

**VISVESVARAYA TECHNOLOGICAL UNIVERSITY**  
“JnanaSangama”, Belgaum -590014, Karnataka.



**LAB REPORT**

**on**

**Artificial Intelligence (23CS5PCAIN)**

*Submitted by*

**Aditya Sharma (1BM22CS021)**

*in partial fulfilment for the award of the degree of*  
**BACHELOR OF ENGINEERING**  
*in*  
**COMPUTER SCIENCE AND ENGINEERING**



**B.M.S. COLLEGE OF ENGINEERING**  
(Autonomous Institution under VTU)  
**BENGALURU-560019**

**Aug 2025 to Dec 2025**

**B.M.S. College of Engineering,  
Bull Temple Road, Bangalore 560019  
(Affiliated To Visvesvaraya Technological University, Belgaum)  
Department of Computer Science and Engineering**



**CERTIFICATE**

This is to certify that the Lab work entitled “Artificial Intelligence (23CS5PCAIN)” carried out by **Aditya Sharma (1BM22CS021)**, who is bonafide student of **B.M.S. College of Engineering**. It is in partial fulfillment for the award of **Bachelor of Engineering in Computer Science and Engineering** of the Visvesvaraya Technological University, Belgaum. The Lab report has been approved as it satisfies the academic requirements in respect of an Artificial Intelligence (23CS5PCAIN) work prescribed for the said degree.

Dr. K.R. Mamatha Assistant Professor Department of CSE, BMSCE	Dr. Kavitha Sooda Professor & HOD Department of CSE, BMSCE
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## ||||| COURSE COMPLETION CERTIFICATE |||||

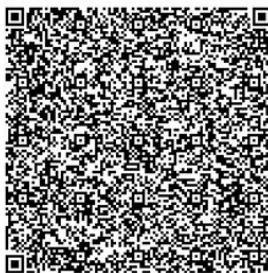
The certificate is awarded to

**Aditya Sharma**

for successfully completing the course

**OpenAI Generative Pre-trained Transformer 3 (GPT-3) for developers**

on November 20, 2025



Issued on: Tuesday, November 25, 2025  
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**Github Link:** <https://github.com/aditya-sharma1230/AI-LAB>

### **Program 1:**

- a) Implement Tic - Tac - Toe Game
- b) Implement vacuum cleaner agent

#### **a) Tic Tac Toe**

#### **Algorithm:**

The image shows a handwritten algorithm for a Tic-Tac-Toe game. At the top, it says "Tic - Tac - Toe". Below that, the algorithm starts with "Create 3x3 board". It then describes the game loop: "Player 1 slot 'X' & System slot 'O'" and "Initialize current - player = 'X'". It states that the game will keep repeating the turns until the player & system tie 3 shells fills. The algorithm then details the steps: 1. Computer player will choose the shell. 2. Next player checks for empty shell & fills his symbol. 3. If the current player has filled a row or column or diagonal then it's a win. 4. If none was filled with some symbols then it's a draw. 5. In order to block if 2 'X' are filled in row, column or diagonal we'll place 'O' to block player no 1.

**Output**

**Step 1:-**

-	-	-
-	-	-
-	-	-

**Step 2:- Row (0-2):- 0      Column (0-2):- 0**

0	-	-
-	-	-
-	-	-

**Computer Player:-**

0	-	-
-	X	-
-	-	-

8	3	4
1	5	9
6	7	2

Player :-  
Row :- 0

Column :- 1

0	0	-
-	x	-
-	-	-

Computer :-

0	0	x
-	x	-
-	-	-

check step 3

Player :- Row :- 2 Column :- 0

0	0	x
-	x	-
0	-	-

Computer :-

0	0	x
x	x	-
0	-	-

check step 3

Player :- Row :- 1 Column :- 2

0	0	x
x	x	-
0	-	-

Computer :-

0	0	x
x	x	0
0	x	-

Check step 3

Player :-

0	0	x
x	x	0
0	x	0

It is done

all the moves

are stored

left just

is left

left</p

Player :-  
Row :- 0

Column :- 1

0	0	-
-	x	-
-	-	-

Computer :-

0	0	x
-	x	-
-	-	-

Player :- Row :- 2 Column :- 0

0	0	x
-	x	-
0	-	-

Computer :-

0	0	x
x	x	-
0	-	-

check step 3

Player :- Row :- 1

Column :- 2

0	0	x
-	x	-
0	-	-

Computer :-

0	0	x
x	x	0
0	x	-

check step 3

Player :-

0	0	x
x	x	0
0	x	0

It is done

**Code:**

```
board = [["-","-","-"], ["-","-","-"], ["-","-","-"]]
Xrow = {"0":0,"1":0,"2":0}
Orow = {"0":0,"1":0,"2":0}
Xcol = {"0":0,"1":0,"2":0}
Ocol = {"0":0,"1":0,"2":0} win
= False

def checkWin():
    global win
    for key in Xrow:
        if Xrow[key] == 3:
            win = True
    for key in Xcol:
        if Xcol[key] == 3:
            win = True
    for key in Orow:
        if Orow[key] == 3:
            win = True
    for key in Ocol:
        if Ocol[key] == 3:
            win = True
    if board[0][0] == board[1][1] == board[2][2] != "-":
        win = True
    if board[0][2] == board[1][1] == board[2][0] != "-":
        win = True

def place(symbol, row, col):
    if board[row][col] != "-":
        print("Can't place at this spot, try again")
        return False

    if symbol == "1":
        board[row][col] = "X"
        Xrow[str(row)] += 1
        Xcol[str(col)] += 1
    elif symbol == "2":
        board[row][col] = "O"
        Orow[str(row)] += 1
        Ocol[str(col)] += 1
    return True
```

```

def displayBoard():
    for row in board:
        print(row)
    print("\n") # Game loop
displayBoard()
switch = input("Enter 1 for X, 2 for O to start: ")

while any("-" in row for row in board) and not win: try:
    row = int(input("Enter Row (1-3): ")) col
    = int(input("Enter Column (1-3): "))
except ValueError:
    print("Invalid input, enter numbers only.") continue

if row > 3 or col > 3 or row < 1 or col < 1:
    print("Invalid input, please try again.") continue

decision = place(switch, row - 1, col -
1) if decision: displayBoard()
checkWin() if not win:
    switch = "2" if switch == "1" else "1"

if win:
    winner = "X" if switch == "1" else "O"
    print(f"\{winner} wins!")
else:
    print("It's a draw!")

```

Output:

```

['-', '-', '-']
['-', '-', '-']
['-', '-', '-']

```

Enter 1 for X, 2 for O to start: 1

Enter Row (1-3): 2

Enter Column (1-3): 2

```

['-', '-', '-']
['-', 'X', '-']
['-', '-', '-']

```

Enter Row (1-3): 1

Enter Column (1-3): 3

['-', '-', 'O']

['-', 'X', '-']

['-', '-', '-']

Enter Row (1-3): 1

Enter Column (1-3): 2

['-', 'X', 'O']

['-', 'X', '-']

['-', '-', '-']

Enter Row (1-3): 2

Enter Column (1-3): 3

['-', 'X', 'O']

['-', 'X', 'O']

['-', '-', '-']

Enter Row (1-3): 3

Enter Column (1-3): 2

['-', 'X', 'O']

['-', 'X', 'O']

['-', 'X', '-']

X wins!

## b) Vacuum Cleaner

Algorithm:

Date: 1/1/14

Vacuum Cleaner

- 1) Start
- 2) Initialize the room A, B, C, D in as 0  
i.e.  $A=0$ ,  $B=0$ ,  $C=0$ ,  $D=0$  0 represents the room is dirty, 1 represents room is clean
- 3) Start the robot from room A  
If room [A] = 0  
Then robot ~~is~~ clean  
The robot cleans the room  
Update  $0 \leftarrow 1$   
move right
- 4) When 1 is returned then it should move to the next room so similarly  
if room [B] = 0  
Then robot ~~is~~ clean  
status  $\rightarrow 1$   
move right
- 5) If room is already clean, then update the ~~room~~ status and then return that move to the next room.  
if room [C] = 1  
Return 1;  
move right
- 6) Similarly traverse all the room A, B, C, D until the status of all the rooms = 1
- 7) Room [A] = Room [B] = Room [C] = Room [D] = 1  
 $\Rightarrow$  Return All the rooms clean

Agent

initial room status:  
[0, 1, 0, 1]

