ELP201 Lab Report 3

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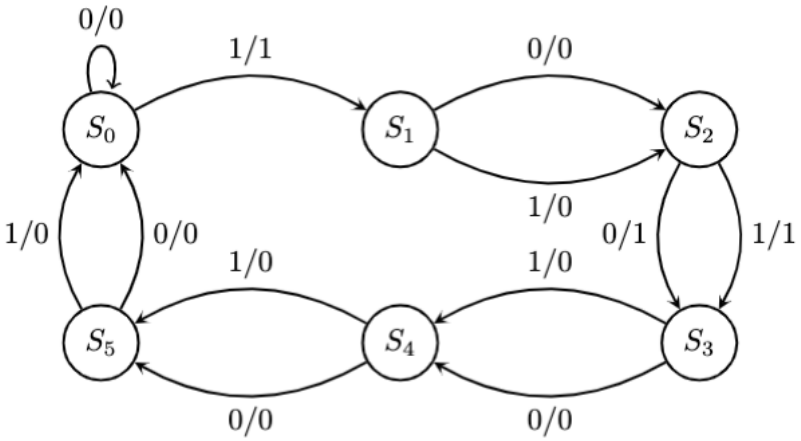
2020EE10458

1 Introduction

According to my entry number ($2020EE10458$), the sequence to be generated at output side is $1, 0, 1, 0, 0, 0$.

2 State diagram

In total there would be 6 states, let them S_i, where $i \in \{0, 1, 2, 3, 4, 5\}$. Let S_0 be the idle state. Then according to the statement of question the state diagram would be:



Since total number of states are 6 and $6 \leqslant 2^3$, hence total of 3 flipflops would be needed.
Let's assign each state S_i the binary value of i.

3 State table

The outputs $Q_2Q_1Q_0$, of the D-flipflops would represent the state at any time t. And since the characteristic equation for the D-flipflop is $Q(t+1) = D$, then the state table would be:

$Q_2(t)$	$Q_1(t)$	$Q_0(t)$	$X(in)$	$Q_2(t+1)$	$Q_1(t+1)$	$Q_0(t+1)$	$Y(out)$	D_2	D_1	D_0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	1	0	0	1	1	0	0	1
0	0	1	0	0	1	0	0	0	1	0
0	0	1	1	0	1	0	0	0	1	0
0	1	0	0	0	1	1	1	0	1	1
0	1	0	1	0	1	1	1	0	1	1
0	1	1	0	1	0	0	0	1	0	0
0	1	1	1	1	0	0	0	1	0	0
1	0	0	0	1	0	1	0	1	0	1
1	0	0	1	1	0	1	0	1	0	1
1	0	1	0	0	0	0	0	0	0	0
1	0	1	1	0	0	0	0	0	0	0

4 Simplification using K-maps

From the state table, the k-maps for *Output* $(Y), D_2, D_1, D_0$ are as follows:

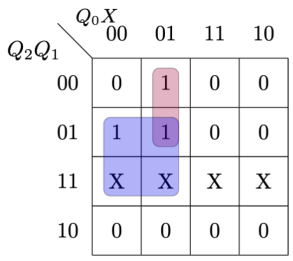


Figure 1: K-Map for *Output* (Y)

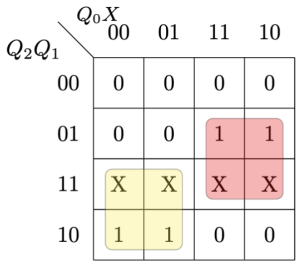


Figure 2: K-Map for D_2

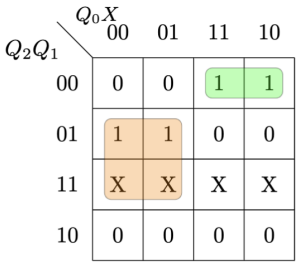


Figure 3: K-Map for D_1

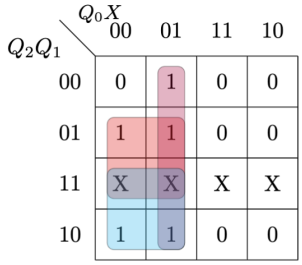


Figure 4: K-Map for D_0

And from the k-maps the simplified expressions are as follows:

$$Y = \bar{Q}_2\bar{Q}_0X \ + \ Q_1\bar{Q}_0$$

$$D_2 = Q_2\bar{Q}_0 \ + \ Q_0Q_1$$

$$D_1 = \bar{Q}_2\bar{Q}_1Q_0 \ + \ Q_1\bar{Q}_0$$

$$D_0 = \bar{Q}_0X \ + \ Q_1\bar{Q}_0 \ + \ Q_2\bar{Q}_0$$

5 Verilog Simulation

5.1 Code

The code file (design.v) for the implementation of the above finite state machine using D-flipflops is: The D-flipflop designed is a postive edge triggered one and has a reset pin which is active low.

```
module DFlipFlop(D,clock,preset,Q,Qbar);
input D,clock,preset;
output reg Q,Qbar;

initial
begin
  if(~preset)
  begin
    Q=1;Qbar=0;
  end
  else
  begin
    Q=0;Qbar=1;
  end
end

always@(posedge clock)
begin
  Q <= D;
  Qbar <= ~D;
end
endmodule

module FSM(in,out,clock,q2,q1,q0,q2bar,q1bar,q0bar);
input in,clock;
output wire q2,q1,q0,q2bar,q1bar,q0bar;
output reg out=0;

DFlipFlop ff1((q0bar & in)|(q1 & q0bar)|(q2 & q0bar),clock,1'b1,q0,q0bar);
DFlipFlop ff2((q2bar & q1bar & q0)|(q1 & q0bar),clock,1'b1,q1,q1bar);
DFlipFlop ff3((q2 & q0bar)|(q1 &q0),clock,1'b1,q2,q2bar);
always @(posedge clock )
begin
  assign out=(q1 & q0bar)|(q2bar & q0bar & in);
end
endmodule
```

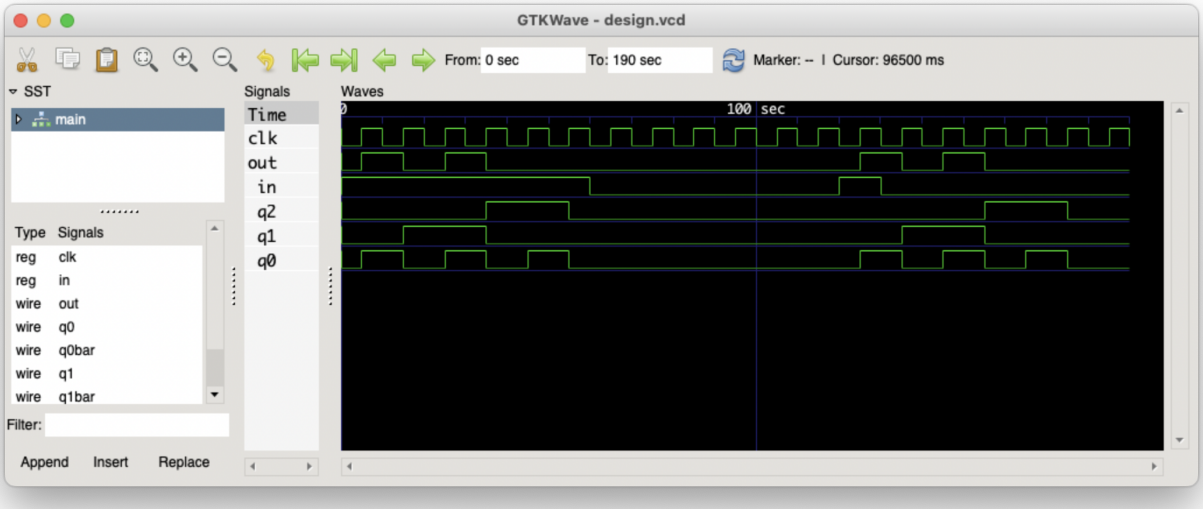
The code file for the testbench (main.v) is: Intitially the input (X) is kept 1 for atleast 6 clock cycles and when it reaches the idle state again, it is then made 0 for again atleast 6 clock cycles, and finally it is again made 1 for one clock cycle so that machine again becomes active then immediately made 0 for again atleast 6 clock cycles. The D-flipflop designed is a postive edge triggered one and has a reset pin which is active low.

```
`timescale 1s/100ms
`include "design.v"

module main();

reg clk,in;
wire q0,q1,q2,q2bar,q1bar,q0bar,out;
```

```
8
9   //Instantating the finite state machine
10  FSM func(in,out,clk,q2,q1,q0,q2bar,q1bar,q0bar);
11
12  initial
13  begin
14  $monitor("CLK=%b,out=%b,in=%b,q2=%b,q1=%b,q0=%b",clk,out,in,q2,q1,q0);
15  $dumpfile("design.vcd");
16  $dumpvars(0,main);
17    clk=0; //initially clock=0;
18    in=1;#60 //initially input=1;
19    in=0;#60; //after running the simulation for 60s, input is made 0;
20    in=1;#10;in=0;
21    #60;
22    $finish;
23  end
24  always
25    #5 clk = ~clk; //changing clock after every 5s
26  endmodule
```

5.2 Waveform

The gtkwave plot obtained is:



Hence it can be observed from the plot, that the FSM once starts generating the sequence, keep generating it no matter whatever is the value of X is and also it remains in the idle state as long as X is kept 0. And at last the sequence generated is $1, 0, 1, 0, 0, 0$ at the output side. Hence, the FSM is working perfectly as required.

Download link for the code files

The code files can be downloaded from **here**.