UNIT 4: Dynamic Programming

Warshall’s and Floyd’s Algorithms

Warshall - Floyd’s Algorithms

- Also known as **Floyd's algorithm**, the **Roy–Warshall algorithm**, the **Roy–Floyd algorithm**, or the **WFI algorithm**

- Robert Floyd in 1962, essentially the same as algorithms previously published by individuals - Bernard Roy in 1959, and also by Stephen Warshall in 1962

- algorithm for finding shortest paths in a directed weighted graph with positive or negative edge weights (but with no negative cycles)

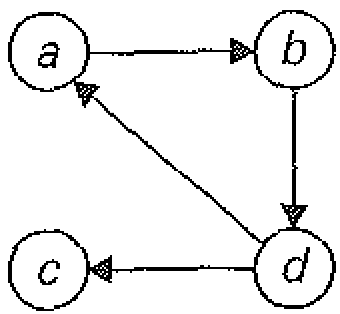
Interesting fact!!

In Season 4 episode **"Black Swan"** of the television crime drama, mathematical genius **Charles Eppes** proposed using the **Floyd-Warshall algorithm** to analyze the most recent destinations of a bombing suspect.

Warshall’s algorithm

- for computing the transitive closure of a directed graph (undirected graph)
- Is an application of the dynamic programming technique.

- Transitive closure is the reachability matrix to reach from vertex u to vertex v of a graph.
- transitive closure of a digraph can be computed by applying DFS/BFS on every vertex – **less efficient**



(a)

Digraph.

$$A = \begin{array}{c} \\ a \\ b \\ c \\ d \end{array} \begin{array}{c} \begin{array}{cccc} a & b & c & d \end{array} \\ \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{bmatrix} \end{array}$$

(b)

adjacency matrix

$$T = \begin{array}{c} \\ a \\ b \\ c \\ d \end{array} \begin{array}{c} \begin{array}{cccc} a & b & c & d \end{array} \\ \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix} \end{array}$$

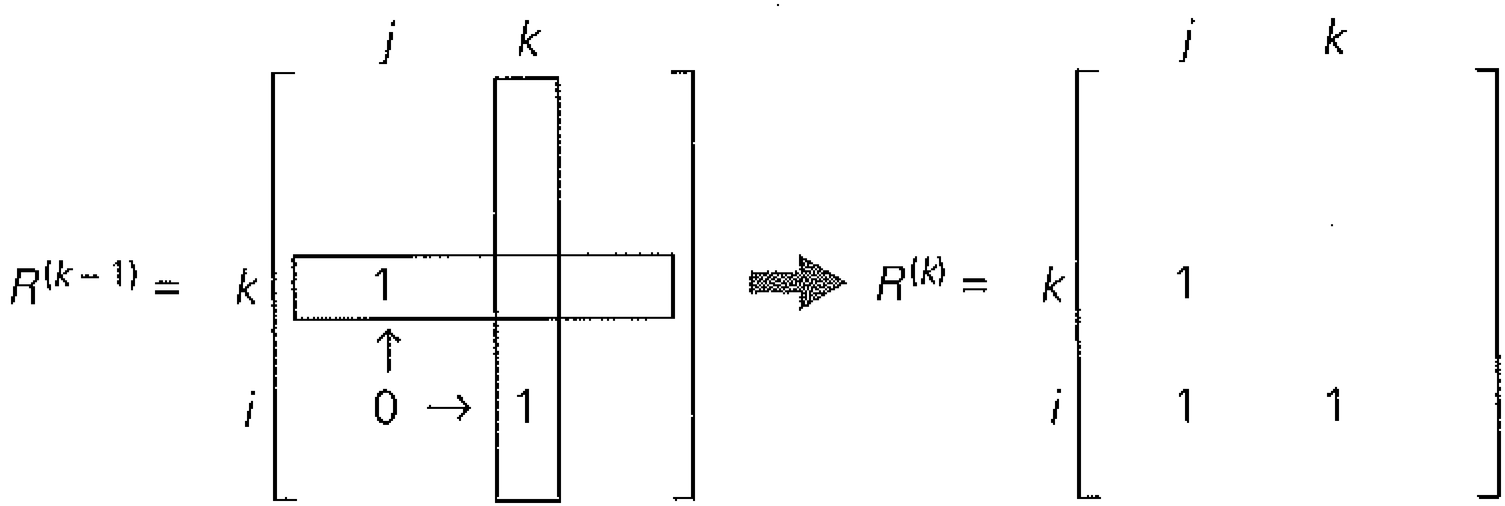
(c)