Room 1 is dirty, cleaning

Room 2 is already clean

Room 3 is already clean

Room 4 is dirty, cleaning

last all room status: [1, 1, 1]

all rooms are now clean

if we do it this way  
it would be much easier  
to apply mold to the walls

method

-	-	-	-	right
-	-	-	-	
-	-	-	-	

0-1(5-0) and 1-0  
0-1(5-0), walls

1-0 0-1(5-0) and 1-0  
1-0 0-1(5-0), walls

**Code:**

```
rooms = int(input("Enter Number of rooms: "))
Rooms = "ABCDEFGHIJKLMNPQRSTUVWXYZ" cost
= 0
Roomval = {} for i in
range(rooms):
    print(f'Enter Room {Rooms[i]} state (0 for clean, 1 for dirty): ')
    n = int(input())
    Roomval[Rooms[i]] = n loc = input(f'Enter Location of vacuum
({Rooms[:rooms]})').upper() while 1 in Roomval.values():
    if Roomval[loc] == 1: print(f'Room {loc}
is dirty. Cleaning...') Roomval[loc] = 0
    cost += 1
    else: print(f'Room {loc} is already
clean.')
move = input("Enter L or R to move left or right (or Q to quit): ").upper()

if move == "L":
    if loc != Rooms[0]:
        loc = Rooms[Rooms.index(loc) - 1] else:
        print("No room to move left.")
    elif move == "R":
        if loc != Rooms[rooms - 1]:
            loc = Rooms[Rooms.index(loc) + 1]
        else:
            print("No room to move right.")
    elif move == "Q":
        break
    else: print("Invalid input. Please enter L, R, or
Q.")

print("\nAll Rooms Cleaned." if 1 not in Roomval.values() else "Exited before cleaning all rooms.")
print(f"Total cost: {cost}")
print("1BM23CS041")
```

**Output:**

```
Enter Number of rooms: 3
Enter Room A state (0 for clean, 1 for dirty):
1
```

Enter Room B state (0 for clean, 1 for dirty): 0

Enter Room C state (0 for clean, 1 for dirty):

1

Enter Location of vacuum (ABC): B Room

B is already clean.

Enter L or R to move left or right (or Q to quit): L Room

A is dirty. Cleaning...

Enter L or R to move left or right (or Q to quit): R Room

B is already clean.

Enter L or R to move left or right (or Q to quit): R Room

C is dirty. Cleaning...

Enter L or R to move left or right (or Q to quit): R No

room to move right.

All Rooms Cleaned.

Total cost: 2

## **Program 2:**

**Implement 8 puzzle problems using DFS**

**Implement Iterative deepening search**

### **a) DFS**

**Code:**

```
goal_state = '123456780'
```

```
moves = {
    'U': -3,
    'D': 3,
    'L': -1,
    'R': 1
}
```

```
invalid_moves = {
    0: ['U', 'L'], 1: ['U'], 2: ['U', 'R'],
    3: ['L'],      5: ['R'],
    6: ['D', 'L'], 7: ['D'], 8: ['D', 'R']
}
```

```
def move_tile(state, direction):
    index = state.index('0') if direction in
    invalid_moves.get(index, []):
        return None

    new_index = index + moves[direction]
    if new_index < 0 or new_index >= 9:
        return None

    state_list = list(state)
    state_list[index], state_list[new_index] =
    state_list[new_index], state_list[index]
    return ''.join(state_list)
```

```
def print_state(state):
    for i in range(0, 9, 3):
        print(''.join(state[i:i+3]).replace('0', ' '))
    print()
```

```
def dfs(start_state, max_depth=50):
```

```

visited = set() stack = [(start_state, [])] # Each
element: (state, path)

while stack:
    current_state, path = stack.pop()
    if current_state in visited:
        continue

    # Print every visited state print("Visited
    state:") print_state(current_state)

    if current_state == goal_state:
        return path
    visited.add(current_state)

    if len(path) >= max_depth:
        continue

    for direction in moves:
        new_state = move_tile(current_state, direction)
        if
new_state and new_state not in visited:
            stack.append((new_state, path + [direction])) return
        None

start = input("Enter start state (e.g., 724506831): ")

if len(start) == 9 and set(start) == set('012345678'):
    print("Start state:")
    print_state(start)
    result = dfs(start)

    if result is not None:
        print("Solution found!") print("Moves:",
        ''.join(result)) print("Number of
        moves:", len(result))
        print("1BM23CS041 Annas\n")

```

```
current_state = start for i, move in
enumerate(result, 1):
    current_state = move_tile(current_state, move)
    print(f"Move {i}: {move}") print_state(current_state)
else: print("No solution exists for the given start state or max depth
reached.")
else: print("Invalid input! Please enter a 9-digit string using digits 0-8 without
repetition.") Output:
```

Enter start state (e.g., 724506831): 123456078 Start

state:

1 2 3  
4 5 6  
7 8

Visited state:

1 2 3  
4 5 6  
7 8

Visited state:

1 2 3  
4 5 6  
7 8

Visited state:

1 2 3  
4 5 6  
7 8

Solution found!

Moves: R R

Number of moves: 2

Move 1: R

1 2 3  
4 5 6  
7 8

Move 2: R

1 2 3  
4 5 6  
7 8

## b) Iterative Deepening

Algorithm:

**IODFS**

IODFS is a hybrid search algorithm that combines the memory efficiency of DFS with the completeness and optimality of BFS. It works by performing a series of increasingly deeper-limited searches (DLS).

**Algorithm**

1. Set a depth-limit to 0.
2. Start a loop that increases the depth-limit by 1 in each iteration.
3. Inside the loop, run a DLS from the start state with the current depth-limit.
4. If DLS finds the goal, IODFS terminates and returns the solution.
5. If DLS fails to find the goal within the depth-limit (a "cutoff"), IODFS starts a new iteration with an increased depth-limit.

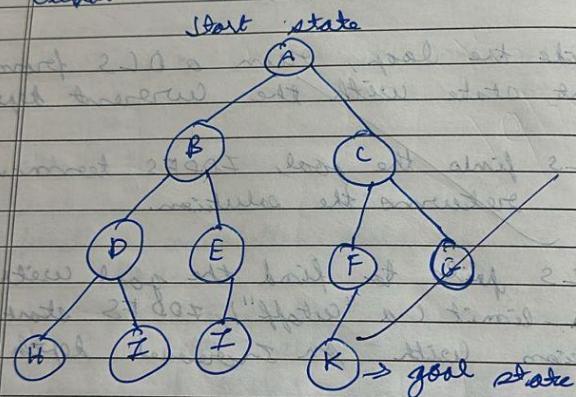
Use Continue until we don't find the solution.

**Pseudocode:**

```
function IterativeDeepening(state)
    for depth-limit from 0 to infinity
        result = DepthLimitedSearch(state, depth-limit)
        if result is a goal
            return result
        else if result is a cutoff
            continue
```

if result is a solution:  
 return result.  
 return "No solution found".  
**function** misplacedTiles (state);  
 count = 0;  
**for** i **from** 0 **to** 8;  
**if** state[i] != goalState[i] **and** state[i] !=  
 emptyCell;  
 count = count + 1;  
**return** count;

**Output:**



Depth = 0

Visit = A

Goal not found

Depth = 1

Visit = A, B, C

Goal not found

Depth = 2

Visited = A, B, D, H, E, F, I, C, G, K → V

goal found

path to goal: A → C → F → K

Output for Misplaced tiles

Start state:

1	2	3
4	0	6
7	5	8

Goal state:

1	2	3
4	5	6
7	8	0

Misplaced tiles: 2

5 → X

8 → Y

Output for Manhattan distance:

Example

Start state: 1 2 3

4	0	6
7	5	8

Goal state: 1 2 3

4	5	6
7	8	0

Misplaced Tides : 2

$\delta \rightarrow x$   
 $\delta \rightarrow y$

## Manhattan Distance

$\Rightarrow s \rightarrow$  in start(2, 1) but goal(1, 1)  $\rightarrow l_2 - l_1$   
 $+ l_1 \leftarrow l = 1$

$\Rightarrow 8 \rightarrow$  in start  $(3, 2)$  but goal  $(2, 1) \Rightarrow$   
 $12 - 21 + 12 - 11 = 1$

Manhattan Distance =  $1+1=2$

~~E 5 / istan l~~

*✓*

0187

25

X 2

X 4 8

1000-1000

卷之三

marked word

— 1 —

卷之三

25 -

204

875

卷之三

— 5 —

3 7 8

085

```
Search goal_state = '123456780'
```

```
moves = {
    'U': -3,
    'D': 3,
    'L': -1,
    'R': 1
}
```

```
invalid_moves = {
    0: ['U', 'L'], 1: ['U'], 2: ['U', 'R'],
    3: ['L'],      5: ['R'],
    6: ['D', 'L'], 7: ['D'], 8: ['D', 'R']
}
```

```
def move_tile(state, direction):
    index = state.index('0') if direction in
    invalid_moves.get(index, []):
        return None
```

```
    new_index = index + moves[direction]
    if new_index < 0 or new_index >= 9:
        return None
```

```
state_list = list(state) state_list[index], state_list[new_index] = state_list[new_index],
    state_list[index] return ".join(state_list)
```

```
def print_state(state):
    for i in range(0, 9, 3):
        print(''.join(state[i:i+3]).replace('0', ' '))
    print()
```

```
def dls(state, depth, path, visited, visited_count):
    visited_count[0] += 1 # Increment visited states count
    if state == goal_state:
        return path
    if depth == 0:
        return None
    visited.add(state)
    for direction in moves:
        new_state = move_tile(state, direction)
        if new_state and new_state not in visited:
```

```

result = dls(new_state, depth - 1, path + [direction], visited, visited_count)
if result is not None: return result

visited.remove(state)
return None

def iddfs(start_state, max_depth=50): visited_count =
[0] # Using list to pass by reference for depth in
range(max_depth + 1):
    visited = set() result = dls(start_state, depth, [], visited,
    visited_count) if result is not None:
        return result, visited_count[0]
    return None, visited_count[0]

# Main start = input("Enter start state (e.g.,
724506831): ")

if len(start) == 9 and set(start) == set('012345678'):
    print("Start state:") print_state(start)

    result, visited_states = iddfs(start,15)
    print(f"Total states visited: {visited_states}")
    if result is not None:
        print("Solution found!") print("Moves:",
        ''.join(result)) print("Number of
        moves:", len(result))
        print("1BM23CS041\n")

        current_state = start
        for i, move in enumerate(result, 1):
            current_state = move_tile(current_state, move)
            print(f"Move {i}: {move}")
            print_state(current_state)
    else: print("No solution exists for the given start state or max depth
        reached.")

else:
    print("Invalid input! Please enter a 9-digit string using digits 0-8 without repetition.")

