

# DESIGN AND DEVELOPMENT OF DAMPED BORING BAR USING CELLULAR SOLIDS



## Batch 3

### STUDENT DETAILS

NAME

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# Problem definition

- A large length to diameter ratio - vibration(chatter) often occurs and it leads to a negative impact on the processing quality and processing performance
- Damping is a way to limit vibrations and is essential for protecting the system in which it operates at high speeds
- To improve machining performance of the tool by eliminating vibration

# Objective

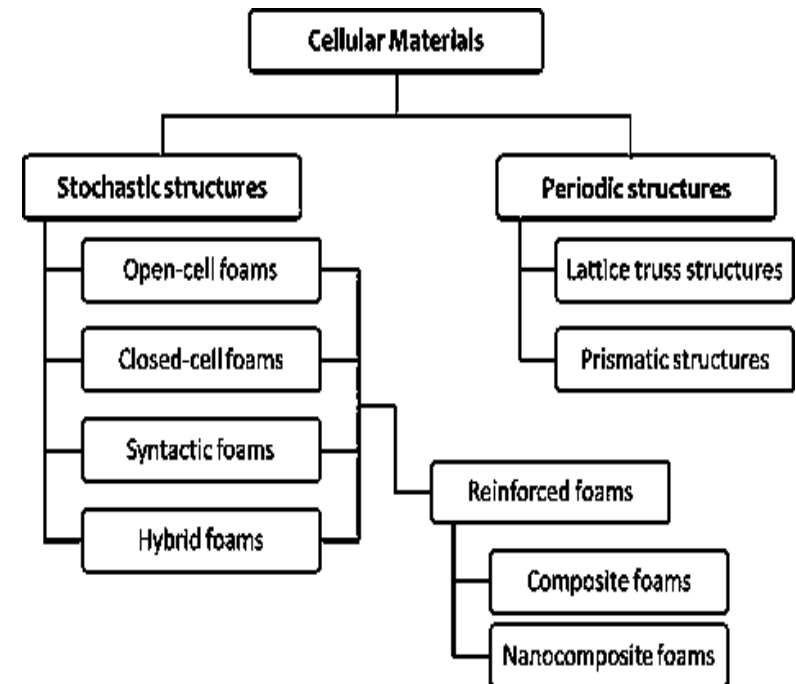
- To design and develop a high damped **cellular structure** boring bar instead of conventional **solid bar** to improve the dynamic stability of the boring tool to bore smaller diameter holes

# Literature survey

## Classification of Cellular Materials

### ❑ Duarte, N. Peixinho et al., 2019

- Based on the base material, these materials are grouped into cellular metals, cellular ceramics and cellular polymers
- Stochastic structure are porous and it has high energy absorbing capacity
- Open cell structure – High surface area
- Closed cell structure has high structural efficiency, and damping



# Classification and selection of cellular material in mechanical design

## □ Dhruv bhate et al., 2019

- Cellular material is classified in three levels – Tessellation, Element type, Connectivity
- Biomimetic approach is used in selection of cellular structure
- Toucan beak structure – high dynamic stiffness, Closed cell foam structure

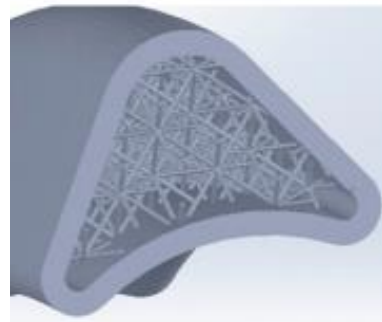
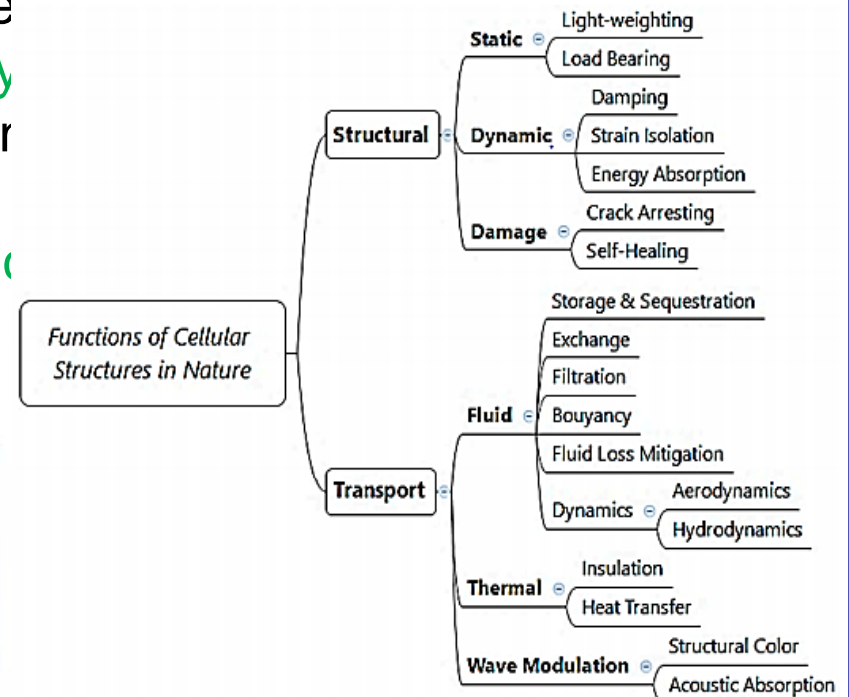


Fig.1 Toucan beak structure

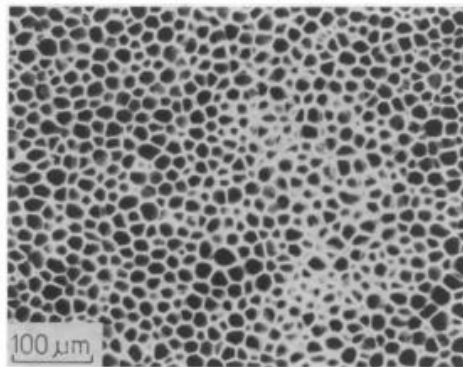


# Cellular Materials characteristics

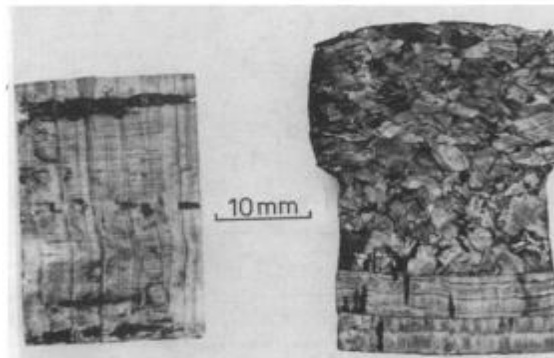
## The Mechanical Properties of Cellular Solids

### ❑ M.F. ASHBY R et al., 1998

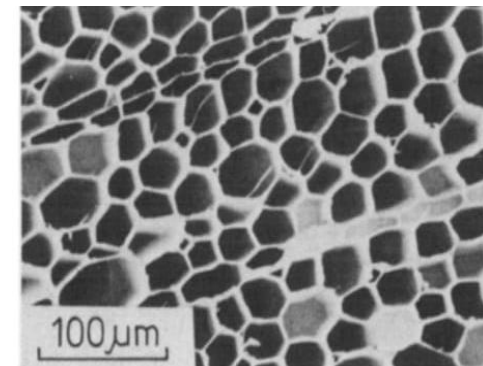
- Mechanics of natural materials such as wood, corks, bones etc.,
- Cellular solids – simultaneous optimization of **strength, stiffness , weight**
- Cellular solids – foundation for designing with foams for **load bearing structure**
- Foam filled sandwich structure gives **longitudinal** and **flexural stiffness**



**Fig.2** Cells in cork



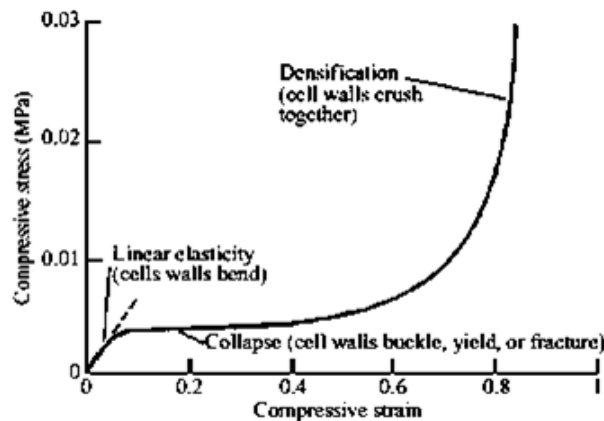
**Fig. 3** Sections through corks.  
(Axis of symmetry of the cork structure)



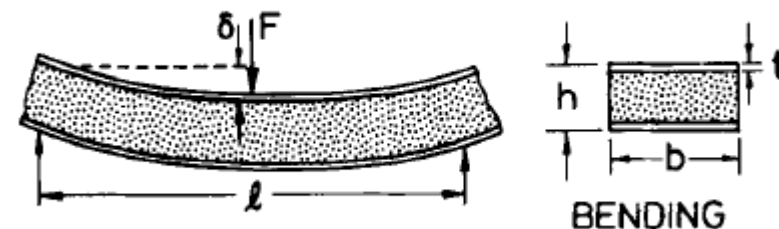
**Fig.4** Sandwich structure in wood

## ❑ F- J. Ulm et al., 2001

- Mechanical behaviour of cellular solids – linear elastic ,cell wall buckle , densification
- Increased **moment of inertia** in sandwich panel – efficient **bending** and **buckling stiffness**
- Combinations of face and core materials are used;
  - Faces - steel, aluminum, or wafer board
  - Cores - foamed polyurethane, foamed polystyrene bead board, or foamed glass
- Sandwich panel – **economic material**



**Fig.5** Stress strain curve for cellular solids

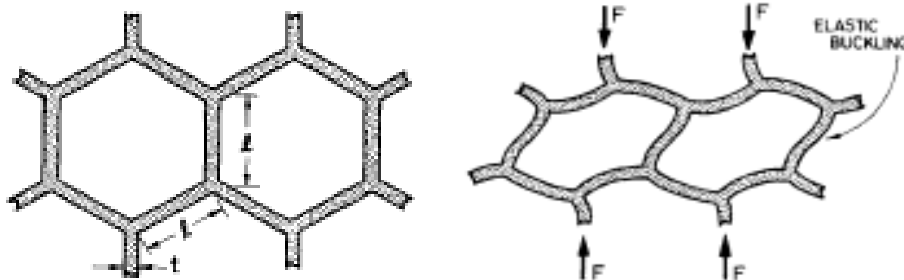


**Fig.6** Bending in sandwich panel

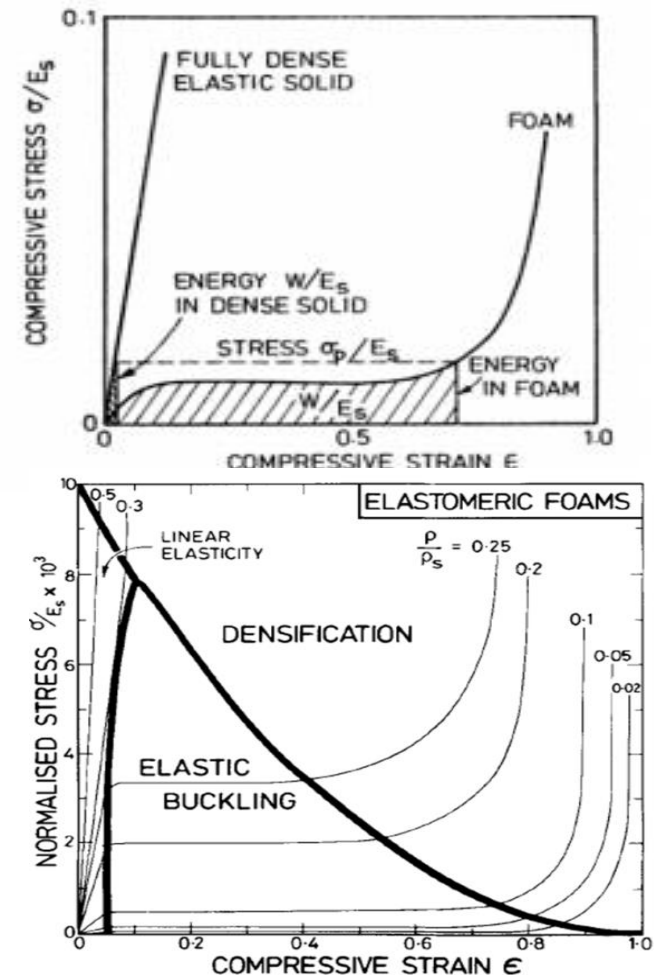
# How cellular structure absorbs energy ?

