

Audio Filter

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I. DIGITAL FILTER

- I.1 The sound file used for this code is obtained from the below link codes/song.wav
 I.2 A Python Code is written to achieve Audio Filtering

```
import soundfile as sf
import numpy as np
from scipy import signal
#read .wav file
input_signal,fs = sf.read('song.wav')

#sampling frequency of Input signal
sampl_freq=fs
print(fs)

#order of the filter
order=4

#cutoff frequency
cutoff_freq=1000.0

#digital frequency
Wn=2*cutoff_freq/sampl_freq

# b and a are numerator and denominator
  polynomials respectively
b, a = signal.butter(order, Wn, 'low')
print(b)
print(a)

#filter the input signal with butterworth filter
output_signal = signal.filtfilt(b, a,
    input_signal,padlen=1)
#output_signal = signal.lfilter(b, a,
    input_signal)

#write the output signal into .wav file
sf.write('Sound_With_ReducedNoise.wav',
    output_signal, fs)
```

- I.3 The audio file is analyzed using spectrogram using the online platform <https://academo.org/demos/spectrum-analyzer>.

The darker areas are those where the frequencies have very low intensities, and the orange and yellow areas represent frequencies that have high intensities in the sound.

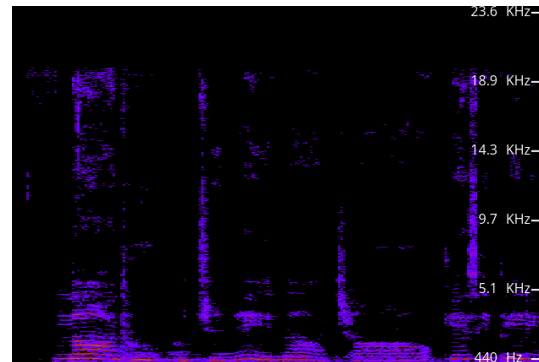


Fig. 1. Spectrogram of the audio file before Filtering

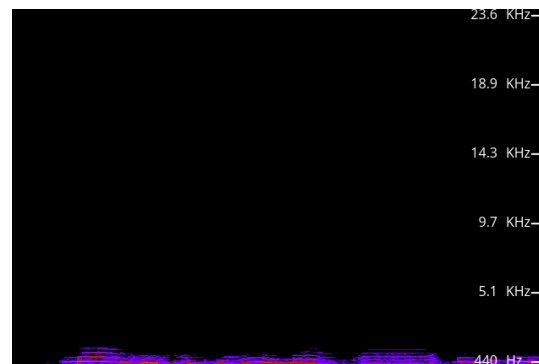


Fig. 2. Spectrogram of the audio file after Filtering

II. DIFFERENCE EQUATION

- II.1 Let

$$x(n) = \left\{ \underset{\uparrow}{1}, 2, 3, 4, 2, 1 \right\} \quad (1)$$

Sketch $x(n)$.

Solution:

$$Z\{\delta[n]\} = \sum_{n=-\infty}^{\infty} \delta[n] \cdot z^{-n} \quad (23)$$

$$= z^0 \quad (24)$$

$$= 1 \quad (25)$$

and from (21),

$$U(z) = \sum_{n=0}^{\infty} z^{-n} \quad (26)$$

$$= \frac{1}{1 - z^{-1}}, \quad |z| > 1 \quad (27)$$

using the formula for the sum of an infinite geometric progression.

III.4 Show that

$$a^n u(n) \xleftrightarrow{Z} \frac{1}{1 - az^{-1}} \quad |z| > |a| \quad (28)$$

Solution:

$$a^n u(n) \xleftrightarrow{Z} \sum_{n=0}^{\infty} (az^{-1})^n \quad (29)$$

$$= \frac{1}{1 - az^{-1}} \quad |z| > |a| \quad (30)$$

III.5 Let

$$H(e^{j\omega}) = H(z = e^{j\omega}). \quad (31)$$

Plot $|H(e^{j\omega})|$. Comment. $H(e^{j\omega})$ is known as the *Discret Time Fourier Transform* (DTFT) of $x(n)$.