```

Output:

Enter start state (e.g., 724506831): 123405678 Start  
state:

1 2 3  
4 5  
6 7 8

Total states visited: 24298 Solution  
found!

Moves: R D L L U R D R U L L D R R

Number of moves: 14

Move 1: R

1 2 3  
4 5  
6 7 8

Move 2: D

1 2 3  
4 5 8  
6 7

Move 3: L

1 2 3  
4 5 8  
6 7

Move 4: L

1 2 3  
4 5 8  
6 7

Move 5: U

1 2 3  
5 8  
4 6 7

Move 6: R

1 2 3  
5 8  
4 6 7

Move 7: D

1 2 3  
5 6 8

4 7

Move 8: R

1 2 3

5 6 8

4 7

Move 9: U

1 2 3

5 6

4 7 8

Move 10: L

1 2 3

5 6

4 7 8

Move 11: L

1 2 3

5 6

4 7 8

Move 12: D

1 2 3

4 5 6

7 8

Move 13: R

1 2 3

4 5 6

7 8

Move 14: R

1 2 3

4 5 6

7 8

### Program 3

Implement A\* search algorithm

**Algorithm:**

A\* algorithm

The A\* algorithm works by exploring the search space, which consists of all possible board configurations. It maintains a frontier.

$$f(n) = g(n) + h(n)$$

$g(n)$  = it finds the cost from initial state to current state

$h(n)$  = it finds the cost from current state to final state

$f(n)$  = it is the sum of  $g(n)$  and  $h(n)$

function A\*Star (start, goal)

    OPEN ← priority queue

    CLOSED ← empty set

$g[\text{start}] \leftarrow 0$

$h[\text{start}] \leftarrow \text{heuristic}$

$f[\text{start}] = g[\text{start}] + h[\text{start}]$

    while OPEN list is not empty:

        current ← node in OPEN list with lowest f if current == goal:

            return reconstructPath (current)

        remove current from OPEN list

        add current to CLOSED list

        for each neighbor in getNeighbors (current):

if neighbor in closed list:  
 continue

$$\text{tentative} = g[\text{current}] + 1$$

if neighbor not in open list or  
 tentative <  $g[\text{start}]$   
 parent[neighbor] = current  
 $g[\text{neighbor}] = \text{tentative}$   
 $f[\text{neighbor}] = g[\text{neighbor}] + h[\text{neighbor}]$   
 if neighbor not in closed list:  
 add neighbor to open list  
 return "No solution found"

8/10/20

Example

goal	1	2	3
	0	4	6
4	5	7	8
7	8	0	

1	2	3
0	4	6
7	5	8
2	3	0

$$g = 0, h = 3$$

Time complexity

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$
0	2	8	1
1	4	6	2
7	0	8	3

$g=1$	$h=6$	$g=1$	$h=5$




<tbl\_r cells="4" ix="4" maxcspan="1" maxrspan="1"

**Code:**

```
Misplaced Tiles import
heapq goal_state =
'123804765'

moves = {

    'U': -3,
    'D': 3,
    'L': -1,
    'R': 1
}

invalid_moves = {
    0: ['U', 'L'], 1: ['U'], 2: ['U', 'R'],
    3: ['L'],      5: ['R'],
    6: ['D', 'L'], 7: ['D'], 8: ['D', 'R']
}

def move_tile(state, direction):
    index = state.index('0') if direction in
    invalid_moves.get(index, []):
        return None

    new_index = index + moves[direction]
    if new_index < 0 or new_index >= 9:
        return None

    state_list = list(state) state_list[index], state_list[new_index] =
    state_list[new_index], state_list[index] return ''.join(state_list)

def print_state(state):
    for i in range(0, 9, 3):
        print(''.join(state[i:i+3]).replace('0', ' '))
    print()

def misplaced_tiles(state):
    """Heuristic: count of tiles not in their goal position (excluding zero)."""
    return sum(1 for i, val in enumerate(state) if val != '0' and val != goal_state[i])

def a_star(start_state): visited_count = 0 open_set = []
    heapq.heappush(open_set, (misplaced_tiles(start_state), 0, start_state, []))
    visited = set()
```

```

while open_set:
    f, g, current_state, path = heapq.heappop(open_set)
    visited_count += 1

    if current_state == goal_state:
        return path, visited_count
    if current_state in visited:
        continue
    visited.add(current_state)

    for direction in moves:
        new_state = move_tile(current_state, direction)
        if new_state and new_state not in visited:
            new_g = g + 1
            new_f = new_g + misplaced_tiles(new_state)
            heapq.heappush(open_set, (new_f, new_g, new_state, path + [direction]))
return None, visited_count

# Main start = input("Enter start state (e.g.,
724506831): ")

if len(start) == 9 and set(start) == set('012345678'):
    print("Start state:")
    print_state(start)
    result, visited_states = a_star(start)

    print(f"Total states visited: {visited_states}")

    if result is not None:
        print("Solution found!")
        print("Moves:", ''.join(result))
        print("Number of moves:", len(result))
        print("1BM23CS041 Annas\n")

        current_state = start
        g = 0
        initialize_cost_so_far_for_i, move_in
        enumerate(result, 1):
            new_state = move_tile(current_state,
            move) g += 1
            h =
            misplaced_tiles(new_state)
            f = g + h
            print(f"Move {i}: {move}")
            print_state(new_state)
            print(f"g(n) = {g}, h(n) = {h}, f(n) = g(n) + h(n) =
            {f}\n")
            current_state = new_state

```

```
    else: print("No solution exists for the given start  
state.") Else:  
print("Invalid input! Please enter a 9-digit string using digits 0-8 without repetition.")
```

Output:

Enter start state (e.g., 724506831): 283164705 Start

state:

2 8 3

1 6 4

7 5

Total states visited: 7 Solution

found!

Moves: U U L D R

Number of moves: 5

Move 1: U

2 8 3

1 4

7 6 5

$g(n) = 1, h(n) = 3, f(n) = g(n) + h(n) = 4$

Move 2: U

2 3

1 8 4

7 6 5

$g(n) = 2, h(n) = 3, f(n) = g(n) + h(n) = 5$

Move 3: L 2

3

1 8 4 7

6 5

$g(n) = 3, h(n) = 2, f(n) = g(n) + h(n) = 5$

Move 4: D

1 2 3 8

4

7 6 5

$g(n) = 4, h(n) = 1, f(n) = g(n) + h(n) = 5$

Move 5: R

1 2 3 8

4

7 6 5

$$g(n) = 5, h(n) = 0, f(n) = g(n) + h(n) = 5$$

a) Manhattan

Distance import heapq  
goal\_state  
= '123456780'

moves = {

'U': -3,  
'D': 3,  
'L': -1,  
'R': 1  
}

invalid\_moves = {  
0: ['U', 'L'], 1: ['U'], 2: ['U', 'R'],  
3: ['L'], 5: ['R'],  
6: ['D', 'L'], 7: ['D'], 8: ['D', 'R']  
}

def move\_tile(state, direction):

index = state.index('0') if direction in  
invalid\_moves.get(index, []):  
return None

new\_index = index + moves[direction]  
if new\_index < 0 or new\_index >= 9:  
return None  
state\_list = list(state) state\_list[index], state\_list[new\_index] =  
state\_list[new\_index], state\_list[index] return ''.join(state\_list)

def print\_state(state):

for i in range(0, 9, 3):  
print(''.join(state[i:i+3]).replace('0', ' '))  
print()

def manhattan\_distance(state):

```

distance = 0 for i, val in
enumerate(state): if val ==
'0':
continue goal_pos = int(val) - 1 current_row, current_col = divmod(i, 3)
goal_row, goal_col = divmod(goal_pos, 3) distance +=
abs(current_row - goal_row) + abs(current_col - goal_col)
return distance

def a_star(start_state): visited_count = 0 open_set = []
heapq.heappush(open_set, (manhattan_distance(start_state), 0, start_state, []))
visited = set()

while open_set:
f, g, current_state, path = heapq.heappop(open_set)
visited_count += 1

if current_state == goal_state:
return path, visited_count

if current_state in visited:
continue visited.add(current_state)

for direction in moves:
new_state = move_tile(current_state, direction)
if new_state and new_state not in visited:
new_g = g + 1 new_f = new_g + manhattan_distance(new_state)
heapq.heappush(open_set, (new_f, new_g, new_state, path +
[direction]))
return None, visited_count

# Main

start = input("Enter start state (e.g., 724506831): ")

if len(start) == 9 and set(start) == set('012345678'):
print("Start state:")
print_state(start)

result, visited_states = a_star(start)
print(f"Total states visited: {visited_states}")

if result is not None:
print("Solution found!") print("Moves:", ''.join(result)) print("Number of moves:", len(result))
print("1BM23CS041\n")

```

```

current_state = start g = 0 #
initialize cost so far for i, move in
enumerate(result, 1):
    new_state = move_tile(current_state, move) g += 1 h =
        manhattan_distance(new_state) f = g + h print(f"Move
            {i}: {move}") print_state(new_state) print(f"g(n) = {g},
            h(n) = {h}, f(n) = g(n) + h(n) = {f}\n") current_state =
            new_state
else: print("No solution exists for the given start
    state.")
else:
    print("Invalid input! Please enter a 9-digit string using digits 0-8 without repetition.")

