

# Aditya Mehrotra

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## EDUCATION

<b>Worcester Polytechnic Institute</b> - Worcester, MA, USA	July 2023
Master of Science in Robotics Engineering	4.0/4.0
Coursework: Deep Learning, Computer Vision, Artificial Intelligence, Motion Planning, Robot Dynamics, Controls	
<b>Manipal Institute of Technology</b> - Manipal, India	Nov 2019
Bachelor of Technology in Mechanical Engineering	
Minor Specialization in Design	

## SKILLS

**Robotics:** PyTorch, CUDA, OpenCV, OpenMMLab, Open3D, Open Gym, Sci-Kit Learn, ROS, Eigen, oneTBB, GoogleTest  
**Programming:** C++, Python, MATLAB, Java, Linux, Git, PerForce, Latex, Docker, AWS  
**Simulation Software:** , OpenGL, Gazebo, RViz, Unity, Webots, CoppeliaSim, AMBF, PyGame, Blender  
**Electronics:** Raspberry Pi, Arduino, Nucleo, Micro:bit, 8085 MPU, ATmega8, NI MultiSim, Eagle  
**Languages:** English (Fluent), French (Intermediate A2), Spanish (Intermediate A2), German (Elementary A1)

## EXPERIENCE

<b>Amazon Robotics</b> - North Reading, MA	Jan 2023 - Present
Perception SDE Co-op	Scene Perception
<ul style="list-style-type: none"><li>Formulating algorithms for item state tracking in Sparrow robot workcell through multi-modal identification</li><li>Leveraging vision transformer-based Dino model for generalizable feature extraction</li><li>Building pipeline, service, imaging algorithm packages (Hungarian assignment), tests, and multithreading in modern C++</li></ul>	
<b>MathWorks</b> - Natick, MA, USA	May - Aug 2022
AI Software Intern	Controls Applications and Charting
<ul style="list-style-type: none"><li>Prepared Requirement and Functional Design Specifications for a high-priority fuzzy clustering enhancement</li><li>Implemented and tested the Gustafson-Kessel algorithm for the 2023a release of the Fuzzy Logic Toolbox on MATLAB</li><li>Developed a MATLAB Example on Brain Tumour MR Image Segmentation using clustering techniques</li></ul>	
<b>Boston Scientific</b> - Worcester, MA, USA	Jan - May 2022
Graduate Research Assistant	PracticePoint, WPI
<ul style="list-style-type: none"><li>Developed cartesian velocity control for KUKA LBR iiwa on MATLAB and ROS communicating with Java Sunrise controller</li></ul>	
<b>Miko</b> - Mumbai, India	Apr 2021 - Aug 2021
Robotics Engineer - I	Robotics Division
<ul style="list-style-type: none"><li>Simulated robot motion and modules with multi-threading for an autonomous social robot on Webots</li><li>Implemented PID control and Odometry on the robot, added modules and maintained a Java-based utility software</li></ul>	
<b>BaseApp Systems</b> - Delhi, India	Mar - Apr 2021
Junior Robotics Engineer	Startup for Embedded Systems & Warehouse Robotics
<ul style="list-style-type: none"><li>Pioneered Robotics Navigation at the firm in ROS running on Raspberry Pi 3</li><li>Prepared test guided path designs for Autonomous Guided Vehicles in warehouse environment</li></ul>	
<b>École Polytechnique Fédérale de Lausanne</b> - Lausanne, Switzerland	Sep 2019 - Aug 2020
Visiting Research Assistant	Mobots Group
<ul style="list-style-type: none"><li>Explored and developed Image Object Detection techniques for a tangible programming platform</li><li>Created an inexpensive Maker-based Educational differential-drive Robot, published multiple papers</li></ul>	

## PROJECTS

<b>Exploring Transfer Learning for 3D Object Detection</b>	Sept 2022 - Present
<ul style="list-style-type: none"><li>Explored the VoxelNet, SECOND and PointPillars networks on PyTorch with the MMDetection3D framework</li><li>Experimented with cross testing and tuning learning rates with the KITTI and nuScenes dataset</li></ul>	
<b>Video Instance Segmentation using MaskTrack R-CNN</b>	Mar - May 2022
<ul style="list-style-type: none"><li>Explored attention-based mechanisms in the FPN and inter-frame affinity to improve mask propagation for end-to-end video instance segmentation</li><li>Compared results to the YouTube-VIS benchmark using the MaskTrack R-CNN pipeline and MMDet toolbox on PyTorch</li></ul>	
<b>Incremental Structure from Motion</b>	Sept - Dec 2021
<ul style="list-style-type: none"><li>Calibrated camera intrinsic parameters, implemented feature tracking, estimation of the camera essential matrix</li><li>Implemented Triangulation, PnP algorithm, bundle adjustment optimization to create a sparse 3D reconstruction of scene with Open3D</li></ul>	
<b>Mini projects</b>	Dec 2021- May 2022
<ul style="list-style-type: none"><li>Generare fake images using a GAN architecture with TensorFlow on the MNIST, CIFAR-10 datasets</li><li>Implemented a Deep Reinforcement Learning architecture for 2D cartpole control</li></ul>	

## PUBLICATIONS

Mehrotra, Aditya, et al. *"Accessible Maker-Based Approaches to Educational Robotics in Online Learning."* IEEE Access 9 (2021): 96877-96889. | [doi.org/10.1109/ACCESS.2021.3094158](https://doi.org/10.1109/ACCESS.2021.3094158)

Mehrotra, Aditya, et al. *"Introducing a Paper-Based Programming Language for Computing Education in Classrooms."* Proceedings of the 2020 ACM Conference on Innovation and Technology in Computer Science Education. 2020. [dl.acm.org/doi/pdf/10.1145/3341525.3387402](https://dl.acm.org/doi/pdf/10.1145/3341525.3387402)