matrices

For a matrix Lie group $G \subseteq GL(n, \mathbb{C})$, the Lie algebra is

$$\mathfrak{g} = \{X \in M_n(\mathbb{C}) : e^{tX} \in G \ \forall t\}.$$

The bracket is the commutator $[X, Y] = XY - YX$.

2.2 Adjoint and coadjoint actions

$${}_g(X) = gXg^{-1}, \quad {}_X(Y) = [X, Y].$$

The coadjoint action on \mathfrak{g}^* is $({}_g^*\lambda)(X) = \lambda({}_g^{-1}X)$.

2.3 Structure constants and normalization

Choose a basis T^a :

$$[T^a, T^b] = f^{ab}{}_c T^c.$$

In a representation one often sets

$$\text{Tr}(T^a T^b) = \kappa \delta^{ab}, \quad (T^a)^\dagger = T^a \text{ (compact groups)}.$$

3 Exact sequences and covering spaces

3.1 Short exact sequences

A short exact sequence

$$1 \rightarrow A \xrightarrow{i} B \xrightarrow{p} C \rightarrow 1$$

means i is injective, p is surjective, and $\text{im}(i) = \ker(p)$. This packages extensions.

3.2 Universal covers (example)

$SU(2)$ is the universal cover of $SO(3)$:

$$1 \rightarrow \mathbb{Z}_2 \rightarrow SU(2) \rightarrow SO(3) \rightarrow 1,$$

hence

$$\pi_1(SO(3)) \cong \mathbb{Z}_2, \quad \pi_1(SU(2)) = 0.$$

4 Homotopy groups: definitions

4.1 Based homotopy groups

For a pointed space (X, x_0) ,

$$\pi_n(X, x_0) := \{f : (\mathbb{S}^n, *) \rightarrow (X, x_0)\} / \sim$$

where \sim is based homotopy. For $n \geq 1$ these are groups, and for $n \geq 2$ they are abelian.

4.2 Relative homotopy and pairs

For a pair (X, A) with basepoint in A , the relative groups $\pi_n(X, A)$ fit into a long exact sequence (LES).

5 Fibrations and the long exact sequence

Given a fibration $F \hookrightarrow E \twoheadrightarrow B$, there is an LES:

$$\cdots \rightarrow \pi_n(F) \rightarrow \pi_n(E) \rightarrow \pi_n(B) \rightarrow \pi_{n-1}(F) \rightarrow \cdots$$

This is among the most practical tools for computing π_n .

5.1 Example: $U(1) \hookrightarrow SU(2) \twoheadrightarrow S^2$

The quotient $SU(2)/U(1) \cong S^2$ yields a fibration

$$U(1) \hookrightarrow SU(2) \twoheadrightarrow S^2.$$

Using $\pi_2(SU(2)) = 0$ and $\pi_1(SU(2)) = 0$, the LES gives

$$\pi_2(S^2) \cong \pi_1(U(1)) \cong \mathbb{Z}.$$

6 Standard computations and facts

6.1 Spheres

$$\pi_1(S^1) \cong \mathbb{Z}, \quad \pi_n(S^n) \cong \mathbb{Z} \ (n \geq 1), \quad \pi_1(S^n) = 0 \ (n \geq 2).$$

6.2 Lie groups (selected low homotopy)

Common values (for $N \geq 2$):

$$\pi_1(SU(N)) = 0, \quad \pi_3(SU(N)) \cong \mathbb{Z}.$$

For $N \geq 3$:

$$\pi_1(SO(N)) \cong \mathbb{Z}_2.$$

6.3 Homogeneous spaces and defects

If G breaks to H , the vacuum manifold is $\mathcal{M} \cong G/H$. Defects are classified by

$$\pi_k(\mathcal{M})$$

depending on codimension.

7 A minimal “physics bridge” appendix

7.1 Gauge fields and characteristic classes (one page)

Write a connection A and curvature $F = dA + A \wedge A$. A basic topological density in 4D is

$$\text{Tr}(F \wedge F),$$

with instanton number (normalization depending on conventions)

$$k = \frac{1}{8\pi^2} \int_{M_4} \text{Tr}(F \wedge F) \in \mathbb{Z},$$

and corresponding θ -term

$$S_\theta = i\theta k.$$

7.2 A quick picture: maps at infinity

For finite-action configurations in 4D Euclidean Yang–Mills, at $|x| \rightarrow \infty$ one effectively gets a map

$$S_\infty^3 \rightarrow G,$$

classified by $\pi_3(G)$, e.g. $\pi_3(SU(N)) \cong \mathbb{Z}$.