## Gibson et.al , cellular solids,

- Energy absorbing capacity of cellular solids is **higher** than dense solids
- Cell wall buckles **up to densification** , so energy is absorbed up to densification
- Using **elastomeric** material provides **linear elastic buckling** of cell wall
- Increase in **relative density** reduces the **elastic buckling range**



**Fig.7** Elastic buckling of honeycombs



**Fig.8** Energy absorption curve

**Source :** Gibson et.al , cellular solids



# Numerical inverse engineering as a route to determine the dynamic mechanical properties of metallic cellular solids

- ❑ **V.H. Carneiro et al., 2020**
- Direct experimental approaches on **low damping cellular solids** tends to be **tampered by external damping sources**, an indirect numerical inverse engineering approach is presented as a solution
- **Numerical inverse engineering** is carried on **AI based** stochastic structure to determine damping ratio



**Fig.9** 3D-printed model



**Fig.10** Experimental setup for vibration testing

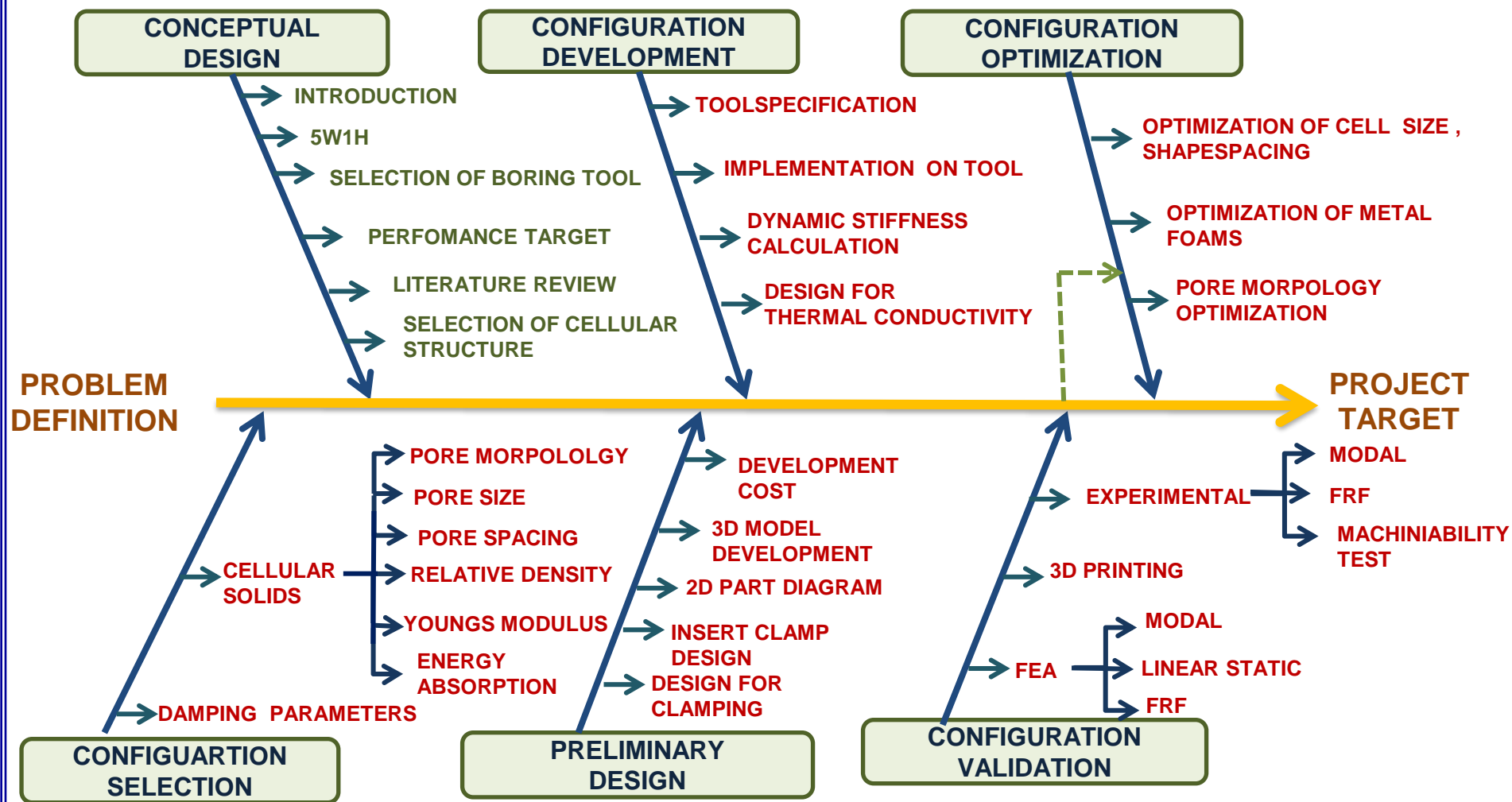
# Summary

- Sandwich structure has high longitudinal and bending stiffness
- Stochastic structure has high energy absorbing capacity
  - Closed cell structure has better damping
- Numerical inverse engineering is used for determining damping ratio

# Gaps in literature

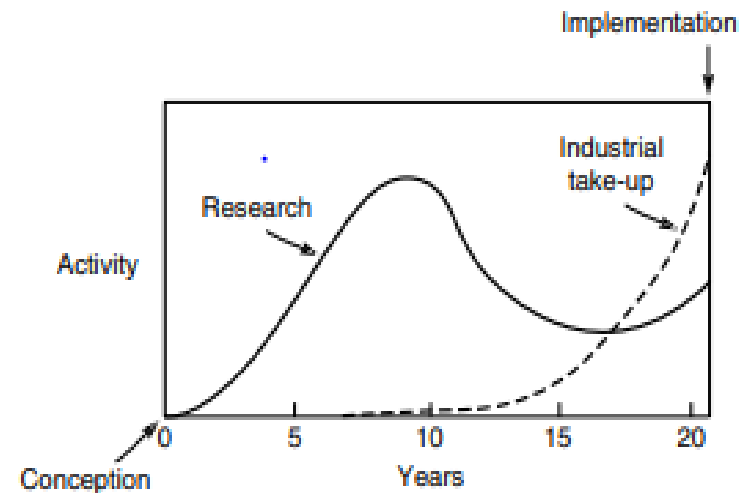
- Cellular solids is not implemented in boring tool
- Very few studies on FEA of closed cell structure

# Fish bone analysis



# Preface

- A **large length to diameter ratio** - vibration(chatter) often occurs and it leads to a **negative impact on the processing quality** and processing performance
- Implementation of **alternate material** over conventional material to enhance damping property
- Improving **dynamic stiffness** of system improves **vibrostaticity**



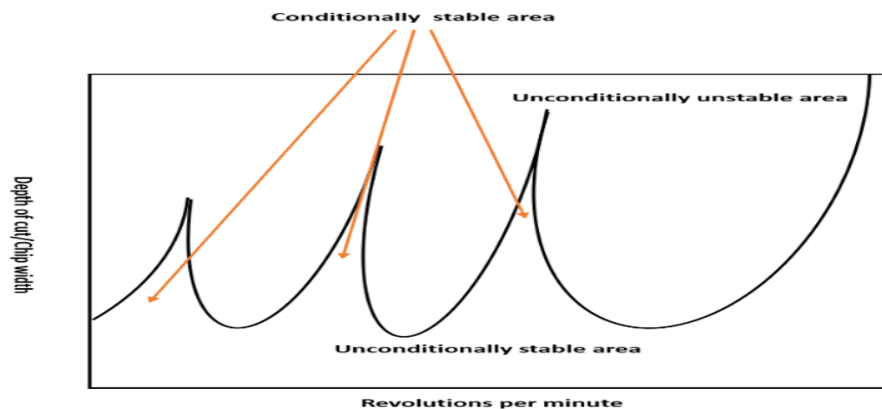
**Fig.11** A development history typical of many new material

**Source:** ASHBY R et al, Metal foams : A design guide M.F., 2000

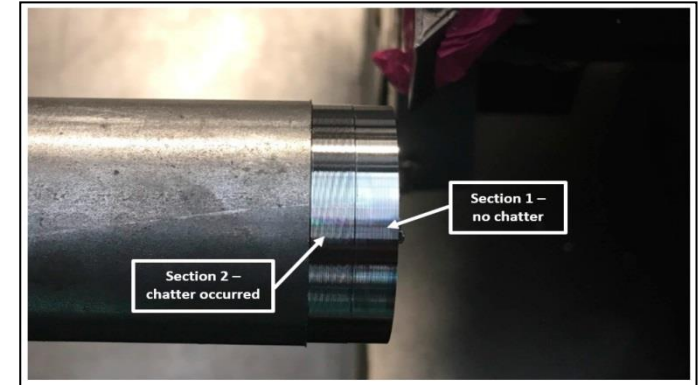
# Why we need to improve the dynamic stiffness of the boring bar ?

## Improved dynamic stiffness in the Boring bar offers

- Chatter free operation
- Increases unconditional stable region
- *Natural frequency* of the system *increases*
- *Overhang length* of tool can be *increased*
- Significant improvement in productivity and better surface quality



**Fig.13** Stability lobe diagram



**Fig. 12** Machined surface of chatter tool

**Source:** Jasiewicz M et al., Implementation of an algorithm to prevent chatter vibration in a CNC system materials. 2019

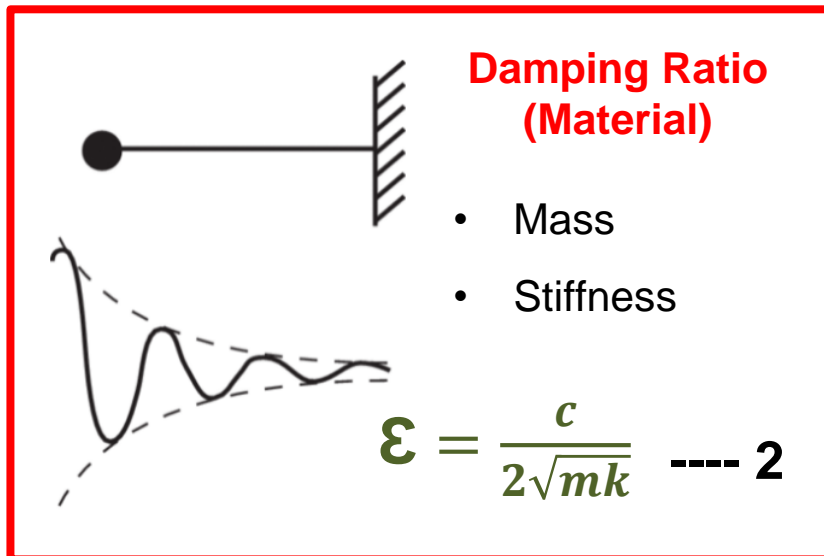
**Source:** Mfg Tech update, Chatter in milling

# How to Improve dynamic stiffness ?

Dynamic stiffness ←  $D = \epsilon * K$  ---- 1

$\downarrow$                        $\downarrow$   
 Damping ratio              Static stiffness

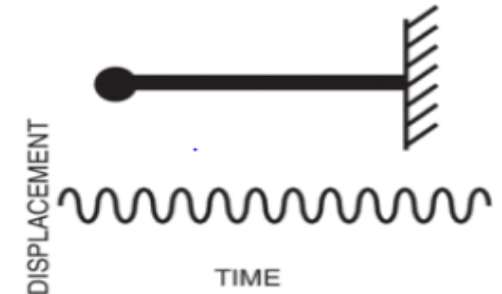
## Factors influencing...