transitive closure.

Warshall’s algorithm: Idea

- constructs the transitive closure of a given digraph with n vertices through a series of n-by-n boolean matrices $R^{(0)}, \dots, R^{(k-1)}, R^{(k)}, \dots, R^{(n)}$.

$$r_{ij}^{(k)} = r_{ij}^{(k-1)} \textbf{ or } \left(r_{ik}^{(k-1)} \textbf{ and } r_{kj}^{(k-1)}\right).$$



Rule for changing zeros in Warshall's algorithm

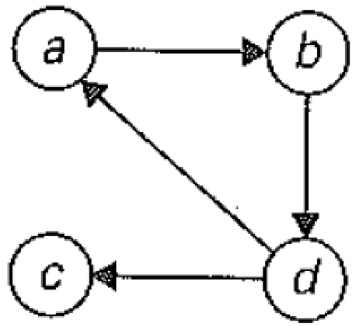
ALGORITHM *Warshall*($A[1..n, 1..n]$)

//Implements Warshall's algorithm for computing the transitive closure
//Input: The adjacency matrix A of a digraph with n vertices
//Output: The transitive closure of the digraph

$R^{(0)} \leftarrow A$
for $k \leftarrow 1$ **to** n **do**
    for $i \leftarrow 1$ **to** n **do**
        for $j \leftarrow 1$ **to** n **do**
            $R^{(k)}[i, j] \leftarrow R^{(k-1)}[i, j]$ **or** $(R^{(k-1)}[i, k]$ **and** $R^{(k-1)}[k, j])$
return $R^{(n)}$

Time efficiency of Warshall's algorithm is cubic

Example



$$R^{(0)} = \begin{array}{cc} & \begin{array}{cccc} a & b & c & d \end{array} \\ \begin{array}{c} a \\ b \\ c \\ d \end{array} & \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{bmatrix} \end{array}$$

$$R^{(1)} = \begin{array}{cc} & \begin{array}{cccc} a & b & c & d \end{array} \\ \begin{array}{c} a \\ b \\ c \\ d \end{array} & \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & \mathbf{1} & 1 & 0 \end{bmatrix} \end{array}$$

$$R^{(2)} = \begin{array}{cc} & \begin{array}{cccc} a & b & c & d \end{array} \\ \begin{array}{c} a \\ b \\ c \\ d \end{array} & \begin{bmatrix} 0 & 1 & 0 & \mathbf{1} \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & \mathbf{1} \end{bmatrix} \end{array}$$

$$R^{(3)} = \begin{array}{cc} & \begin{array}{cccc} a & b & c & d \end{array} \\ \begin{array}{c} a \\ b \\ c \\ d \end{array} & \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix} \end{array}$$

$$R^{(4)} = \begin{array}{cc} & \begin{array}{cccc} a & b & c & d \end{array} \\ \begin{array}{c} a \\ b \\ c \\ d \end{array} & \begin{bmatrix} \mathbf{1} & 1 & \mathbf{1} & 1 \\ \mathbf{1} & \mathbf{1} & \mathbf{1} & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix} \end{array}$$

