

Lecture - 20

Thursday, October 22, 2020 1:51 PM

Last class

* Discrete Fourier Transform (DFT) : $x[n] \xleftrightarrow{N\text{-DFT}} X[k]$

$n=0, 1, \dots, N-1$

$k=0, 1, \dots, N-1$

* DFT as samples of DTFT spectrum

$$\text{at } \omega_k = \frac{2\pi}{N} k, k=0, 1, \dots, N-1.$$

$$X[k] = \left. x(e^{j\omega}) \right|_{\omega = \frac{2\pi}{N} k}$$

N samples in interval $[0, 2\pi)$ Spaced $\frac{2\pi}{N}$ apart.

* given N -length signal $x[n], n=0, 1, \dots, N-1$; N -point DFT given by :

$$\text{DFT: } X[k] = \sum_{n=0}^{N-1} x[n] e^{-j \frac{2\pi}{N} kn} \quad k=0, 1, \dots, N-1.$$

$$\text{IDFT: } x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j \frac{2\pi}{N} kn} \quad n=0, 1, \dots, N-1$$

linear combination of periodic signals

* Note that above formulae are valid for any integer k & n with the following periodicity

$$* X[k+N] = X[k] \quad * x[n+N] = x[n]$$

* We can treat $x[n]$ & $X[k]$ as N -length vectors with the relation

$$X_N = F_N x_N, \quad F_N - \text{DFT matrix}, \quad W_N = e^{-j \frac{2\pi}{N}}$$

Today's Class:

as function of discrete-time n , the set of signals

$$* \left\{ e^{j \left(\frac{2\pi}{N} k \right) n} \right\}, k=0, 1, 2, \dots, N-1 \quad \text{are all periodic with period } N.$$

Zero padding :

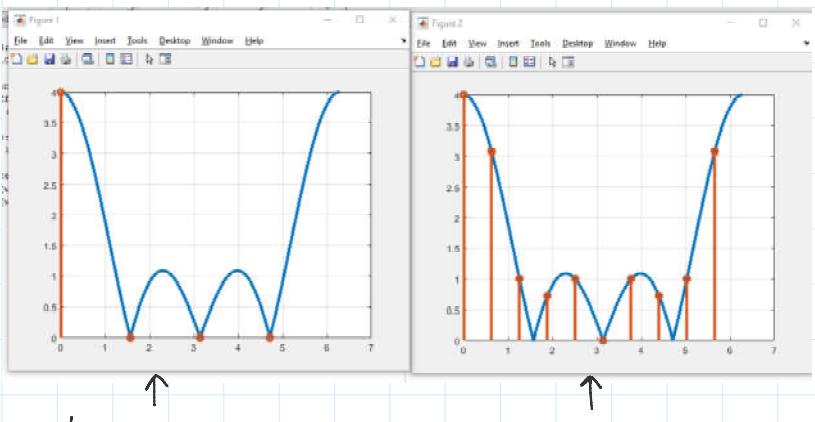
DTFT in blue.

DFT in red (stem plot)

$$x(n) = 1, n=0, 1, 2, 3.$$

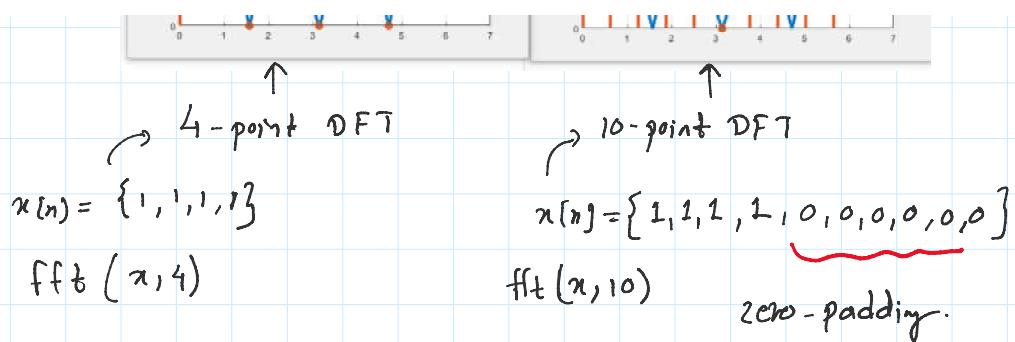
↑

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$$x(n) = 1, n=0,1,2,3$$

zero-padding is useful to get more DFT samples.



* Properties:

① Linearity.

② Time shift: $x[n-n_0] \xrightarrow{\text{DFT}} e^{-j\frac{2\pi}{N}kn_0} X[k]$.