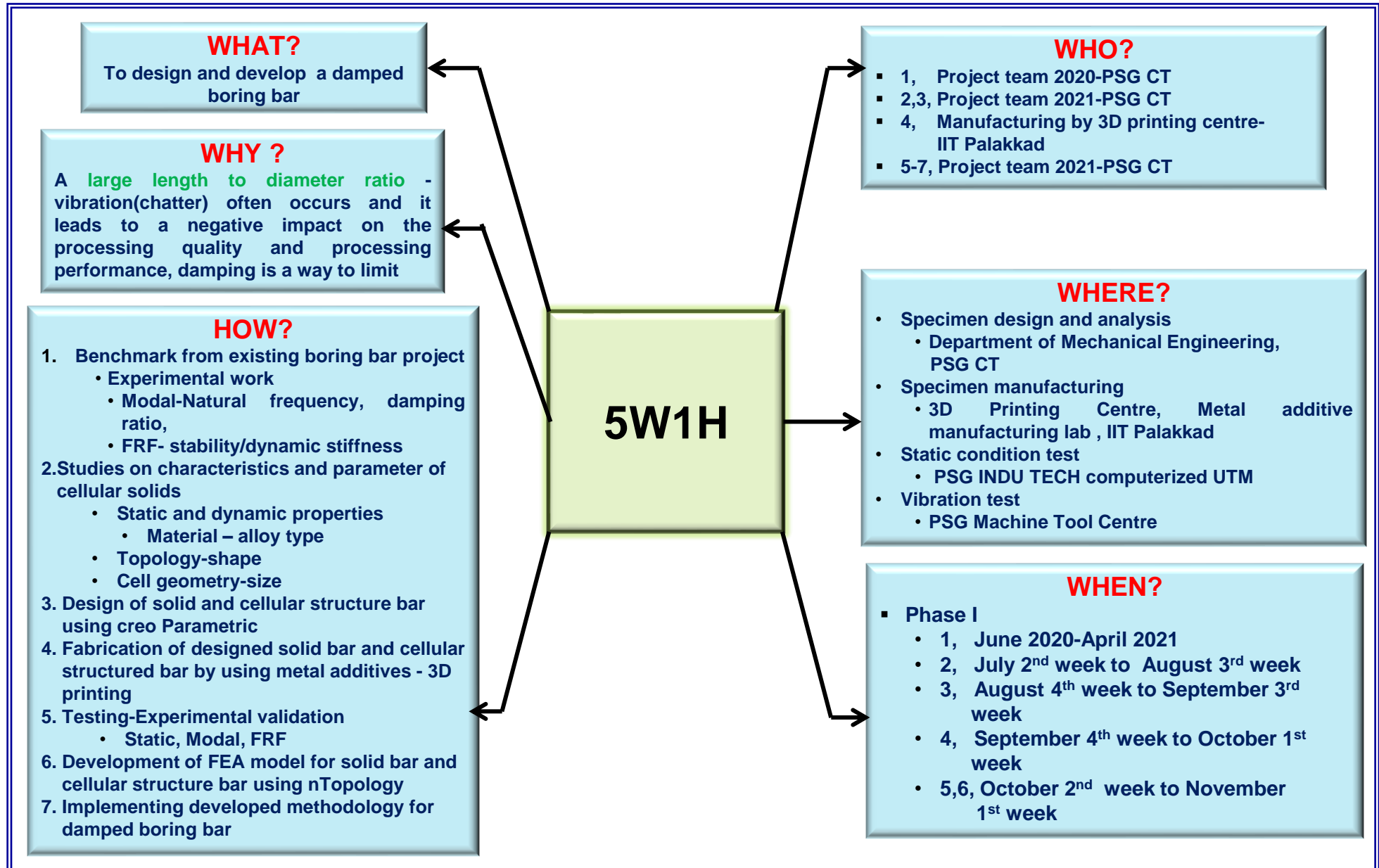
## Static stiffness

- Clamping method
- Over hang length
- Young's modulus
- Moment of inertia

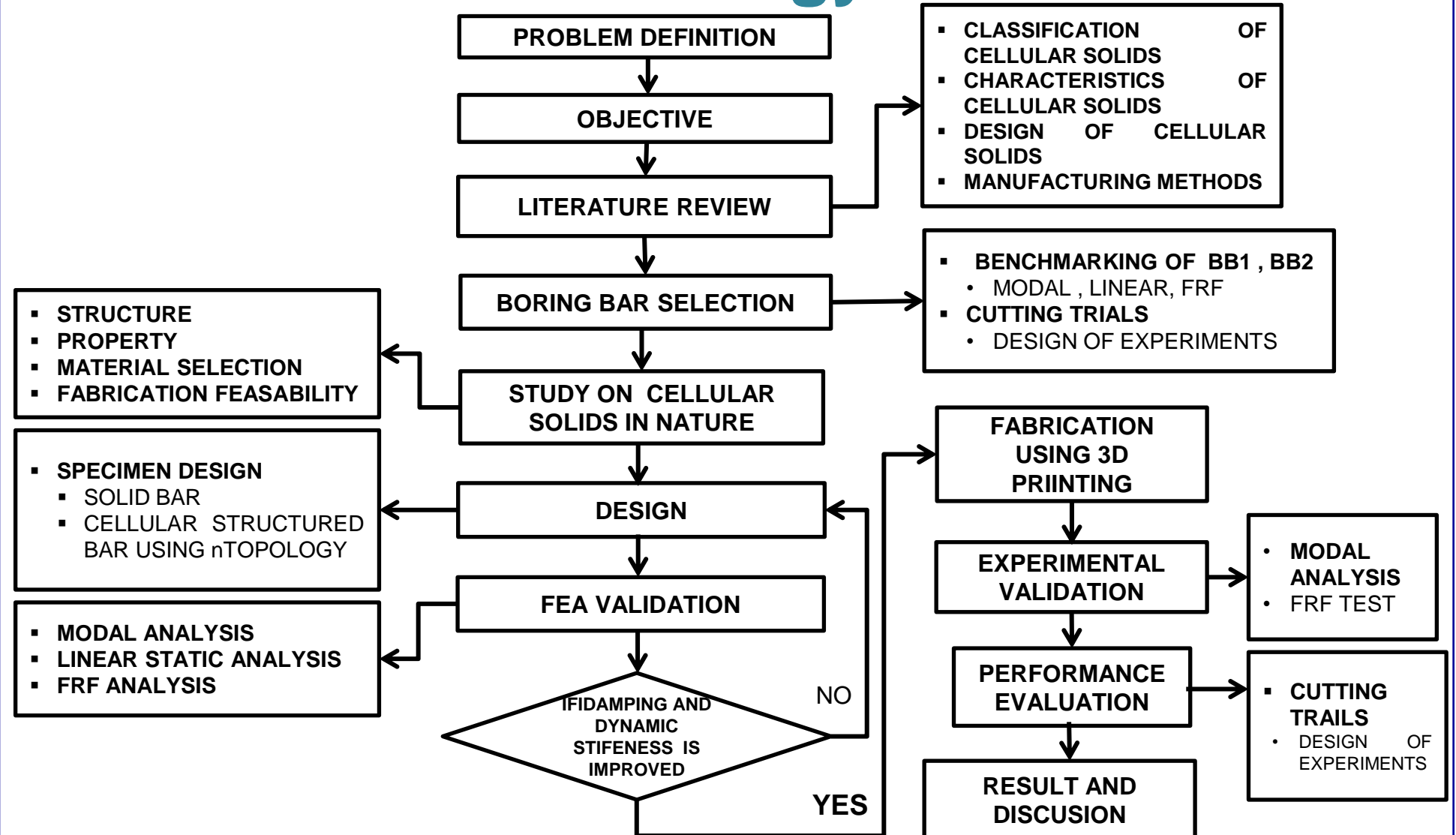
$$n = \frac{1}{2\pi} \sqrt{\frac{k}{m}} \text{ ---- 3}$$



*‘Natural frequency of the system depends **mass** and **stiffness**’*



# Methodology

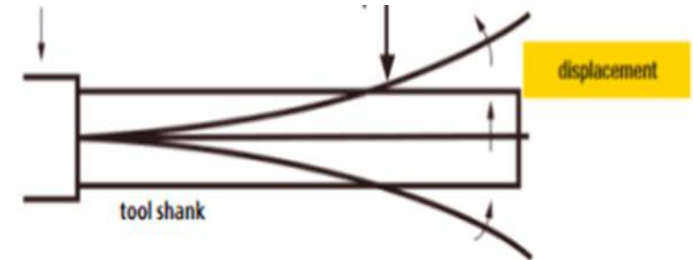




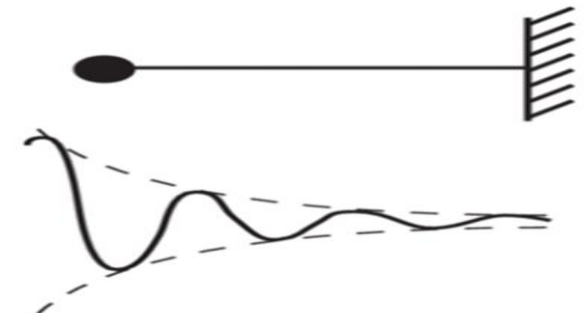
# Why to improve damping in boring bar?

## Problem definition

- Vibration is often the **limiting parameter** in gaining high output in the machine i.e. speed, feed and depth of cut
- Damping is a way to **limit vibrations** and is essential for protecting the system in which it operates at high speeds
- Damped boring bar **reduces cost of operation**



**Fig.14** Chatter in boring bar  
**Source** : Kennametal

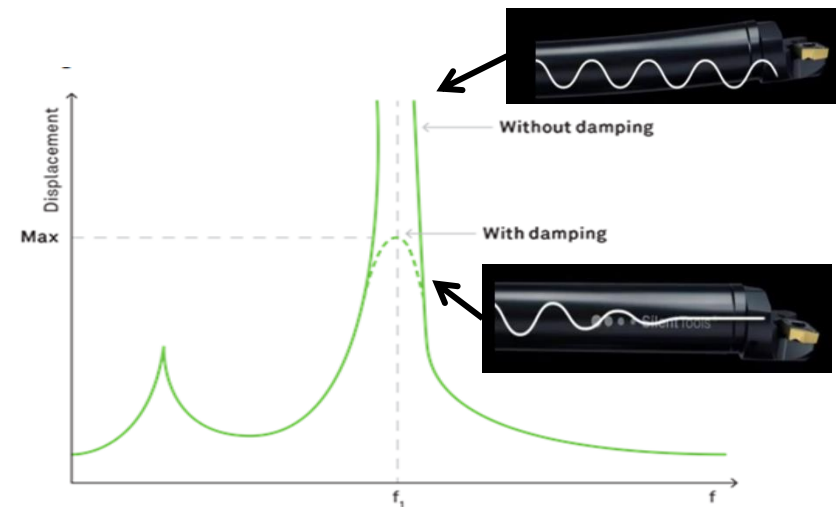


**Fig.15** Damping in cantilever beam  
**Source** : Kip Hanson et al.  
2020, boring tool sme

# What is damping in boring bar?

## Objective

- Damping is the **dissipation of vibratory energy** in solid mediums and structures over **time and distance**
- To design and develop a high damped **cellular structure** boring bar instead of conventional **solid bar** to improve the dynamic stability of the boring tool to bore smaller diameter holes



**Fig.16** Frequency response plot

**Source :** ACC ,Why damping is important for construction ?

# Where we use damped boring bar?

The damped boring bars are used for manufacturing

- Machining **small diameter holes**
- Superior quality and highly accurate **industrial automation equipment**
- Automotive parts
- Medical implant accessories
- **Thin walled** aerospace parts
- IC engines, hydraulic cylinders



**Fig.19** Machining medical implants

**Source :** New engineering practice BlogSpot



**Fig.17** Thin wall machining



**Fig.18** Engine block machining

# When damped boring bars are used?

- Large length to diameter ratio is required for machining
- **High material removal rate** is required
- When **surface quality** of machining is required to be improved by increasing the
  - ✓ Natural frequency
  - ✓ Static stiffness
  - ✓ Damping ratio
- **Low operating cost** is required



**Fig.20** Conventional boring bar

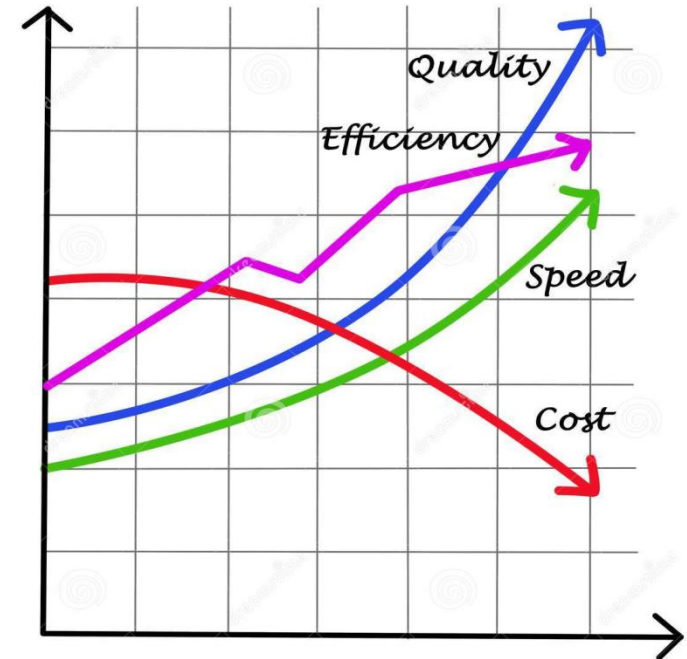


**Fig.21** Damped boring bar

**Source :** Canstockphoto

# Who are beneficiaries ?

- Manufacturing company who requires **close tolerance** with long overhang
- **Aerospace** and **medical** equipment manufacturer
- Small scale companies aiming for low production cost



**Fig.22** Quality vs cost graph

**Source :** Colonialtool

# How to improve damping in boring bars?

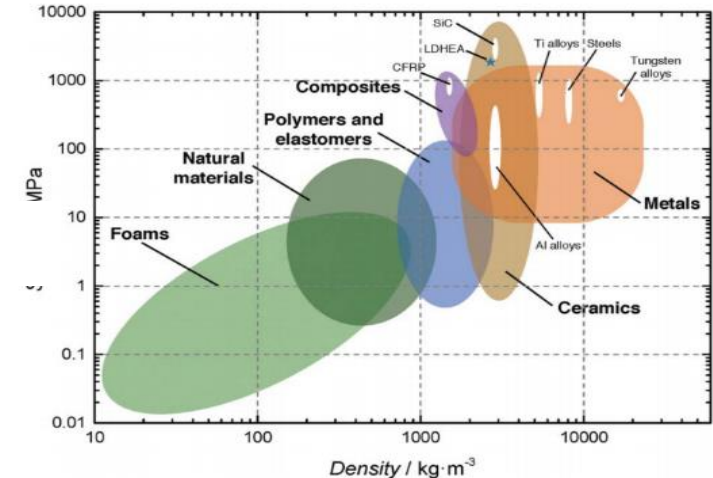
- Reducing critical damping constant improves vibrational damping of tool

- Damping ratio :

$$\xi = \frac{c}{2\sqrt{mk}} \quad \leftarrow \text{Damping constant} \quad \text{----} \quad 4$$

$\leftarrow \text{Critical damping constant}$

- Replacing with **low weight to high strength** ratio material i.e. Cellular solids
- Using **high energy absorbing** structure i.e. cellular
- Using tuned mass dampers in tool.



**Fig. 23** Strength to weight ratio of engineering materials

**Source :** North Carolina State University, Materials research letters



**Fig.24** Tuned mass dampers  
**Source :** Sandvik coromant

# Concluding remarks

- Damping plays a major role **improving surface quality** during boring
- **Overhang length** of tool can be increased in damped boring bar
- Replacing conventional solid tools with **low weight to high strength material** improves damping
- Damped boring bars **reduces operational cost**
- **Metal foams** has low weight to strength ratio i.e. Cymat, Alulight, Alporas, ERG, Inco
- **Cellular structured** solids has high energy absorbing capacity

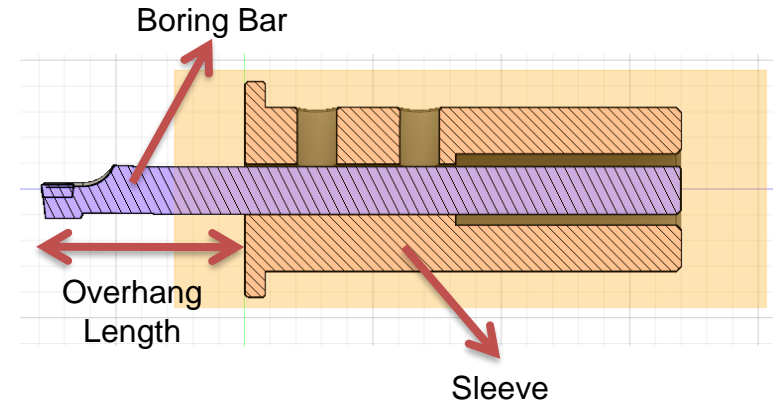


# Boring tool selection

## Overhang Lengths

Selection of overhang length for different boring tool materials.

|  |              |
|--|--------------|
| Steel boring bars:                     | Up to 4 x D  |
| Carbide boring bars:                   | Up to 6 x D  |
| Steel damped boring bars short design: | Up to 7 x D  |
| Carbide reinforced damped boring bars: | Up to 14 x D |



**Fig.25** Overhang length

| Properties             | BB1                             | BB2    |
|------------------------|---------------------------------|--------|
| Size – Dia/length (mm) | 10/125                          | 10/125 |
| Material               | Steel ( with alloying elements) | Steel  |
| Cross Section          | Hollow                          | Solid  |
| Cost (INR)             | 11,250                          | 3,500  |

