

Build Robot Create Science

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By



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GSM



GSM



CODE I:

```
#include <avr/io.h>
#include <avr/interrupt.h>
#include <util/delay.h>

char A[100]="",index=0;

ISR(USART_RXC_vect) {
    A[index] = UDR;
    if (A[index]==10)index = 0;
    else index++;
}

void main() {
    LCDinit();
    LCDclr();
    set_uartbaud(9600);
    enable_uart_rxcint();
    sei();
    LCDdisplay("*****");
    _delay_ms(1000);
    while(1){
        sendstring_uart("AT\r");
        _delay_ms(1000);
        LCDGotoXY(0,1);
        LCDstring(A,20);
    }
}
```

This Code will send "AT" to GSM MODEM and it will print the text received from the MODEM.

CODE II:

```
#include <avr/io.h>
#include <avr/interrupt.h>
#include <util/delay.h>

char A[100]="",index=0;

ISR(USART_RXC_vect) {
    A[index] = UDR;
    if (A[index]==10)index = 0;
    else index++;
}

void main() {
    LCDinit();
    LCDclr();
    set_uartbaud(9600);
    enable_uart_rxcint();
```



```

sei();
LCDdisplay("*****");
_delay_ms(1000);
while(1){
    sendstring_uart("ATD*123#\r");
    _delay_ms(3000);
    _delay_ms(3000);
    _delay_ms(3000);
    LCDGotoXY(0,1);
    LCDstring(A,20);

}
}

```

This code will call at *123# and it will print the replied message on the LCD display. You can use "LCDShiftRight(1);" to see complete message on display.

CODE III:

```

#include <avr/io.h>
#include <avr/interrupt.h>
#include <util/delay.h>
#include <uart_lib.h>
#include <stdio.h>
char A[200]=" ",index=0;

ISR(USART_RXC_vect) {
    A[index] = UDR;
    if (A[index]==10)index = 0;
    else index++;
}

int main() {
    set_uartbaud(9600);
    enable_uart_rxcint();
    sendchar_uart(0x1a);
    sei();
    while(1){
        sendstring_uart("ATD09415511117;\r\n");
        _delay_ms(1000);
        delay=0;
        while(1){
            sendstring_uart("AT+CLCC\r\n");
            _delay_ms(100);
            if(strncmp(A+5,": 1,0,3,0,0,",10)==0)break;
            if(delay>100)break;
            delay++;
        }
        sendstring_uart("ATH\r\n");
        _delay_ms(2000);
    }
    return 0;
}

```



This Code will give a continuous missed call to the mobile number specified in code..

CODE IV:

```
#include <avr/io.h>
#include <avr/interrupt.h>
#include <util/delay.h>
#include <uart_lib.h>
#include <stdio.h>

static char line=0, status = 0, index = 0, mob[10] = "          ", A[20]="asdfghjk",b,c;
ISR(USART_RXC_vect){
    c = UDR;
    if(index<16)A[index]=c;
    index++;
    if (c==0x0A){status|=1;index = 0;line=0;}

    else if(index == 5){
        if((strcmp(A,"+CMTI",5) == 0)){ status|=4;line=1;}
        else if((strcmp(A,"+CLIP",5) == 0)){ status|=2;line=1;}
        else if((strcmp(A,"NO CA",5) == 0)){ status&=~2;line=1;}
    }
    else if(index>11&index<22&(status>>1))mob[index-12]=c;
}

int main(void) {
    DDRA=255;
    set_uartbaud(9600);
    enable_uart_rxcint();
    LCDinit();
    LCDclr();
    sei();
    _delay_ms(2000);
    sendstring_uart("AT\r");
    sendstring_uart("at+clip=1\r");
    _delay_ms(2000);
    while (1) {
        if(status==3){
            _delay_ms(100);
            if(status>>1&(strcmp(mob,"9750058326",10) == 0)){
                sendstring_uart("ath\r");
                PORTA=255;
                status=1;
            }
            if(status>>1&(strcmp(mob,"8754515884",10) == 0)){
                sendstring_uart("ath\r");
                PORTA=0;
                status=1;
            }
        }
    }
}
```



```

        LCDGotoXY(0,0);
        LCDstring(A,16);
        LCDGotoXY(0,1);
        LCDsendChar(status+48);
        LCDsendChar(30);
        LCDstring(mob,10);
    }
}

```

This code will switch on/off the LEDs on Port-A when you will call on it from two numbers specified in codes.