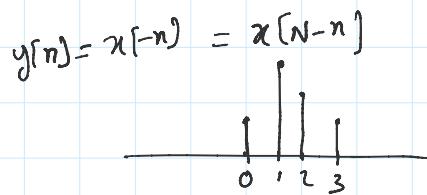
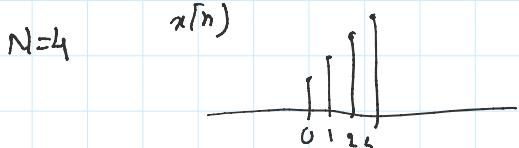
shift of the periodic signal / circular shift



③ Time reversal:

$$x[-n] \xrightarrow{\text{DFT}} X[-k] = X[N-k]$$

$x[N-n] \xrightarrow{\text{(periodicity)}} \text{periodicity (N)}$



④ Freq. shift:

$$x[n] e^{j\frac{2\pi}{N}nk_0} = X[k - k_0]$$

⑤ Complex conjugate: $x^*[n] \longleftrightarrow X^*[-k] = X^*[N-k]$

real signal: $X^*[N-k] = X[k]$.

⑥ Parseval's Theorem:

$$\sum_{n=0}^{N-1} |x[n]|^2 = \frac{1}{N} \sum_{k=0}^{N-1} |X[k]|^2$$

⑦ Convolution:

$$\begin{aligned} x_1[n] &\xleftrightarrow{N} X_1[k] \\ x_2[n] &\xleftrightarrow{N} X_2[k] \end{aligned}$$

} N-point DFT

$\star x_3[n] = x_1[n] \otimes x_2[n] \xleftrightarrow{N} X_3[k] = X_1[k] X_2[k]$ \star

circular convolution.

by IDFT

$$x_3[n] = \frac{1}{N} \sum_{k=0}^{N-1} X_3[k] e^{j \frac{2\pi}{N} kn} = \frac{1}{N} \sum_{k=0}^{N-1} X_1[k] X_2[k] e^{j \frac{2\pi}{N} kn}$$

$$x_3[n] = \frac{1}{N} \sum_k \left[\left(\sum_m x_1[m] e^{-j \frac{2\pi}{N} km} \right) \left(\sum_l x_2[l] e^{-j \frac{2\pi}{N} lk} \right) \right] e^{j \frac{2\pi}{N} kn}$$

$$x_3[n] = \frac{1}{N} \sum_m \sum_l x_1[m] x_2[l] \left(\sum_{k=0}^{N-1} e^{j \frac{2\pi}{N} k(n-m-l)} \right)$$

$$x_3[n] = \frac{1}{N} \sum_m \left(\sum_l x_1[m] x_2[l] \right)$$

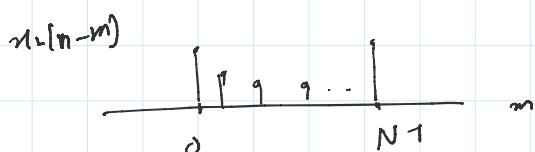
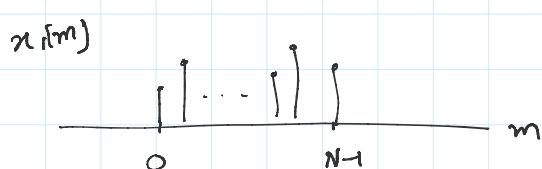
$\left\{ \begin{array}{ll} N & , n-m-l = pN \\ 0 & , \text{otherwise.} \end{array} \right.$

$$x_3[n] = \sum_{m=0}^{N-1} x_1[m] x_2[n-m]$$

} circular convolution.

$$n-m-l=0$$

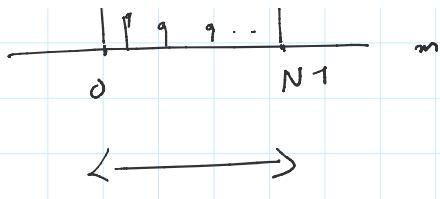
$$\Rightarrow l = n-m$$



only uses one period (N)

define for some length signals

Ex. $x_1 = \{0, 1, 2, 3\}$



$$\text{Ex. } x_1 = \{0, 1, 2, 3\}$$

$$x_2 = \{1, 2, 3, 4\}$$

Find $x_1 \otimes x_2$. (HW)



⑧ Multiplication property:

both N -length $\underbrace{x_1[n]}_{\curvearrowright} \underbrace{x_2[n]}_{\curvearrowright} \xleftarrow{N} \frac{1}{N} (x_1[k] \otimes x_2[k])$.