```

Output:

Enter start state (e.g., 724506831): 123678450 Start

state:

1 2 3  
6 7 8  
4 5

Total states visited: 21 Solution

found!

Moves: L U L D R R U L D R

Number of moves: 10

Move 1: L

1 2 3  
6 7 8  
4 5  
g(n) = 1, h(n) = 9, f(n) = g(n) + h(n) = 10

Move 2: U

1 2 3 6  
8  
4 7 5  
g(n) = 2, h(n) = 8, f(n) = g(n) + h(n) = 10

Move 3: L

1 2 3 6  
8  
4 7 5  
g(n) = 3, h(n) = 7, f(n) = g(n) + h(n) = 10

Move 4: D

1 2 3  
4 6 8

$$\begin{array}{l} 7 \ 5 \ g(n) = 4, h(n) = 6, f(n) = g(n) + h(n) \\ = 10 \end{array}$$

Move 5: R

1 2 3  
4 6 8  
7 5

$$g(n) = 5, h(n) = 5, f(n) = g(n) + h(n) = 10$$

Move 6: R

1 2 3  
4 6 8 7  
5

$$g(n) = 6, h(n) = 4, f(n) = g(n) + h(n) = 10$$

Move 7: U

1 2 3 4  
6  
7 5 8

$$g(n) = 7, h(n) = 3, f(n) = g(n) + h(n) = 10$$

Move 8: L

1 2 3 4  
6  
7 5 8

$$g(n) = 8, h(n) = 2, f(n) = g(n) + h(n) = 10$$

Move 9: D

1 2 3  
4 5 6 7 8  
 $g(n) = 9, h(n) = 1, f(n) = g(n) + h(n) = 10$

Move 10: R

1 2 3  
4 5 6  
7 8

$$g(n) = 10, h(n) = 0, f(n) = g(n) + h(n) = 10$$

## Program 4

Implement Hill Climbing search algorithm to solve N-Queens problem

Algorithm:

8/10/20  
hill - climbing algorithm

```
def hill - climbing (problem):
    current = problem . initial - state ()
    while True:
        neighbor = problem . get - best - neighbor
        if problem . value (neighbor) <= problem .
            value
            (current)
        return current
        current = neighbor
```

initial state () - gives the start solution  
get best neighbor (state) - finds the best neighboring solution & looks around the lowest sol  
value (state) - evaluates the quality (score) of a solution  
If the best neighbor is not better than current, then stop and return the current solution otherwise move to the next neighbor and continue.

Eg: finding the maximum value

Output

Print at x=3.00 with value = 10.00

.....

**Code:**

```
import random
import time

def print_board(state):
    """Prints the chessboard for a given state."""
    n = len(state)
    for row in range(n):
        line = ""
        for col in range(n):
            if state[col] == row:
                line += "Q "
            else:
                line += "."
        print(line)
    print()

def compute_heuristic(state):
    """Computes the number of attacking pairs of queens."""
    h = 0
    n = len(state)
    for i in range(n):
        for j in range(i + 1, n):
            if state[i] == state[j] or abs(state[i] - state[j]) == abs(i - j):
                h += 1
    return h

def get_neighbors(state):
    """Generates all possible neighbors by moving one queen in its column."""
    neighbors = []
    n = len(state)
    for col in range(n):
        for row in range(n):
            if row != state[col]:
                neighbor = list(state)
                neighbor[col] = row
                neighbors.append(neighbor)
    return neighbors

def hill_climb_verbose(initial_state, step_delay=0.5):
    """Hill climbing algorithm with verbose output at each step."""
    current = initial_state
    current_h = compute_heuristic(current)
    step = 0

    print(f"Initial state (heuristic: {current_h}):")
    print_board(current)
    time.sleep(step_delay)
```

```

while True:
    neighbors =
        get_neighbors(current) next_state
        = None next_h = current_h

    for neighbor in neighbors:
        h =
            compute_heuristic(neighbor) if
            h < next_h: next_state =
                neighbor next_h = h

    if next_h >= current_h: print(f'Reached local minimum at step {step},'
        heuristic: {current_h}) return current, current_h

    current = next_state current_h = next_h step
    += 1 print(f'Step {step}: (heuristic:
        {current_h})') print_board(current)
    time.sleep(step_delay)

def solve_n_queens_verbose(n, max_restarts=1000):
    """Solves N-Queens problem using hill climbing with restarts and verbose output."""
    for attempt in range(max_restarts):
        print(f"\n==== Restart {attempt + 1} ====\n") initial_state
        = [random.randint(0, n - 1) for _ in range(n)] solution, h
        = hill_climb_verbose(initial_state) if h == 0:
            print(f" Solution found after {attempt + 1} restart(s):") print_board(solution)
            return solution
        else:
            print(f" No solution in this attempt (local minimum).\n")
            print("Failed to find a solution after max restarts.")
            return None

# --- Run the algorithm --- if
name == "__main__":
    N = int(input("Enter the number of queens (N): "))
    solve_n_queens_verbose(N)

```

Output:  
Enter the number of queens (N): 4

==== Restart 1 ====

Initial state (heuristic: 3):

Q . Q ..  
Q ..  
... Q .  
...

Step 1: (heuristic: 1) .

. Q .  
. Q ..  
... Q Q  
...

Reached local minimum at step 1, heuristic: 1

No solution in this attempt (local minimum).

==== Restart 2 ====

Initial state (heuristic: 3):

. Q ..  
.. Q .  
.... Q  
.. Q

Step 1: (heuristic: 1) .

Q ..  
.. Q .  
Q ...  
... Q

Reached local minimum at step 1, heuristic: 1

No solution in this attempt (local minimum).

==== Restart 3 ====

Initial state (heuristic: 2):

....  
. Q . Q .  
... Q .  
Q .

Step 1: (heuristic: 1) .

Q ..  
... Q  
.... Q .  
Q .

Step 2: (heuristic: 0) .

Q ..  
... Q Q  
...  
.. Q .

Reached local minimum at step 2, heuristic: 0

Solution found after 3 restart(s):

. Q ..  
... Q Q  
...  
.. Q .

## Program 5

### Simulated Annealing to Solve 8-Queens problem

Algorithm:

*Simulated Annealing*  
Date: 1/01/20  
Pengrajan

```
current ← initial state
T ← a large positive value
while T > 0 do
    next ← a random neighbour of current
    ΔE ← current.cost - next.cost
    if ΔE > 0 then
        current ← next
    else
        current ← next with probability  $e^{-\Delta E/T}$ 
    end if
    decrease T (e.g.  $T \leftarrow T/2$ )
end while
return current
```

Simulated Annealing is a probabilistic optimization technique inspired by the annealing process in metallurgy. It tries to find a global minimum of a function by allowing occasional uphill moves to escape local minima.

