Aditya Mehrotra

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EDUCATION

Worcester Polytechnic Institute – Worcester, MA, USA   May 2023
Master of Science in Robotics Engineering
Coursework: Computer Vision, Artificial Inteliigence, Robot Dynamics

Manipal Institute of Technology – Manipal, India   Nov 2019
Bachelor of Technology in Mechanical Engineering
Minor Specialization in Design

SKILLS

Engineering : Fusion 360, SolidWorks, CATIA, AutoCAD, Ansys, FluidSim, 3D Printing
Robotics : ROS, OpenCV, Open 3D, Sci-Kit Learn, Webots, Blender, CoppeliaSim, Unity 3D
Electronics: Arduino, Raspberry Pi, Nucleo, Micro:bit, 8085 MPU, ATmega8, NI MultiSim, Eagle
Programming : C++, Python, Java, C, Matlab, Linux, Git, Visual Basic, HTML
Others : Photoshop, Illustrator, Flash, Premiere, Microsoft Office (Word, Excel, PowerPoint)
Languages : English (Fluent), French (Intermediate A2), Spanish (Intermediate A2), German (Elementary A1), Hindi (Native)

INDUSTRY EXPERIENCE

Boston Scientific – Worcester, USA   Jan 2022
Graduate Research Assistant   PracticePoint, WPI
• Developing robotic endoscopic & urology devices. [Work protected by NDA]

Miko – Mumbai, India   Apr 2021 - Aug 2021
Robotics Engineer – I   Robotics Division
• Simulated Robot Motion, RGB Controller, Display, ToF modules of the two product versions of an autonomous social robot
  on Webots
• Implemented PID control and Odometry on the robot
• Added modules and maintained a Java-based utility software

BaseApp Systems – Delhi, India   Mar - Apr 2021
Junior Robotics Engineer   Startup for Embedded Systems & Warehouse Robotics
• Explored Navigation Stack in ROS running on Raspberry Pi
• Prepared test guided path designs for Autonomous Guided Vehicles in warehouse environment
• Implemented an SMTP Server

Maruti Suzuki India Limited – Gurgaon, India   Jun - July 2018
Intern   Vehicle Inspection Department
• Prepared Work Instruction Sheets for inspection line technicians

Seelen HealthTech Pvt Ltd – Manipal, India   Feb - Dec 2017
Product Development Intern   Startup for Oral Cancer Rehabilitation Device
• Created the model mechanism for the prototype
• Fabrication through milling and 3D printing techniques
• Provided support in PCB designing and clinical trials

Air India Engineering Services – Mumbai, India   Jun - July 2017
Trainee   Engine Overhauling Department
• Assisted in overhauling of CFM56, GE90, & GEnX commercial airline engines

RESEARCH EXPERIENCE

École Polytechnique Fédérale de Lausanne – Lausanne, Switzerland   Sep 2019 - Aug 2020
& University of Applied Sciences and Arts of Southern Switzerland - Lugano, Switzerland   Feb - Aug 2020
Visiting Research Assistant   Mobots Group | Department of Education & Learning
• Developed a Computer Vision-based tangible programming platform
• Created an inexpensive Maker-based Educational Robot
• Designed & analyzed experimental studies, published multiple scientific papers

Zurich University of Applied Sciences – Winterthur, Switzerland   Jan - Sep 2019
Research Intern   Institute of Mechatronic Systems
• Optimized the design of an industrial Delta Robot, analyzed its working area and static stiffness
• Fabricated and commissioned a Fused Deposition Modelling Printer
• Prepared a detailed report on the undertaken projects | dx.doi.org/10.13140/RG.2.2.25342.10568

Manipal Institute of Technology – Manipal, India   May 2016 - Jun 2018
Undergraduate Research Assistant   Biomedical Department
• Developed the prototype of a gesture-controlled robotic arm | dx.doi.org/10.13140/RG.2.2.25650.84169
• Developed a multi-level 3D game for the therapy of Tremor patients | dx.doi.org/10.13140/RG.2.2.24811.98085
• Provided support for the development of a surgical fluid collection device

PUBLICATIONS

Mehrotra, Aditya, et al. "*Accessible Maker-Based Approaches to Educational Robotics in Online Learning.*" IEEE Access 9 (2021): 96877-96889.| doi.org/10.1109/ACCESS.2021.3094158

Mehrotra, Aditya, et al. "*Introducing a Paper-Based Programming Language for Computing Education in Classrooms.*" Proceedings of the 2020 ACM Conference on Innovation and Technology in Computer Science Education. 2020.
dl.acm.org/doi/pdf/10.1145/3341525.3387402

AWARDS

• 8th International position   University Rover Challenge   Jun 2018
• National Qualifier Funding   Defence Research & Development Organisation of India   May 2018
• State Qualifier Funding   Defence Research & Development Organisation of India   Jan 2018

PROJECTS

Inverse Dynamics Controller for the da Vinci Research Kit - Worcester, MA   Sept 2021 - Present
• Modeled Forward & Inverse Kinematics for multiple models of the Patient Side Manipulator (PSM) of the da Vinci Research Kit
• Developed ROS nodes on C++ to communicate with the simulator Asynchronous Multi-Body Framework (AMBF)
• Implemented Inverse Dynamics control for gravity compensation

Incremental Structure from Motion - Worcester, MA   Sept 2021 - Present
• Calibrated camera intrinsic parameters, implemented feature tracking, estimation of the camera essential matrix
• Performed RANSAC for outlier rejection, estimated camera pose from essential matrix
• Imposed cheirality condition for Triangulation
• Implemented Perpsective-N-Point algorithm and bundle adjustment for Sparse 3D reconstruciton

Machine Learning for Computing Education - Worcester, MA   Sept 2021 - Present
• Using students' programming classroom datasets to model their cognitive knowledge
• Preprocessed dataset using the Sci-Kit Learn & ProgSnap2 library and extraced relevant features
• Applyed models of Random Forrest Regression, Deep Knowledge Tracing and Performance Factor Analysis to predict
  student performance
• Authored a paper on the results

Lower Limb Active Orthosis Exoskeleton - Manipal, India   May 2016 - Jun 2018
• Designed multiple 2 DoF mechanisms with linear electromechanical actuators on CAD, and modeled mechanism kinematics
• Programmed an open-loop controller for the gait and wireless joystick control with C++
• Fabricated the mechanical prototype with lightweight construction and rapid prototyping techniques
• Designed and fabricated and inhouse PCB
• Led the team to the National Showcase of the DRDO Robotics and Unmanned Systems Exposition (DRUSE) 2018 organized
  by Defence Research & Development Organisation (DRDO) of India | doi.org/10.13140/RG.2.2.23577.24169

Mars Rover Manipal - Manipal, India   Aug 2017 - Jan 2018
• Management Head for the Mars Rover Student Team the University Rover Challenge
• Organized events, sourced components, sponsorships, managed funds and administration

Engineers Without Borders - Manipal, India   Jan 2017 - Dec 2018
• Conducted a SolidWorks for Beginners workshop for professionals with the Engineers Without Borders: Manipal Chapter
• Conducted literacy surveys in economically deprived communities around Udupi, Karnataka
• Designed an automed suntracking solar panel based on ATMega 328

MEMBERSHIPS

• Engineers WIthout Borders   Sept 2016 - Nov 2019
• International Association for the Exchange of Students for Technical Experience   Oct 2017 - Nov 2019
• IECSE (Computer Science Engineering Club), Manipal, India   Sept 2016 - Nov 2019
• The Astronomy Club, Manipal   Jan 2017 - Nov 2019