Q: The state equation of a second order system is

x(0) is the initial condition. $\dot{\boldsymbol{x}}(t) = A\boldsymbol{x}(t),$

Suppose λ_1 and λ_2 are two distinct eigenvalues of A, and ν_1 and ν_2 are the corresponding eigenvectors. For constants α_1 and α_2 , the solution, $\mathbf{x}(t)$, of the state equation is

(A)
$$\sum_{i=1}^{2} \alpha_{i} e^{\lambda_{i}t} v_{\mathbf{i}}$$
(B)
$$\sum_{i=1}^{2} \alpha_{i} e^{2\lambda_{i}t} v_{\mathbf{i}}$$
(C)
$$\sum_{i=1}^{2} \alpha_{i} e^{3\lambda_{i}t} v_{\mathbf{i}}$$
(D)
$$\sum_{i=1}^{2} \alpha_{i} e^{4\lambda_{i}t} v_{\mathbf{i}}$$

(B)
$$\sum_{i=1}^{2} \alpha_i e^{2\lambda_i t} v_i$$

(C)
$$\sum_{i=1}^{2} \alpha_i e^{3\lambda_i t} v_i$$

(D)
$$\sum_{i=1}^{2} \alpha_i e^{4\lambda_i t} v_i$$

Solution:

Using Laplace transform:

Given Equation:

$$\dot{\boldsymbol{x}}(t) = A\boldsymbol{x}(t) \tag{1}$$

$$\frac{d\mathbf{x}(t)}{dt} = A\mathbf{x}(t) \tag{2}$$

Taking Laplace Transform:

$$\mathcal{L}\left(\frac{d\mathbf{x}(t)}{dt}\right) = \mathcal{L}\left(A\mathbf{x}(t)\right) \tag{3}$$

$$sX(s) - x(0) = AX(s) \tag{4}$$

$$(sI - A)X(s) = x(0) \tag{5}$$

$$X(s) = (sI - A)^{-1}x(0)$$
(6)

$$=\sum_{i=1}^{2} \frac{1}{s - \lambda_i} x(0) \tag{7}$$

Now take inverse Laplace Transform

$$\mathcal{L}^{-1}(X(s)) = \mathcal{L}^{-1}\left(\sum_{i=1}^{2} \frac{1}{s - \lambda_i} x(0)\right)$$
 (8)

$$x(t) = \sum_{i=1}^{2} e^{\lambda_i t} x(0) \tag{9}$$

$$=\sum_{i=1}^{2}\alpha_{i}e^{\lambda_{i}t}v_{i}$$
(10)

Hence the answer is option (A).