

Mobile Robotics

Multi-view triangulation and Non-linear optimization Assignment -4

Submitted By:

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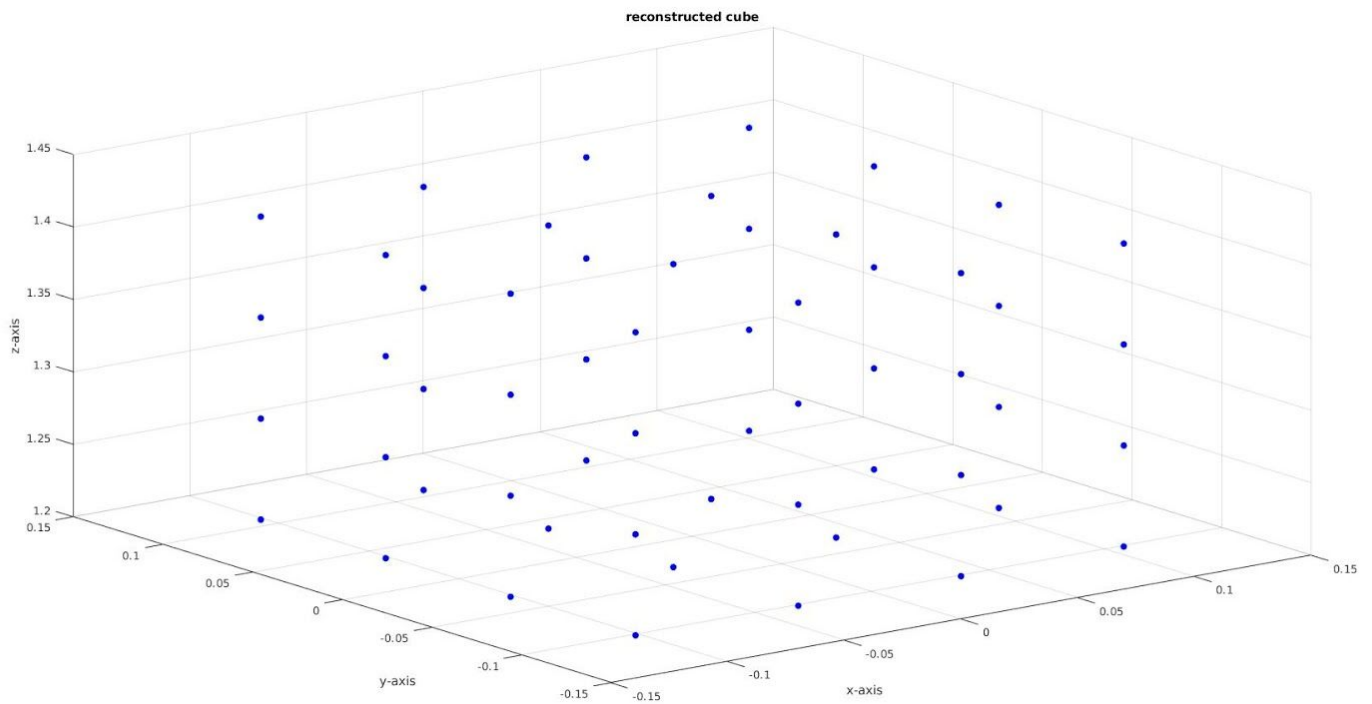
Note:

Q1.) Run 'Q1_main.m' to reconstruct the 3D image of cube using multi view triangulation.

Q2.) Run 'testLevenbergMarquardt.m' for the error plots and estimated parameters using LM algorithm.

OUTPUTS:

Q1.)



Q2.)

