

# Aditya Mehrotra

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## EDUCATION

**Worcester Polytechnic Institute** - Worcester, MA, USA May 2023  
Master of Science in Robotics Engineering 4.0/4.0  
Coursework: Computer Vision, Deep Learning, Artificial Intelligence, Robot Dynamics, Controls

**Manipal Institute of Technology** - Manipal, India Nov 2019  
Bachelor of Technology in Mechanical Engineering  
Minor Specialization in Design

## SKILLS

**Engineering:** Fusion 360, SolidWorks, CATIA, AutoCAD, Ansys, FluidSim, 3D Printing  
**Robotics:** ROS, Eigen, OpenCV, Open 3D, Sci-Kit Learn, PyGame, Blender  
**Simulation Software:** Gazebo, Webots, CoppeliaSim, Unity 3D, AMBF  
**Electronics:** Arduino, Raspberry Pi, Nucleo, Micro:bit, 8085 MPU, ATmega8, NI MultiSim, Eagle  
**Programming:** C++, Python, Java, C, Matlab, Linux, Git, Latex, Visual Basic, HTML  
**Others:** Photoshop, Illustrator, Flash, Premiere, Microsoft Office (Word, Excel, PowerPoint)  
**Languages:** English (Fluent), French (Intermediate A2), Spanish (Intermediate A2), German (Elementary A1), Hindi (Native)

## INDUSTRY EXPERIENCE

**Boston Scientific** - Worcester, USA Jan 2022 - Present  
Graduate Research Assistant PracticePoint, WPI  
• Developing a surgical device with the KUKA LBR iiwa. [Work protected by NDA]

**Miko** - Mumbai, India Apr 2021 - Aug 2021  
Robotics Engineer - I Robotics Division  
• Simulated Robot Motion, LED Controller, Display, ToF modules of the two product versions of an autonomous social robot on Webots  
• Implemented PID control and Odometry on the robot  
• Added modules and maintained a Java-based utility software

**BaseApp Systems** - Delhi, India Mar - Apr 2021  
Junior Robotics Engineer Startup for Embedded Systems & Warehouse Robotics  
• Explored Navigation Stack in ROS running on Raspberry Pi  
• Prepared test guided path designs for Autonomous Guided Vehicles in warehouse environment  
• Implemented an SMTP Server

**Maruti Suzuki India Limited** - Gurgaon, India Jun - July 2018  
Intern Vehicle Inspection Department  
• Prepared Work Instruction Sheets for inspection line technicians

**Seelen HealthTech Pvt Ltd** - Manipal, India Feb - Dec 2017  
Product Development Intern Startup for Oral Cancer Rehabilitation Device  
• Created the model mechanism for the prototype  
• Fabrication through milling and 3D printing techniques  
• Provided support in PCB designing and clinical trials

**Air India Engineering Services** - Mumbai, India Jun - July 2017  
Trainee Engine Overhauling Department  
• Assisted in overhauling of CFM56, GE90, & GEnX commercial airline engines

## RESEARCH EXPERIENCE

**École Polytechnique Fédérale de Lausanne** - Lausanne, Switzerland Sep 2019 - Aug 2020  
**& University of Applied Sciences and Arts of Southern Switzerland** - Lugano, Switzerland Feb - Aug 2020  
Visiting Research Assistant Mobots Group | Department of Education & Learning  
• Developed a Computer Vision-based tangible programming platform  
• Created an inexpensive Maker-based Educational Robot  
• Designed & analyzed experimental studies, published multiple scientific papers

**Zurich University of Applied Sciences** - Winterthur, Switzerland Jan - Sep 2019  
Research Intern Institute of Mechatronic Systems  
• Optimized the design of an industrial Delta Robot, analyzed its working area and static stiffness  
• Fabricated and commissioned a Fused Deposition Modelling Printer  
• Prepared a detailed report on the undertaken projects | [dx.doi.org/10.13140/RG.2.2.25342.10568](https://doi.org/10.13140/RG.2.2.25342.10568)