Solution: The following code plots the magnitude of transfer function. /codes/III.5.py Substituting $z = e^{j\omega}$ in (19), we get

$$|H(e^{j\omega})| = \left| \frac{1 + e^{-2j\omega}}{1 + \frac{1}{2}e^{-j\omega}} \right| \quad (32)$$

$$= \sqrt{\frac{(1 + \cos 2\omega)^2 + (\sin 2\omega)^2}{\left(1 + \frac{1}{2}\cos \omega\right)^2 + \left(\frac{1}{2}\sin \omega\right)^2}} \quad (33)$$

$$= \frac{4|\cos \omega|}{\sqrt{5 + 4\cos \omega}} \quad (34)$$

$$|H(e^{j(\omega+2\pi)})| = \frac{4|\cos(\omega + 2\pi)|}{\sqrt{5 + 4\cos(\omega + 2\pi)}} \quad (35)$$

$$= \frac{4|\cos \omega|}{\sqrt{5 + 4\cos \omega}} \quad (36)$$

$$= |H(e^{j\omega})| \quad (37)$$

Therefore its fundamental period is 2π , which verifies that DTFT of a signal is always periodic.

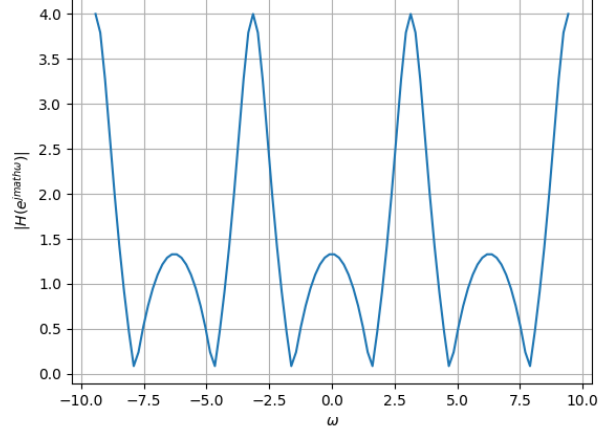


Fig. 4. $|H(e^{j\omega})|$

IV. IMPULSE RESPONSE

IV.1 Find an expression for $h(n)$ using $H(z)$, given that

$$h(n) \xleftrightarrow{Z} H(z) \quad (38)$$

and there is a one to one relationship between $h(n)$ and $H(z)$. $h(n)$ is known as the *impulse response* of the system defined by (2).

Solution: From (19),

$$H(z) = \frac{1}{1 + \frac{1}{2}z^{-1}} + \frac{z^{-2}}{1 + \frac{1}{2}z^{-1}} \quad (39)$$

$$\Rightarrow h(n) = \left(-\frac{1}{2}\right)^n u(n) + \left(-\frac{1}{2}\right)^{n-2} u(n-2) \quad (40)$$

using (28) and (16).

IV.2 Sketch $h(n)$. Is it bounded? Convergent?

Solution: The following code plots $h(n)$ codes/IV.2.py



Fig. 5. $h(n)$ as the inverse of $H(z)$

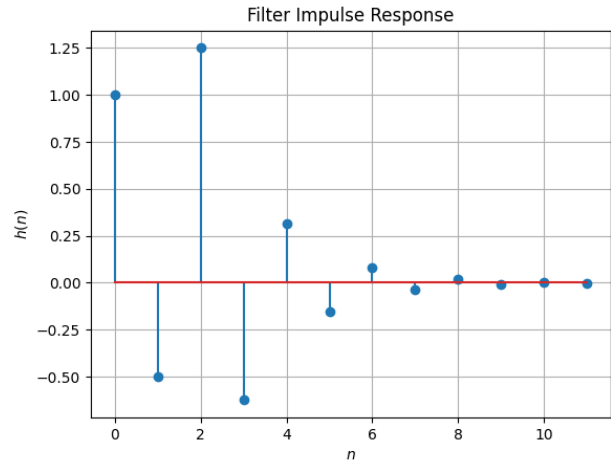


Fig. 6. $h(n)$ from the definition is same as Fig. 5

IV.3 The system with $h(n)$ is defined to be stable if

$$\sum_{n=-\infty}^{\infty} h(n) < \infty \quad (41)$$

Is the system defined by (2) stable for the impulse response in (38)?

