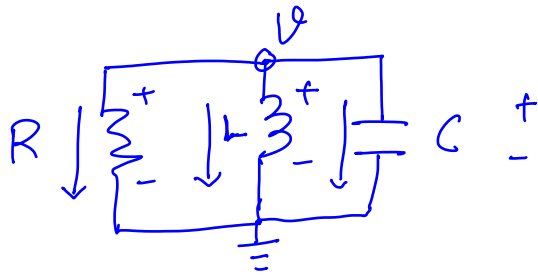


### Quick Recap

- natural response of a parallel RLC circuit



$$V_R = V_C = V_L = V, \quad \forall t \geq 0$$

$$\underline{I_R} + \underline{I_L} + \underline{I_C} = 0 \quad \forall t \geq 0$$

$$V_C(0) = V_0, \quad I_L(0) = I_0$$

$$C \frac{d^2 V}{dt^2} + \frac{1}{R} \frac{dV}{dt} + \frac{1}{L} V = 0$$

$$V(t) = A e^{st} \quad (\text{Assumption})$$

$$Cs^2 + \frac{1}{R}s + \frac{1}{L} = 0 \quad (\text{characteristic eq.})$$

$$s_{1,2} = -\frac{1}{2RC} \pm \sqrt{\left(\frac{1}{2RC}\right)^2 - \frac{1}{LC}}$$

$$= -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$\alpha \rightarrow$  decay rate,  $\omega_0 \rightarrow$  resonant frequency

$$\alpha = \frac{1}{2RC}, \quad \omega_0^2 = \frac{1}{LC}$$

$$V(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} \quad (\text{general structure})$$

$$A_1, A_2, s_1, s_2 \longrightarrow (\text{complex numbers})$$

$$(\alpha > \omega_0) \longrightarrow \text{Overdamped system}$$

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$\Rightarrow \text{real roots} \quad s_1 = -\alpha - \sqrt{\alpha^2 - \omega_0^2} < 0$$

$$\alpha > \sqrt{\alpha^2 - \omega_0^2} \Rightarrow s_2 = -\alpha + \sqrt{\alpha^2 - \omega_0^2} < 0$$

negative real roots

$$V(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} \quad \checkmark$$

$\Rightarrow A_1$  and  $A_2$  are real numbers.

$$V(0) = V_C(0) = V_0$$

$t=0$

$$V_0 = A_1 + A_2 \quad \text{—————} \quad \textcircled{1}$$

$$\frac{dV}{dt} = A_1 s_1 e^{s_1 t} + A_2 s_2 e^{s_2 t}$$

$$I_R(t) + I_L(t) + I_C(t) = 0 \quad \forall t \geq 0$$

$$I_R(0) + I_L(0) + I_C(0) = 0$$

$$I_R(0) = \frac{V_R(0)}{R} = \frac{V(0)}{R} = \frac{V_0}{R}$$

$$\begin{aligned} I_C(0) &= -I_R(0) - I_L(0) \\ &= -\frac{V_0}{R} - I_0 \end{aligned}$$

$$\frac{dV(0)}{dt} = \frac{dV_C(0)}{dt} = \frac{1}{C} I_C(0) = -\frac{1}{C} \left( I_0 + \frac{V_0}{R} \right)$$

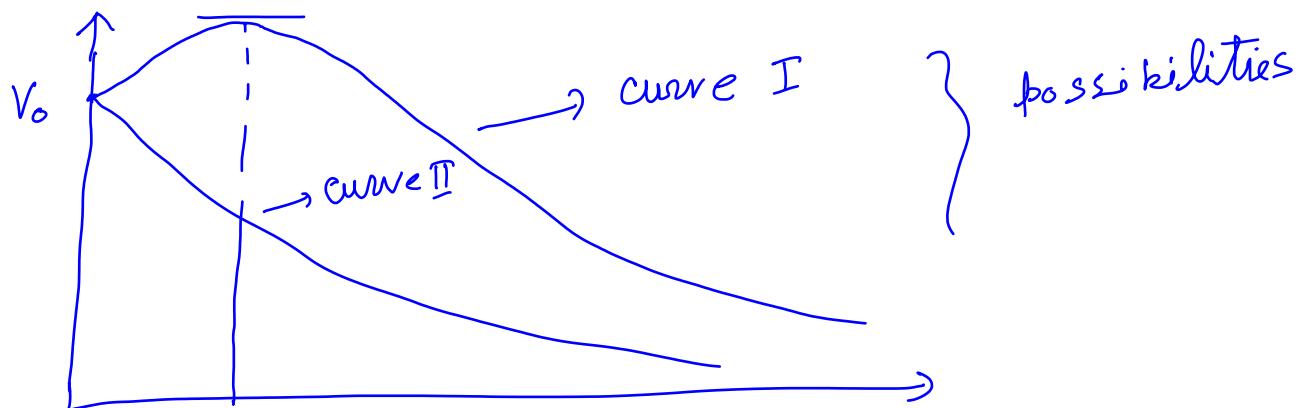
$$\frac{dV}{dt} = A_1 s_1 e^{s_1 t} + A_2 s_2 e^{s_2 t}$$