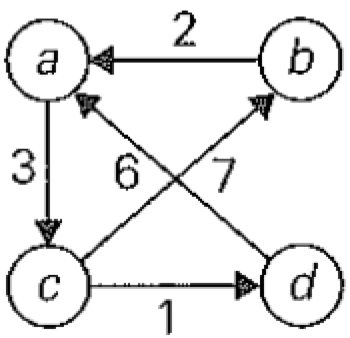
Let's check our understanding…

Apply Warshall's algorithm to find the transitive closure of the digraph defined by the following adjacency matrix

$$\begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Floyd’s algorithm

- for computing all-pairs shortest-paths problem.
- Is an application of the dynamic programming technique.
- It is applicable to both undirected and directed weighted graphs provided that they do not contain a cycle of a negative length



(a)

Digraph.

$$W = \begin{array}{c} \\ a \\ b \\ c \\ d \end{array} \begin{array}{c} \begin{array}{cccc} a & b & c & d \end{array} \\ \begin{bmatrix} 0 & \infty & 3 & \infty \\ 2 & 0 & \infty & \infty \\ \infty & 7 & 0 & 1 \\ 6 & \infty & \infty & 0 \end{bmatrix} \end{array}$$

(b)

weight matrix.

$$D = \begin{array}{c} \\ a \\ b \\ c \\ d \end{array} \begin{array}{c} \begin{array}{cccc} a & b & c & d \end{array} \\ \begin{bmatrix} 0 & 10 & 3 & 4 \\ 2 & 0 & 5 & 6 \\ 7 & 7 & 0 & 1 \\ 6 & 16 & 9 & 0 \end{bmatrix} \end{array}$$

(c)

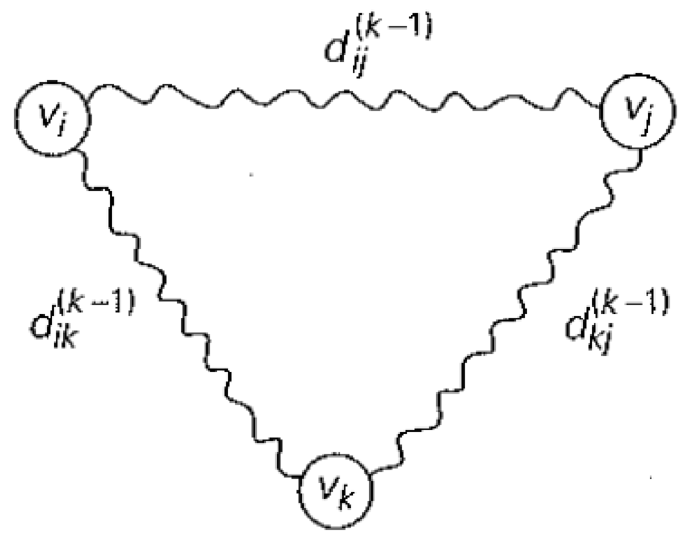
distance matrix

Floyd's algorithm: Idea

- computes the distance matrix of a weighted graph with n vertices through a series of n-by-n matrices

$$D^{(0)}, \ldots, D^{(k-1)}, D^{(k)}, \ldots, D^{(n)}.$$

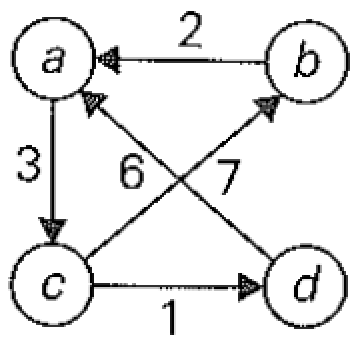
$$d_{ij}^{(k)} = \min\{d_{ij}^{(k-1)},\ d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\} \quad \text{for } k \geq 1, \quad d_{ij}^{(0)} = w_{ij}.$$



ALGORITHM *Floyd*($W[1..n, 1..n]$)

```
//Implements Floyd's algorithm for the all-pairs shortest-paths problem
//Input: The weight matrix W of a graph with no negative-length cycle
//Output: The distance matrix of the shortest paths' lengths
D ← W //is not necessary if W can be overwritten
for k ← 1 to n do
    for i ← 1 to n do
        for j ← 1 to n do
            D[i, j] ← min{D[i, j], D[i, k] + D[k, j]}
return D
```

