

Last Class:

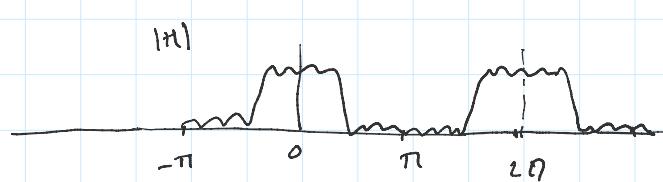
- * FIR filter design
- * Linear phase & FIR filters - symmetry / anti-symmetry conditions on $h[n]$
 - ↳ corresponds to delay / shift
- * FIR filter design using Windows

Todays class:

- * Linear phase and impulse response (Type I, Type II, etc.)
- * FIR filter design using frequency sampling (least squares)
- * Optimum Equiripple FIR filters (Chebyshev filters)
- * Example of Analog signal processing using digital filter

Ex. Let $h[n]$ be a low-pass filter then $h_1[n] = (-1)^n h[n]$ behaves

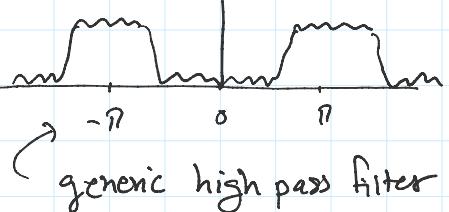
as a
 $h[n] \xleftrightarrow{\text{DTFT}} H(e^{j\omega})$



generic LPF

shift by π

|H₁|



generic high pass filter

* Linear-phase & FIR impulse response.

Let $h[n]$, $n = 0, 1, \dots, N-1$ be an FIR impulse response.

Case :

N is odd, let $M = \frac{N-1}{2}$

$$\begin{aligned}
 H(e^{j\omega}) &= \sum_{n=0}^{N-1} h[n] e^{-j\omega n} = e^{-j\omega M} \left(\sum_{n=0}^{N-1} h[n] e^{-j\omega n} e^{j\omega M} \right) \\
 &= e^{-j\omega M} \left(\sum_{n=0}^{N-1} h[n] e^{j\omega(M-n)} \right)
 \end{aligned}$$

$n=0 \quad h[0] e^{j\omega M}$ & $n=N-1 \quad h[N-1] e^{-j\omega M}$

$$= \underbrace{\dots}_{n=0} + \underbrace{h[0]e^{j\omega M}}_{n=0} + h[N-1]e^{-j\omega M} + h[1]e^{j\omega(N-1)} + h[N-2]e^{-j\omega(N-1)} + \dots + h[M+1]e^{-j\omega}, \quad n=(N-1)-(M+1)$$

$$\vdots$$

$$n=M \quad h[M]$$

$$H(e^{j\omega}) = e^{-j\omega M} \left\{ (h[0]e^{j\omega M} + h[N-1]e^{-j\omega M}) + (h[1]e^{j\omega(N-1)} + h[N-2]e^{-j\omega(N-1)}) + \dots + h[M] \right\}$$

Euler's formula

$$(h[0] + h[N-1]) \cos(\omega M) + j(h[0] - h[N-1]) \sin(\omega M)$$

$$\Rightarrow H(e^{j\omega}) = e^{-j\omega M} \left\{ h[M] + \sum_{n=0}^{M-1} (h[n] + h[N-1-n]) \cos(\omega(M-n)) + j(h[n] - h[N-1-n]) \sin(\omega(M-n)) \right\}$$

we design filters with real coefficients i.e. $h[n]$ is real.

under what conditions the quantity in $\{ \}$ is real?

Selecting: $h[n] = h[N-1-n], \quad n=0, 1, \dots, M-1$

$\Rightarrow \{ \}$ will be real

$\Rightarrow H(e^{j\omega})$ will have linear phase (due to $e^{-j\omega M}$)

symmetric $h[n] \Rightarrow$ linear phase of $H(e^{j\omega})$.

Type I FIR filters : N-odd & $h[n]$ is symmetric.

Alternately selecting: $h[n] = -h[N-1-n] \quad n=0, 1, \dots, M-1$

& $h[M] = 0$

$\Rightarrow H(e^{j\omega})$ will have linear phase

anti-symmetric $h[n] \Rightarrow$

Type III FIR filters : N-odd & $h[n]$ is anti-symmetric.

Case: N is even & $M = N/2$

we can show

$$H(e^{j\omega}) = e^{-j\omega M} \left\{ \sum_{n=0}^{M-1} (h[n] + h[N-1-n]) \cos(\omega(n-n)) + j(h[n] - h[N-1-n]) \sin(\omega(n-n)) \right\}$$

Type II FIR : N -even & $h[n]$ symmetric.