~~Cost Function: Output:-~~  
Optimized  $X = 0.02347$   
Minimum  $\cos(X^{12}) = 0.00057$

~~Eg: Find the minimum of a Sample 2D function~~

~~Cost Function: The function being minimized~~  
~~Initial State: The starting point of the search~~  
~~Neighbour: A state that is a small step away from the current state e.g. swapping two cities~~  
~~Cooling schedule: The rule used to gradually lower T~~  
~~7. A proper scheme ensures the system "freezes" into a good function solution. A common method is geometric cooling.~~

**Code:**

```
import random import
math

def compute_heuristic(state):
    """Number of attacking pairs."""
    h = 0 n = len(state) for i in
    range(n):
        for j in range(i + 1, n):
            if state[i] == state[j] or abs(state[i] - state[j]) == abs(i - j):
                h += 1 return
    h

def random_neighbor(state):
    """Returns a neighbor by randomly changing one queen's
    row.""" n = len(state) neighbor = state[:] col = random.randint(0,
    n - 1) old_row = neighbor[col] new_row = random.choice([r for
    r in range(n) if r != old_row]) neighbor[col] = new_row return
    neighbor

def dual_simulated_annealing(n, max_iter=10000, initial_temp=100.0, cooling_rate=0.99):
    """Simulated Annealing with dual acceptance strategy."""
    current = [random.randint(0, n - 1) for _ in range(n)]
    current_h = compute_heuristic(current) temperature =
    initial_temp

    for step in range(max_iter):
        if current_h == 0: print(f" Solution found
        at step {step}") return current

        neighbor = random_neighbor(current)
        neighbor_h = compute_heuristic(neighbor)
        delta = neighbor_h - current_h

        if delta < 0:
            current = neighbor current_h
            = neighbor_h else:
                # Dual acceptance: standard + small chance of higher uphill
                move probability = math.exp(-delta / temperature) if
                random.random() < probability:
```

```

        current = neighbor current_h
        = neighbor_h

temperature *= cooling_rate if
temperature < 1e-5: # Restart if stuck
    temperature = initial_temp
current = [random.randint(0, n - 1) for _ in
range(n)] current_h = compute_heuristic(current)

print(" Failed to find solution within max iterations.") return
None

# --- Run the algorithm --- if
name == "__main__":
    N = int(input("Enter number of queens (N): ")) solution
    = dual_simulated_annealing(N)
if solution:
    print("Position format:") print("[", "
    ".join(str(x) for x in solution), "]")
    print("Heuristic:",
    compute_heuristic(solution))
    print("1BM23CS041")

```

Output:

Enter number of queens (N): 8

Solution found at step 675 Position  
format:

[ 3 0 4 7 5 2 6 1 ]

Heuristic: 0

## Program 6

Create a knowledge base using propositional logic and show that the given query entails the knowledge base or not.

### Algorithm:

The image shows a handwritten algorithm on lined paper. At the top right, it says "papergrid Date: / /". Below the header, the algorithm is written in blue ink. It starts with a function definition for "TT-Entails? (KB, a)". The algorithm then defines "Symbols" as a list of propositional symbols in "d", followed by a return statement for "TT-Check-All (KB, a, Symbols; &)". It then defines a function "TT-Check-All (KB, d, Symbols, model)". This function returns true or false. It checks if "empty? (Symbols)" and if "PL-true? (KB, model)". If so, it returns "PL-true? (d, model)". Otherwise, it returns "true!" (when KB is false, always returns true). If neither condition is met, it splits "Symbols" into "p" (first symbol) and "rest" (rest of symbols), and recursively calls "TT-Check-All (KB, d, rest, model)". A red line through the text "TT-check-all (KB, d, rest, model, v = f; e = e)" is followed by "T = (T & T) -> v = (T, T, T)" and "decomposition of the w.r.t v".

```
function TT-Entails? (KB, a) returns true or false
    inputs: KB, the knowledge base; a sentence in propositional logic; d, the query a sentence in propositional logic
    Symbols ← a list of the propositional symbols in d, KB
    return TT-Check-All (KB, a, Symbols; &)

function TT-Check-All (KB, d, Symbols, model)
    returns true or false
    if empty? (Symbols) then
        if PL-true? (KB, model) then return PL-true? (d, model)
        else return true! (When KB is false, always returns true)
    else do
        p ← First (Symbols)
        rest ← rest (Symbols)
        return (TT-Check-All (KB, d, rest, model))
    if p = true?
        and & q ∈ p list & v & e (P)
        TT-check-all (KB, d, rest, model, v = f; e = e)
        T = (T & T) -> v = (T, T, T)
        decomposition of the w.r.t v
        & f & g = & T & e (v)
```

Date: / /

**TRUTH TABLE**

Ex:-

$$KB = \{ G \rightarrow P, P \rightarrow Q, G, V \wedge 3 = 2^3 \}$$

P	Q	R	$G \rightarrow P$	$P \rightarrow Q$	$G \wedge R$
T	T	T	T	F	T
T	T	F	T	F	T
T	F	T	T	T	T
T	F	F	T	T	F
F	T	T	F	T	T
F	T	F	F	T	T
F	F	T	T	T	T
F	F	F	T	T	F

2) Does  $KB$  entail  $R \rightarrow P$ ?

$$(T, F, T) \models R \rightarrow P \text{ hence } KB = R$$

$$(F, F, T) \not\models R \rightarrow P \text{ hence } R \neq T$$

3) Does  $KB$  entail  $R \rightarrow P$ ?

Not true in all mode

$$(T, F, T) : R \rightarrow P = (T \rightarrow T) = T$$

$$(F, F, T) : R \rightarrow P = (T \rightarrow F) = F$$

~~hence  $KB$  is true~~  $\therefore KB \neq R \rightarrow P$

4) Does  $KB$  entail  $Q \rightarrow R$ ?

$$(T, F, T) : G \rightarrow (F \rightarrow T) = T$$

$$(F, F, T) : G \rightarrow R = (F \rightarrow T) = T$$

True in all  $KB$  model

$$\text{hence } KB = Q \rightarrow R$$

satn  
impl

**Code:**

```
from itertools import product
```

```
# ----- Propositional Logic Symbols
-----class Symbol: def __init__(self,
name):
    self.name = name

    def __invert__(self): # ~P
        return Not(self)

    def __and__(self, other): # P & Q
        return And(self, other)
    def __or__(self, other): # P | Q
        return Or(self, other)

    def __rshift__(self, other): # P >> Q (implication) return Or(Not(self),
other)

    def __eq__(self, other): # P == Q (biconditional) return And(Or(Not(self),
other), Or(Not(other), self))

    def eval(self, model):
        return model[self.name]

    def symbols(self):
        return {self.name}

    def __repr__(self):
        return self.name

class Not:
    def __init__(self, operand):
        self.operand = operand

    def eval(self, model):
        return not self.operand.eval(model)

    def symbols(self):
        return self.operand.symbols()

    def __repr__(self):
```

```

        return f"~{self.operand}"

    def _invert_(self): # allow ~~A
        return Not(self)

class And: def __init__(self,
    left, right):
    self.left, self.right = left, right

    def eval(self, model):
        return self.left.eval(model) and self.right.eval(model)

    def symbols(self):
        return self.left.symbols() | self.right.symbols()

    def __repr__(self):
        return f"({self.left} & {self.right})"

    def _invert_(self): # allow ~(A & B) return Not(self)

class Or:
    def __init__(self, left, right):
        self.left, self.right = left, right

    def eval(self, model):
        return self.left.eval(model) or self.right.eval(model)

    def symbols(self):
        return self.left.symbols() | self.right.symbols()

    def __repr__(self):
        return f"({self.left} | {self.right})"

    def _invert_(self): # allow ~(A | B) return
        Not(self)

# ----- Truth Table Entailment def tt_entails(kb,
alpha, show_table=False):
    symbols = sorted(list(kb.symbols() | alpha.symbols()))
    if show_table:
        print_truth_table(kb, alpha, symbols)
    return tt_check_all(kb, alpha, symbols, {})
```

```

def tt_check_all(kb, alpha, symbols, model):
    if not symbols: # all symbols assigned
        if kb.eval(model): # KB is true
            return alpha.eval(model)
        else: return True # if KB is false, entailment
            holds
    else:
        P, rest = symbols[0], symbols[1:]

        model_true = model.copy() model_true[P] = True
        result_true = tt_check_all(kb, alpha, rest,
                                   model_true)

        model_false = model.copy() model_false[P] = False
        result_false = tt_check_all(kb, alpha, rest,
                                   model_false) return result_true and result_false

# ----- Truth Table Printer -----
def print_truth_table(kb, alpha, symbols):
    header = symbols + ["KB", "Query"] print(
        | ".join(f'{h:^5}' for h in header)) print("-"
        * (7 * len(header)))

    for values in product([False, True], repeat=len(symbols)):
        model = dict(zip(symbols, values)) kb_val = kb.eval(model)
        alpha_val = alpha.eval(model) row = [str(model[s]) for s in
                                             symbols] + [str(kb_val), str(alpha_val)]
        print(" | ".join(f'{r:^5}' for r in row))
    print()

# ----- Example -----
S = Symbol("S")
C = Symbol("C")
T = Symbol("T")

```

$c = T \mid \sim T$

```
# KB: P → Q  
kb1 = ~ (S|T) #  
Query: Q  
alpha1 = S & T
```

```
print("Knowledge Base:", kb1) print("Query:",  
alpha1) print() result = tt_entails(kb1, alpha1,  
show_table=True) print("Does KB entail  
Query?", result)
```

Output:

```
Knowledge Base: (P | (Q & P))  
Query: (Q | P)
```

P | Q | KB | Query

---

```
-----  
False | False | False | False  
False | True | False | True  
True | False | True | True  
True | True | True | True
```