Time efficiency of Floyd's algorithm is cubic



$$D^{(0)} = \begin{array}{c} \\ a \\ b \\ c \\ d \end{array} \begin{array}{c} \begin{array}{cccc} a & b & c & d \end{array} \\ \left[\begin{array}{cccc} 0 & \infty & 3 & \infty \\ 2 & 0 & \infty & \infty \\ \infty & 7 & 0 & 1 \\ 6 & \infty & \infty & 0 \end{array}\right] \end{array}$$

$$D^{(1)} = \begin{array}{c} \\ a \\ b \\ c \\ d \end{array} \begin{array}{c} \begin{array}{cccc} a & b & c & d \end{array} \\ \left[\begin{array}{cccc} 0 & \infty & 3 & \infty \\ 2 & 0 & \mathbf{5} & \infty \\ \infty & 7 & 0 & 1 \\ 6 & \infty & \mathbf{9} & 0 \end{array}\right] \end{array}$$

$$D^{(2)} = \begin{array}{c} \\ a \\ b \\ c \\ d \end{array} \begin{array}{c} \begin{array}{cccc} a & b & c & d \end{array} \\ \left[\begin{array}{cccc} 0 & \infty & 3 & \infty \\ 2 & 0 & 5 & \infty \\ \mathbf{9} & 7 & 0 & 1 \\ 6 & \infty & 9 & 0 \end{array}\right] \end{array}$$

$$D^{(3)} = \begin{array}{c} \\ a \\ b \\ c \\ d \end{array} \begin{array}{c} \begin{array}{cccc} a & b & c & d \end{array} \\ \left[\begin{array}{cccc} 0 & \mathbf{10} & 3 & \mathbf{4} \\ 2 & 0 & 5 & \mathbf{6} \\ 9 & 7 & 0 & 1 \\ 6 & \mathbf{16} & 9 & 0 \end{array}\right] \end{array}$$

$$D^{(4)} = \begin{array}{c} \\ a \\ b \\ c \\ d \end{array} \begin{array}{c} \begin{array}{cccc} a & b & c & d \end{array} \\ \left[\begin{array}{cccc} 0 & 10 & 3 & 4 \\ 2 & 0 & 5 & 6 \\ \mathbf{7} & 7 & 0 & 1 \\ 6 & 16 & 9 & 0 \end{array}\right] \end{array}$$

Let’s check our understanding…

Solve the all-pairs shortest-path problem for the digraph with the weight matrix

$$
\begin{bmatrix}
0 & 2 & \infty & 1 & 8 \\
6 & 0 & 3 & 2 & \infty \\
\infty & \infty & 0 & 4 & \infty \\
\infty & \infty & 2 & 0 & 3 \\
3 & \infty & \infty & \infty & 0
\end{bmatrix}
$$

Comparison with other shortest path algorithms

- **Floyd–Warshall algorithm** is a good choice for computing paths between all pairs of vertices in **dense graphs**, in which most or all pairs of vertices are connected by edges.

- For **sparse graphs** with non-negative edge weights, lower asymptotic complexity can be obtained by running **Dijkstra's algorithm** from each possible starting vertex
- For **sparse graphs** with negative edges but no negative cycles, **Johnson's algorithm** can be used, with the same asymptotic running time as the repeated Dijkstra approach.

Warshall – Floyd's algorithm: Applications

- **Software engineering**: investigating data flow and control flow dependencies as well as for inheritance testing of object-oriented software.
- **Optimal routing**: finding the path with the maximum flow between two vertices.
- **Electronic engineering**: for redundancy identification and test generation for digital circuits
- Fast computation of Pathfinder networks.
- Widest paths/Maximum bandwidth paths
- Computing canonical form of difference bound matrices (DBMs)
- Computing the similarity between graphs
- Finding a regular expression denoting the regular language accepted by a finite automaton
- Inversion of real matrices