

Homework 06

ME1020 - Engineering Mechanics

1.

(a)

$$x(\text{cm}) = 2t - 6t^3 \rightarrow \text{Eqn. 1}$$

Differentiating wrt time, we get

$$v_x(\text{cm/s}) = dx/dt = 2 - 18t^2 \rightarrow \text{Eqn. 2}$$

$$\begin{aligned} a_x(\text{cm/s}^2) &= d^2x/dt^2 = dv_x/dt \\ &= -36t \rightarrow \text{Eqn. 3} \end{aligned}$$

∴ At $t = 5\text{s}$,

$$\begin{aligned} \text{Velocity of head} &= v_x \text{ (at } t = 5) \\ &= 2 - 18 \times 5^2 \text{ (From Eqn 2)} \\ &= -448 \text{ cm/s} \end{aligned}$$

$$\begin{aligned} \text{Acceleration of head} &= a_x \text{ (at } t = 5) \\ &= -36 \times 5 \text{ (From Eqn 3)} \\ &= -180 \text{ cm/s}^2 \end{aligned}$$

(b)

$$\text{Initial velocity of car} = 20\text{km/h} = 50/9 = 5.555 \text{ m/s}$$

$$\text{Acceleration of car after 2 seconds} = a = 3\text{m/s}^2$$

First, let us see how long the car takes to reach the signal which is 100m away (say 't' seconds).

If this time is **less than 5 seconds** (time taken to turn from yellow to red), that means **he reaches the signal before it turns red**. If the calculated time is **more than 5 seconds**, he **doesn't reach the signal on time**.

$$\text{Total distance} = (v_{\text{initial}})(2\text{s}) + (v_{\text{initial}})(t-2) + \frac{1}{2} a(t-2)^2$$

$$100\text{m} = (5.555 \text{ m/s})(2\text{s}) + (5.555)(t-2) + \frac{1}{2} (3 \text{ m/s}^2)(t-2)^2$$

$$1.5(t-2)^2 + 5.555(t-2) - 88.89$$

Solving, we get

$$(t-2) = 6.065\text{s}$$

$$t = 8.065\text{s} > 5\text{s}$$

∴ The car doesn't reach the signal on time.

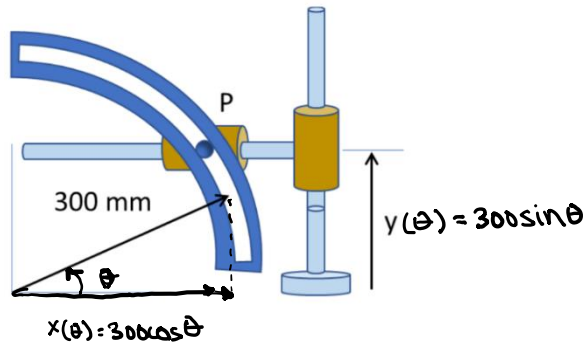
$$\text{The velocity of the car when it reaches the signal} = v_{\text{initial}} + a(t-2)$$

$$= 5.555 + 3(6.065)$$

$$= 23.75 \text{ m/s}$$

2.

(a)



$$y = 300 \sin \theta \rightarrow \text{Eqn 1}$$

Differentiating wrt t,

$$dy/dt (\text{mm/s}) = (300 \cos \theta) d\theta/dt \rightarrow \text{Eqn 2}$$

Differentiating again wrt t,

$$d^2y/dt^2 (\text{mm/s}^2) = 300[(\cos \theta) (d^2\theta/dt^2) - (\sin \theta) (d\theta/dt)^2] \rightarrow \text{Eqn 3}$$

$$\text{When } y = 200 \text{ mm, } \sin \theta = y/300 = 2/3 = 0.666 (\text{From Eqn 1})$$

$$\therefore \cos \theta = \sqrt{5}/3 = 0.745$$

$$\tan \theta = 0.894$$

At $y = 200 \text{ mm}$,

$$(i) dy/dt = 200 \text{ mm/s (Given)}$$

$$\therefore 300 \cos \theta d\theta/dt = 200$$

$$d\theta/dt = 2/(3 \cos \theta) [\text{Eqn 1}]$$

$$= 0.894 \text{ rad/s}$$

$$\therefore \text{Radial acceleration (towards centre) at point P } (a_R) = (d\theta/dt)^2 R$$

$$= 240 \text{ mm/s}^2$$

$$(ii) d^2y/dt^2 = 0$$

$$(\cos \theta) (d^2\theta/dt^2) = (\sin \theta) (d\theta/dt)^2$$

$$d^2\theta/dt^2 = 0.894(0.894)^2$$

$$= \mathbf{0.7155 \text{ rad/s}^2 \text{ (Angular acceleration)}}$$

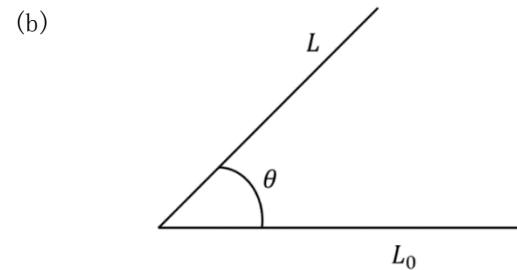
$$\therefore \text{Tangential acceleration } (a_t) = (d^2\theta/dt^2)R$$

$$= 0.7155 \times 300$$

$$= \mathbf{214.65 \text{ mm/s}^2}$$

$$\therefore \text{Net acceleration} = \sqrt{(a_r^2 + a_t^2)}$$

$$= \mathbf{321.98 \text{ mm/s}^2}$$



$$\alpha = d\omega/dt = 2 - 1.5t$$

$$d\omega = (2 - 1.5t)dt$$

Integrating with suitable limits,

$$\int_5^{\omega(t)} d\omega = \int_0^t (2 - 1.5t)dt$$

$$\omega(t) - 5 = 2t - 0.75t^2$$

$$\omega(t) = 5 + 2t - 0.75t^2 \rightarrow \text{Eqn. 1}$$

$$d\theta/dt = \omega(t) = 5 + 2t - 0.75t^2$$

$$d\theta = (5 + 2t - 0.75t^2)dt$$

Integrating with suitable limits,

$$\int_0^{\theta(t)} d\theta = \int_0^t (5 + 2t - 0.75t^2)dt$$

$$\theta(t) = 5t + t^2 - 0.25t^3 \rightarrow \text{Eqn 2}$$

$$\therefore \omega(3s) = 5 + 2 \times 3 - 0.75 \times 3^2$$

$$= \mathbf{4.25 \text{ rad/s}}$$

$$\begin{aligned}\theta(3s) &= 5x3 + 3^2 - 0.25x3^3 \\ &= 17.25 \text{ rad}\end{aligned}$$