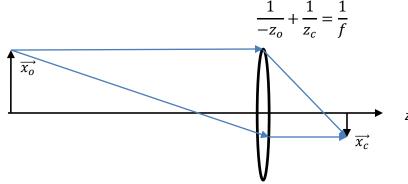
HW #1

1. Prove that for a thin lens, the image is in focus when



Reason as follows: A ray leaving the object at $\overrightarrow{x_o} = (y_o, z_o)$ parallel to the z axis passes through the lens, then bends to pass through focal point (0, f) before hitting the image plane at $\overrightarrow{x_c} = (y_c, z_c)$. If the image is in focus, then similarly, a ray leaving the object at $\overrightarrow{x_o}$ passing through the negative focal point (0, -f) will be bent parallel to the z axis and hit the image plane at the same point $\overrightarrow{x_c}$.

Hint: As discussed in class, consider similar triangles from the lens to the focal point and the focal point to the image plane. There are 2 pairs of similar triangles, one for the positive and negative focal point. Then show that

$$-z_c f + z_o f = z_c z_o$$

- 2. A typical human eyeball is 2.4 cm in diameter and contains roughly 150,000,000 receptors. Ignoring the fovea, assume that the receptors are uniformly distributed across a hemisphere (it is actually closer to 160°).
 - a. How many receptors are there per mm²?
 - b. Mars has a diameter of 8,000 km and an average distance from Earth of 225,000,000 km. Using a value of f equal to the eye's diameter, on how many receptors does the image of Mars fall?
- 3. An image has object and background pixels whose brightness values are distributed according to the Gaussian (Normal) distribution with the same mean μ but different variances σ_0 and σ_b with $\sigma_0 < \sigma_b$.

$$P_o(x) = \frac{1}{\sqrt{2\pi}\sigma_o} e^{-\frac{1}{2}\frac{x^2}{2\sigma_o^2}}$$
 and $P_b(x) = \frac{1}{\sqrt{2\pi}\sigma_b} e^{-\frac{1}{2}\frac{x^2}{2\sigma_b^2}}$

It is desired to segment the image into object and background. Show that the decision rule that maximizes the probability of a correct decision is to label each pixel with brightness x as *object* if

$$|x - \mu| < \sigma_o \sigma_b \sqrt{2 \frac{\ln \sigma_b - \ln \sigma_o}{\sigma_b^2 - \sigma_o^2}}$$

and background otherwise.

4. In heterogeneous coordinates, a rotation followed by a translation is represented by

$$\begin{bmatrix} \mathbf{R} & \vdots & \overrightarrow{T} \\ \cdots & & \cdots \\ 0 & \vdots & 1 \end{bmatrix}$$

What is the inverse operation? Hint: It is not $\begin{bmatrix} \mathbf{R}^{-1} & \vdots & -\vec{T} \\ \dots & & \dots \\ 0 & \vdots & 1 \end{bmatrix}.$

- 5. Not for extra credit: Binarize your selfie from HW0 in 2 ways:
 - a. Threshold the image such that \sim 50% of the pixels are black and \sim 50% are white.
 - b. Some other method of your choosing. Explain your method.