

ASSIGNMENT - 2

$$1. \vec{r}^n \vec{P} = (x^2 + y^2)^{\frac{n}{2}} (x\hat{i} + y\hat{j} + z\hat{k})$$

$\vec{v} \cdot (\vec{r}^n \vec{P})$

$$2. \vec{v} \cdot (\vec{r}^n \vec{P}) = \frac{1}{2x^2 \times \sin\theta} \frac{\partial}{\partial r} (r^{n+2} \times x^2 \sin\theta)$$

For $\frac{\partial}{\partial r} (r^{n+2} \times x^2 \sin\theta)$ to be 0,

$$2r^{n+1} = 2r^{-2} \Rightarrow n+1 = -2 \Rightarrow n = -3$$

$$2. (a) \text{Cartesian: } \vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$

$$\vec{v} \cdot (\vec{r}) = 1 + 1 + 1 = 3$$

$$(b) \text{cylindrical: } \vec{r} = e\hat{e}_r + z\hat{k}$$

$$\vec{v} \cdot (\vec{r}) = \frac{1}{2 \times r \times 1} \left[\frac{\partial [e^2]}{\partial e} + \frac{\partial [0]}{\partial \phi} + \frac{\partial [ze]}{\partial z} \right]$$

$$= \frac{1}{r} [2e + e] = 3$$

$$(c) \text{spherical: } \vec{r} = r\hat{e}_r$$

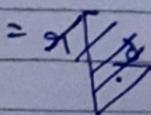
$$\vec{v} \cdot (\vec{r}) = \frac{1}{2 \times r \times r \sin\theta} \left[\frac{\partial (r^3 \sin\theta)}{\partial r} + 0 \right]$$

$$= \frac{3r^2 \sin\theta}{r^2 \sin\theta} = 3$$

$$3. \quad \vec{B} = \vec{\nabla} \times (A\phi(r, \theta)) \hat{e}_\phi$$

$$= \begin{vmatrix} \hat{e}_r & \hat{e}_\theta & \hat{e}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 0 & \cancel{e_\theta} & r \sin \theta \end{vmatrix}$$

$$= \frac{\partial (r \sin \theta A\phi)}{\partial \theta} \hat{e}_r - r \left(\frac{\partial (r \sin \theta A\phi)}{\partial r} \right) \hat{e}_\phi$$



$$\vec{v} = \vec{\nabla} \times \vec{B}$$

$$= \begin{vmatrix} \hat{e}_r & \hat{e}_\theta & \hat{e}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ \frac{\partial (r \sin \theta A\phi)}{\partial \theta} & -r \left(\frac{\partial (r \sin \theta A\phi)}{\partial r} \right) & 0 \end{vmatrix}$$

$$= \boxed{ \frac{\partial}{\partial \phi} \left[r \frac{\partial (r \sin \theta A\phi)}{\partial \theta} \right] \hat{e}_r + r \left(\frac{\partial}{\partial \theta} \left(\frac{\partial (r \sin \theta A\phi)}{\partial r} \right) \right) \hat{e}_\theta }$$

$$+ r \sin \theta \left[\frac{\partial}{\partial r} \left(-r \frac{\partial (r \sin \theta A\phi)}{\partial \theta} \right) \right]$$

$$- \frac{\partial^2 (r \sin \theta A\phi)}{\partial \theta^2} \hat{e}_\phi]$$

$$= r \sin\theta \left[\frac{\partial}{\partial r} \left(\cancel{r \sin\theta} \sin\theta \left(A\phi + \cancel{r \frac{\partial A\phi}{\partial r}} \right) \right) \right]$$

$$- r \frac{\partial}{\partial \theta} \left(\cos\theta A\phi + \sin\theta \frac{\partial A\phi}{\partial r} \right) \hat{e}_\theta$$

$$= r^2 \sin\theta \left[\sin\theta \left[\frac{\partial A\phi}{\partial r} + \frac{\partial A\phi}{\partial \theta} + r \frac{\partial^2 A\phi}{\partial r^2} \right] \right]$$

$$- \left[-\sin\theta A\phi + \cos\theta \frac{\partial A\phi}{\partial \theta} \right. \\ \left. + \cos\theta \frac{\partial A\phi}{\partial r} + \sin\theta \frac{\partial^2 A\phi}{\partial \theta^2} \right]$$

$$= \boxed{r^2 \sin\theta \left(2\sin\theta \frac{\partial A\phi}{\partial r} + r \sin\theta \frac{\partial^2 A\phi}{\partial r^2} \right. \\ \left. + \sin\theta A\phi - 2\cos\theta \frac{\partial A\phi}{\partial \theta} \right. \\ \left. - \sin\theta \frac{\partial^2 A\phi}{\partial \theta^2} \right) \hat{e}_\theta}$$