$\downarrow$   
 $t=0$

$$-\frac{1}{C} \left( I_0 + \frac{V_0}{R} \right) = A_1 s_1 + A_2 s_2 \quad \text{--- (11)}$$

Solve for  $A_1$  and  $A_2$  from (1) and (11).

$$V(\infty) = 0 \quad \text{because} \quad s_1, s_2 < 0$$

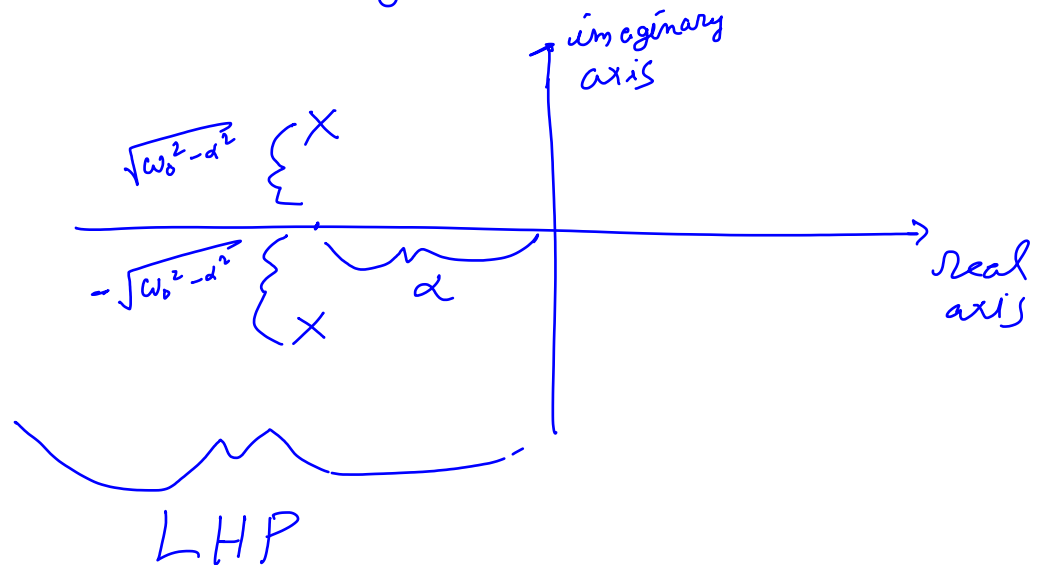


$(\alpha < \omega_0) \rightarrow$  Underdamped System

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$= -\alpha \pm \sqrt{(-1)(\omega_0^2 - \alpha^2)}$$

$$= -\alpha \pm j \sqrt{(\omega_0^2 - \alpha^2)}, \quad (j = \sqrt{-1})$$



$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$e^{j\omega t} = \cos \omega t + j \sin \omega t$$

$$\omega_d = \sqrt{\omega_0^2 - \alpha^2}$$

$$\Rightarrow s_{1,2} = -\alpha \pm j\omega_d$$

$$\Rightarrow v(t) = e^{-\alpha t} (A_1 e^{j\omega_d t} + A_2 e^{-j\omega_d t})$$

$$A_1 = \gamma_1 + j\delta_1$$

$$A_2 = \gamma_2 + j\delta_2$$

$$v(t) = e^{-\alpha t} \left( (\gamma_1 + j\delta_1) e^{j\omega_d t} + (\gamma_2 + j\delta_2) e^{-j\omega_d t} \right)$$

$$= e^{-\alpha t} \left( (\gamma_1 + j\delta_1) (\cos \omega_d t + j \sin \omega_d t) + (\gamma_2 + j\delta_2) (\cos \omega_d t - j \sin \omega_d t) \right)$$