Solution: For stable system (41) should converge.

By using ratio test

$$\lim_{n \rightarrow \infty} \left| \frac{h(n+1)}{h(n)} \right| < 1 \quad (42)$$

$$(43)$$

For large n

$$u(n) = u(n-2) = 1 \quad (44)$$

$$\lim_{n \rightarrow \infty} \left(\frac{h(n+1)}{h(n)} \right) = 1/2 < 1 \quad (45)$$

Therefore it converges. Hence it is stable.

IV.4 Compute and sketch $h(n)$ using

$$h(n) + \frac{1}{2}h(n-1) = \delta(n) + \delta(n-2), \quad (46)$$

This is the definition of $h(n)$.

Solution:

Definition of $h(n)$: The output of the system when $\delta(n)$ is given as input.

The following code plots Fig. 6. Note that this is the same as Fig. 5.
codes/IV.2.py

IV.5 Compute

$$y(n) = x(n) * h(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k) \quad (47)$$

Comment. The operation in (47) is known as *convolution*.

Solution: The following code plots Fig. 7. Note that this is the same as $y(n)$ in Fig. 3. codes/IV.5.py

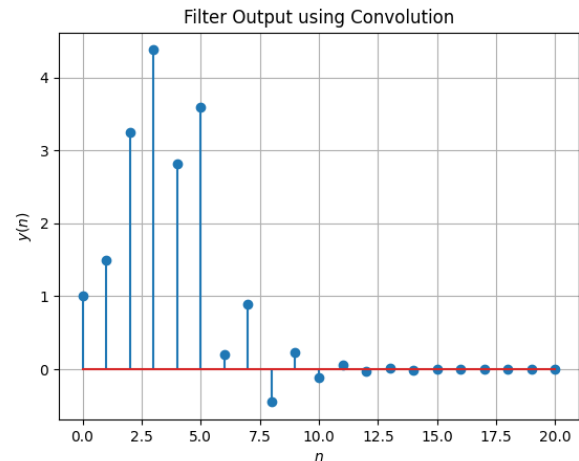


Fig. 7. $y(n)$ from the definition of convolution

IV.6 Show that

$$y(n) = \sum_{k=-\infty}^{\infty} x(n-k)h(k) \quad (48)$$

Solution: In (47), we substitute $k = n - k$ to get

$$y(n) = \sum_{k=-\infty}^{\infty} x(k) h(n-k) \quad (49)$$

$$= \sum_{n-k=-\infty}^{\infty} x(n-k) h(k) \quad (50)$$

$$= \sum_{k=-\infty}^{\infty} x(n-k) h(k) \quad (51)$$

V. DFT AND FFT

V.1 Compute

$$X(k) \triangleq \sum_{n=0}^{N-1} x(n) e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (52)$$

and $H(k)$ using $h(n)$.

V.2 Compute

$$Y(k) = X(k)H(k) \quad (53)$$

V.3 Compute

$$y(n) = \frac{1}{N} \sum_{k=0}^{N-1} Y(k) \cdot e^{j2\pi kn/N}, \quad n = 0, 1, \dots, N-1 \quad (54)$$

Solution: The above three questions are solved using the code below. codes/V.py

V.4 Repeat the previous exercise by computing $X(k)$, $H(k)$ and $y(n)$ through FFT and IFFT.

Solution: The solution of this question can be found in the code below. codes/V.4.py This code verifies the result by plotting the obtained result with the result obtained by IDFT.