$$4. \nabla^2 \psi = 0 \Rightarrow \nabla \cdot (\nabla \psi) = 0$$

$$\nabla \psi = \frac{1}{r} \frac{\partial \psi}{\partial r} \hat{e}_r + \frac{1}{r} \frac{\partial \psi}{\partial \theta} \hat{e}_{\theta} + \frac{1}{r} \frac{\partial \psi}{\partial z} \hat{e}_z$$

$$= \boxed{\frac{\partial \psi}{\partial r} \hat{e}_r}$$

$$\therefore \nabla \cdot (\nabla \psi) = \frac{1}{r^2} \left[\frac{\partial}{\partial r} \left(\frac{\partial \psi}{\partial r} \right) \right]$$

$$= \frac{1}{r} * \frac{\partial}{\partial r} \left(r \frac{\partial \psi}{\partial r} \right) = 0.$$

$$\therefore \cancel{\frac{\partial^2 \psi}{\partial r^2}} \frac{1}{r} \left[\frac{\partial \psi}{\partial r} + \frac{r \partial^2 \psi}{\partial r^2} \right] = 0$$

(or)

$$\cancel{\frac{1}{r} \frac{\partial^2 \psi}{\partial r^2}}$$

$$\boxed{\frac{\partial^2 \psi}{\partial r^2} = -\frac{1}{r} \frac{\partial \psi}{\partial r}}$$

$$\boxed{\frac{\partial}{\partial r} \left(\frac{\partial \psi}{\partial r} \right) = -\frac{1}{r} \frac{\partial \psi}{\partial r}}$$

$$\ln \left(\frac{\partial \psi}{\partial r} \right) = -\ln(c r)$$

$$(or) \boxed{r \frac{\partial \psi}{\partial r} = c}$$

$$\int \frac{\partial P}{P} = \int k d\theta$$

$$\ln P = k\theta + C$$

$$\therefore \boxed{\Psi = k_1 \ln r + k_2}$$

$$5. \quad \vec{\nabla} f(r) = \frac{1}{r} \frac{\partial f(r)}{\partial r} \hat{e}_r + \frac{1}{r^2} \frac{\partial f(r)}{\partial \theta} \hat{e}_{\theta} + \frac{1}{r \sin \theta} \frac{\partial f(r)}{\partial \phi} \hat{e}_{\phi} = 0$$

$$= \boxed{\frac{df(r)}{dr} \hat{r}} = 0$$

$$6. \quad \vec{\nabla} r^n = \frac{df(r)}{dr} \hat{r} = \boxed{n r^{n-1} \hat{r}}$$

$$7. \quad (i) \quad X = 2z^2 p \cos \phi \quad \text{at} \quad (1, \pi/2, -1)$$

$$\vec{\nabla} X = \frac{1}{1} \frac{\partial (2z^2 p \cos \phi)}{\partial \theta} \hat{e}_{\theta} + \frac{1}{p} \frac{\partial (2z^2 p \cos \phi)}{\partial \phi} \hat{e}_{\phi}$$

$$+ \frac{1}{1} \frac{\partial (2z^2 p \cos \phi)}{\partial z} \hat{e}_z$$

$$= \boxed{2z^2 \cos \phi \hat{e}_\theta + -2z^2 \sin \phi \hat{e}_\phi + 4z^2 \cos \phi \hat{e}_z}$$

$$= 2(0) \hat{e}_\theta - 2(0) \hat{e}_\phi + (-4)(0) \hat{e}_z$$

$$= \boxed{-2 \hat{e}_\phi}$$

$$(ii) \chi = 2r\sin\theta\cos\phi \leftrightarrow \text{at } (1, \pi/2, \pi)$$

$$\vec{\nabla} \chi = \frac{1}{1} \times \frac{\partial (2r\sin\theta\cos\phi)}{\partial r} \hat{e}_r$$

$$+ \frac{1}{\pi} \times \frac{\partial (2r\sin\theta\cos\phi)}{\partial \theta} \hat{e}_{\theta}$$

$$+ \frac{1}{\sin\theta} \frac{\partial (2r\sin\theta\cos\phi)}{\partial \phi} \hat{e}_{\phi}$$

