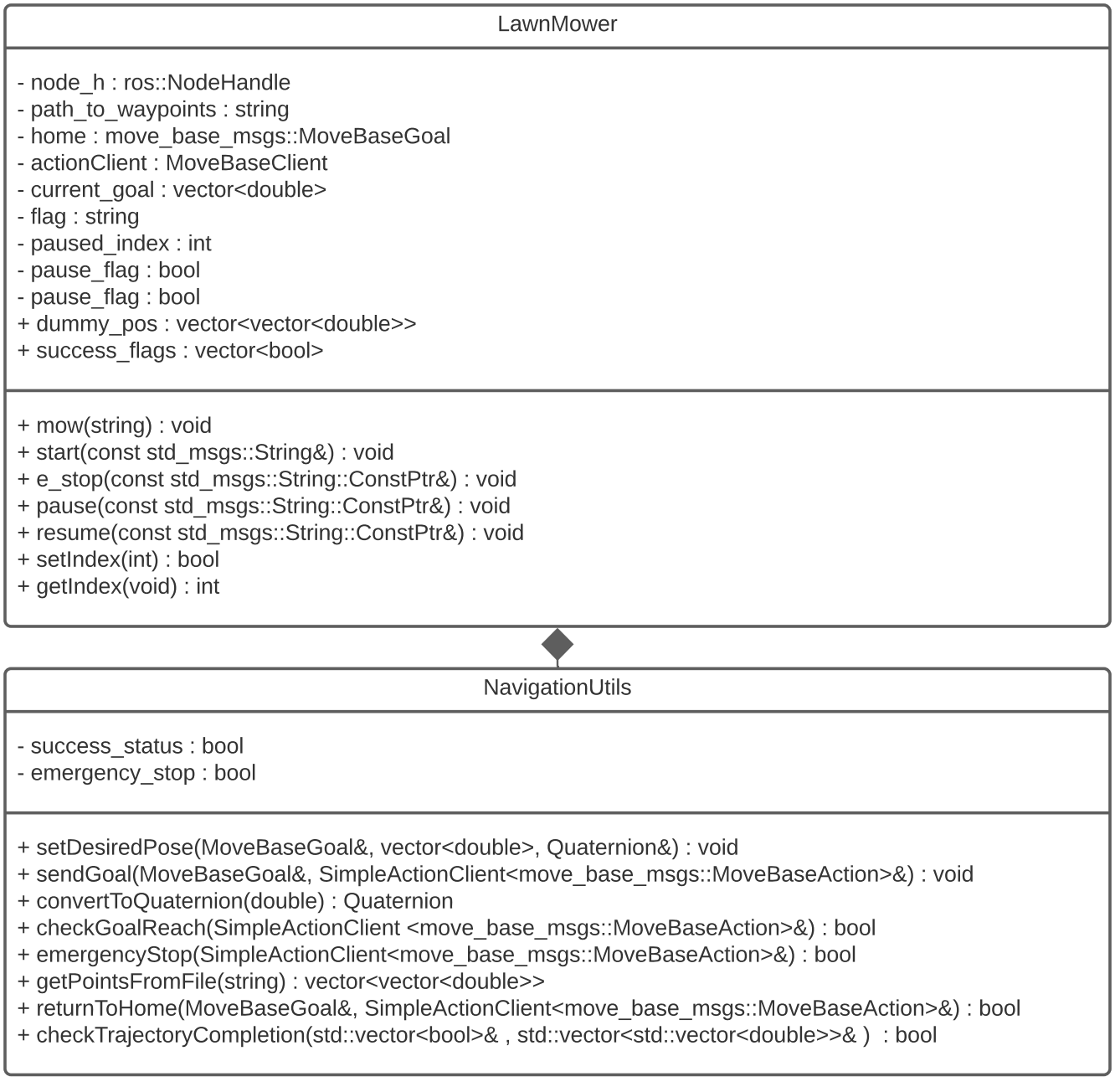

Note:

Defining the custom datatypes:

1. MoveBaseGoal is of type move_base_msgs from move_base package
2. Quaternion is of type geometry_msgs
3. SimpleActionClient <move_base_msgs::MoveBaseAction> is part of the acitionlib package
4. ros:NodeHandle is a ros class which provides a RAII interface to a process' node