**Table.1** Properties of tool

BB2



BB1

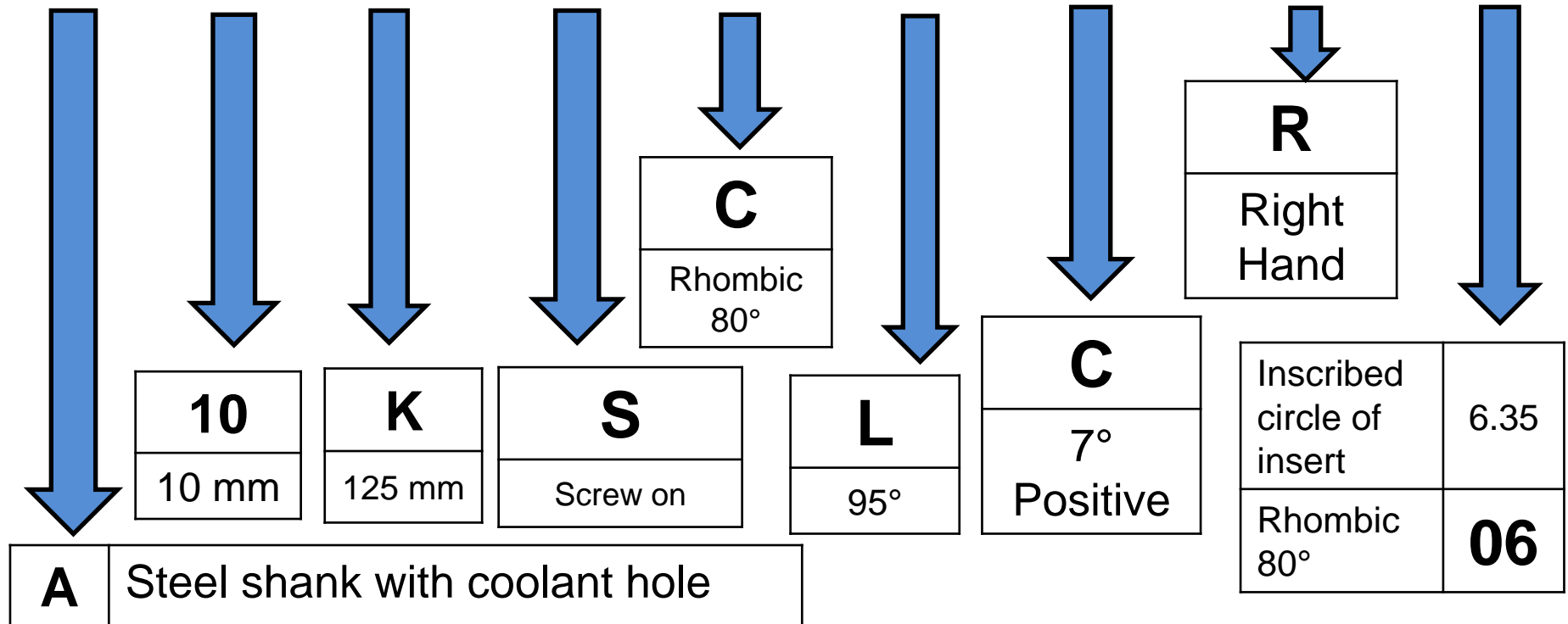


**Fig.26** Boring bars – BB1 & BB2



# BB1 Specifications

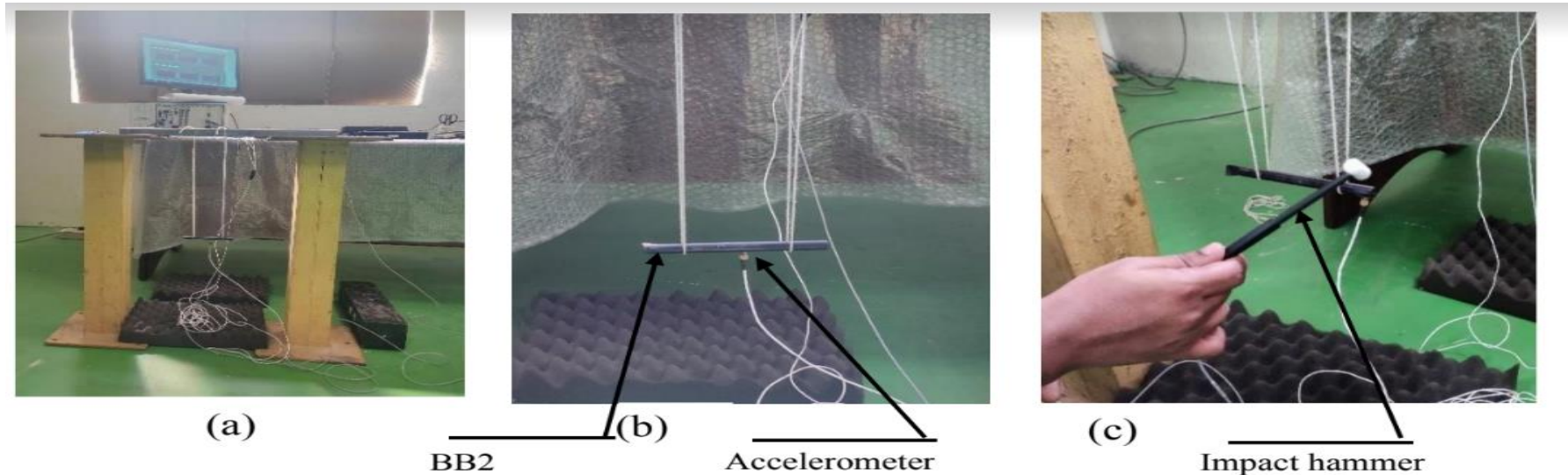
| 1 | 2  | 3 | 4 | 5 | 6 | 7 | 8 | 9  |
|---|----|---|---|---|---|---|---|----|
| A | 10 | K | S | C | L | C | R | 06 |



# Benchmarking data

## EXPERIMENTAL MODAL ANALYSIS – FREE FREE CONDITION

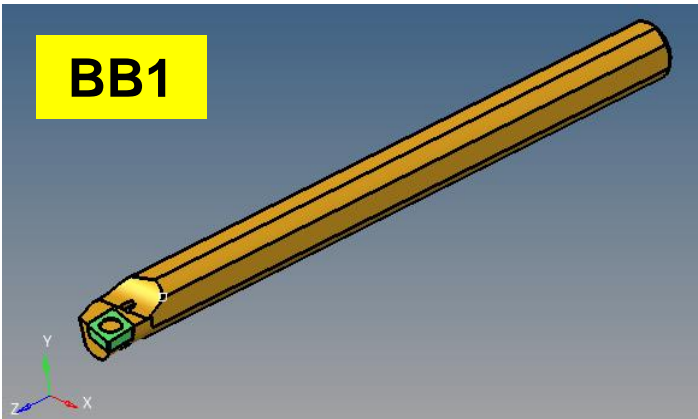
| Parameter             | BB1  | BB2  |
|-----------------------|------|------|
| Natural Frequency(Hz) | 2908 | 2846 |



**Fig. 27 (a-c)** Experimental modal analysis setup and testing

# BORING BAR FEA - MODAL ANALYSIS

## GEOMETRY AND MATERIAL

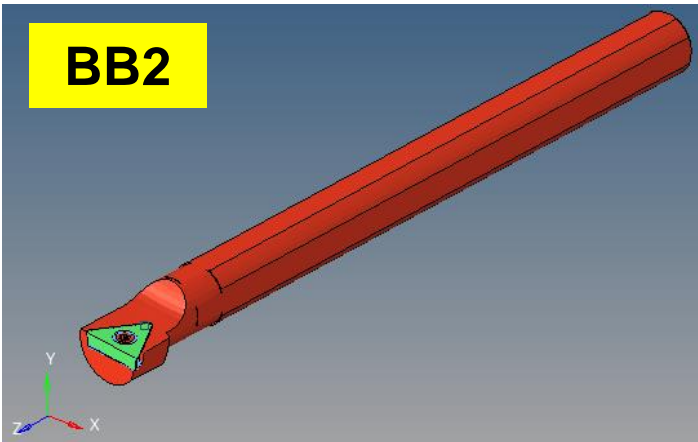
**BB1**

**TOOL :BB1**
**MANUFACTURER:** SANDVIK COROMANT

**MASS :** 0.064 Kg

**COOLANT DIA :** 3mm

**TOOL :BB2**
**MANUFACTURE:** WIDIA

**MASS :** 0.069 Kg

**BB2**


| PART       | MATERIAL | YOUNGS MODULUS | POISON RATIO | DENSITY     |
|------------|----------|----------------|--------------|-------------|
| BORING BAR | STEEL    | 210GPa         | 0.3          | 7890 Kg/m3  |
| INSERT     | CARBIDE  | 600GPa         | 0.2          | 14800 Kg/m3 |
| SLEEVE     | STEEL    | 210GPa         | 0.3          | 7890 Kg/m3  |

**Table.2** Mechanical properties of boring tool

**Preprocessor** : Hyper mesh

**Solver** : OptiStruct

**Postprocessor** : Hyper view

## MESH CRITERIA

Element size : 1 mm

Element type : 3D tetrahedral  
second order

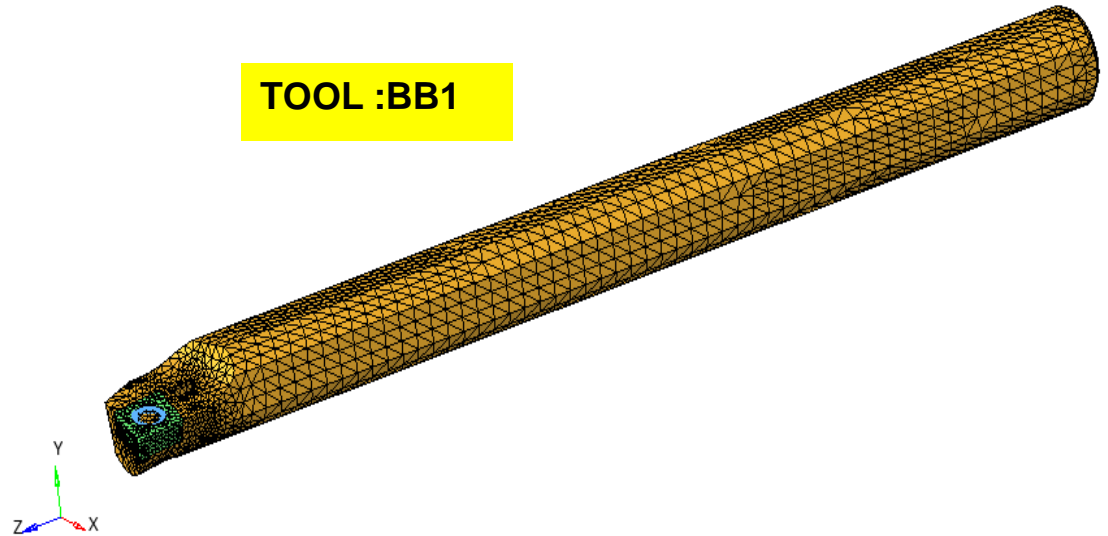
Tet collapse : 0.2

Number of elements

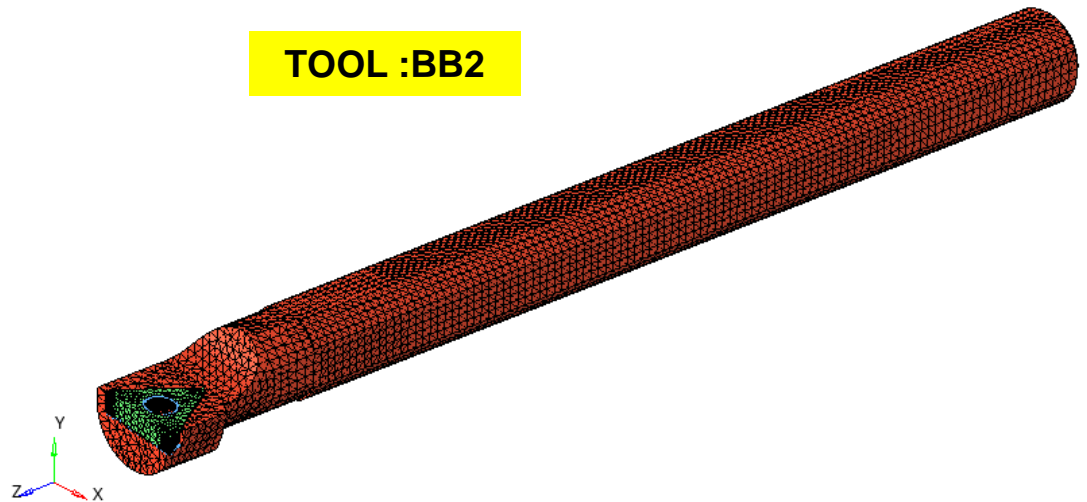
BB1 = 57071

BB2 = 60915

TOOL :BB1

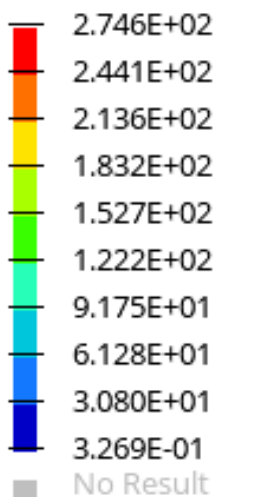


TOOL :BB2

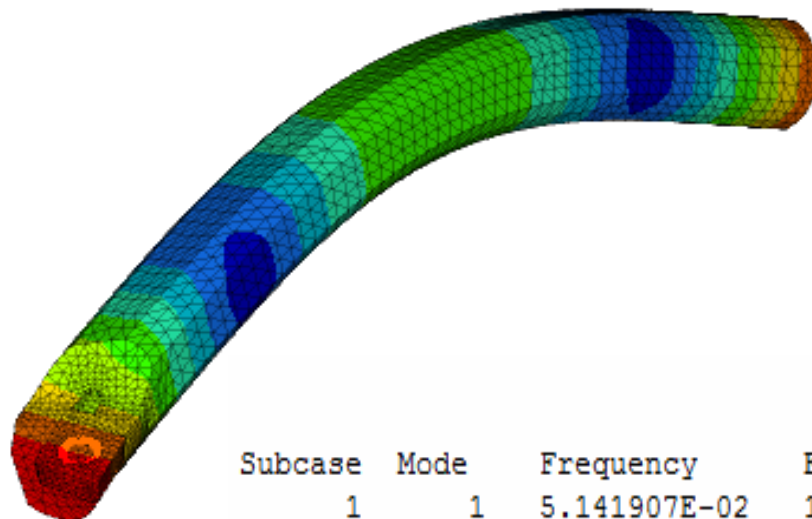


# MODAL ANALYSIS - FREE FREE CONDITION

Contour Plot  
Eigen Mode(Mag)  
Analysis system



Max = 2.746E+02  
Grids 143285  
Min = 3.269E-01  
Grids 140606

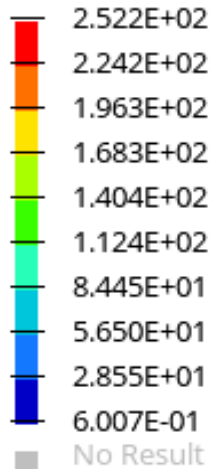


**TOOL :BB1**

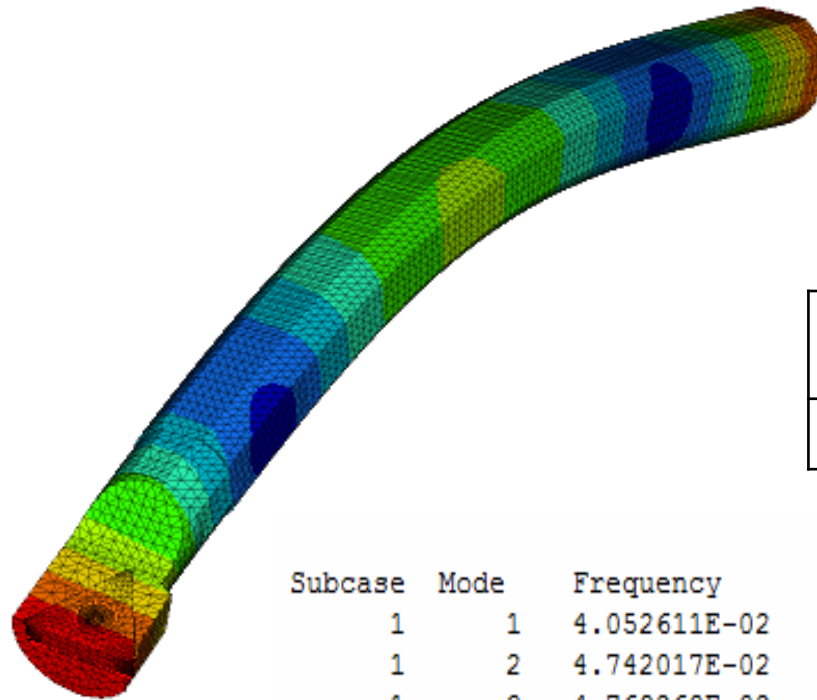
| 1 <sup>ST</sup> MODAL FREQUENCY | EXPERIMENTAL RESULT |
|---------------------------------|---------------------|
| 2964 Hz                         | 2908Hz              |