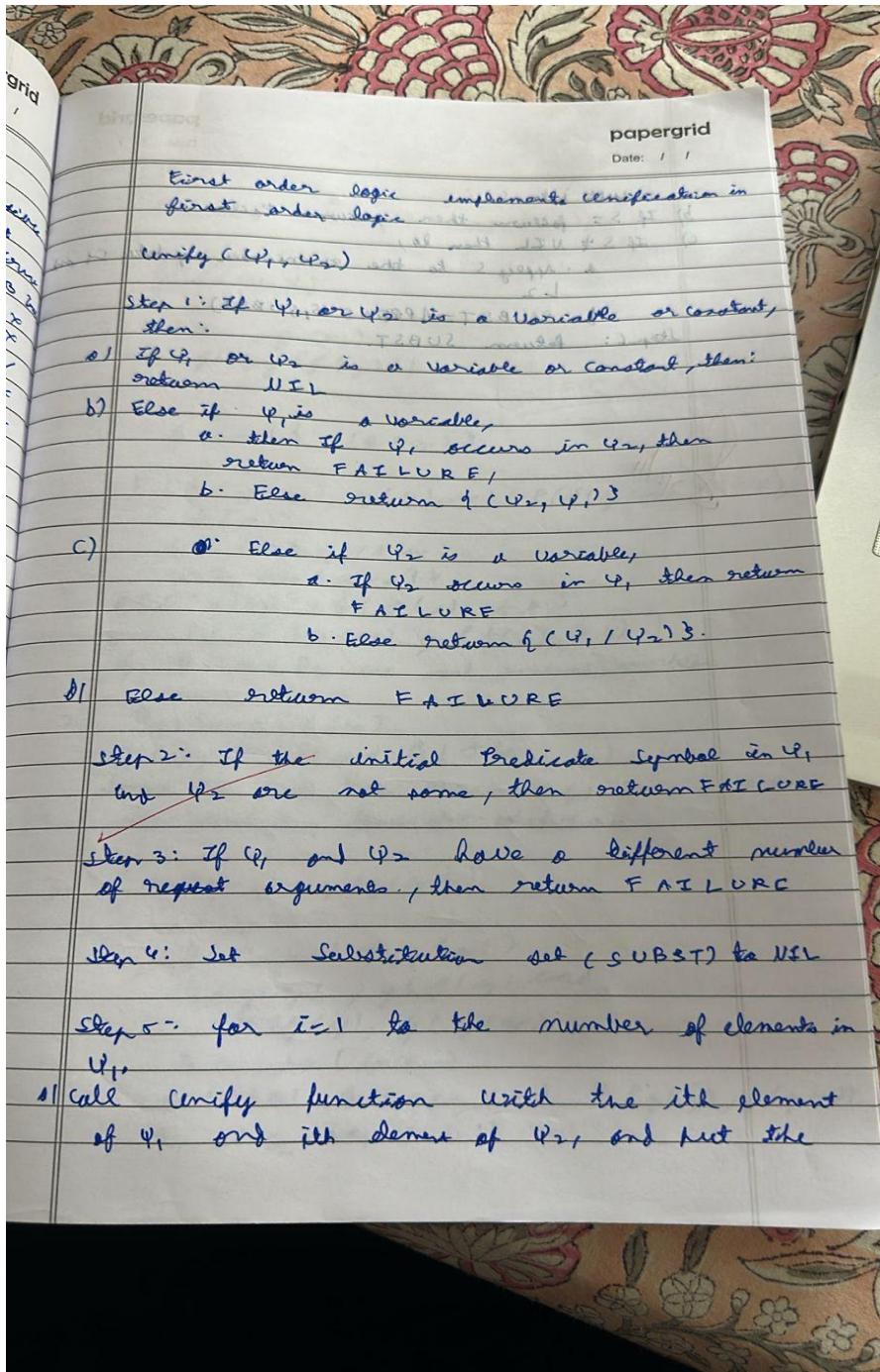
Does KB entail Query? True

---

## Program 7

Implement unification in first order logic

### Algorithm:



- result into  $s$ .
- b) If  $s = \text{failure}$  then return  $\text{failure}$
  - c) If  $s \neq \text{NIL}$  then do,
    - a. apply  $s$  to the remainder of both  $L_1$  and  $L_2$
    - b.  $\text{SUBST} = \text{APPEND}(s, \text{SUBST})$
- Step 6: return  $\text{SUBST}$ .

8/20/11

1.  $P(f(x), g(g), y)$  and  $Q(f(g), f(g), f(a))$
2.  $Q(x, f(x))$   
 $Q(f(g), x)$
3.  $H(x, g(x))$   
 $H(f(x), g(f(x)))$

### UNIFICATION

1.  $\theta = \text{Sub}(x \rightarrow g(y), y \rightarrow z)$

$P(f(g(x)), g(y), y) \models P(f(g(z)), g(f(z)),$   
 $f(a))$

$\theta_1 = \text{Sub}(y \rightarrow f(x))$

$\theta_3 = \text{Sub}(y \rightarrow a)$

$\theta \& f(g(x)) \models f(f(x), f(a))$

$\theta \& P(f(g(y)), g(f(g(a)), f(b)))$

$\theta_1, \theta_2$  and  $\theta_3$  are most general unifiers

2.  $\theta_1 = \text{Sub}(x \rightarrow y)$

$f(y, f(y)) \text{ and } Q(f(y), y)$

longer for last two unless  $f(y)$  needs to be  
 some time true generalization is a witness

3.  $H(y(g), y(g(y)))$

~~$\theta_1 = \text{Sub}(x \rightarrow y(g))$~~

~~$H(y(g), y(g(y)))$  and~~

~~$H(y(y), y(g(y)))$~~

$\theta_2 = \text{Sub}(y \rightarrow y)$

$H(y(g), y(g(y)))$  and  $H(y(g), y)$

$\theta_1$  and  $\theta_2$  are MGV

**Code:**

```
class UnificationError(Exception):
    pass

def occurs_check(var, term):
    """Check if a variable occurs in a term (to prevent infinite recursion)."""
    if var == term:
        return True
    if isinstance(term, tuple): # Term is a compound (function term)
        return any(occurs_check(var, subterm) for subterm in term)
    return False

def unify(term1, term2, substitutions=None):
    """Try to unify two terms, return the MGU (Most General Unifier)."""
    if substitutions is None: substitutions = {}

    # If both terms are equal, no further substitution is
    # needed if term1 == term2: return substitutions

    # If term1 is a variable, we substitute it with term2
    # elif isinstance(term1, str) and term1.isupper():
    # If term1 is already substituted, recurse
    if term1 in substitutions:
        return unify(substitutions[term1], term2, substitutions)
    elif occurs_check(term1, term2):
        raise UnificationError(f"Occurs check fails: {term1} in {term2}")
    else:
        substitutions[term1] = term2
        return substitutions

    # If term2 is a variable, we substitute it with term1
    # elif isinstance(term2, str) and term2.isupper(): # If
    # term2 is already substituted, recurse
    # if term2 in
    # substitutions:
    #     return unify(term1, substitutions[term2], substitutions)
    # elif occurs_check(term2, term1):
    #     raise UnificationError(f"Occurs check fails: {term2} in {term1}")
    # else:
    #     substitutions[term2] = term1
    #     return substitutions
```

```

# If both terms are compound (i.e., functions), unify their parts recursively
elif isinstance(term1, tuple) and isinstance(term2, tuple):
    # Ensure that both terms have the same "functor" and number of arguments
    # if len(term1) != len(term2):
    #     raise UnificationError(f'Function arity mismatch: {term1} vs {term2}')
    for subterm1, subterm2 in zip(term1, term2): substitutions
        = unify(subterm1, subterm2, substitutions) return
    substitutions

else:
    raise UnificationError(f'Cannot unify: {term1} with {term2}')

# Define the terms as tuples
term1 = ('p', 'b', 'X', ('f', ('g', 'Z'))) term2
= ('p', 'Z', ('f', 'Y'), ('f', 'Y'))

try:
    # Find the MGU result = unify(term1,
    term2) print("Most General Unifier
    (MGU):") print(result)
except UnificationError as e:
    print(f"Unification failed: {e}")
finally:
    print("1BM23CS041 Annas")

```

Output:

Most General Unifier (MGU):  
{'Z': 'b', 'X': ('f', 'Y'), 'Y': ('g', 'Z')}

## Program 8

Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.

