

## Lecture: 2

8/01/25

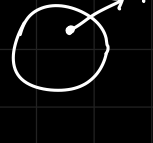
- Gradient operator
- Level surface

$$\text{Directional derivative: } \frac{d\phi}{dr} = (\bar{\nabla}\phi) \cdot \hat{r} = |\bar{\nabla}\phi| \cos\theta$$

$$\left| \frac{d\phi}{dr} \right|_{\max} = |\bar{\nabla}\phi|$$

- for a level surface, directional derivative is along the surface normal

eg. for a sphere, the direction  $\hat{r}$  at a specific point will be outwards from that point



$$\bar{r} = x\hat{x} + y\hat{y} + z\hat{z}$$

$$d\bar{r} = dx\hat{x} + dy\hat{y} + dz\hat{z}$$

$$\phi(x, y, z) : \text{func of } x, y, z$$

$$d\phi = \frac{\partial\phi}{\partial x} dx + \frac{\partial\phi}{\partial y} dy + \frac{\partial\phi}{\partial z} dz$$

## Potential

$$\text{1 dimension: } \bar{E} = -\frac{d\phi}{dx} \hat{x} \quad \text{electrostatic potential}$$

$$\text{3 dimension: } \bar{E} = -\left( \frac{\partial\phi}{\partial x} \hat{x} + \frac{\partial\phi}{\partial y} \hat{y} + \frac{\partial\phi}{\partial z} \hat{z} \right)$$

## Cylindrical coordinates

$$\rho, \phi, z$$

differential length

differential area

differential solid angle

## Spherical coordinates

$$0 \leq r < \infty \quad 0 \leq \theta \leq \pi \quad 0 \leq \phi \leq 2\pi$$

differential length

differential area

$$\text{differential solid angle} = \frac{\text{length of arc}}{\text{area}} = \frac{ds}{r^2} = \sin\theta d\theta d\phi$$

## Line Integral

$$\text{WORK: } \int_A^B \bar{F} \cdot d\bar{l} \rightarrow \text{for any force} \quad \left. \begin{array}{l} \text{Electrostatic: } \Phi_{AB} = -\int_A^B \bar{E} \cdot d\bar{l} \\ \text{potential} \end{array} \right\} \text{path dependent}$$

- Note: some are path independent

$$\text{assume: } \bar{V} = \bar{\nabla}u$$

$$\int_A^B \bar{V} \cdot d\bar{l} = \int_A^B (\bar{\nabla}u) \cdot d\bar{l} = \int_A^B du = u_B - u_A$$

here, path independent

← only depends on end points

- A field which can be written as the gradient of a scalar is called

conservative field

- note: <sup>represented as gradient of gravitational potential</sup> gravitational and <sup>represented as gradient of electrostatic potential</sup> electric fields are conservative whereas magnetic field cannot be represented as the gradient of a scalar.

$$\text{for closed loop} \rightarrow \oint_A^B \bar{V} \cdot d\bar{l} = \int_A^B du + \int_B^A du = u_B - u_A + u_A - u_B = 0$$

So, work done by a conservative field in a closed loop is zero.

i.e. closed loop line integral = 0

## FLUX

$$\text{open surface: } \int_{S_{\text{closed}}} \bar{V} \cdot d\bar{s}$$

$$\text{closed surface: } \oint_{S_{\text{open}}} \bar{V} \cdot d\bar{s}$$

$$\oint_{S_{\text{closed}}} \bar{V} \cdot d\bar{s} = \lim$$

## Divergence operator

$$\bar{\nabla} = \left( \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right)$$

$$\text{Gradient of } \left\{ \begin{array}{l} \text{dot product of vector} = \text{Divergence operator} \\ \text{Cross product of vector} = \text{CURL} \\ \text{scalar} = \text{Conservative field} \end{array} \right.$$

if  $\bar{\nabla} \times \bar{A} = 0$  it does not necessarily mean they are parallel because you cannot practically determine direction of  $\frac{\partial}{\partial x} / \frac{\partial}{\partial y} / \frac{\partial}{\partial z} / \bar{\nabla}$

Some goes for dot product as well

$$\text{divergence for a very small surface} = \frac{\text{total outward flux}}{\text{volume}}$$