$$v(0) = (\gamma_1 + j\delta_1) + (\gamma_2 + j\delta_2)$$

$$= (\gamma_1 + \gamma_2) + j(\delta_1 + \delta_2)$$

$$\Rightarrow \delta_1 + \delta_2 = 0 \quad \checkmark$$

$$\delta_1 = \delta \quad \Rightarrow \quad \delta_2 = -\delta$$

$$v(t) = e^{-\alpha t} \left( A_1 e^{j\omega_d t} + A_2 e^{-j\omega_d t} \right)$$

$$\begin{aligned} \frac{dv(t)}{dt} &= -\alpha e^{-\alpha t} (A_1 e^{j\omega_d t} + A_2 e^{-j\omega_d t}) \\ &\quad + e^{-\alpha t} (A_1 j\omega_d e^{j\omega_d t} - A_2 j\omega_d e^{-j\omega_d t}) \end{aligned}$$

$$\frac{dv(0)}{dt} = -\alpha (A_1 + A_2) + A_1 j\omega_d - A_2 j\omega_d$$

$$= -\alpha (\gamma_1 + j\delta + \gamma_2 - j\delta) + (\gamma_1 + j\delta) \cdot j\omega_d \\ - (\gamma_2 - j\delta) j\omega_d$$

$$= -\alpha(\gamma_1 + \gamma_2) + j\omega_d(\gamma_1 - \gamma_2) \\ - \delta\omega_d - \delta\omega_d$$

$$= -\alpha(\gamma_1 + \gamma_2) - 2\delta\omega_d + j\omega_d(\gamma_1 - \gamma_2)$$

$$\Rightarrow \gamma_1 - \gamma_2 = 0$$

$$\Rightarrow \gamma_1 = \gamma_2 = \gamma$$

$$\left. \begin{array}{l} A_1 = \gamma + j\delta \\ A_2 = \gamma - j\delta \end{array} \right\} \begin{array}{l} \text{complex} \\ \text{conjugates} \end{array}$$

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$= e^{-\alpha t} \left( A_1 e^{j\omega_d t} + A_2 e^{-j\omega_d t} \right)$$

$$= e^{-\alpha t} \left( A_1 \cos \omega_d t + j A_1 \sin \omega_d t \right. \\ \left. + A_2 \cos \omega_d t - j A_2 \sin \omega_d t \right)$$

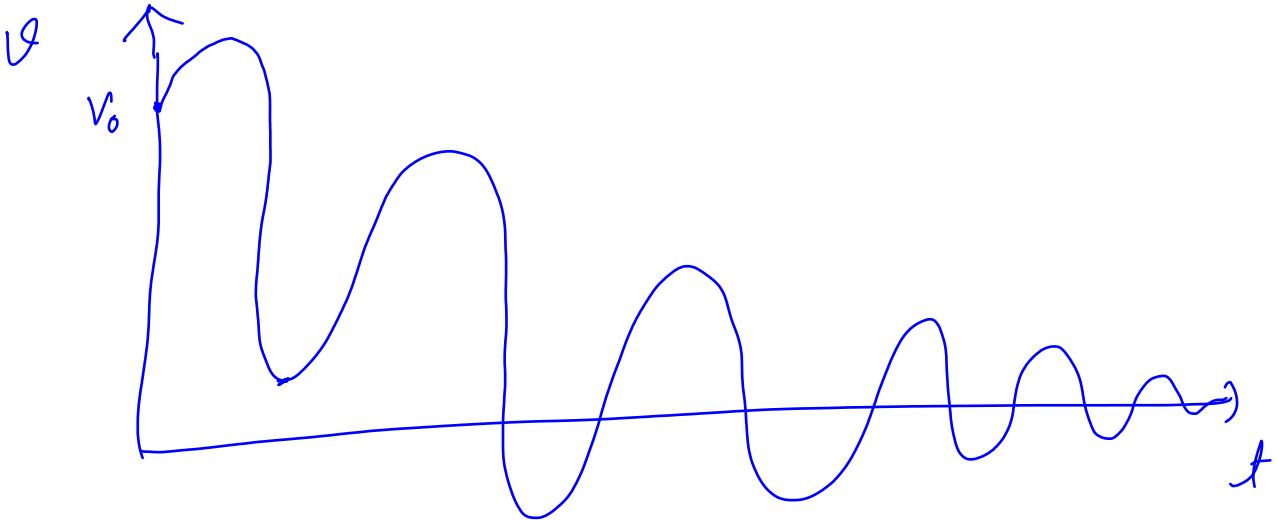
$$= e^{-\alpha t} \left( \underbrace{(A_1 + A_2)}_{2\gamma} \cos \omega_d t + j \underbrace{(A_1 - A_2)}_{-2\delta} \sin \omega_d t \right)$$