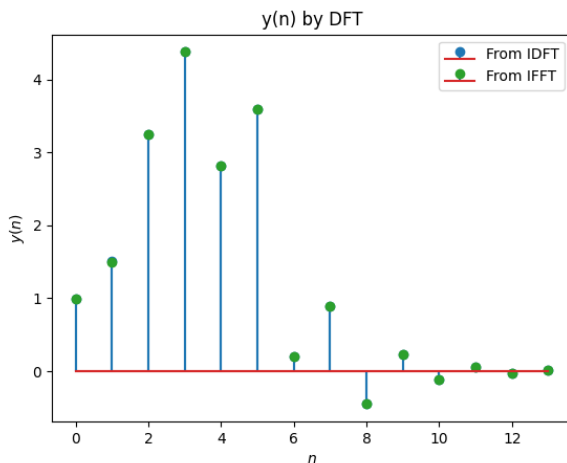


Fig. 8. $y(n)$ obtained from IDFT and IFFT is plotted and verified

V.5 Wherever possible, express all the above equations as matrix equations.

Solution: The DFT matrix is defined as :

$$\mathbf{W} = \begin{pmatrix} \omega^0 & \omega^0 & \dots & \omega^0 \\ \omega^0 & \omega^1 & \dots & \omega^{N-1} \\ \vdots & \vdots & \ddots & \vdots \\ \omega^0 & \omega^{N-1} & \dots & \omega^{(N-1)(N-1)} \end{pmatrix} \quad (55)$$

where $\omega = e^{-j2\pi/N}$. Now any DFT equation can be written as

$$\mathbf{X} = \mathbf{W}\mathbf{x} \quad (56)$$

where \mathbf{x} is the original signal and \mathbf{X} is the frequency-domain representation.

$$\mathbf{x} = \begin{pmatrix} x(0) \\ x(1) \\ \vdots \\ x(n-1) \end{pmatrix} \quad (57)$$

$$\mathbf{X} = \begin{pmatrix} X(0) \\ X(1) \\ \vdots \\ X(n-1) \end{pmatrix} \quad (58)$$

Thus we can rewrite (53) as:

$$\mathbf{Y} = \mathbf{X} \odot \mathbf{H} = (\mathbf{W}\mathbf{x}) \odot (\mathbf{W}\mathbf{h}) \quad (59)$$

where the \odot represents the Hadamard product which performs element-wise multiplication. This is specifically called "SCHUR PRODUCT" when defined for matrices.

The below code computes $y(n)$ by DFT Matrix and then plots it. codes/V.5.py

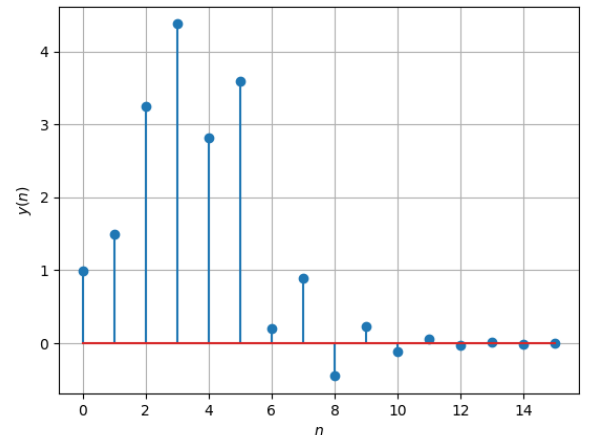


Fig. 9. $y(n)$ obtained from DFT Matrix

VI. EXERCISES

Answer the following questions by looking at the python code in Problem I.2.

VI.1 The command

```
output_signal = signal.lfilter(b, a,
                               input_signal)
```

in Problem I.2 is executed through the following difference equation

$$\sum_{m=0}^M a(m) y(n-m) = \sum_{k=0}^N b(k) x(n-k) \quad (60)$$

where the input signal is $x(n)$ and the output signal is $y(n)$ with initial values all 0. Replace **signal.filtfilt** with your own routine and verify.