| Subcase | Mode | Frequency    | Eigenvalue   | Generalized Stiffness | Generalized Mass |
|---------|------|--------------|--------------|-----------------------|------------------|
| 1       | 1    | 5.141907E-02 | 1.043778E-01 | 1.043778E-01          | 1.000000E+00     |
| 1       | 2    | 5.341533E-02 | 1.126397E-01 | 1.126397E-01          | 1.000000E+00     |
| 1       | 3    | 5.429686E-02 | 1.163883E-01 | 1.163883E-01          | 1.000000E+00     |
| 1       | 4    | 5.443759E-02 | 1.169924E-01 | 1.169924E-01          | 1.000000E+00     |
| 1       | 5    | 5.865880E-02 | 1.358395E-01 | 1.358395E-01          | 1.000000E+00     |
| 1       | 6    | 6.449059E-02 | 1.641922E-01 | 1.641922E-01          | 1.000000E+00     |
| 1       | 7    | 2.964649E+03 | 3.469816E+08 | 3.469816E+08          | 1.000000E+00     |
| 1       | 8    | 3.068312E+03 | 3.716712E+08 | 3.716712E+08          | 1.000000E+00     |
| 1       | 9    | 7.812315E+03 | 2.409457E+09 | 2.409457E+09          | 1.000000E+00     |
| 1       | 10   | 8.063843E+03 | 2.567106E+09 | 2.567106E+09          | 1.000000E+00     |

Contour Plot  
Eigen Mode(Mag)  
Analysis system



Max = 2.522E+02  
Grids 62279  
Min = 6.007E-01  
Grids 132720



**TOOL :BB2**

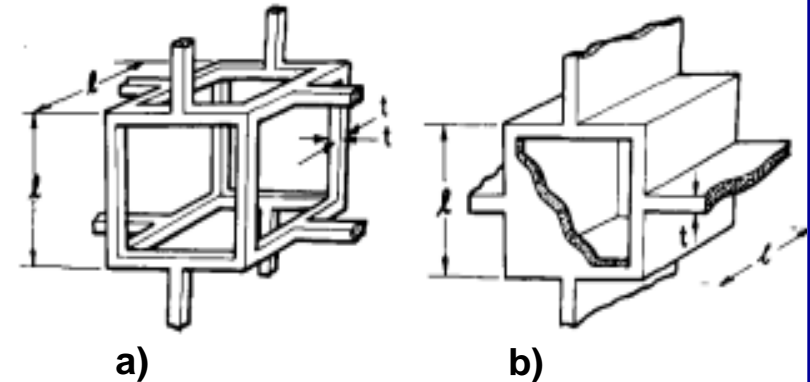
| 1ST MODAL FREQUENCY | EXPERIMENTAL RESULT |
|---------------------|---------------------|
| 2718 Hz             | 2846 Hz             |

| Subcase | Mode | Frequency    | Eigenvalue   | Generalized Stiffness | Generalized Mass |
|---------|------|--------------|--------------|-----------------------|------------------|
| 1       | 1    | 4.052611E-02 | 6.483800E-02 | 6.483800E-02          | 1.000000E+00     |
| 1       | 2    | 4.742017E-02 | 8.877403E-02 | 8.877403E-02          | 1.000000E+00     |
| 1       | 3    | 4.769268E-02 | 8.979726E-02 | 8.979726E-02          | 1.000000E+00     |
| 1       | 4    | 5.307609E-02 | 1.112135E-01 | 1.112135E-01          | 1.000000E+00     |
| 1       | 5    | 5.415954E-02 | 1.158003E-01 | 1.158003E-01          | 1.000000E+00     |
| 1       | 6    | 5.562908E-02 | 1.221697E-01 | 1.221697E-01          | 1.000000E+00     |
| 1       | 7    | 2.718155E+03 | 2.916810E+08 | 2.916810E+08          | 1.000000E+00     |
| 1       | 8    | 2.822189E+03 | 3.144357E+08 | 3.144357E+08          | 1.000000E+00     |
| 1       | 9    | 7.139099E+03 | 2.012086E+09 | 2.012086E+09          | 1.000000E+00     |
| 1       | 10   | 7.426188E+03 | 2.177166E+09 | 2.177166E+09          | 1.000000E+00     |

# Properties of Cellular solids



- The mechanical behaviour of cellular materials can be described by analysing the mechanisms by which the cells deform
- At **low relative densities**, it is made up of a network of rod like elements which form **open cells**. At **higher relative densities** (greater than 0.2) it is made up of a network of plate-like elements forming **closed Cells**
- **The results of the analysis depend on three parameters:**
  - The type of structure the cells form (for example, open or closed cells)
  - The volume fraction of solids, or relative density
  - Properties of the cell wall material

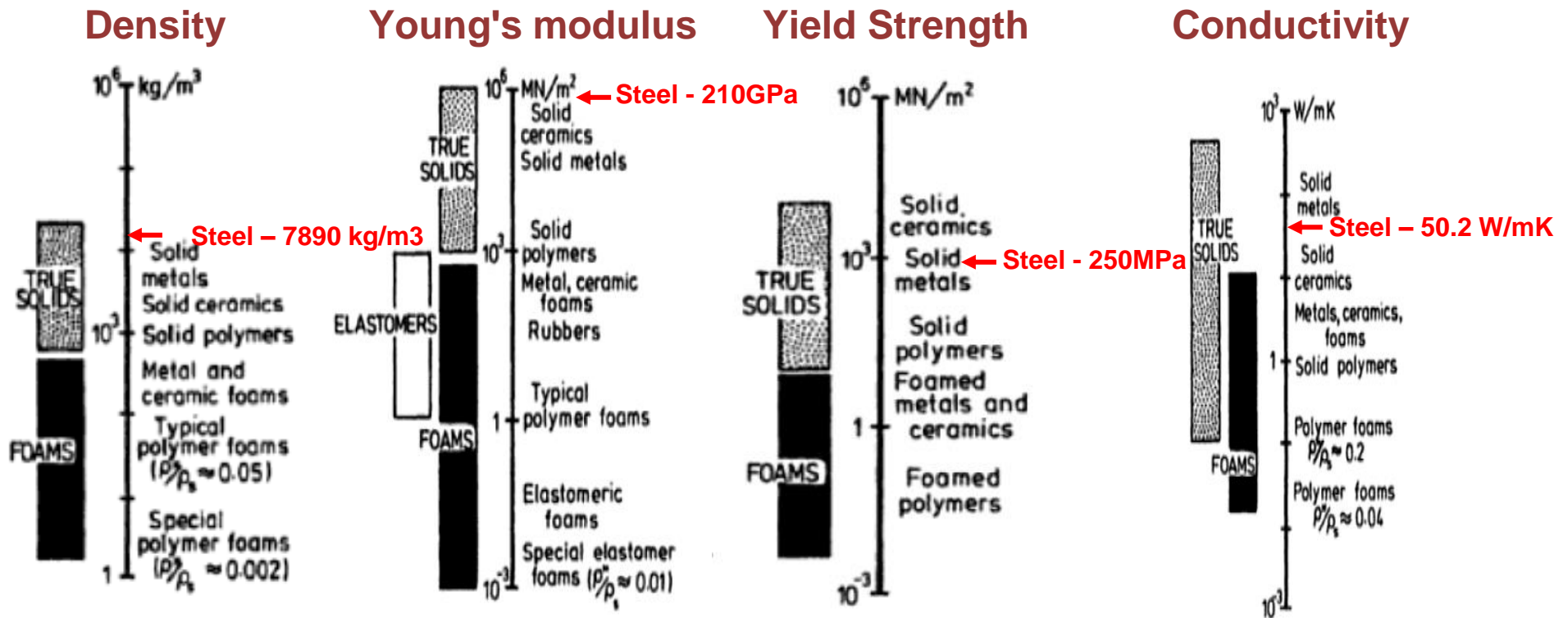


**Fig. 28** a) Open cell structure  
b) closed cell structure

**Source :** Gibson et al., 1981



# Properties of cellular solids


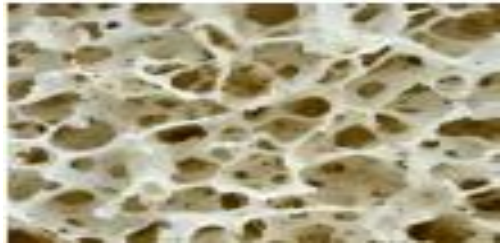



**Fig. 29** Properties of cellular solids (a) Density (b) Young's modulus (c) Yield Strength (d) Conductivity

**Source :** Classification and selection of cellular materials in mechanical design, 2019

# Study on Cellular solids cell shape , size and topology

# Cellular solids in nature

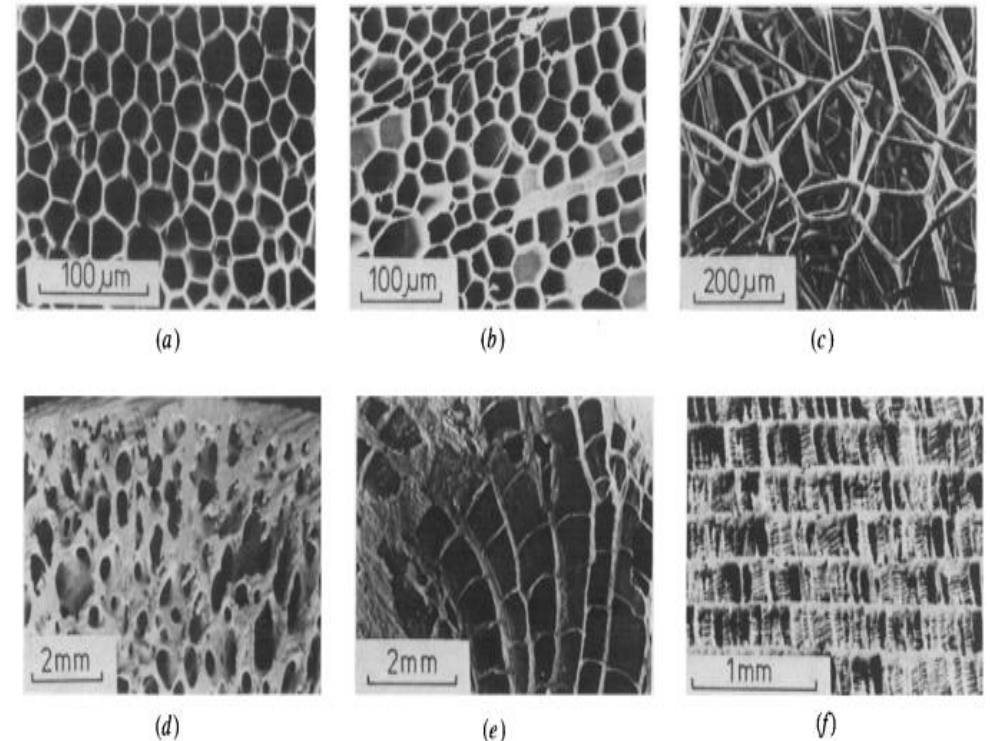
|  | Mechanical properties                          | Structure  |
|--|--|--|
| <b>Honeybee nest<br/>(Periodic)</b>      | High flexural , compressive strength           |  (a)  |
| <b>Trabecular bone<br/>(stochastic)</b>  | Toughness under compressive and impact loading |  (b)  |
| <b>Dragonfly wing<br/>(Hierarchical)</b> | Flexural rigidity , flexural stiffness         |  (c) |

**Table.3** Cellular solids in nature

**Fig. 30** Cellular solids in nature  
(a) Honeybee nest (b) Trabecular bone  
(c) Dragonfly wing.

# Structure of cellular solids in nature

- Natural cellular solids are anisotropic, they have directional property
- Natural cellular solids have pore size of minimum 10 microns

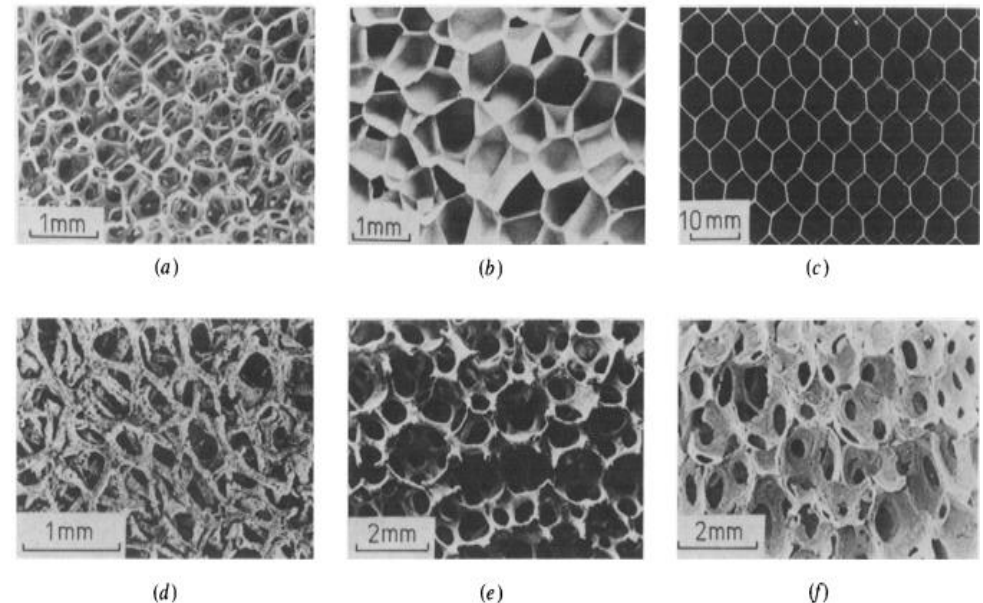


**Fig. 31** Natural cellular materials: (a) cork, (b) wood, (c) sponge, (d) coral, (e) bone (f) cuttle bone.

**Source :** Gibson et al., 1981

# Manufactured cellular solids

- Man made cellular solids are almost isotropic, meaning that their structure and their properties have no directionality
- Pore size of minimum 100 microns can be manufactured