$$= 2\sin\theta\cos\phi \hat{e}_r + 2r\cos\theta\cos\phi \hat{e}_{\theta}$$

$$- 2\sin\phi \hat{e}_{\phi}$$

$$= 2(1)(-1) \hat{e}_r + 2(0)(-1) \hat{e}_{\theta}$$

$$- 2(0) \hat{e}_{\phi}$$

$$= \boxed{-2\hat{e}_r}$$

$$8. (i) \vec{v} \cdot (r\sin\phi \hat{e}_r + r^2 z \hat{e}_{\theta} + z\cos\phi \hat{z})$$

$$= \frac{1}{1 \times r \times 1} \left[\frac{\partial (r^2 \sin\phi)}{\partial r} + \frac{\partial (r^2 z)}{\partial \theta} + \frac{\partial (z \cos\phi)}{\partial z} \right]$$

$$= 2\sin\phi + 0 + 0 = \boxed{2\sin\phi}$$

$$(ii) \vec{v} \cdot \left(\frac{1}{r^2} \cos\theta \hat{r} + r\sin\theta \cos\phi \hat{\theta} + r\cos\theta \hat{z} \right)$$

$$= \frac{1}{r^2 \sin\theta} \left[\frac{\partial}{\partial r} \left(\frac{1}{r^2} \cos\theta \right) \sin\theta + \frac{\partial}{\partial \theta} (r^2 \sin^2\theta \cos\phi) \right. \\ \left. + \frac{\partial (r\cos\theta)}{\partial \phi} \right]$$

$$= \frac{\cos\theta}{\sin\theta}, 2\sin\theta\cos\theta = \boxed{2\cos\theta\cos\theta}$$

$$(iii) \vec{\nabla} \cdot [(2\rho + \rho \sin^2\theta) \hat{r} + (\rho \sin\phi \cos\phi) \hat{\phi} + z \hat{z}]$$

$$= \frac{1}{1 \times \rho \times 1} \left[\frac{\partial}{\partial \rho} (2\rho^2 + \rho^2 \sin^2\theta) + \frac{\partial}{\partial \phi} (\rho \sin\phi \cos\phi) \right.$$

$$\left. + \frac{\partial}{\partial z} (z\rho) \right]$$

$$= \frac{1}{\rho} \left[4\rho + 2\rho \sin^2\theta + \frac{\rho}{2} \times \cancel{\rho \cos(2\phi)} + 3\rho \right]$$

$$= \frac{1}{\rho} \left[4\rho + 2\rho \sin^2\theta + \rho \cos(2\phi) + 3\rho \right]$$

$$= \boxed{2\sin^2\theta + \cos(2\phi) + 7}$$

$$(iv) \vec{\nabla} \cdot ((\rho \sin\phi) \hat{r} + (\rho^2 z) \hat{\phi} + (z \cos\phi) \hat{z})$$

$$= \frac{1}{1 \times \rho \times 1} \left[\cancel{\frac{\partial}{\partial \rho}} (\rho^2 \sin\phi) + \frac{\partial}{\partial \phi} (\rho^2 z) + \frac{\partial}{\partial z} (z \rho \cos\phi) \right]$$

$$= \frac{1}{\rho} [2\rho \sin\phi + \rho \cos\phi]$$

$$= \boxed{2\sin\phi + \cos\phi}$$

$$9. \vec{G}(\varrho, \delta, z) = (-\cos^2 \delta \tanh \varrho) \hat{e}_r + \left[\sin^2 \delta \frac{(\cosh \varrho)^{\frac{1}{2}}}{\cosh z} \right] \hat{e}_{\delta} \\ + (\cos^2 \delta + \tanh z) \hat{e}_z$$

$$\vec{\nabla} \times \vec{G} = \frac{1}{1 \times r \times 1} \begin{vmatrix} \hat{e}_r & \hat{e}_{\delta} & \hat{e}_z \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \delta} & \frac{\partial}{\partial z} \\ G_r & G_{\delta} & G_z \end{vmatrix}$$

$$= \frac{1}{r} \left[\left(\frac{\partial}{\partial \delta} \left(\sin^2 \delta \frac{(\cosh \varrho)^{\frac{1}{2}}}{\cosh z} \right) \right) \right]$$