$$V(t) = e^{-\alpha t} \left( A_d \cos \omega_d t + B_d \sin \omega_d t \right)$$

$A_d, B_d$  are real numbers

$$(A_d = 2\gamma, B_d = -2\delta)$$

$$V(\infty) = 0$$



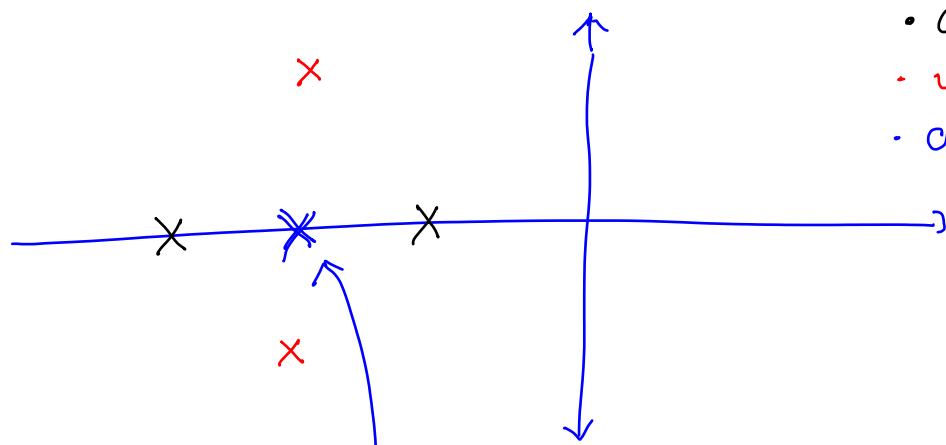
$\alpha = \omega_0$   $\rightarrow$  (Critically damped)

$$C \frac{d^2 V}{dt^2} + \frac{1}{R} \frac{dV}{dt} + \frac{1}{L} V = 0$$

$$\frac{d^2 V}{dt^2} + \frac{1}{RC} \frac{dV}{dt} + \frac{1}{LC} V = 0$$

$$\alpha = \frac{1}{2RC}, \quad \omega_0^2 = \frac{1}{LC}$$

$$\frac{d^2 V}{dt^2} + 2\alpha \frac{dV}{dt} + \alpha^2 V = 0$$



- overdamped
- underdamped
- critically damped

two roots  
are same (-ve)

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$= -\alpha \quad (\text{since } \alpha = \omega_0)$$

Let's assume,

$$v(t) = A_2 e^{st}$$

It's a valid  
solution

but, only unknown  $A_2$ , however, we have two initial conditions.

$$v(t) = A_1 t e^{st} \quad (\text{Assumption})$$

This is also  
a valid  
solution

$$\frac{dv(t)}{dt} = A_1 t s e^{st} + A_1 e^{st}$$

$$\frac{d^2 v}{dt^2} = A_1 t s^2 e^{st} + A_1 s e^{st} + A_1 s e^{st}$$



$$\frac{d^2 u}{dt^2} + 2\alpha \frac{du}{dt} + \alpha^2 u$$

$$= A_1 t s^2 e^{st} + A_1 s e^{st} + A_1 s e^{st} + 2\alpha (A_1 t s e^{st} + A_1 e^{st}) + \alpha^2 A_1 t e^{st}$$

$$= A_1 t \alpha^2 e^{-\alpha t} - A_1 \alpha e^{-\alpha t} - A_1 \alpha e^{-\alpha t} + 2\alpha (-A_1 t \alpha e^{-\alpha t} + A_1 e^{-\alpha t}) + \alpha^2 A_1 t e^{-\alpha t}$$

$$= 0$$

general solution

$$u(t) = A_1 t e^{st} + A_2 e^{st}$$

$$= e^{st} (A_1 t + A_2)$$

$$= e^{-\alpha t} (A_1 t + A_2)$$