**Fig. 32** Man-made cellular solids: (a) open cell polyurethane (b) closed cell polyurethane (c) aluminium honeycomb (d) copper (e) mullite (f) zirconia

**Source :** Gibson et al., 1981

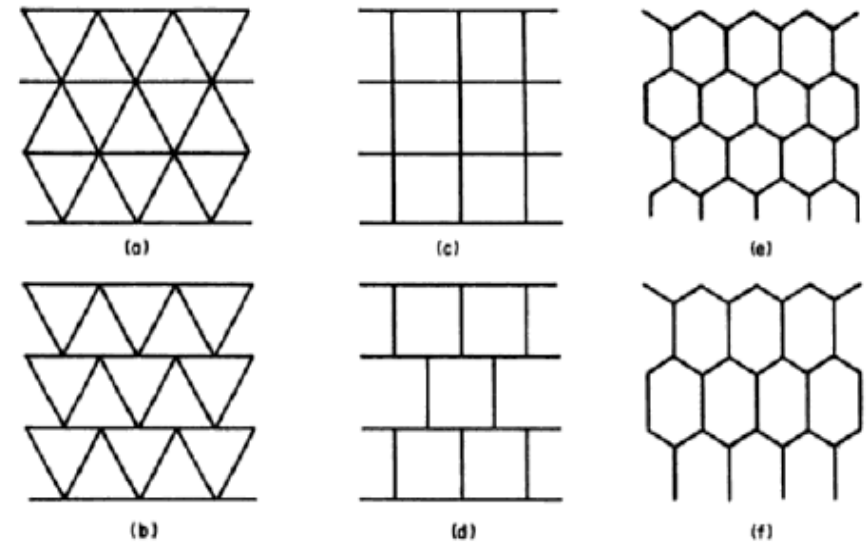
## Cell shape

- Periodic structure – Honeycomb has high flexural and compressive strength
- Selection of cell shape by Euler's law  

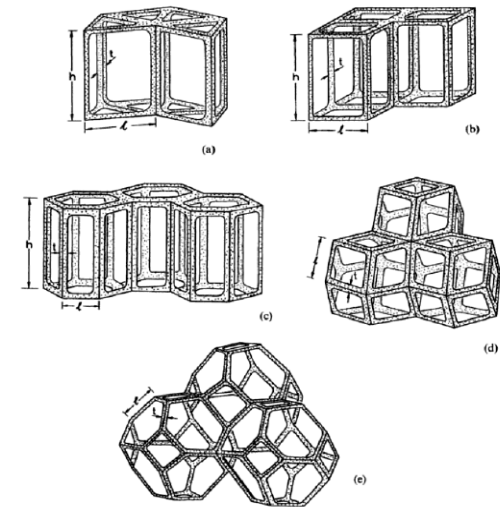
$$F - E + V = 1 \text{ (Two dimension)}$$

$$-C + F - E + V = 1 \text{ (Three dimension)}$$
- Using **hexagonal prism** structure has **uniform infill** throughout
- 4 and 5 sided cells can be also implemented in hexagonal prism infill
- Implementation of hexagonal prism(polyhedral)infill isotropic property can be achieved

**Source :** Gibson et.al , Cellular solids 1997



**Fig. 33** Packing of two dimensional cell to fill space



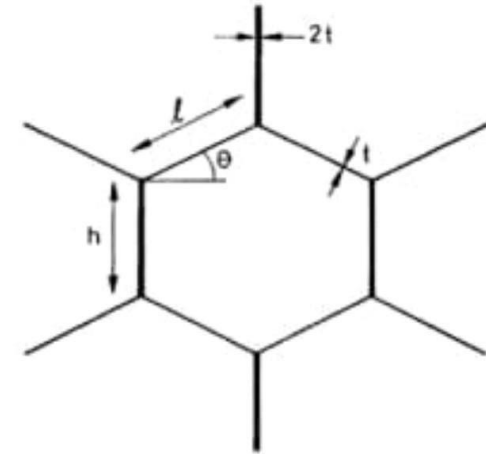
**Fig. 34** Packing of polyhedral to fill space



## Cell size

- Parameters for selection of cell size
  - Vertical length of cell wall (h-height of cell wall)
  - Inclined length of cell wall (length of cell wall)
  - Thickness of the cell wall (t)
  - Angle between the vertical and inclined cell wall known as cell angle ( $\theta$ )
  - Depth of the cell wall (d)
- Manufacturing by 3D printing limits the minimum size cell
- Minimum wall thickness manufactured by **3D printing** is **400 microns**

**Source :** msesuppliers, [www.3ders.org](http://www.3ders.org)



**Fig.35** Honeycomb cell parameters

**Source :** Gibson et.al , Cellular solids 1997

$$\text{Young's modulus } E_1^* = E_s \frac{\beta^3 \cos \theta}{(\alpha + \sin \theta) \sin^2 \theta}$$

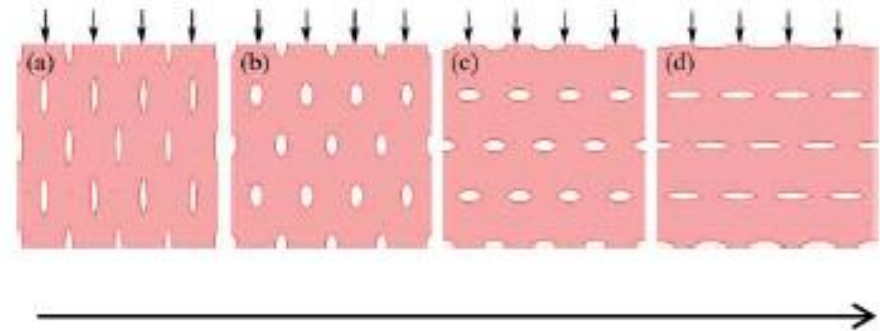
$$\text{Shear modulus } G_{12}^* = E_s \beta^3 \frac{(\alpha + \sin \theta)}{\alpha^2 (1 + 2\alpha) \cos \theta}$$

$$\text{Poison ratio } \nu_{12}^* = \frac{\cos^2 \theta}{(\alpha + \sin \theta) \sin \theta}$$

$$\beta = t/l \quad \alpha = h/l$$

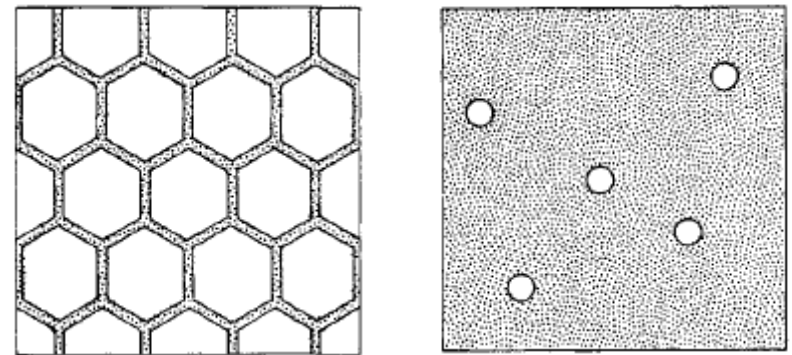
## Cell topology

- Pores having major axis parallel to the loading direction has better strength characteristics
- Large and low aspect ratio pores enhance flexural and compressive strength at the same relative density



Strength decreases

**Source:** Tuncer, N., et al. *Materials Science and Engineering A* 528 (2011):



**Fig.36** Comparison between a cellular solid and a solid with isolated pores

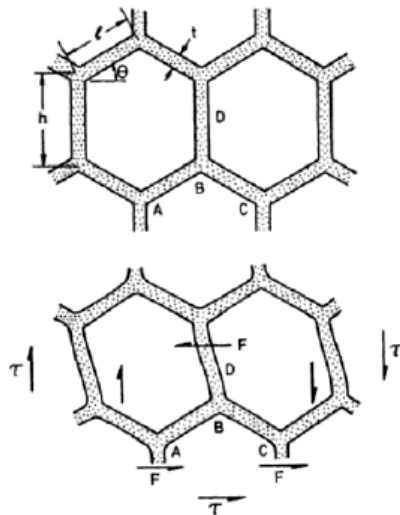
**Source :** Gibson et.al , Cellular solids 1997



# Deformation mechanism of Honeycombs

## Cell wall bending

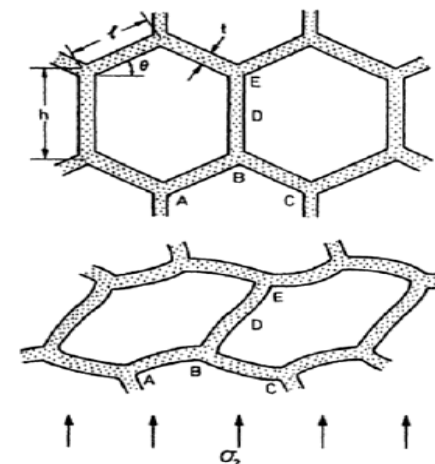
- Layer-wise collapse perpendicular to loading direction
  - Oscillation in stress strain curve



**Fig.37** Cell wall bending

## Cell wall buckling

- Shear localization occurs .  
Deformation at nearly constant applied stress by shear bands
  - Smooth stress strain diagram

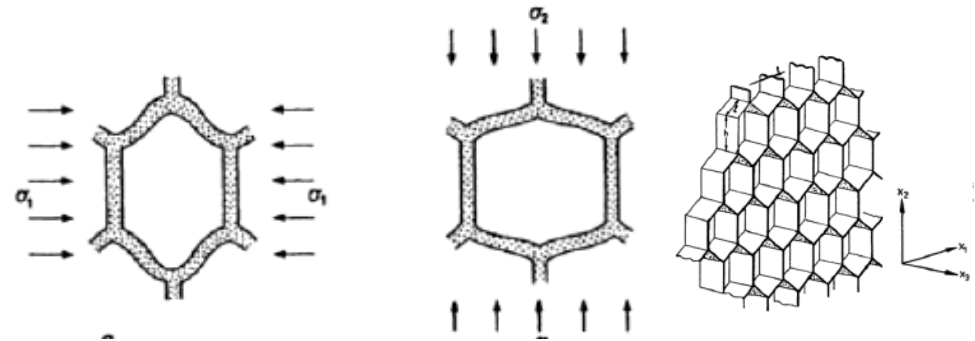


**Fig.38** Cell wall buckling

**Source :** Gibson et.al , Cellular solids 1997

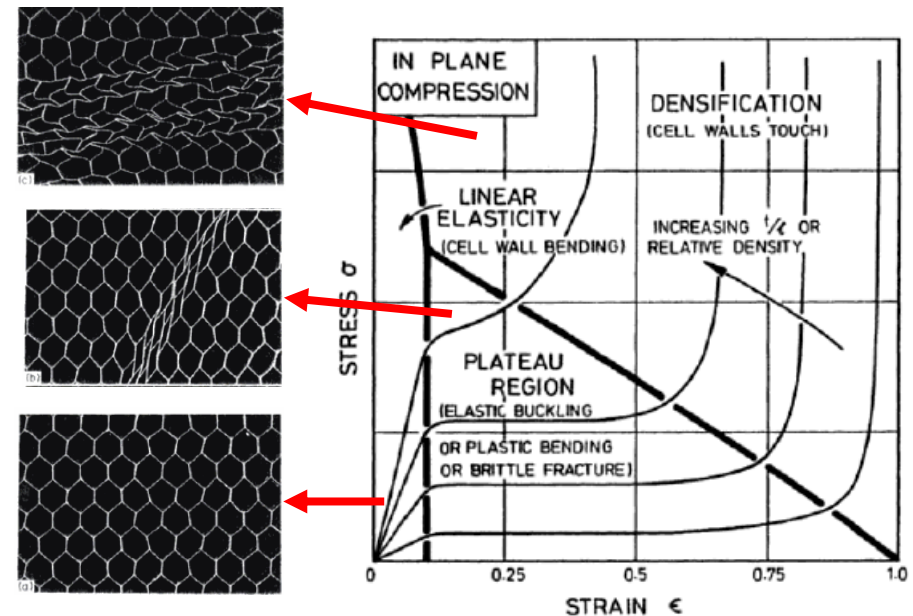
# In-plane deformation

- In-plane occurs in  $x_1$  and  $x_2$  direction of the honeycombs
- The **resistance to the cell wall bending** and cell collapse goes up, giving a higher modulus and plateau stress and cell walls touch sooner, reducing the strain at which densification begins
- To calculate deformation
  - **Isotropic** - two independent elastic moduli (young's modulus  $E$  and shear modulus  $G$ ) and size value of plateau stress ( $\sigma$ )
  - **Anisotropic** - ( $E_1^*$ ,  $E_2^*$ ,  $G_{12}^*$ ,  $\lambda_{12}^*$ ) two plateau stress ( $\sigma_1^*$ ,  $\sigma_2^*$ )



**Fig.39** In-plane deformation of honeycombs by cell wall bending (a) In  $X_1$  direction (b)  $X_2$  direction

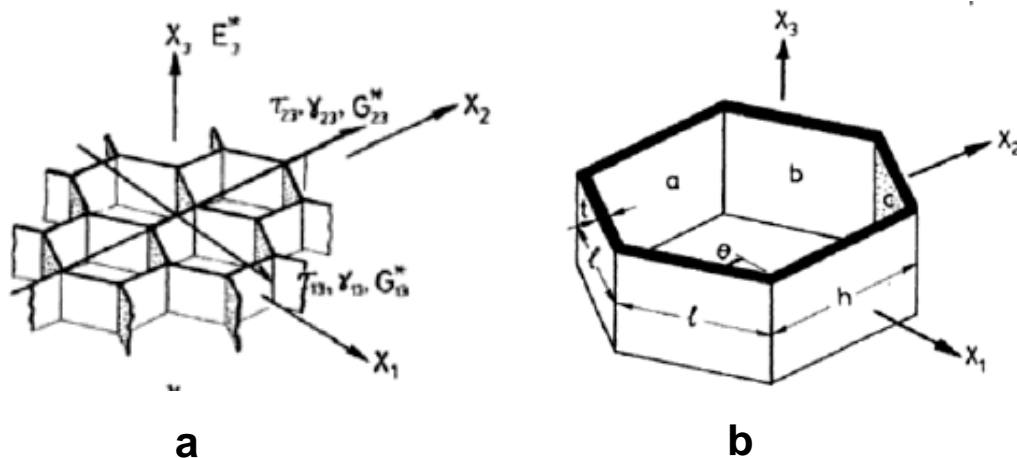
**Source :** Gibson et.al , Cellular solids 1997