Solution: The below code gives the output of an Audio Filter without using the built in function `signal.lfilter`. codes/VI.1.py

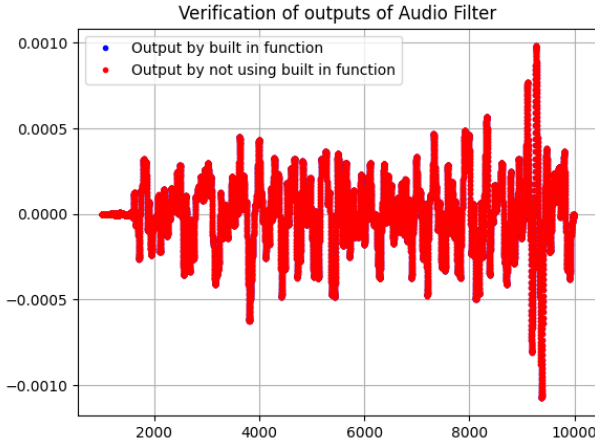


Fig. 10. Both the outputs using and without using function overlap

VI.2 Repeat all the exercises in the previous sections for the above a and b .

Solution: The code in I.2 generates the values of a and b which can be used to generate a difference equation.

And,

$$M = 5 \quad (61)$$

$$N = 5 \quad (62)$$

From 60

$$a(0)y(n) + a(1)y(n-1) + a(2)y(n-2) + a(3) \quad (63)$$

$$y(n-3) + a(4)y(n-4) = b(0)x(n) + b(1)x(n-1) + b(2)x(n-2) + b(3)x(n-3) + b(4)x(n-4)$$

Difference Equation is given by :

$$\begin{aligned} & y(n) - (3.66)y(n-1) + (5.05)y(n-2) \\ & - (3.099)y(n-3) + (0.715)y(n-4) \\ & = (1.45 \times 10^{-5})x(n) + (5.74 \times 10^{-5})x(n-1) \\ & + (8.62 \times 10^{-5})x(n-2) + (5.74 \times 10^{-5})x(n-3) \\ & + (1.43 \times 10^{-5})x(n-4) \end{aligned} \quad (64)$$

From (60)

$$H(z) = \frac{b_0 + b_1z^{-1} + b_2z^{-2} + \dots + b_Mz^{-M}}{a_0 + a_1z^{-1} + a_2z^{-2} + \dots + a_Nz^{-M}} \quad (65)$$

$$H(z) = \frac{\sum_{k=0}^N b(k)z^{-k}}{\sum_{k=0}^M a(k)z^{-k}} \quad (66)$$

Partial fraction on (66) can be generalised as:

$$H(z) = \sum_i \frac{r(i)}{1 - p(i)z^{-1}} + \sum_j k(j)z^{-j} \quad (67)$$

Now,

$$a^n u(n) \xleftrightarrow{z} \frac{1}{1 - az^{-1}} \quad (68)$$

$$\delta(n-k) \xleftrightarrow{z} z^{-k} \quad (69)$$

Taking inverse z transform of (67) by using (68) and (69)

$$h(n) = \sum_i r(i)[p(i)]^n u(n) + \sum_j k(j)\delta(n-j) \quad (70)$$

The below code computes the values of $r(i)$, $p(i)$, $k(i)$ and plots $h(n)$ codes/VI.2.py

$r(i)$	$p(i)$	$k(i)$
$0.06558697 - 0.015997359j$	$0.87507075 + 0.0480371j$	3.214014×10^{-5}
$0.06558697 - 0.015997359j$	$0.87507075 + 0.0480371j$	—
$-0.06558697 - 0.015997359j$	$0.93885135 + 0.12442455j$	—
$-0.06558697 - 0.015997359j$	$0.93885135 + 0.12442455j$	—

TABLE I
VALUES OF $r(i)$, $p(i)$, $k(i)$

Stability of $h(n)$:

According to (41)

$$H(z) = \sum_{n=0}^{\infty} h(n) z^{-n} \quad (71)$$

$$H(1) = \sum_{n=0}^{\infty} h(n) = \frac{\sum_{k=0}^N b(k)}{\sum_{k=0}^M a(k)} < \infty \quad (72)$$

As both $a(k)$ and $b(k)$ are finite length sequences they converge.

VI.3 What is the sampling frequency of the input signal?

Solution: The Sampling Frequency is 44.1KHz

VI.4 What is type, order and cutoff-frequency of the above butterworth filter

Solution: The given butterworth filter is low-pass with order=4 and cutoff-frequency=1kHz.

VI.5 Modify the code with different input parameters and get the best possible output.

Solution: A better filtering was found on setting the order of the filter to be