We are interested in linear filtering i.e linear convolution.

$$x[n] \quad h[n]$$

How to do linear/regular convolution using circular convolution?

a) Circular convolution:

Ex. $N=4$ & $y[n] = x[n] \otimes h[n] = \sum_{m=0}^{N-1} x[m] h[n-m]$

$$y[0] = x[0] h[0] + x[1] h[3] + x[2] h[2] + x[3] h[1]$$

$$y[1] = x[0] h[1] + x[1] h[0] + x[2] h[3] + x[3] h[2]$$

$$y[2] = x[0] h[2] + x[1] h[1] + x[2] h[0] + x[3] h[3]$$

$$y[3] =$$

$$\begin{bmatrix} y[0] \\ y[1] \\ y[2] \\ y[3] \end{bmatrix} = \begin{bmatrix} h[0] & h[3] & h[2] & h[1] \\ h[1] & h[0] & h[3] & h[2] \\ h[2] & h[1] & h[0] & h[3] \\ h[3] & h[2] & h[1] & h[0] \end{bmatrix} \begin{bmatrix} x[0] \\ x[1] \\ x[2] \\ x[3] \end{bmatrix}$$

↳ Circulant matrix.

(b) Linear convolution:

$$y_1[n] = x_1[n] * h_1[n]$$

$$y_1[n] = \sum_{m=0}^2 x_1[m] h_1[n-m]$$

$$y_1[0] = x_1[0] h_1[0]$$

$$y_1[1] = x_1[0] h_1[1] + x_1[1] h_1[0]$$

$$y_1[2] = x_1[0] h_1[2] + x_1[1] h_1[1] + x_1[2] h_1[0]$$

$$y_1[3] = x_1[0] h_1[3] + x_1[1] h_1[2] + x_1[2] h_1[1]$$

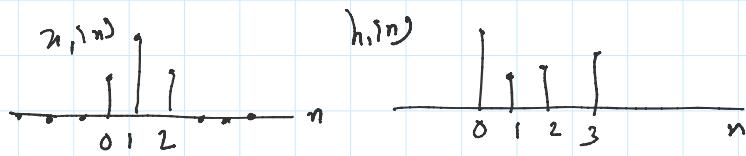
$$y_1[4] = x_1[1] h_1[3] + x_1[2] h_1[2]$$

$$y_1[5] = x_1[2] h_1[3]$$

$$\text{Ex. } x_1[n] = \{x_1[0], x_1[1], x_1[2]\}$$

$$h_1[n] = \{h_1[0], h_1[1], h_1[2], h_1[3]\}$$

Other terms are zero.



Putting in a matrix

$$\begin{bmatrix} y_1[0] \\ y_1[1] \\ \vdots \\ y_1[5] \end{bmatrix} = \begin{bmatrix} h_1[0] & 0 & 0 \\ h_1[1] & h_1[0] & 0 \\ h_1[2] & h_1[1] & h_1[0] \\ h_1[3] & h_1[2] & h_1[1] \\ 0 & h_1[3] & h_1[2] \\ 0 & 0 & h_1[3] \end{bmatrix} \begin{bmatrix} x_1[0] \\ x_1[1] \\ x_1[2] \\ x_1[3] \end{bmatrix}$$

↑ partly circulant

$$\begin{bmatrix} y_1[0] \\ y_1[1] \\ \vdots \\ y_1[5] \end{bmatrix} = \begin{bmatrix} h_1[0] & 0 & 0 & h_1[3] & h_1[2] & h_1[1] \\ h_1[1] & h_1[0] & 0 & 0 & h_1[3] & h_1[2] \\ h_1[2] & h_1[1] & h_1[0] & 0 & 0 & h_1[3] \\ h_1[3] & h_1[2] & h_1[1] & h_1[0] & 0 & 0 \\ 0 & h_1[3] & h_1[2] & h_1[1] & h_1[0] & 0 \\ 0 & 0 & h_1[3] & h_1[2] & h_1[1] & h_1[0] \end{bmatrix} \begin{bmatrix} x_1[0] \\ x_1[1] \\ x_1[2] \\ x_1[3] \\ 0 \\ 0 \end{bmatrix} = \tilde{y} = \tilde{H}_1 \cdot \tilde{x},$$

- circulant matrix

Circular convolution.

$$y_1[n] = \tilde{h}_1[n] \circledast \tilde{x}_1[n]$$

$$\tilde{h}_1[n] = [h_1[0], h_1[1], h_1[2], h_1[3], 0, 0]$$

$$\tilde{x}_1[n] = [x_1[0], x_1[1], x_1[2], 0, 0, 0]$$