

Activity analysis for reverse-mode differentiation of (CUDA) GPU kernels

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Removing exessive AtomicAdd's

```
__global___ void kernel_call(double *out, double *in) {
   int index = threadIdx.x + blockIdx.x * blockDim.x;
   out[index] = in[index];
}

void fn(double *out, double *in) {
   kernel_call<<<1, 10>>>(out, in);
}
```

```
{
    out[index0] = _t2;
    double _r_d0 = _d_out[index0];
    _d_out[index0] = 0.;
    atomicAdd(&_d_in[index], _r_d0);
}

_d_in[index] += _rd0;
```

Removing exessive AtomicAdd's

```
__global__ void kernel_call(double *out, double *in) {
  int index = threadIdx.x;
  out[index] = in[index];
}

void fn(double *out, double *in) {
  kernel_call<<<1, 10>>>(out, in);
}
```

Loop analysis and optimizations

Sparsity Patterns

```
double f1(double a[100], double b double _clad_out_output[]){
  for(int i = 0; i<100; i++)
    a[i] = i * b;
}</pre>
```

Loop analysis and optimizations

Merging forward and reverse loops

```
void only_for(double* x, double y){
  for(int i = 0; i<100; i++)
    x[i] += y;
}</pre>
```

```
void only_for_pullback(...) {
   for (i = 0; ; i++) {
            if (!(i < 100))
                break;
        _t0++;
        x[i] += y;
    for (;; _t0--) {
            if (!_t0)
                break;
        double _r_d0 = _d_x[i];
        *_d_y += _r_d0;
```

```
void only_for_pullback(...) {
   for (i = 0; ; i++) {
            if (!(i < 100))
                break;
       x[i] += y;
           double _r_d0 = _d_x[i];
            *_d_y += _r_d0;
```

Reworking TBR and AA

```
struct VarData {
    enum VarDataType { UNDEFINED, FUND_TYPE, OBJ_TYPE, ARR_TYPE, REF_TYPE };
    union VarDataValue {
        bool m_FundData;
        std::unique_ptr<ArrMap> m_ArrData;
        Expr* m_RefData;
        VarDataValue() : m_ArrData(nullptr) {}
        ~VarDataValue() {}
    };
    VarDataType m_Type = UNDEFINED;
    VarDataValue m_Val;
};
```

```
using VarsData = std::set<const clang::VarDecl*>;
```

suggestions?