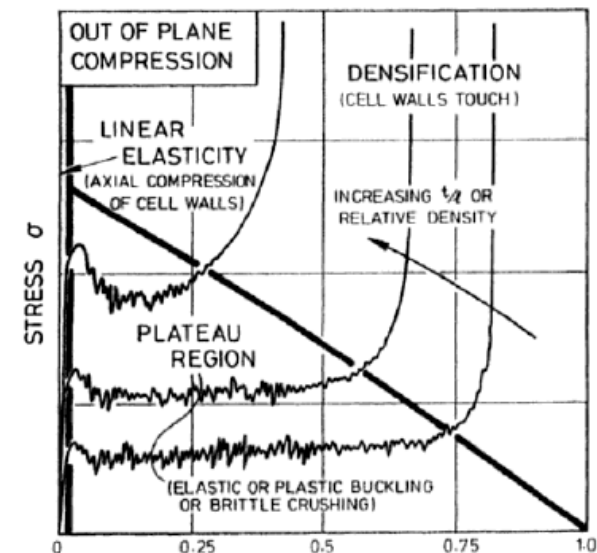
**Fig.40** In-plane mechanism of aluminium in compression  $X_1$  ,  $X_2$  direction

# Out of plane deformation

- Out of plane deformation occurs in  $x_3$  direction of the honeycombs.
- Cell wall thickness determines the stiffness and strength when it is loaded along the axis in the  $x_3$  direction



**Fig.41** Out-plane deformation of honeycombs in  $X_3$  direction  
(a) In honeycombs (b) In unit cell

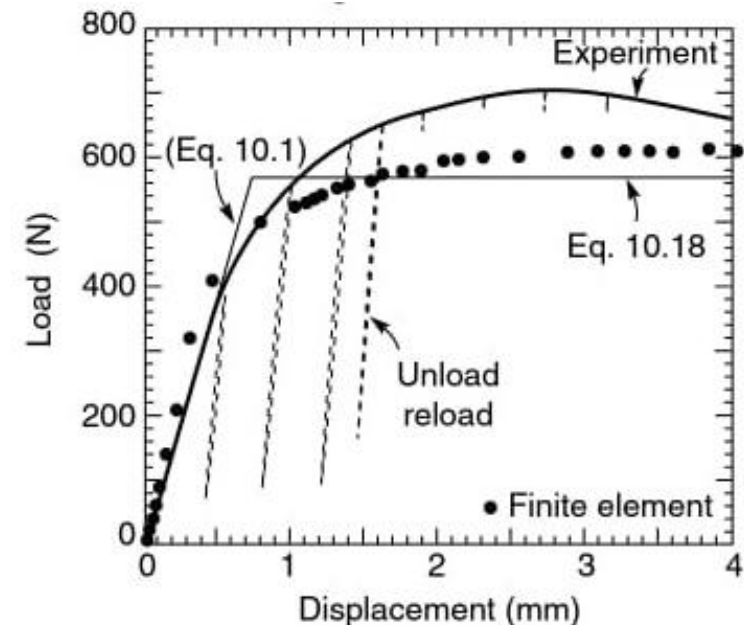
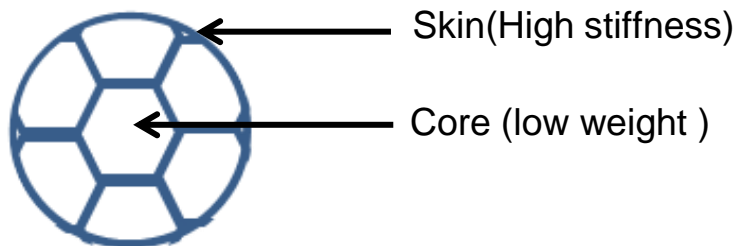


**Fig.42** Out-plane mechanism of aluminium in compression in  $X_3$  direction

**Source :** Gibson et.al , Cellular solids 1997

## Why sandwich structure?

- Two solid surfaces(skins) separated by a lightweight core
- Separation of skins by core increases moment of inertia, with little increase in weight
- Sandwich plate exhibits high bending stiffness (flexural rigidity) for lower mass and has a low shear modulus which makes them a better source of damping
- Mechanical behavior of sandwich panel depends on properties of core , face and on its geometry



**Fig. 43** Load vs displacement of sandwiched structure

**Source** : ASHBY R et al, Metal foams : A design guide M.F., 2000

# DESIGN OF HONEYCOMB STRUCTURE

Cellular solids relative density should be less than 0.3

## RELATIVE DENSITY OF CELL AGGREGATE

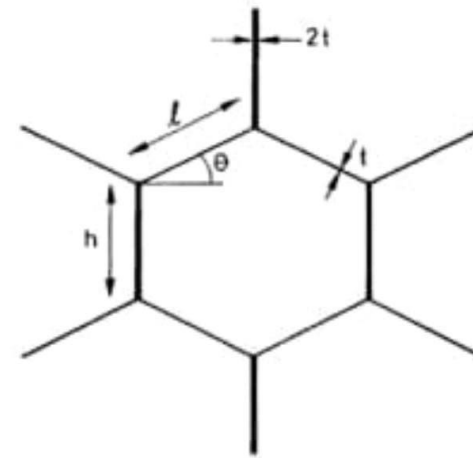
$$\frac{\rho^*}{\rho_s} = \frac{2}{\sqrt{3}} \frac{t}{l} \left( 1 - \frac{2}{\sqrt{3}} \frac{t}{l} \right) \text{ ---- Eq.26}$$

$$\frac{t}{l} = \mathbf{0.365}$$

$$\frac{\rho^*}{\rho_s} = \frac{t/l (h/L + 1)}{(h/l + \sin \theta) \cos \theta} \text{ ---- Eq.27 } \theta = 30^\circ$$

Substituting  $t/l$  in Eq.2

$$\frac{h}{L} = \mathbf{0.566}$$



**Fig.44** Honeycomb cell parameters

**Source :** Gibson et.al , Cellular solids 1997

# Concluding remarks

- **Honeycomb structure** has high flexural strength and compressive strength
- Cell size of minimum 400 microns wall thickness can be only manufactured
- High flexural strength is resulted in topology having pore size major axis in loading direction

# Selection of material



| <b>Properties</b>                                  | <b>17-4 PH<br/>Stainless Steel</b> | <b>H13 Tool<br/>Steel</b> | <b>Inconel 625</b> | <b>Titanium<br/>(Ti6Al4V)</b> |
|--|------------------------------------|---------------------------|--------------------|-------------------------------|
| <b>Density, <math>\rho</math> g/cm<sup>3</sup></b> | 7.75                               | 7.80                      | 8.44               | 4.83                          |
| <b>Young's<br/>modulus, E –GPa</b>                 | 210                                | 250                       | 200                | 113                           |
| <b>Ultimate tensile<br/>strength MPa</b>           | 1050-1250                          | 1420-1500                 | 558-765            | 900-950                       |
| <b>Poisson's ratio, <math>\nu</math></b>           | 0.27-0.30                          | 0.27-0.30                 | 0.26-0.28          | 0.31-0.37                     |
| <b>Cost<br/>(RS)(approx.)</b>                      | 12,000/Kg                          | 17,000/Kg                 | 12,000/Kg          | 20,000/Kg                     |

**Table.4** Materials for manufacturing cellular solids**Source :** Msesuppliers, [www.3ders.org](http://www.3ders.org)

- Material is finalized based on availability of manufacturing resources

# Why additive manufacturing for cellular materials ?

## ➤ Additive manufacturing offers advantages

- Local tunability
- Complex, Non-stochastic shapes
- Low cost penalty for complexity
- Multi-material

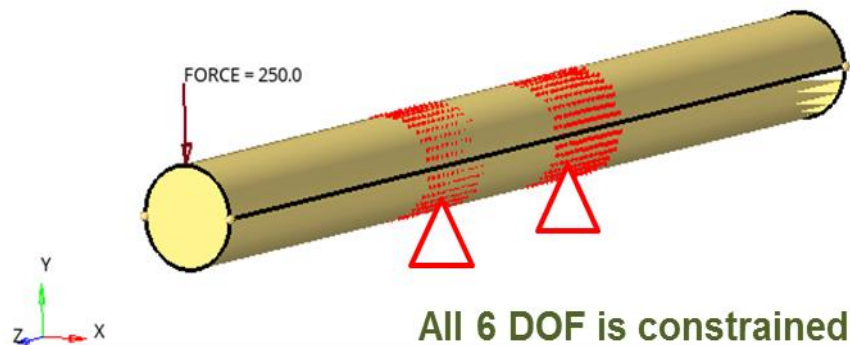
## ➤ Additive manufacturing considerations

- Dimensional accuracy
- Feature resolution
- Defects
- Cleaning
- Inspection

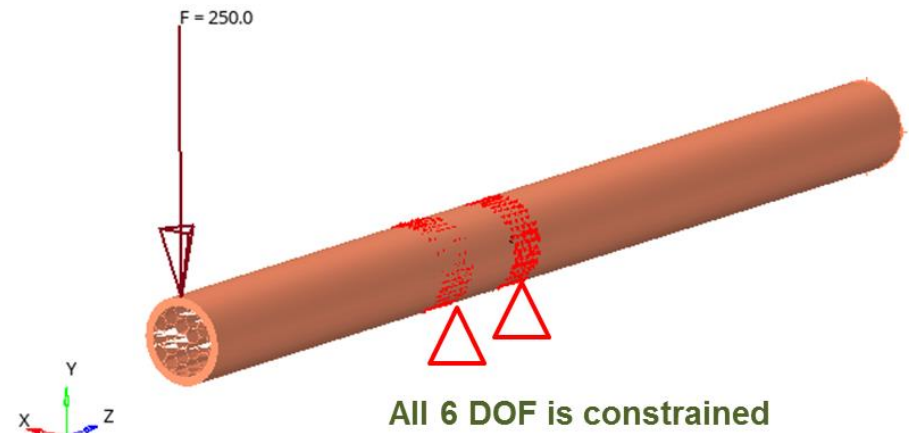
# Linear static analysis

## Loads and boundary condition

Solid structured bar

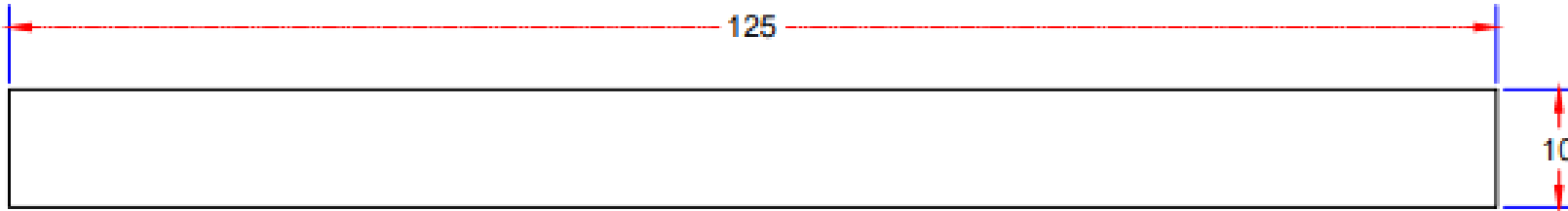


Honeycomb structured bar

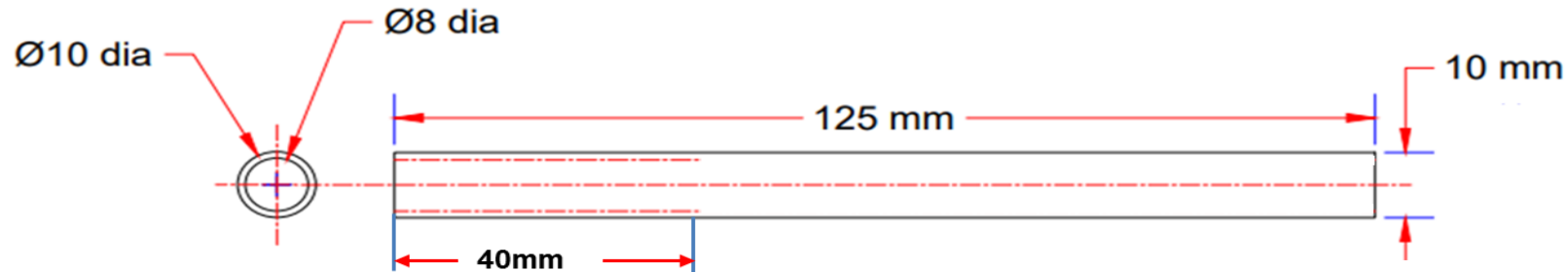


# Specimen design

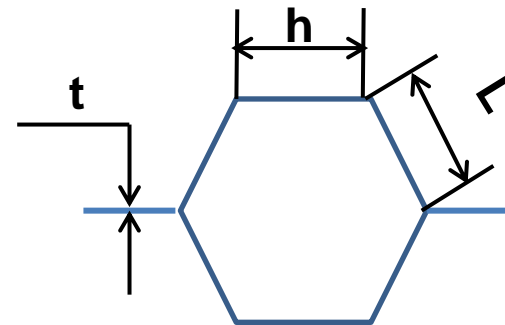
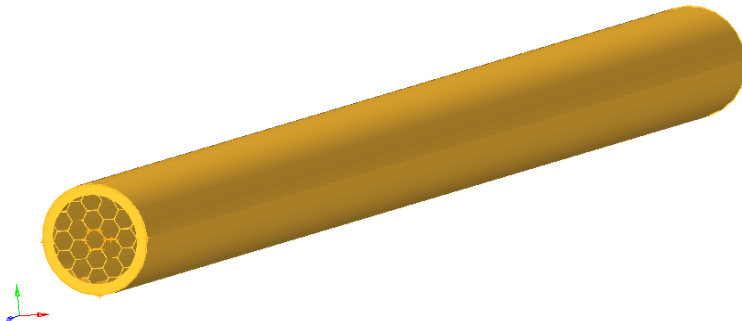
## SOLID BAR