$$\begin{aligned}
 &= \frac{1}{e} \left[\left(\frac{\partial}{\partial \phi} (\cos^2 \phi + \tanh z) - \frac{\partial}{\partial z} \left(\sin 2\phi \ln \left(\frac{\cosh \rho}{\cosh z} \right) \right) \hat{e} \right. \right. \\
 &\quad - e \left(\frac{\partial}{\partial \rho} (\cos^2 \phi + \tanh z) - \frac{\partial}{\partial z} (-\cos^2 \phi \tanh \rho) \right) \hat{\phi} \\
 &\quad \left. \left. + \left(\frac{\partial}{\partial \rho} \left(\sin 2\phi \ln \left(\frac{\cosh \rho}{\cosh z} \right) \right) - \frac{\partial}{\partial \phi} (-\cos^2 \phi) \right) \hat{\rho} \right] \\
 &= \frac{1}{e} \left[(+2\sin\phi \cos\phi + \tanh z - \sin 2\phi \tanh z) \hat{e} \right. \\
 &\quad \left. - e(\hat{\phi}) \right. \\
 &\quad \left. + (\sin 2\phi \tanh \rho + (-2\sin\phi \cos\phi + \tanh \rho)) \hat{\rho} \right] \\
 &= \boxed{\vec{0}}
 \end{aligned}$$

$$(\alpha^2 + \beta^2)$$

$$10. \quad \vec{\nabla} \phi = \frac{1}{h_\alpha} \frac{\partial \phi}{\partial \alpha} \hat{\alpha} + \frac{1}{h_\beta} \frac{\partial \phi}{\partial \beta} \hat{\beta} + \frac{1}{h_\gamma} \frac{\partial \phi}{\partial \gamma} \hat{\gamma}$$

$$h_\alpha = h_\beta = \frac{1}{(\alpha^2 + \beta^2)} \quad \left(\left| \frac{\partial \vec{r}}{\partial \alpha} \right| = \left| \frac{\partial \vec{r}}{\partial \beta} \right| = \frac{1}{\alpha^2 + \beta^2} \right)$$

$$h_\gamma = 1$$

$$\boxed{\therefore \vec{\nabla} \phi = (\alpha^2 + \beta^2) \frac{\partial \phi}{\partial \alpha} \hat{\alpha} + (\alpha^2 + \beta^2) \frac{\partial \phi}{\partial \beta} \hat{\beta} + \frac{\partial \phi}{\partial \gamma} \hat{\gamma}}$$

$$11. \quad F = \frac{x^2 y}{(x^2 + y^2)^2} \hat{i} + \sqrt{x^2 + y^2} \hat{j} + z(1 - x^2 - y^2) \hat{k}$$

$$\text{we know } x^2 + y^2 = r^2$$

$$x = r \cos \phi$$

$$y = r \sin \phi$$

$$\therefore F = \frac{r^2 \cos^2 \phi \sin \phi}{r^4} \hat{i} + r \hat{j} + z(1 - r^2) \hat{k}$$

$$\begin{aligned}\hat{i} &= \hat{e} \cos \phi - \hat{g} \sin \phi \\ \hat{j} &= \hat{e} \sin \phi + \hat{g} \cos \phi\end{aligned}$$

$$\therefore \vec{F} = \frac{\cos^2\phi \sin\phi}{e} [\cos\phi \hat{e} - \sin\phi \hat{k}] + e [\sin\phi \hat{e} + \cos\phi \hat{k}] + z(1-e^2) \hat{k}$$

$$= \left[\frac{\cos^3\phi \sin\phi}{e} + e \sin\phi \right] \hat{e} + \left[e \cos\phi - \frac{\cos^2\phi \sin^2\phi}{e} \right] \hat{k} + z(1-e^2) \hat{k}$$

$$\vec{\nabla} \cdot \vec{F} = \frac{1}{1 \times e \times 1} \left[\frac{\partial}{\partial e} \left[\cos^3\phi \sin\phi + e^2 \sin\phi \right] + \frac{\partial}{\partial \phi} \left[e \cos\phi - \frac{\cos^2\phi \sin^2\phi}{e} \right] + \frac{\partial}{\partial z} (z(e-e^3)) \right]$$

$$= \frac{1}{e} \left[2e \sin\phi \cancel{+} - e \sin\phi - \frac{1}{e} \cancel{\times} \sin 2\phi \cos 2\phi + e - e^3 \right]$$

$$= 3 \sin\phi - \frac{\sin 2\phi \cos 2\phi}{e^2} + 1 - e^2$$

$$= \boxed{1 + \sin\phi - e^2 - \frac{\sin 4\phi}{2e^2}}$$

$$12. \vec{A} = 2y\hat{i} - 3\hat{j} + 2z\hat{k}$$

$$y = r \sin \theta$$

$$\hat{i} = \cos \theta \hat{e} - \sin \theta \hat{\phi}$$

$$\hat{j} = \sin \theta \hat{e} + \cos \theta \hat{\phi}$$

$$\therefore \vec{A} = 2r \sin \theta (\cos \theta \hat{e} - \sin \theta \hat{\phi})$$

$$- 3(\sin \theta \hat{e} + \cos \theta \hat{\phi}) + 2z\hat{k}$$

$$= [r \sin(2\theta) - 3 \sin \theta] \hat{e} - [2r \sin^2 \theta + 3 \cos \theta] \hat{\phi} + 2z\hat{k}$$