Type IV FIR : N -even & $h[n]$ anti-symmetric.



Type III - cannot make LPF & C()

Type IV - cannot make LPF

$$\left. H(e^{j\omega}) \right|_{\omega=0} = \sum_{n=0}^{N-1} h[n] = 0 \quad (\text{for anti-symmetry})$$

∴ do not pass low frequencies.

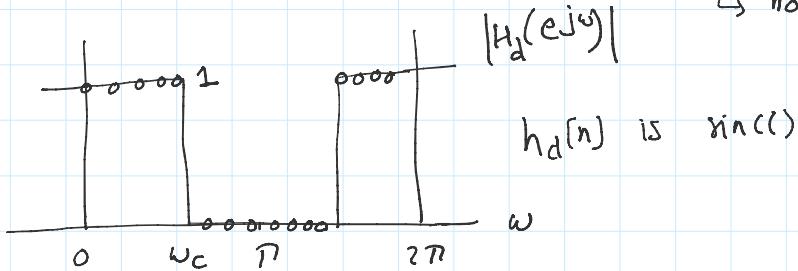
H.W. show that for symmetric & anti-symmetric filters $h[n]$

$$h[n] \longleftrightarrow H(z)$$

→ If z_0 is a zero of $H(z)$ then so is $\frac{1}{z_0}$.

* FIR filter design using frequency sampling. (method of least squares)
 ↳ not proved here.

Ex. Iced LPF



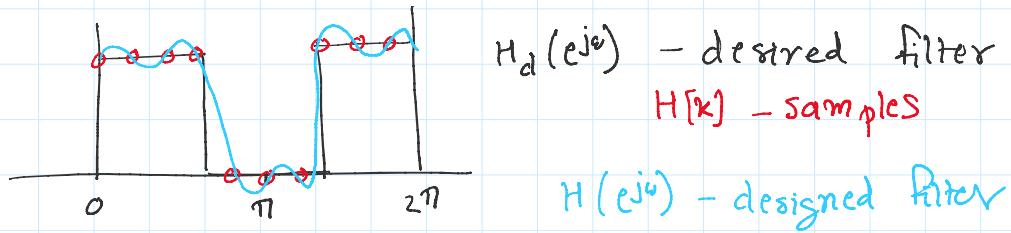
(equi-spaced) Sample the iced spectrum. to get $H[k]$, $k=0, 1 \dots N-1$

$$H[k] = H_d(e^{j\omega}) \quad \left| \begin{array}{l} \omega = \frac{2\pi}{N} k = \omega_k \\ \uparrow \text{DFT} \end{array} \right.$$

$$M = \begin{cases} \frac{N-1}{2}, & N - \text{odd} \\ \frac{N}{2}, & N = \text{even} \end{cases}$$

get $h[n]$ from inverse DFT of $H[k] e^{-j\omega_k n}$

$\downarrow \text{IDFT}$
 $H(e^{j\omega}) = H[k]$ samples this spectrum.

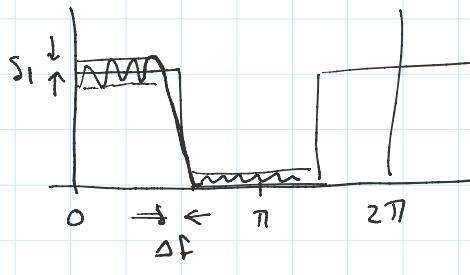


For real $h[n]$, select $H[k]$ symmetric.

Ex. In matlab, $N=15$, design FIR filter (low-pass) using freq. sampling.

* Optimum Equinipple FIR filters (Chebyshev)

- This method allows choosing various parameters i.e.



$\left\{ \begin{array}{l} S_1 - \text{pass band ripple} \\ S_L - \text{stop band ripple} \\ \Delta f - \text{transition region} \\ N - \text{length of filter} \end{array} \right.$

of

(N - length of filter)

This method minimizes the absolute error between desired filter & designed filter. \Rightarrow hence optimality.

\Rightarrow This process gives a filter with equal size ripples in the passband.
(also for stop band).

Ex.

given speech signal (cont. time) with frequency content $< 8 \text{ kHz}$.

we want to perform LPF on this digitally.

requirement : analog LPF with cutoff of 6 kHz

design : a digital LPF to achieve this when signal is sampled at
 $\text{(a) } 18 \text{ kHz}$ $\text{(b) } 20 \text{ kHz}$.

Q. What should be the digital LPF cutoff ω_c ?