CODE V:

```

#include <avr/io.h>
#include <avr/interrupt.h>
#include <util/delay.h>
#include <uart_lib.h>
#include <stdio.h>

```

```

static char b,c,line=0, status = 0,index = 0,mob[10] = "          ",A[20]="asdfghjk";
ISR(USART_RXC_vect){
    c = UDR;
    if(index<16)A[index]=c;
    index++;
    if (c==0x0A){status|=1;index = 0;line=0;}

    else if(index == 5){
        if((strncmp(A,"+CMTI",5) == 0)){ status|=4;line=1;}
        else if((strncmp(A,"+CLIP",5) == 0)){ status|=2;line=1;}
        else if((strncmp(A,"NO CA",5) == 0)){ status&=~2;line=1;}
    }
    else if(index>11&index<22&(status>>1))mob[index-12]=c;
}

```

```

int main(void) {
    DDRA=255;
    set_uartbaud(9600);
    enable_uart_rxcint();
    LCDinit();
    LCDclr();
    sei();
    _delay_ms(2000);
    sendstring_uart("AT\r");
    sendstring_uart("at+clip=1\r");
    _delay_ms(2000);
    while (1) {
        if(status==3){
            _delay_ms(100);
            if(status>>1&(strncmp(mob,"9750058326",10) == 0)){
                sendstring_uart("ath\r");
            }
        }
    }
}

```



```

        PORTA=~PORTA;
        status=1;
    }
}
LCDGotoXY(0,0);
LCDstring(A,16);
LCDGotoXY(0,1);
LCDsendChar(status+48);
LCDsendChar(30);
LCDstring(mob,10);
}
}

```

This code will switch on/off the LEDs on Port-A when you will call on it from single number specified in codes.

CODE VI:

```

#include <avr/io.h>
#include <avr/interrupt.h>
#include <util/delay.h>
#include "lcd_lib.h"
#include <uart_lib.h>
#include <string.h>

unsigned char mob[10]="",sms[100]="";
int index=0;
char A[50]="",status=0,line=0,sts=0;

ISR(USART_RXC_vect) {
    char c=UDR;
    A[index]=c;
    index++;
    if (c==0x0A){
        status|=1;
        index = 0;
        if((status>>3)%2){status|=16;status&=~8;}
        else status&=~16;
    }
    else if((index == 5)&((status>>4)%2==0)){
        if((strcmp(A,"OK",2) == 0)){ status|=1;}
        else if((strcmp(A,"+CLIP",5) == 0)){ status|=2;}
        else if((strcmp(A,"NO CA",5) == 0)){ status&=~2;}
        else if((strcmp(A,"+CMTI",5) == 0)){ status|=4;}
        else if((strcmp(A,"+CMGR",5) == 0)){ status|=8;}
    }
    else if(index>11&index<22&(status>>1))mob[index-12]=c;
    else if(index>24&index<35&((status>>3)%2))mob[index-25]=c;
    else if((status>>4)%2)sms[index-1]=A[index-1];
}

void delete_sms(){
    status&=~1;
    while ((status%2)!=1) {

```



```

        sendstring_uart("AT+CMGD=1\r");
        _delay_ms(1000);
    }
    status&=~4;
    status&=~8;
    status&=~16;
}

void read_sms(){
    if((status>>2)%2){
        sendstring_uart("AT+CMGR=1\r");
        _delay_ms(1000);
    }
    delete_sms();
    _delay_ms(1000);
}

void check_gsm(){
    status&=~1;
    while ((status%2)!=1) {
        sendstring_uart("AT\r");
        _delay_ms(100);
    }
    sendstring_uart("AT+CLIP=1\r");
}

int main() {
    LCDinit();
    LCDclr();
    set_uartbaud(9600);
    enable_uart_rxcint();
    sei();
    check_gsm();
    delete_sms();
    LCDdisplay("*****");
    _delay_ms(1000);
    while(1){
        read_sms();
        _delay_ms(1000);
        LCDGotoXY(0,0);
        LCDstring(sms,16);
        _delay_ms(100);
        LCDGotoXY(0,1);
        LCDsendChar(status+48);
        LCDsendChar(30);
        LCDstring(mob,10);
        _delay_ms(1000);
        if(strncmp(sms,"ON",2) == 0)PORTA=255;
        if(strncmp(sms,"OF",2) == 0)PORTA=0;
    }
}

```



```
}  
    return 0;  
}
```

This code will switch on/off the LEDs on Port-A when you will send SMS having text “on” / “of” on it from any other code. If you want you can change the SMS text for operation.

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