13.

$$x = 1$$

$$y = 1$$

$$z = 1$$

(A) cylindrical:

$$\begin{cases} r \cos \theta = 1 \\ r \sin \theta = 1 \end{cases} \quad \begin{cases} \tan \theta = 1 \\ \theta = 45^\circ \end{cases} \quad r = \sqrt{2}$$

\therefore In cylindrical, coordinates are $(\sqrt{2}, \pi/4, 1)$

(B) spherical:

$$\begin{cases} r \sin \theta \cos \phi = 1 \\ r \sin \theta \sin \phi = 1 \\ r \cos \theta = 1 \end{cases} \quad \begin{cases} \theta = 45^\circ \\ \phi = 45^\circ \end{cases}$$

$$\begin{matrix} \sqrt{3} \\ \sqrt{2} \end{matrix}$$

$$\begin{cases} r \sin \theta = \sqrt{2} \\ r \cos \theta = 1 \end{cases} \quad \begin{cases} \tan \theta = \sqrt{2} \\ \theta = \tan^{-1}(\sqrt{2}) \\ r = \sqrt{3} \end{cases}$$

\therefore In spherical, coordinates are

$$(\sqrt{3}, \tan^{-1}(\sqrt{2}), \pi/4)$$

14.

$$F = \rho^3 \sin\phi$$

$$\begin{aligned}
 (a) \vec{\nabla} F &= \frac{1}{1} \times \frac{\partial}{\partial \rho} (\rho^3 \sin\phi) \hat{\rho} + \frac{1}{\rho} \times \frac{\partial}{\partial \phi} (\rho^3 \sin\phi) \hat{\phi} \\
 &\quad + \frac{1}{1} \times \frac{\partial}{\partial \theta} (\rho^3 \sin\phi) \hat{\theta} \\
 &= (3\rho^2 \sin\phi) \hat{\rho} + (\rho^2 \cos\phi) \hat{\phi} \\
 &= \boxed{\rho^2 [3\sin\phi \hat{\rho} + \cos\phi \hat{\phi}]}
 \end{aligned}$$

$$(b) \rho = (x^2 + y^2)^{1/2}$$

$$\sin\phi = \frac{y}{(x^2 + y^2)^{1/2}}$$

$$\begin{aligned}
 \therefore F &= \rho^3 \sin\phi = (x^2 + y^2)^{3/2} \frac{y}{(x^2 + y^2)^{1/2}} \\
 &= \frac{y(x^2 + y^2)}{\sqrt{x^2 + y^2}}
 \end{aligned}$$

$$\vec{\nabla} F = \frac{\partial}{\partial x} (x^2 y + y^3) \hat{i} + \frac{\partial}{\partial y} (x^2 y + y^3) \hat{j}$$

$$= \boxed{(2xy) \hat{i} + (x^2 + 3y^2) \hat{j}}$$

$$x = \rho \cos\phi$$

$$y = \rho \sin\phi$$

$$\hat{i} = \rho \cos\phi \hat{\rho} - \rho \sin\phi \hat{\theta}$$

$$\hat{j} = \sin\phi \hat{\rho} + \cos\phi \hat{\theta}$$

$$\therefore \vec{\nabla} F = 2\rho^2 \sin\phi \cos\phi [\cos\phi \hat{\rho} - \sin\phi \hat{\theta}]$$

$$\begin{aligned}
 &+ [\rho^2 \cos^2\phi + 3\rho^2 \sin^2\phi] \\
 &\quad [\sin\phi \hat{\rho} + \cos\phi \hat{\theta}]
 \end{aligned}$$

$$= \left[2e^2 \sin\phi \cos^2\phi + e^2 \sin\phi \cos^2\phi \right] \hat{e} \\ + 3e^2 \sin^3\phi$$

$$+ \left[-2e^2 \sin^2\phi \cos\phi + e^2 \cos^3\phi \right] \hat{\phi} \\ + 3e^2 \sin^2\phi \cos\phi$$

$$= [3e^2 \sin\phi (\sin^2\phi + \cos^2\phi)] \hat{e} + [e^2 \cos\phi (\sin^2\phi + \cos^2\phi)] \hat{\phi}$$

$$= 3e^2 \sin\phi \hat{e} + e^2 \cos\phi \hat{\phi}$$

$$= e^2 [3\sin\phi \hat{e} + \cos\phi \hat{\phi}]$$

\therefore it is same in both systems.