**Manipal Institute of Technology** – Manipal, India

Undergraduate Research Assistant

May 2016 - Jun 2018

Biomedical Department

- Developed the prototype of a gesture-controlled robotic arm | [dx.doi.org/10.13140/RG.2.2.25650.84169](https://doi.org/10.13140/RG.2.2.25650.84169)
- Developed a multi-level 3D game for the therapy of Tremor patients | [dx.doi.org/10.13140/RG.2.2.24811.98085](https://doi.org/10.13140/RG.2.2.24811.98085)
- Provided support for the development of a surgical fluid collection device

**PUBLICATIONS**

Mehrotra, Aditya, et al. *"Accessible Maker-Based Approaches to Educational Robotics in Online Learning."* IEEE Access 9 (2021): 96877-96889. | [doi.org/10.1109/ACCESS.2021.3094158](https://doi.org/10.1109/ACCESS.2021.3094158)

Mehrotra, Aditya, et al. *"Introducing a Paper-Based Programming Language for Computing Education in Classrooms."* Proceedings of the 2020 ACM Conference on Innovation and Technology in Computer Science Education. 2020. [dl.acm.org/doi/pdf/10.1145/3341525.3387402](https://dl.acm.org/doi/pdf/10.1145/3341525.3387402)

**AWARDS**

- |                              |  |          |
|------------------------------|--|----------|
| • 8th International position | University Rover Challenge                           | Jun 2018 |
| • National Qualifier Funding | Defence Research & Development Organisation of India | May 2018 |
| • State Qualifier Funding    | Defence Research & Development Organisation of India | Jan 2018 |

**PROJECTS****Inverse Dynamics Controller for the da Vinci Research Kit - Worcester, MA** Sept 2021 - Present

- Modeled Forward & Inverse Kinematics for multiple models of the Patient Side Manipulator (PSM) of the da Vinci Research Kit
- Developed ROS nodes on C++ to communicate with the simulator Asynchronous Multi-Body Framework (AMBF)
- Implemented Inverse Dynamics control for gravity compensation

**Incremental Structure from Motion - Worcester, MA** Sept 2021 - Present

- Calibrated camera intrinsic parameters, implemented feature tracking, estimation of the camera essential matrix
- Executed the incremental structure from motion pipeline to create a sparse 3D reconstruction of scene with Open3D

**Machine Learning for Computing Education - Worcester, MA** Sept 2021 - Present

- Preprocessed dataset using the Sci-Kit Learn & ProgSnap2 library and extracted relevant features
- Modeled students' cognitive knowledge by developing regression models and predicted performance
- Authored a paper on the results

**Lower Limb Active Orthosis Exoskeleton - Manipal, India** May 2016 - Jun 2018

- Designed multiple 2 DoF mechanisms with linear electromechanical actuators on CAD, and modeled mechanism kinematics
- Programmed an open-loop controller for the gait and wireless joystick control with C++
- Fabricated the mechanical prototype with lightweight construction and rapid prototyping techniques
- Designed and fabricated PCB inhouse
- Led the team to the National Showcase of DRUSE 2018 organized by Defence Research & Development Organisation (DRDO) of India | [doi.org/10.13140/RG.2.2.23577.24169](https://doi.org/10.13140/RG.2.2.23577.24169)

**Mars Rover Manipal - Manipal, India** Aug 2017 - Jan 2018

- Management Head for the Mars Rover Student Team the University Rover Challenge
- Organized events, sourced components, sponsorships, managed funds and administration

**Engineers Without Borders - Manipal, India** Jan 2017 - Dec 2018

- Conducted a "SolidWorks for Beginners" workshop for professionals
- Conducted literacy survey in economically deprived communities around Udupi, Karnataka
- Designed an automated suntracking solar panel based on ATMega 328

**MEMBERSHIPS**

- |   |                      |
|---|----------------------|
| • Engineers Without Borders   | Sept 2016 - Nov 2019 |
| • International Association for the Exchange of Students for Technical Experience | Oct 2017 - Nov 2019  |
| • IECSE (Computer Science Engineering Club), Manipal, India                       | Sept 2016 - Nov 2019 |
| • The Astronomy Club, Manipal   | Jan 2017 - Nov 2019  |