Algorithm:

The image shows a handwritten algorithm for forward reasoning in first-order logic, written in blue ink on lined paper. The algorithm is structured as follows:

- First order logic create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.**
- function FOL-FC-1ST(KB, d) returns a subset or false**
  - inputs: KB, the knowledge base, a set of first-order definite clauses d, the query, an atomic sentence**
- local variables: new, the new sentences inferred on each iteration**
- repeat until new is empty**
  - new  $\leftarrow \emptyset$**
  - for each rule in KB do**
    - $(p_1, A_1 \wedge \dots \wedge p_m \Rightarrow q) \leftarrow \text{Standardize-HR}(p_1, A_1, \dots, p_m)$**
    - for each  $\theta$  such that  $\text{SUBST}(\theta, p_1, A_1, \dots, p_m) \neq \text{UNIFY}(\theta, q)$**
    - $\theta \leftarrow \text{UNIFY}(\theta, q)$**
    - if  $\theta$  does not unify with some atom already in KB or new then**
      - add  $\theta$  to new**
      - $\phi \leftarrow \text{UNIFY}(\theta, d)$**
      - if  $\phi$  is not fail then return  $\phi$**
    - add new to KB**
  - return false**

**Code:**

```
# Define the knowledge base facts
= {
    'American(Robert)': True, # Robert is an American
    'Hostile(A)': True,      # Country A is hostile to America
    'Sells_Weapons(Robert, A)': True # Robert sold weapons to Country A }

# Define the law/rule: If American(X) and Hostile(Y) and Sells_Weapons(X, Y), then Crime(X) def
forward_reasoning(facts):
    # Apply the rule: If American(X) and Hostile(Y) and Sells_Weapons(X, Y), then Crime(X) if
    facts.get('American(Robert)', False) and facts.get('Hostile(A)', False) and
    facts.get('Sells_Weapons(Robert, A)', False):
        facts['Crime(Robert)'] = True # Robert is a criminal

# Perform forward reasoning to see if we can deduce that Robert is a criminal forward_reasoning(facts)
# Output the result based on the fact derived if facts.get('Crime(Robert)', False):
    print("Robert is a criminal.")
print("Annas 1BM23CS041") else:
    print("Robert is not a criminal.")
```

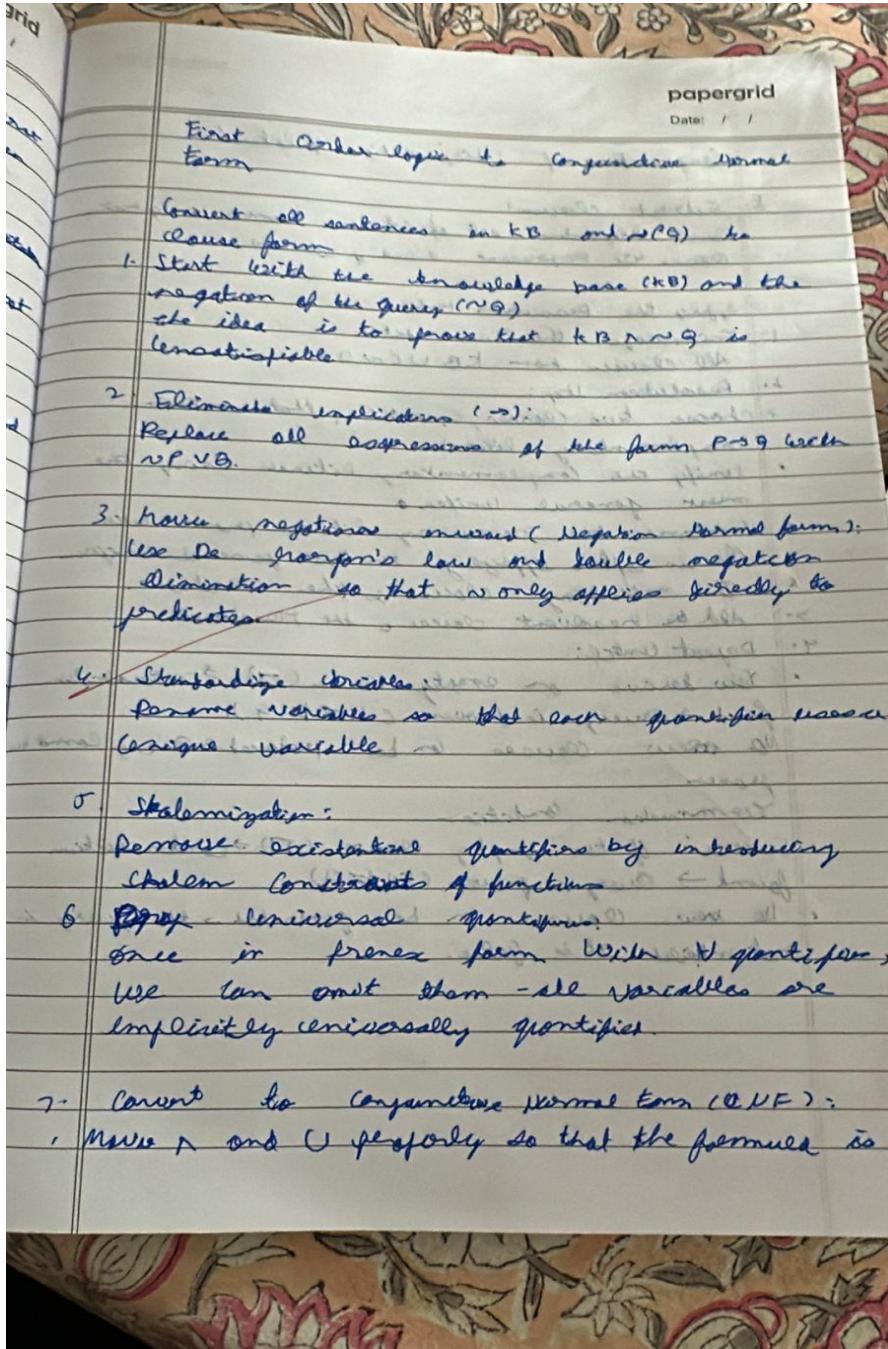
**Output:**

Robert is a criminal.

## Program 9

Create a knowledge base consisting of first order logic statements and prove the given query using Resolution.

Algorithm:



## Conjunctions of disjunctions of literals

### 8. Extract clauses:

Each disjunction (set of literals) becomes a clause.  
Clauses we represent as set of literals.

(E.g.)

Apply the Resolution rule

### 1. Initialize the Clause set:

All clauses from KB U (NQ).

### 2. Resolution step:

- choose two clauses,  $C_1$  and  $C_2$ , that contain complementary literals
- unify the complementary literals using the most general unifier
- combine the remaining literals from both clauses after applying the most general unifier
- the resulting clause is the resolvent

### 3. Add the resolvent clause to the Moscavent.

### 4. Repeat until:

- You derive an empty clause ( $\emptyset$ )  $\Rightarrow$  contradiction found  $\rightarrow$  query is proven (KB  $\vdash Q$ ).
- No new clauses can be generated  $\Rightarrow$  query can't prove

### Termination condition

- Success: if the empty clause ( $\emptyset$ )  $\Rightarrow$  contradiction found  $\rightarrow$  query is proven (KB  $\vdash Q$ ).
- No new clauses can be generated  $\Rightarrow$  the query is not entailed  $\Rightarrow$  it is false.

**Code:**

```
import copy

class Predicate:    def __init__(self,
predicate_string):
    self.predicate_string = predicate_string      self.name, self.arguments,
    self.negative = self.parse_predicate(predicate_string)

    def parse_predicate(self, predicate_string):
neg = predicate_string.startswith('~')      if
neg:
    predicate_string = predicate_string[1:]      m = re.match(r"([A-
Za-z_][A-Za-z0-9_]*)(.*?))", predicate_string)      if not m:
        raise ValueError(f"Invalid predicate: {predicate_string}")
name, args = m.groups()      args = [a.strip() for a in
args.split(",")]
return name, args, neg

    def negate(self):
        self.negative = not self.negative
if self.predicate_string.startswith('~'):
    self.predicate_string = self.predicate_string[1:]
else:
    self.predicate_string = '~' + self.predicate_string

    def unify_with_predicate(self, other):
        """Attempt to unify two predicates; return substitution dict or False."""
if self.name != other.name or len(self.arguments) != len(other.arguments):
        return False      subs = {}      for a, b in
zip(self.arguments, other.arguments):      if a ==
b:          continue      if a[0].islower():
subs[a] = b
        elif b[0].islower():
subs[b] = a      else:
return False      return
subs

    def substitute(self, subs):      """Apply substitution
dictionary."""
        self.arguments = [subs.get(a, a) for a in
self.arguments]      self.predicate_string = ('~' if
```

```

        self.negative else ") +      self.name + '(' +
        ','.join(self.arguments) + ')'
    )

def __repr__(self):
    return self.predicate_string

class Statement: def __init__(self,
statement_string):
    self.statement_string = statement_string
    self.predicate_set = self.parse_statement(statement_string)

    def parse_statement(self, statement_string):
        parts = statement_string.split('|')
        predicates = [] for p in parts:
            predicates.append(Predicate(p.strip()))
        return set(predicates)

    def add_statement_to_KB(self, KB, KB_HASH):
        KB.add(self) for predicate in
        self.predicate_set:
            key = predicate.name
            if key not in KB_HASH:
                KB_HASH[key] = set()
                KB_HASH[key].add(self)

    def get_resolving_clauses(self, KB_HASH):
        resolving_clauses = set() for
        predicate in self.predicate_set:
            key = predicate.name if key in
            KB_HASH:             resolving_clauses |=
            KB_HASH[key]         return resolving_clauses

    def resolve(self, other):
        """Resolve two statements; return new derived statements or False if contradiction."""
        new_statements = set() for p1 in self.predicate_set: for p2 in
        other.predicate_set: if p1.name == p2.name and p1.negative != p2.negative:

```

```

        subs = p1.unify_with_predicate(p2)
if subs is False:
    continue
    new_pred_set = set()
for pred in self.predicate_set.union(other.predicate_set):
    if pred not in (p1, p2):
        pred_copy = copy.deepcopy(pred)
        pred_copy.substitute(subs)
        new_pred_set.add(pred_copy)
    else:
        new_pred_set.add(pred)
return new_pred_set

def __repr__(self):
    return self.statement_string

```

```

def fol_to_cnf_clauses(sentence):
    """
    Convert simple implications and conjunctions into CNF.

    Example:
    "A(x,y) => B(x,y)" becomes "~A(x,y)|B(x,y)"
    "A(x,y) & B(y,z) => C(x,z)" becomes "~A(x,y)|~B(y,z)|C(x,z)"

    sentence =
    sentence.replace(' ', '') if '=>' in
    sentence:
        lhs, rhs = sentence.split('=>')
        parts = lhs.split('&')
        negated_lhs = ['~' + p for
        p in parts]
        disjunction =
        '|'.join(negated_lhs + [rhs])
        return
        [disjunction]

    # Split conjunctions into separate clauses
    if '&' in sentence:
        return
        sentence.split('&')
        return [sentence]

```

KILL\_LIMIT = 8000

```

def prepare_knowledgebase(fol_sentences):
    KB = set()
    KB_HASH = {}
    for sentence in fol_sentences:
        clauses = fol_to_cnf_clauses(sentence)
    for clause in clauses:
        stmt = Statement(clause)
        stmt.add_statement_to_KB(KB, KB_HASH)    return KB,
    KB_HASH

def FOL_Resolution(KB, KB_HASH, query):
    KB2 = set()
    query.add_statement_to_KB(KB2, KB_HASH)
    # Note: Adding query to main KB logic depends on implementation,
    # but usually we add Negated Query to KB. Here logic seems to handle it externally.
    while True:
        new_statements = set()
        if len(KB) > KILL_LIMIT:
            return False      for s1 in KB:
                for s2 in s1.get_resolving_clauses(KB_HASH):
                    if s1 == s2:          continue      resolvents
                    = s1.resolve(s2)      if resolvents is False:
                        return True
                    new_statements |= resolvents

        if new_statements.issubset(KB):
            return False

        # Add new statements to KB and Hash
        for s in new_statements:      if s not in
            KB:                      s.add_statement_to_KB(KB, KB_HASH)

def main():
    fol_sentences = [
        "Parent(John, Mary)",
        "Parent(Mary, Sam)",
        "Parent(x, y) => Ancestor(x, y)",

```

```

    "Parent(x, y) & Ancestor(y, z) => Ancestor(x, z)"
]
queries = ["Ancestor(John, Sam)"]

KB, KB_HASH = prepare_knowledgebase(fol_sentences)
print("\nKnowledge Base CNF Clauses:") for stmt in KB:
print(" ", stmt)

for query_str in queries:
    query_predicate = Predicate(query_str)
    query_predicate.negate() query_stmt =
Statement(str(query_predicate))

# We pass a copy because resolution modifies the KB satisfiable =
FOL_Resolution(copy.deepcopy(KB), copy.deepcopy(KB_HASH), query_stmt)
print(f"\nQuery: {query_str} =>", "TRUE" if satisfiable else "FALSE")

if __name__ == "__main__":
main()

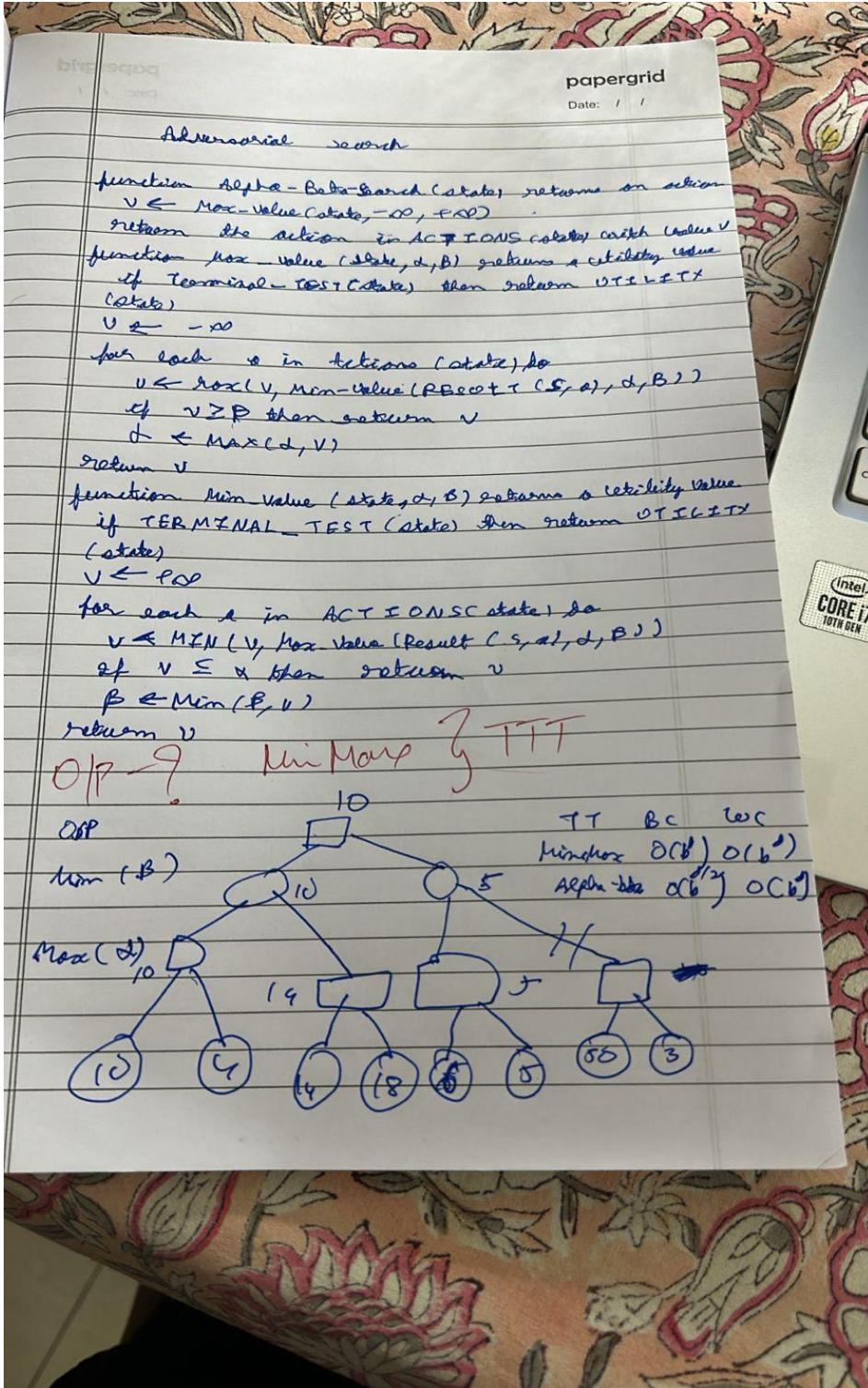
Output:
Knowledge Base CNF Clauses:
~Parent(x,y)|Ancestor(x,y)
Parent(John,Mary)
Parent(Mary,Sam)
~Parent(x,y)|~Ancestor(y,z)|Ancestor(x,z)
Query: Ancestor(John, Sam) => TRUE

```

## Program 10:

Implement Alpha-Beta Pruning.

Algorithm:



**Code:**

```
import math

def alpha_beta(node, depth, alpha, beta, maximizingPlayer, game_tree):
    """
    Alpha-Beta pruning search algorithm
    node: current node in game tree
    depth: current depth

    alpha: best value for maximizer
    beta: best value for minimizer
    maximizingPlayer: True if maximizer's turn game_tree:
        dictionary representing tree {node: children or value}
    """
    # If leaf node or depth 0, return its value if depth
    == 0 or isinstance(game_tree[node], int):
        return game_tree[node]

    if maximizingPlayer:
        maxEval
        = -math.inf for child in
            game_tree[node]:
                eval = alpha_beta(child, depth-1, alpha, beta, False, game_tree)
                maxEval = max(maxEval, eval) alpha = max(alpha, eval) if
                    beta <= alpha:
                        break # Beta cut-off
        return maxEval else:
            minEval = math.inf for child in game_tree[node]: eval =
                alpha_beta(child, depth-1, alpha, beta, True, game_tree) minEval
                = min(minEval, eval) beta = min(beta, eval) if beta <= alpha:
                    break # Alpha cut-off
            return minEval

# Example game tree
game_tree = {
    'A': ['B', 'C'],
    'B': ['D', 'E'],
    'C': ['F', 'G'],
    'D': 3,
    'E': 5,
    'F': 2,
```

```
'G': 9 } best_value = alpha_beta('A', depth=3, alpha=-math.inf, beta=math.inf,
maximizingPlayer=True, game_tree=game_tree)
print("Best value for maximizer:", best_value)
```

Output:

Best value for maximizer: 3