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# METHODS FOR HANDLING DEADLOCKS (Part-4) Banker's Algorithm

### Methods for Handling Deadlocks

Deadlock Prevention

Deadlock Avoidance

- Deadlock Detection
- Ignore the problem

## DEADLOCK AVOIDANCE Continue...

#### **AVOIDANCE ALGORITHMS**

#### Avoidance algorithms

- Single instance of a resource type:
  - ➤ Use a resource-allocation graph

- Multiple instances of a resource type:
  - > Use the banker's algorithm

#### **BANKER'S ALGORITHM**

### Banker's Algorithm

- Multiple instances of resources of the same type.
- Each process must a priori claim maximum use.
- The algorithm allocates resources to a requesting thread if the allocation leaves the system in a safe state. Otherwise, the thread must wait.
- When a process gets all its resources it must return them in a finite amount of time.

#### Data Structure

- Let n = number of *processes*, and m = number of *resources* types.
  - > Available: Vector of length m.
    - If available[j] = k, there are k instances of resource type Rj are available
  - Max: n x m matrix.

If Max[i,j] = k, then process Pi may request at most k instances of resource

type Rj		Amocation	Mux	Available	
type nj		ABC	ABC	ABC	
	$P_0$	010	753	332	
	$P_1$	200	322		
	$P_2$	302	902		
ocation: n x m matrix.	$P_3$	211	222		
ocation. If A III illatilia.	$P_4$	002	433	Need	1

- > Allo
  - If Allocation[i,j] = k then Pi is currently allocated k instances of Rj

	- 0	
	$P_1$	122
	$P_2$	600
Need: n x m matrix.	$P_3$	011
	$P_{\Lambda}$	431

• If Need[i,j] = k, then Pi may need k more instances of Rj to complete its task Need [i,j] = Max[i,j] - Allocation <math>[i,j]

## Safety Algorithm

- Safety algorithm finds out whether or not a system is in a safe state.
  - 1. Let *Work* and *Finish* be vectors of length m and n, respectively. Initialize Work = Available and Finish[i] = false for i = 0, 1, ..., n 1.
  - 2. Find an index i such that both
    - a. Finish[i] == false
    - b.  $Need_i \leq Work$

If no such *i* exists, go to step 4.

- Work = Work + Allocation<sub>i</sub>
   Finish[i] = true
   Go to step 2.
- 4. If Finish[i] == true for all i, then the system is in a safe state.

#### Resource-Request Algorithm

Let  $Request_i$  be the request vector for process  $P_i$ . If  $Request_i$  [j] == k, then process  $P_i$  wants k instances of resource type  $R_j$ . When a request for resources is made by process  $P_i$ , the following actions are taken:

- 1. If  $Request_i \leq Need_i$ , go to step 2. Otherwise, raise an error condition, since the process has exceeded its maximum claim.
- 2. If  $Request_i \leq Available$ , go to step 3. Otherwise,  $P_i$  must wait, since the resources are not available.
- 3. Have the system pretend to have allocated the requested resources to process  $P_i$  by modifying the state as follows:

```
Available = Available - Request_i;

Allocation_i = Allocation_i + Request_i;

Need_i = Need_i - Request_i;
```

- If safe -> the resources are allocated to Pi
- If unsafe -> Pi must wait, and the old resource-allocation state is restored

#### References

- 1. Silberschatz, Galvin and Gagne, "Operating Systems Concepts", Wiley.
- 2. William Stallings, "Operating Systems: Internals and Design Principles", 6<sup>th</sup> Edition, Pearson Education.
- D M Dhamdhere, "Operating Systems: A Concept based Approach", 2<sup>nd</sup> Edition, TMH.