## HOLLOW BAR

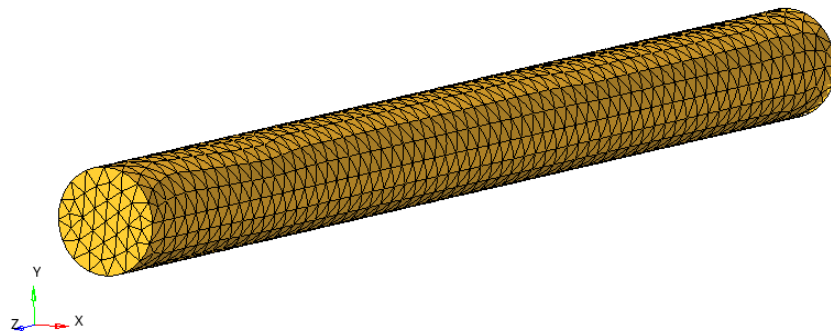


## HOLLOW BAR FILLED WITH CELLULAR STRUCTURE

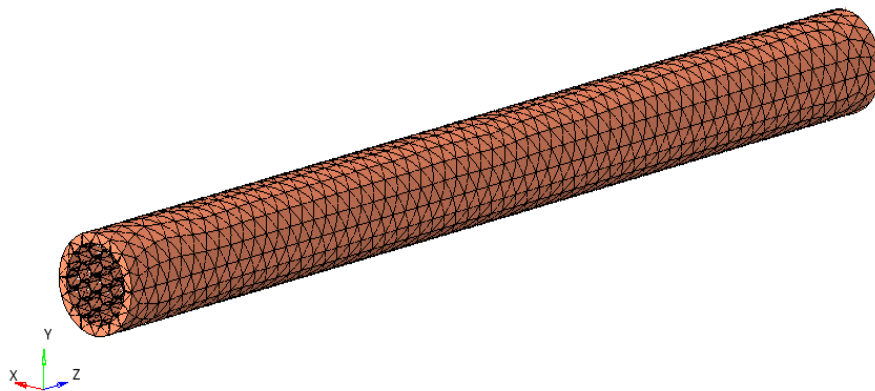


# Finite element model

## Solid structured bar



## Honeycomb structured bar



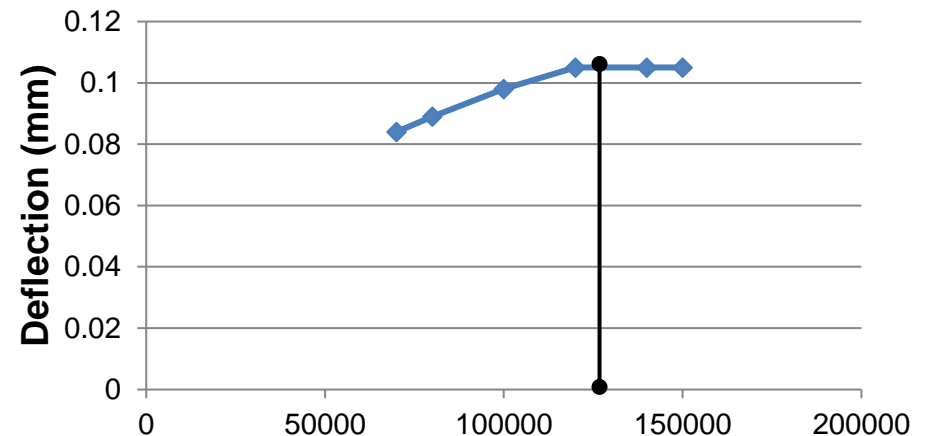
**Preprocessor** : Hyper mesh

**Solver** : OptiStruct

**Postprocessor** : Hyper view

| MATERIAL | YOUNGS MODULUS<br>E | POISON RATIO<br>$\nu$ | DENSITY<br>$\rho$ |
|----------|---------------------|-----------------------|-------------------|
| STEEL    | 210GPa              | 0.3                   | 7890 Kg/m3        |

## Mesh convergence study



**No of elements**

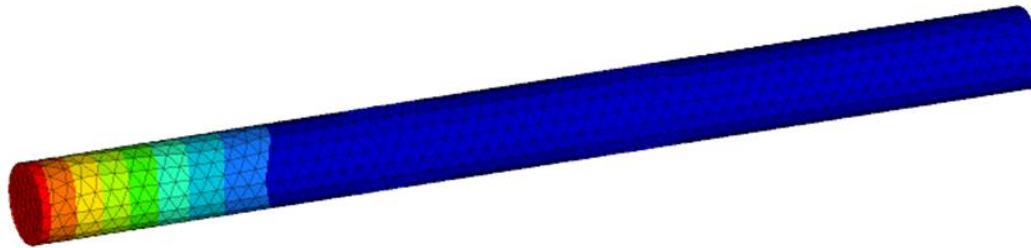
Number of elements = 121649

## Displacement plot - Solid bar

Contour Plot  
Displacement(Mag)  
Analysis system

5.710E-02  
5.076E-02  
4.441E-02  
3.807E-02  
3.172E-02  
2.538E-02  
1.903E-02  
1.269E-02  
6.345E-03  
0.000E+00  
No Result

Max = 5.710E-02  
Grids 149746  
Min = 0.000E+00  
Grids 149596



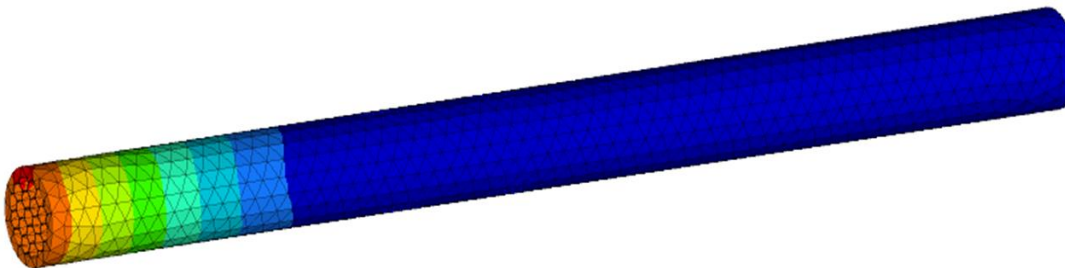
Maximum displacement = 0.0571 mm

## Honeycomb structure bar

Contour Plot  
Displacement(Mag)  
Analysis system

1.050E-01  
9.337E-02  
8.170E-02  
7.003E-02  
5.835E-02  
4.668E-02  
3.501E-02  
2.334E-02  
1.167E-02  
0.000E+00  
No Result

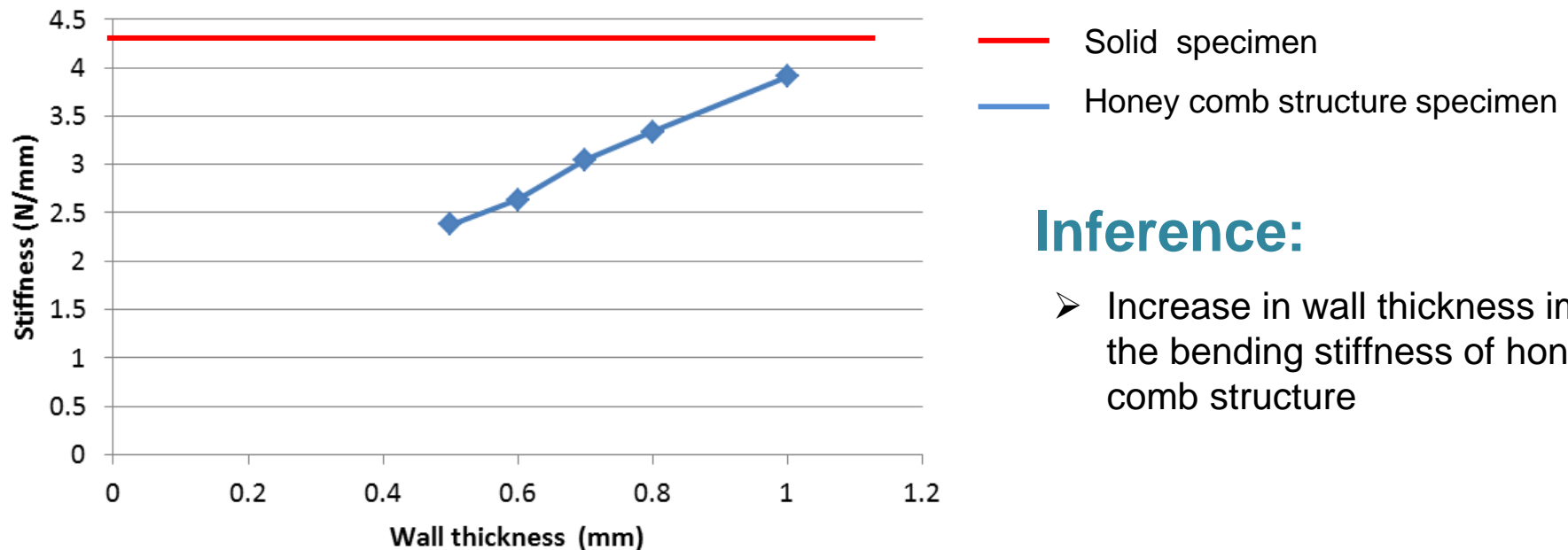
Max = 1.050E-01  
Grids 660  
Min = 0.000E+00  
Grids 1 Z



Maximum displacement = 0.105 mm

| Thickness (t)<br>(mm) | Height (h)<br>(mm) | Length (l)<br>(mm) | Displacement<br>(mm) | Stiffness<br>(kN/mm) | Mass<br>(kg ) |
|-----------------------|--------------------|--------------------|----------------------|----------------------|---------------|
| 0.5                   | 0.70               | 1.38               | 0.105                | 2.380                | 0.034         |
| 0.6                   | 0.85               | 1.67               | 0.095                | 2.631                | 0.039         |
| 0.7                   | 0.98               | 1.94               | 0.082                | 3.048                | 0.041         |
| 0.8                   | 1.12               | 2.22               | 0.075                | 3.333                | 0.046         |
| 1                     | 1.40               | 2.77               | 0.064                | 3.906                | 0.053         |
| Solid bar             |                    |                    | 0.0571               | 4.378                | 0.077         |

**Table.5** FEA results of honeycomb structure bar

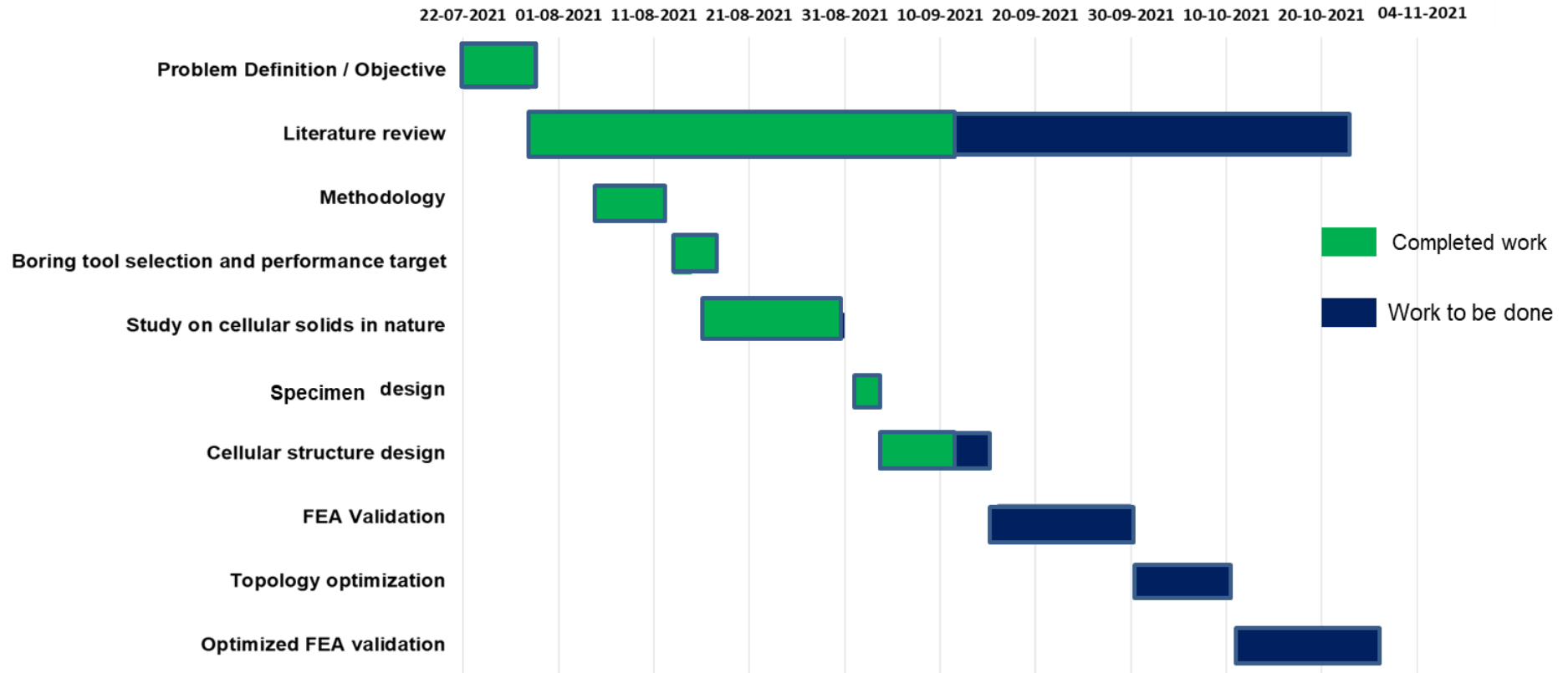


## Inference:

- Increase in wall thickness improves the bending stiffness of honey comb structure



# Gantt chart



| TASK             | Problem Definition / Objective | Literature review | Methodology | Boring tool selection and performance target | Study on cellular solids in nature | Specimen design | Cellular structure design | FEA Validation | Topology optimization | Optimized FEA validation |
|------------------|--------------------------------|-------------------|-------------|--|------------------------------------|-----------------|---------------------------|----------------|-----------------------|--------------------------|
| START DATE       | 22-07-2021                     | 29-07-2021        | 05-08-2021  | 13-08-2021                                   | 16-08-2021                         | 01-09-2021      | 04-09-2021                | 16-09-2021     | 01-10-2021            | 11-10-2021               |
| DAYS TO COMPLETE | 7                              | 84                | 7           | 2  | 15                                 | 2               | 11                        | 14             | 9                     | 10                       |

*Thank you*